

# Linear Algebra Notes

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## Spectral Theorem, Positive/Negative Operators

Need more info on the min polynomial of  $T$  over  $\mathbb{C}$ . In  $\mathbb{C}$ , this factors into linear factors  $(z - z_j)$  we already know each  $z_j$  must be real since  $T$  is self-adjoint. Over  $\mathbb{R}$ , we need to rule out quadratic factors:  $z^2 + az + b$  or in other words, we require that  $a^2 - 4b < 0$ . Plug in  $T$  and consider

$$\begin{aligned}\langle Tv, v \rangle &= \langle (T^2 + aT + bI)v, v \rangle = \langle T^2v, v \rangle + a\langle Tv, v \rangle + b\langle v, v \rangle \\ &= \langle Tv, Tv \rangle + a\langle Tv, v \rangle + b\langle v, v \rangle \\ &= \|Tv\|^2 + a\langle Tv, v \rangle + b\|v\|^2 \\ &\geq \|Tv\|^2 - |a|\|Tv\|\|v\| + b\|v\|^2 = (\|Tv\| - \frac{|a|}{2}\|v\|)^2 - \frac{|a|^2}{4}\|v\|^2 + b\|v\|^2 \\ &= (\|Tv\| - \|v\|\frac{|a|}{2})^2 + (b - \frac{a^2}{4})\|v\|^2 \geq 0\end{aligned}$$

This expression can be 0 only if  $\|v\| = 0$  which means that  $v = 0$ . So  $T^2 + aT + bI$  is an invertible operator. So if  $p_{\min}(z)$  contains  $q(z)$  as a factor, we would have

$$p_{\min}(T) = q(T) \cdot h(T) = 0 \quad \text{for some polynomial } h(z)$$

So  $h(T) = 0$  and  $q(T)$  does not belong in the minimal polynomial. So if  $T = T^*$ , its minimal polynomial has only linear factors  $z - z_j$ , where each  $z_j \in \mathbb{R}$ . So  $\mathcal{M}(T)$  is upper triangular in some orthonormal basis. But then  $\mathcal{M}(T^*) = \overline{\mathcal{M}(T)}^T = \mathcal{M}(T)$ . That means that  $\mathcal{M}(T)$  is diagonal.

## Complex Spectral Theorem

Theorem

### Complex Spectral Theorem

Over  $\mathbb{C}$ , the following are equivalent

- (a)  $T \in \mathcal{L}(V)$  is normal
- (b) There is a diagonal matrix representation for  $T$  with respect to some orthonormal basis.

Main points of the proof: (a)  $\rightarrow$  (b) we start by Schur's theorem with an upper-triangular form

for  $T$  with respect to some orthonormal basis:

$$\begin{aligned}\mathcal{M}(T) &= \begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ 0 & a_{22} & a_{23} & \dots & a_{2n} \\ 0 & 0 & a_{33} & \dots & a_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & a_{nn} \end{bmatrix} \\ &= \|Te_1\|^2 = |a_{11}^2| \\ &= \|T^*e_1\|^2 = \sum_{j=1}^n |a_{1,j}|^2\end{aligned}$$

Since the norms are equal, then for  $a_{1,j}$  for  $j \neq 1$ , they must be 0. By applying this same observation, to each  $Te_j$  and  $T^*e_j$ , we conclude all off-diagonal entries must be zero.  $(b) \rightarrow (a)$  is clear since any 2 diagonal matrices commute.

## Nonnegative and Positive Operators

### Definition

#### Positive and Nonnegative Operators

**Definition:** Let  $V$  be a finite-dimensional inner product space. An operator  $T \in \mathcal{L}(V)$  is called nonnegative if  $T = T^*$  and

$$\langle Tv, v \rangle \geq 0 \quad \forall v \in V$$

$T$  is called positive if  $T = T^*$  and

$$\langle Tv, v \rangle > 0 \quad \forall v \in V \setminus \{0\}$$

Characterization of nonnegative and positive operators. Let  $T \in \mathcal{L}(V)$ , then the following are equivalent

- (a)  $T$  is positive /  $T$  is nonnegative
- (a)  $T = T^*$  and all its eigenvalues are positive /  $T = T^*$  and all its eigenvalues are nonnegative.
- (c) With respect to some orthonormal basis,  $\mathcal{M}(T)$  is diagonal with all diagonal terms positive / With respect to some orthonormal basis,  $\mathcal{M}(T)$  is diagonal with all diagonal terms nonnegative
- (d)  $T$  has a positive square root /  $T$  has a nonnegative square root.
- (e)  $T$  has a self-adjoint square root  
 $T$  is invertible No requirements
- (f)  $T = R^*R$  for some  $R$  invertible /  $T = R^*R$  for some  $R$

*Proof.*  $(a) \rightarrow (b) \rightarrow (c)$  is straightforward.

