

Math 124 - Programming for Mathematical Applications

UC Berkeley, Spring 2023

Project 3 - Triangular mesh generator

Due Friday, March 24

First we include some libraries and define utility functions from the lecture notes:

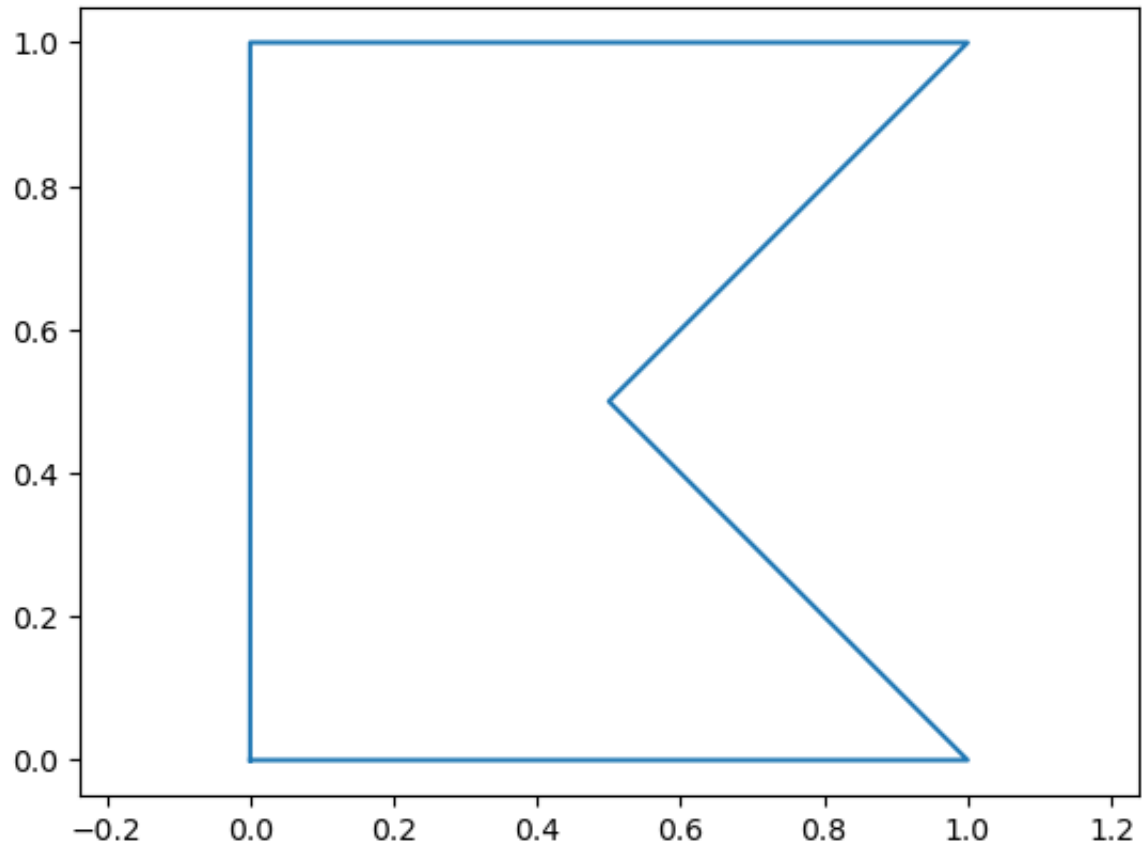
```
In [1]: 1 using PyPlot, LinearAlgebra, PyCall
        2
        3 function tplot(p, t)
        4     # Plot triangular mesh with nodes `p` and triangles `t`
        5     tris = convert(Array{Int64}, hcat(t...))
        6     tripcolor(first.(p), last.(p), tris .- 1, 0*tris[:,1],
        7               cmap="Set3", edgcolors="k", linewidth=1)
        8     axis("equal")
        9     return
       10 end
       11
       12 function delaunay(p)
       13     # Delaunay triangulation `t` of array of nodes `p`
       14     tri = pyimport("matplotlib.tri")
       15     t = tri[:Triangulation](first.(p), last.(p))
       16     t = Int64.(t[:triangles] .+ 1)
       17     t = [ t[i,:] for i = 1:size(t,1) ]
       18 end
```

Out[1]: delaunay (generic function with 1 method)

