# CSED601 Dependable Computing Lecture 12

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## Review of Previous Lecture

- Reliability Evaluation Techniques
  - Combinatorial Model
    - Series/Parallel Model
    - Reliability Block Diagram
    - Non-series/Non-parallel model
    - M-out-of-N model
  - Markov modeling

- A stochastic process is a function whose values are random variables
- The classification of a random process depends on different quantities
  - state space
  - index (time) parameter
  - statistical dependencies among the random variables X(t)
     for different values of the index parameter t.

#### • State Space

- the set of possible values (states) that X(t) might take on.
- if there are finite states => discrete-state process or chain
- if there is a continuous interval => continuous process

#### • Index (Time) Parameter

- if the times at which changes may take place are finite or countable, then we say we have a discrete-(time) parameter process.
- if the changes may occur anywhere within a finite or infinite interval on the time axis, then we say we have a continuous-parameter process.

- States must be
  - mutually exclusive
  - collectively exhaustive
- Let  $P_i(t)$  = Probability of being in state  $S_i$  at time t.

$$\Sigma P_i(t) = 1$$

- Markov Properties
  - future state prob. depends only on current state
    - independent of time in state
    - path to state

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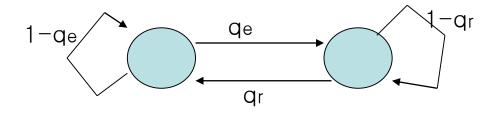
# Discrete parameter Markov chain

#### • Concept

- A Markov process whose state space is discrete is called as a Markov chain
- State transition occurs at discrete time intervals
- Let  $P(X_n=j) = P_j(n)$  and  $P_{jk}(m,n) = P(X_n=k|X_m=j)$  where  $P_{jk}(m,n)$  represents the probability that the precedence makes a transition from state j at step m to state k at step n.
- $P_{jk}(n) = P(X_{m+n}=k|X_{m}=j)$ : n-step transition probability
- $P_{jk}(1) = P_{jk}$ : one-step transition probability and used to denote the transition probability matrix.
- $-0 \le P_{jk} \le 1$  and  $\Sigma P_{jk} = 1$

# Discrete parameter Markov chain

## Example



$$-P = [Pij] = [1 - qe qe]$$

$$[qr 1 - qr]$$

 How to find n step transition probability matrix from P

 $P(n) = P^n$ : multiply P matrix with itself n-1 times

# Discrete parameter Markov chain

## State Probability

- Let initial state  $P(0) = [p_0(0), p_1(0), ...,]$
- $-P_{j}(n) = P(X_{n}=j) = \sum P(X_{0}=i)P(X_{n}=j|X_{0}=i)$  $= \sum P_{i}(0)P_{ij}(n)$
- $Pn = P(0) P(n) = P(0) P^n$

## Example

$$-P = [1-a, a] P^n(a+b) = [(b+a(1-a-b)^n), (a-a(1-a-b)^n)]$$

$$[b, 1-b] [(b-b(1-a-b)^n), (a+b(1-a-b)^n)]$$

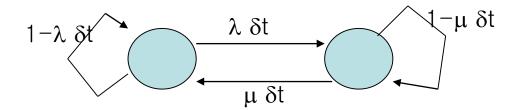
# Types of State

## Types of State

- Transient State : (non-recurrent state)
  - A state j is called a transient state if there is a positive probability that it would not come back to state j.
- Recurrent State
  - A state j is called recurrent if starting from state j it eventually returns to state j with probability 1.
- Absorbing State
  - A state j is called an absorbing state if there is a positive probability that there is a transition to state j from other states, but there is no transition to other states from state j.
- Irreducible Markov chain
  - Iff each state can be reached from each other state.

#### Concept

- The transition from one state to another can be at any instance of time.
- Transitions are given by rate s.
- The time spent in a state is exponentially distributed.
- M/M/1 (arrival / service / # of server)
   Markovian arrival / Markovian service / one server



• Equation development

```
\square \lambda, \mu: rates
\square \lambda \delta t, \mu \delta t: probabilities
- P = [1 - \lambda \delta t, \lambda \delta t]
          [\mu \delta t, 1 - \mu \delta t]
- P(t + \delta t) = [p_0(t + \delta t), p_1(t + \delta t)]
                = [p_0(t), p_1(t)] X P
   \rightarrow p0(t+\deltat) = p0(t)(1 - \lambda \deltat) + p1(t) \mu \deltat
         p1(t+\delta t) = p0(t)(\lambda \delta t) + p1(t)(1 - \mu \delta t)
   \rightarrow (p0(t+\delta t) - p0(t)) / \delta t = -\lambda p0(t) + \mu p1(t)
        (p1(t+\delta t) - p1(t)) / \delta t = \lambda p0(t) - \mu p1(t)
   \rightarrow dp0(t) / dt = -\lambda p0(t) + \mu p1(t) \rightarrow P'(t) = P(t) X [ -\lambda, \lambda] = P(t) X T
        dp1(t) / dt = \lambda p0(t) - \mu p1(t)
                                                                                           [\mu, -\mu]
                                                                  Chapman-Kolmogorv Equation
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- How to solve?
  - Using Laplace transform
    - $dp0(t) / dt = -\lambda p0(t) + \mu p1(t)$
    - $dp1(t) / dt = \lambda p0(t) \mu p1(t)$



- $s p0(s) p0(0) = -\lambda p0(s) + \mu p1(s)$
- $s p1(s) p1(0) = \lambda p0(s) \mu p1(s)$



- $[p0(0), p1(0)] = [p0(s), p1(s)] X [s+\lambda, -\lambda]$ [-  $\mu$ ,  $s+\mu$ ]
- → P(0) = P(s) X [sI T] →  $P(s) = P(0) X [sI T] ^(-1)$
- $\rightarrow$  Take Inverse Laplace transform to find p(t): transient probability

- Steady-state analysis
  - All states are in steady-state.
  - What does it mean?
    - In-transition is equal to out-transition.
    - Change rate per time is zero  $\rightarrow$  dPi(t) / dt = 0
  - Hence, PXT = 0
    - Solve n-variable 1<sup>st</sup> order n-equations

- Example: Reliability of TMR without repair
  - State diagram : Draw your one here
  - T?
- Example: Availability of single system with repair
  - State diagram
  - -T?
  - Result?