$(c) \rightarrow (a)$ : Any vector  $v \in V$  can be written as  $v = a_1e_1 + \dots + a_ne_n$  where  $(e_j)$  are orthonormal and  $Te_j = \lambda_je_j$ .

$$Tv = a_1\lambda_1e_1 + \dots + a_n\lambda_ne_n$$

So

$$\begin{aligned}\langle Tv, v \rangle &= \langle a_1\lambda_1e_1 + a_2\lambda_2e_2 + \dots + a_n\lambda_ne_n, a_1e_1 + a_2e_2 + \dots + a_ne_n \rangle \\ &= \lambda_1|a_1|^2 + \lambda_2|a_2|^2 + \dots + \lambda_n|a_n|^2 \geq 0\end{aligned}$$

Moreover, in case  $\lambda_j > 0$  for all  $j = 1, \dots, n$ , this expression is positive unless every  $a_j = 0$ . This would imply that  $v = 0$ .  $\square$

What about square roots? We say that  $R$  is a square root of  $T$  if  $R = R^*$ ,  $T = R^2$ . If  $T$  is positive, it has a positive square root and if  $T$  is nonnegative, it has a nonnegative square root. Actually, the positive/nonnegative square root is necessarily unique.

$$\begin{aligned} T e_j &= \lambda_j e_j \\ R e_j &= \sqrt{\lambda_j} e_j \end{aligned}$$

the eigenvector of  $R$  is the same as with  $T$ , and the eigenvalues are determined by  $T$ . So the square root is unique.

(e) corresponds to dropping the positivity / nonnegativity condition on the square root and (f) corresponds to dropping the self-adjointness condition on the square root.

$$R^* R = \begin{bmatrix} \lambda_1 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \lambda_n \end{bmatrix}$$

## SVD

### Theorem

Suppose that  $T \in \mathcal{L}(V, W)$ . Then

- (a)  $T^*T$  is nonnegative
- (b)  $\ker T^*T = \ker T$
- (c)  $\text{Im}\{T^*T\} = \text{Im}\{T^*\}$
- (d)  $\dim \text{Im}\{T^*T\} = \dim \text{Im}\{T^*\} = \dim \text{Im}\{T\}$

*Proof.* (a)  $(T^*T)^* = T^*T^{**} = T^*T \rightarrow \langle T^*T v, v \rangle = \langle T v, T v \rangle \geq 0$   
 (b)  $\ker T \subseteq \ker T^*T$ . Suppose  $v \in \ker T^*T$  so  $T^*T v = 0$  so  $\|T v\| = 0 \rightarrow T v = 0 \rightarrow v \in \ker T$   
 (c)  $\text{Im}\{T^*T\} = [\ker (T^*T)^*]^\perp = (\ker T^*T)^\perp = (\ker T)^\perp = \text{Im}\{T^*\}$   
 (d)  $\dim \text{Im}\{T^*T\} = \dim \text{Im}\{T^*\} = \dim \text{Im}\{T\}$

$\square$

### Definition

#### Singular Value Decomposition

The singular values of  $T$  are defined as the square roots of the eigenvalues of  $T^*T$ , usually ordered from largest to smallest and called

$$s_1 \geq s_2 \geq \dots \geq s_n \geq 0$$

### Theorem

Suppose  $T \in \mathcal{L}(V, W)$  and the positive singular values of  $T$  are  $s_1, \dots, s_m$ . Then there exist orthonormal vectors  $e_1, \dots, e_m$  in  $V$  and  $f_1, \dots, f_m$  in  $W$  such that

$$T v = s_1 \langle v, e_1 \rangle f_1 + \dots + s_m \langle v, e_m \rangle f_m$$