Description

In this project you will write an unstructured triangular mesh generator based on the Delaunay refinement algorithm. The steps will be described in detail, and for testing we will use the following simple polygon:

```
In [2]: 1 pv = [[0,0], [1,0], [0.5,.5], [1,1], [0,1], [0,0]]  
2 plot(first.(pv), last.(pv))  
3 axis("equal");
```



Problem 1 - Point in polygon

Write a function `inpolygon(p, pv)` which determines if a point `p` is inside the closed polygon `pv`. For example, in the test polygon above, the point $(0.6, 0.3)$ is inside but $(0.8, 0.3)$ is outside. For the algorithm, use the "Crossing number method" as described here: <https://observablehq.com/@tmcw/understanding-point-in-polygon> (<https://observablehq.com/@tmcw/understanding-point-in-polygon>).

```

In [3]: 1 function inpolygon(p, pv)
        2     y = p[2]
        3     inside = false
        4     for i = 1:length(pv) - 1
        5         p1 = pv[i]
        6         p2 = pv[i + 1]
        7         if (p1[2] < y) != (p2[2] < y)
        8             if p[1] < (p2[1] - p1[1]) * (y - p1[2]) / (p2[2] - p1[2])
        9                 inside = !inside
       10             end
       11         end
       12     end
       13     inside
       14 end
       15 inpolygon((0.6, 0.3), pv), inpolygon((0.8,0.3), pv)

```

Out[3]: (true, false)

Problem 2 - Triangle properties

Next we need functions for computing some basic quantities from triangles. Here, a triangle `tri` is represented as an array of 3 points, e.g.

```

In [4]: 1 tri = [[1,0.5], [2,1], [0,3]]

```

Out[4]: 3-element Vector{Vector{Float64}}:

```

[1.0, 0.5]
[2.0, 1.0]
[0.0, 3.0]

```

Problem 2(a) - Triangle area

Write a function `tri_area(tri)` which returns the area of `tri`.

```

In [5]: 1 function tri_area(tri)
          2     a = tri[1] - tri[2]
          3     b = tri[3] - tri[2]
          4     a_norm = norm(a)
          5     b_norm = norm(b)
          6     cosθ = dot(a, b) / (a_norm * b_norm)
          7     base = a_norm * cosθ
          8     if cosθ > 1
          9         cosθ = 1
         10     elseif cosθ < -1
         11         cosθ = -1
         12     end
         13     height = base * tan(acos(cosθ))
         14     area = abs(b_norm * height / 2)
         15 end
         16 tri_area(tri)

```

Out [5]: 1.5000000000000002

Problem 2(b) - Triangle centroid

Write a function `tri_centroid(tri)` which returns the centroid of `tri`

(https://en.wikipedia.org/wiki/Centroid#Of_a_triangle

(https://en.wikipedia.org/wiki/Centroid#Of_a_triangle)).

```

In [6]: 1 function tri_centroid(tri)
          2     c = tri[2] + tri[3]
          3     centroid = 2(c / 2 - tri[1])/3 + tri[1]
          4 end
          5 tri_centroid(tri)

