

1 Selected Topics

1.1 DFT vs. FFT

This section investigates different aspects of the discrete Fourier transform (DFT) and its inverse (IDFT). First, consider the discrete boxcar frequency spectrum:

$$X(\omega) = \{ 1, for |\omega| \leq \frac{\pi}{3}, otherwise \} \quad (1)$$

We can transform this back into time space using the inverse transform.

Both the forward and inverse Fourier transform can be thought of as a linear transformation on a vector, and thus can be represented through matrix multiplication, with each element corresponding to the equation

$$F_{nm} = e^{-2\pi i \frac{nm}{N}} F_{nm}^{-1} = \frac{1}{N} e^{2\pi i \frac{nm}{N}} \quad (2)$$

where N is the total number of points. To transform a 3-point vector, the forward transformation matrix is then the 3×3 matrix

$$F = e^{-\frac{2\pi}{3}i} e^{-\frac{4\pi}{3}i} e^{-2\pi i} e^{-\frac{4\pi}{3}i} e^{-\frac{8\pi}{3}i} e^{-4\pi i} e^{-2\pi i} e^{-4\pi i} e^{-6\pi i} \quad (3)$$

and its inverse is

$$F^{-1} = \frac{1}{3} ccc e^{\frac{2\pi}{3}i} e^{\frac{4\pi}{3}i} e^{2\pi i} e^{\frac{4\pi}{3}i} e^{\frac{8\pi}{3}i} e^{4\pi i} e^{2\pi i} e^{4\pi i} e^{6\pi i} \quad (4)$$

We can easily confirm that these matrices are inverses of one another through matrix multiplication, or by using their definitions as written in equation ???. The result of matrix multiplication should be the identity matrix, which can be proved by showing the diagonal elements (when $n = m$) are equal to 1:

$$\sum_{j=1}^N F_{nj} F_{jn}^{-1} = \frac{1}{N} \sum_{j=1}^N e^{-\frac{2\pi}{N} nji} e^{\frac{2\pi}{N} nji} = \frac{1}{N} \sum_{j=1}^N 1 = 1 \quad (5)$$

and that the off-diagonal elements (when nm) are equal to zero:

$$\sum_{j=1}^N F_{nj} F_{jn}^{-1} = \frac{1}{N} \quad (6)$$