*Proof.* Recall the eigenvalues of  $T^*T$  are  $s_1^2, \dots, s_m^2, \underbrace{s_{m+1}^2, \dots, s_n^2}_{=0}$ . Since  $T^*T$  is self-adjoint, there

is an orthonormal basis  $e_1, e_2, \dots, e_n$  such that  $T^*Te_j s_j^2 e_j$ . Define  $f_j := \frac{1}{s_j}Te_j$  for  $j = 1, \dots, m$

$$\begin{aligned}\langle f_j, f_k \rangle &= \frac{1}{s_j s_k} \langle Te_j, Te_k \rangle \\ &= \frac{1}{s_j s_k} \langle \underbrace{T^*Te_j}_{s_j^2 e_j}, e_k \rangle = \begin{cases} 1 & \text{if } j = k \\ 0 & \text{otherwise} \end{cases}\end{aligned}$$

An arbitrary  $v \in V$  can be written as  $v = \langle v, e_1 \rangle e_1 + \dots + \langle v, e_n \rangle e_n$ . the action:

$$\begin{aligned}Tv &= \langle v, e_1 \rangle Te_1 + \dots + \langle v, e_n \rangle Te_n \\ &= s_1 \langle v, e_1 \rangle f_1 + \dots + s_m \langle v, e_m \rangle f_m.\end{aligned}$$

□

## Isometries

Special class of operators/linear maps where  $S \in \mathcal{L}(V, W)$  iff

$$\begin{aligned}\|Sv\| &= \|v\| & \forall v \in V \\ \langle Sv, Sv \rangle &= \langle v, v \rangle \\ \langle S^*Sv, v \rangle &= \langle v, v \rangle \\ \langle (S^*S - I)v, v \rangle &= 0 \\ S^*S &= I\end{aligned}$$

## Jordan Normal Form

$$\begin{bmatrix} \lambda_1 & 1 & \dots & 0 \\ 0 & \lambda_1 & 1 & \vdots \\ 0 & 0 & \ddots & 1 \\ 0 & 0 & 0 & \lambda_1 \\ & & & \lambda_2 & 1 & \dots & 0 \\ & & & 0 & \lambda_2 & 1 & \vdots \\ & & & 0 & 0 & \ddots & 1 \\ & & & 0 & 0 & 0 & \lambda_2 \\ & & & & & \ddots & \\ & & & & & & \lambda_n & 1 & \dots & 0 \\ & & & & & & 0 & \lambda_n & 1 & \vdots \\ & & & & & & 0 & 0 & \ddots & 1 \\ & & & & & & 0 & 0 & 0 & \lambda_n \end{bmatrix}$$

Disclaimer: to guarantee this decomposition, we need to work over  $\mathbb{R} = \mathbb{C}$ .

1. If  $\mathbb{F} = \mathbb{C}$  and  $\dim B \geq 1$ , then  $T$  always has an eigen value. Call it  $\lambda_1 \in \mathbb{C}$ . Consider the chain

$$\ker(T - \lambda_1 I) \subseteq \ker(T - \lambda_1 I)^2 \subseteq \ker(T - \lambda_1 I)^3$$

Since  $V$  is finite-dimensional, there exists a  $k$  such that

$$\ker(T - \lambda_1 I)^k = \ker(T - \lambda_1 I)^{k+j}$$

Now consider

$$\ker(T - \lambda_1 I)^k \cap \text{Im}\{(T - \lambda_1 I)^k\}$$

If  $v \in \ker(T - \lambda_1 I)^k$ , then  $v = (T - \lambda_1 I)^k u$  and that  $(T - \lambda_1 I)^k v = 0$ , or in other words,  $(T - \lambda_1 I)^{2k} u = 0$ . But then  $(T - \lambda_1 I)^k u = 0$ . So  $v = \ker(T - \lambda_1 I)^k \oplus \text{Im}\{(T - \lambda_1 I)^k\}$ . Both of these spaces are  $T$  invariant.