```

Out [6]: 2-element Vector{Float64}:
1.0
1.5

Problem 2(c) - Triangle circumcenter

Write a function `tri_circumcenter(tri)` which returns the circumcenter of `tri`

(https://en.wikipedia.org/wiki/Circumscribed_circle#Cartesian_coordinates_2

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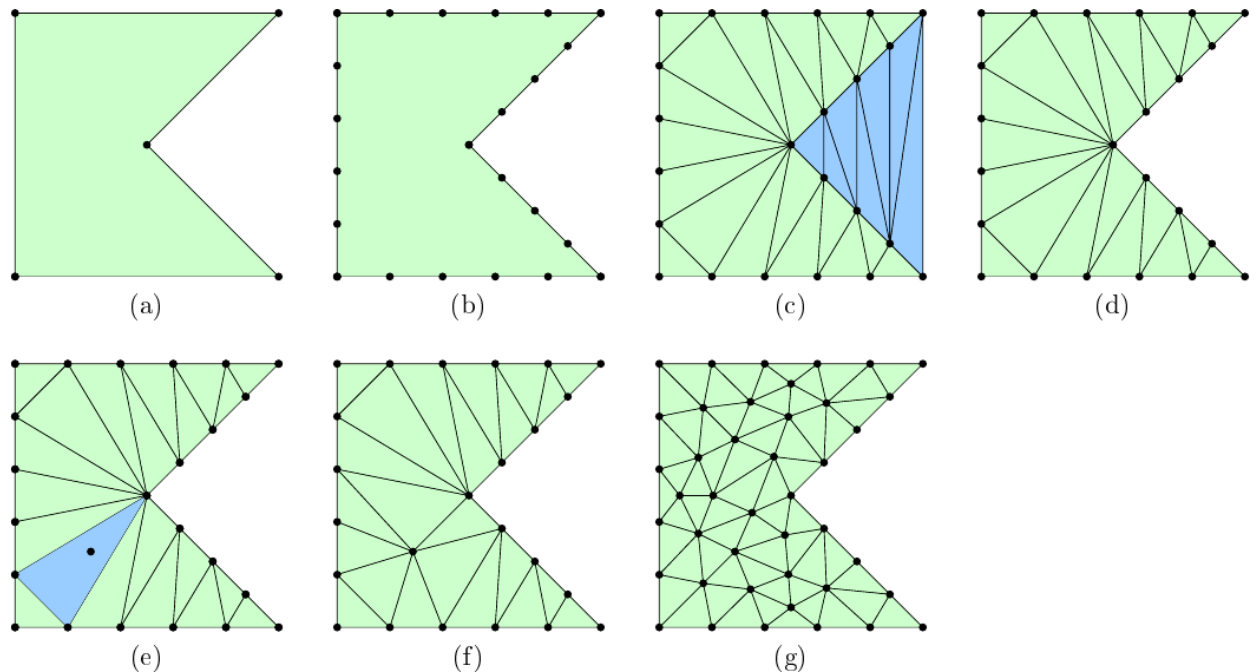
```
In [7]: 1 function tri_circumcenter(tri)
2         a = tri[1] - tri[2]
3         b = tri[2] - tri[3]
4         p1 = a/2 + tri[2]
5         p2 = b/2 + tri[3]
6         aperp = [-a[2], a[1]]
7         bperp = [-b[2], b[1]]
8         A = [bperp aperp]
9         y = p1 - p2
10        x = A \ y
11        center = x[1] * bperp + p2
12    end
13    tri_circumcenter([[1,0], [0,1], [0,0]])
```

```
Out[7]: 2-element Vector{Float64}:
 0.5
 0.5
```

Problem 3 - Mesh generator

Write a function with the syntax `p, t = pmesh(pv, hmax)` which generates a mesh `p, t` of the polygon `pv`, with triangle side lengths approximately `hmax`. Follow the algorithm as described below.

- The input `pv` is an array of points which defines the polygon. Note that the last point is equal to the first (a closed polygon).
- First, create node points `p` along each polygon segment, separated by a distance approximately equal to `hmax`. Make sure not to duplicate any nodes.
- Triangulate the domain using the `deLaunay` function.
- Remove the triangles outside the polygon, by computing all the triangle centroids (using `tri_centroid`) and determining if they are inside (using `inpolygon`).
- Find the triangle with largest area A (using `tri_area`). If $A > h_{\max}^2/2$, add the circumcenter of the triangle to the list of node points `p`.
- Repeat steps (c)-(d), that is, re-triangulate and remove outside triangles.
- Repeat steps (e)-(f) until no triangle area $A > h_{\max}^2/2$.



```

In [8]: 1 function pmesh(pv, hmax)
        2     p = []
        3     for i = 1:length(pv) - 1
        4         edge = pv[i + 1] - pv[i]
        5         length = norm(edge)
        6         spaces = ceil(length / hmax)
        7         push!(p, pv[i])
        8         for j = 1:spaces - 1
        9             push!(p, j/spaces*edge + pv[i])
       10         end
       11     end
       12
       13     while true
       14         t1 = delaunay(p)
       15         t2 = []
       16         maxarea = -1
       17         maxindex = 0
       18         for i = 1:length(t1)
       19             tri_points = p[[t1[i][1], t1[i][2], t1[i][3]]]
       20             if inpolygon(tri_centroid(tri_points), pv)
       21                 push!(t2, t1[i])
       22             end
       23         end
       24
       25         for i = 1:length(t2)
       26             tri_points = p[[t2[i][1], t2[i][2], t2[i][3]]]
       27             current_area = tri_area(tri_points)
       28             if current_area > maxarea
       29                 maxarea = current_area
       30                 maxindex = i
       31             end
       32         end
       33
       34         if maxarea ≤ hmax^2/2
       35             return p, t2
       36             break
       37         else
       38             push!(p, tri_circumcenter(p[[t2[maxindex][1], t2[maxindex][2], t2[maxindex][3]]))
       39         end
       40     end
       41 end