This reduces the problem to the case of a single eigenvalue. In fact, wlog,  $\lambda_1 = 0$ , by shifting. Recall  $T^k = 0$  on our subspace but  $T^{k-1} \neq 0$ . So there exists  $v \in$  our subspace such that  $T^{k-1} v \neq 0$ . Then there exists a  $u \in$  the same subspace such that  $\langle T^{k-1} v, u \rangle \neq 0$ . Here our subspace is  $\ker(T - \lambda_1 I)^k$ . Call  $T' = T - \lambda_1 I$ . Consider the matrix  $\langle \langle T'^{j-1} v, T'^{k-j} u \rangle \rangle_{j=1, \dots, k}^{i=1, \dots, k}$ . This is a matrix of size  $k \times k$ .

$$\begin{aligned} & \langle T'^{j-1} v, T'^{k-i} u \rangle \\ &= \langle T^{k+j-i-1} v, u \rangle = \begin{cases} \neq 0 & \text{if } i = j \\ 0 & \text{if } j > i \end{cases} \end{aligned}$$

This matrix is invertible because it's triangular with nonzeros on the main diagonal. Take the vectors

$$v, T v, \dots, T^{k-1} v$$

Since any dependence among these vectors would give rise to the same dependence among the columns of the above matrix, they must be independent. So

$$T = \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Since every  $T$ -invariant space is subject to this process, we can split the entire space into subspaces spanned by these Jordan chains.

## Instructions for Jordan Normal Form

### Examples

1. Find the JNF and Jordan basis for  $D : \mathcal{L}(V)$  where  $V = \mathcal{P}_3(\mathbb{R})$ .

$$\text{JNF}(D) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{aligned} f_1(x) &= 1 \\ f_2(x) &= x \\ f_3(x) &= \frac{x^2}{2} \\ f_4(x) &= \frac{x^3}{3!} \end{aligned}$$

2.

$$\begin{bmatrix} 1 & 1 & 0 & & & & & & \\ 0 & 1 & 1 & & & & & & \\ 0 & 0 & 1 & & & & & & \\ & & & 1 & 1 & & & & \\ & & & 0 & 1 & & & & \\ & & & & & 0 & 1 & 0 & \\ & & & & & 0 & 0 & 1 & \\ & & & & & 0 & 0 & 0 & \\ & & & & & & & & 0 & 1 & 0 \\ & & & & & & & & 0 & 0 & 1 \\ & & & & & & & & 0 & 0 & 0 \end{bmatrix}$$

$\dim V = 11j$	$\dim \ker T = 2$
$\dim \ker T^2 = 4$	$\dim \ker T^3 = 6$
$\dim \ker T^4 = 6 = \dim \ker (T^6)$	

We also have

- (a)  $\dim \ker T - I = 2$
- (b)  $\dim \ker T - I^2 = 4$
- (c)  $\dim \ker T - I^3 = 5$
- (d)  $\dim \ker T - I^4 = 5$

3. Given the following info:

- (a)  $T$  has 3 eigenvalues:  $i, -i, 0$
- (b)  $\dim \ker (T) = 3$
- (c)  $\dim \ker T^2 = 5$
- (d)  $\dim \ker T^3 = 6$
- (e)  $\dim \ker T - iI = 2$
- (f)  $\dim \ker T + iI^2 = 4$
- (g)  $\dim \ker T + iI^3 = 6$
- (h)  $\dim \ker T - iI = 4$
- (i)  $\dim \ker T - iI = 6$

Let the operator be  $T: \frac{\partial}{\partial x} + \frac{\partial}{\partial y}$  and  $V$  has a basis  $\{1, x, y, x^2, xy, y^2\}$ . The action of  $T$  reduces the degree of the polynomials. The eigenvalue is 0 because we need to apply  $T$  enough times to kill all the basis vectors. We need to apply  $T$  3 times to send all vectors to 0. So the  $\dim \ker (T)^3 = 6$ , as it kills the whole space. What are

- Take

We can find the dimension of the null space by looking at the dimension of the range:

- So we can find the Jordan Normal Form:

$$\begin{bmatrix} 0 & 1 & 0 & & & \\ 0 & 0 & 1 & & & \\ 0 & 0 & 0 & & & \\ & & & 0 & 1 & \\ & & & 0 & 0 & \\ & & & & & 0 \end{bmatrix}$$

Now for the Jordan Basis, The first column goes to 2, then  $2x$ , then,  $x^2$ . Take the next block to have  $2(x - y)$ ,  $x^2 - y^2$ . Last basis vector is  $(x - y)^2$ .