```

Out [8]: pmesh (generic function with 1 method)

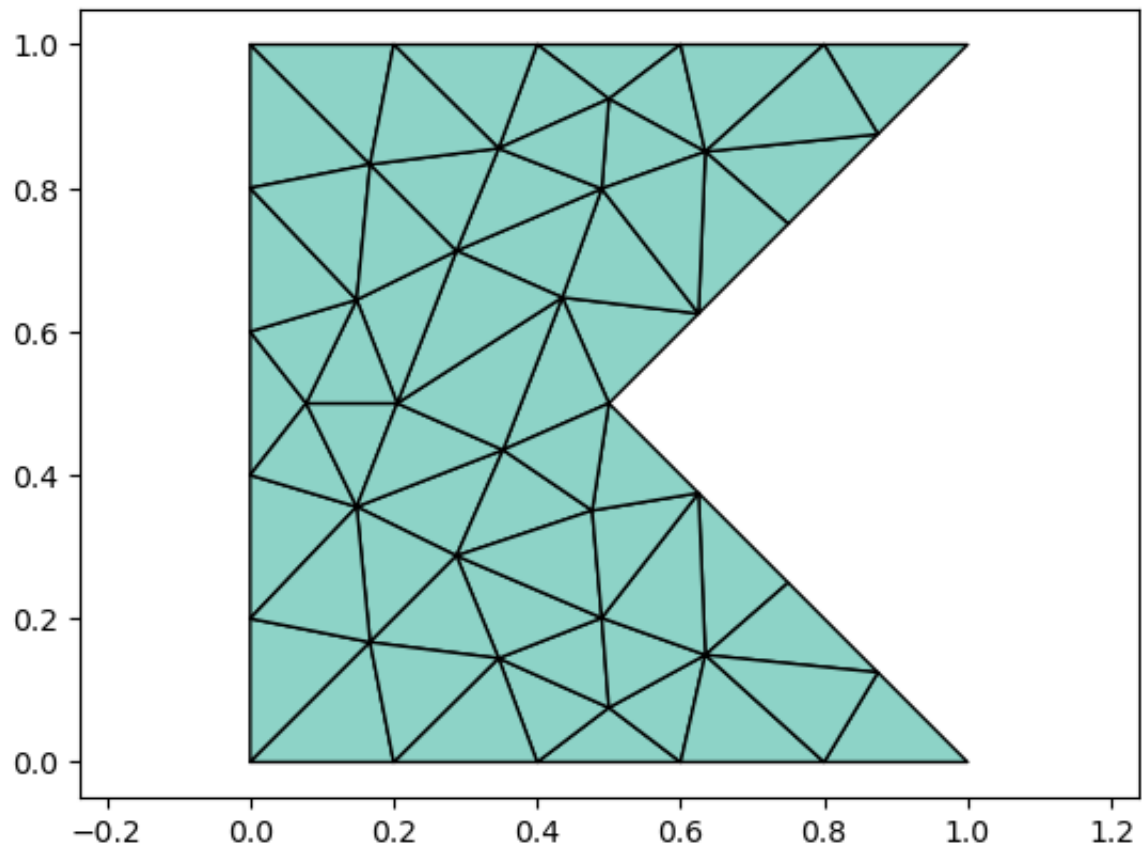
Test cases

Run the cases below to test your mesh generator.

```
In [9]: 1 tri_area([[0.625, 0.625], [0.4, 1.0], [0.5, 0.5]])
```

```
Out[9]: 0.03749999999999997
```

```
In [10]: 1 # The polygon in the examples
2 pv = [[0,0], [1,0], [0.5,.5], [1,1], [0,1], [0,0]]
3 p,t = pmesh(pv, 0.2)
4 tplot(p,t)
```




```
In [11]: 1 # A more complex shape
2 pv = [[i/10, 0.1*(-1)^i] for i = 0:10]
3 append!(pv, [[.5, .6], [0, .1]])
4 p, t = pmesh(pv, 0.04)
5 tplot(p, t)
```

