

# Written Section

$$1. (a) {}^A T_B = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & \cos \theta & -\sin \theta & 2 \\ 0 & \sin \theta & \cos \theta & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

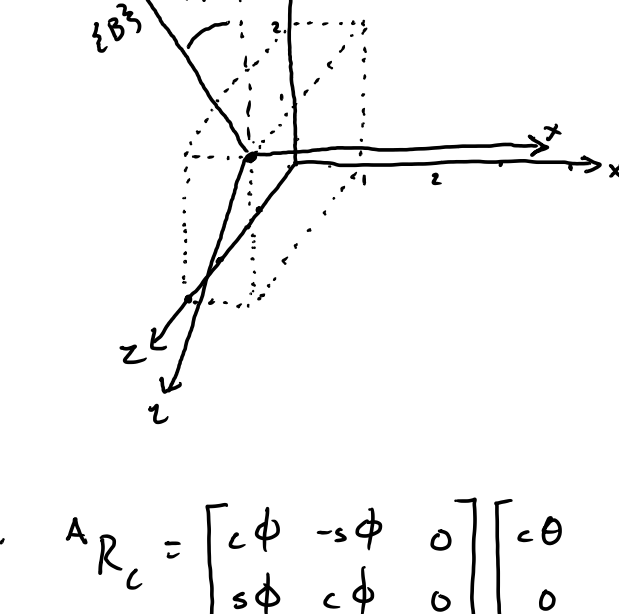
$$(b) {}^B T_A = {}^A T_B^{-1} = \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & \cos \theta & \sin \theta & (-2 \cos \theta - 3 \sin \theta) \\ 0 & -\sin \theta & \cos \theta & (2 \sin \theta - 3 \cos \theta) \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$(c) {}^B P = {}^B T_A {}^A P$$

$$= \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & \sqrt{2}/2 & \sqrt{2}/2 & (-2\sqrt{2}/2 - 3\sqrt{2}/2) \\ 0 & -\sqrt{2}/2 & \sqrt{2}/2 & (2\sqrt{2}/2 - 3\sqrt{2}/2) \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 4 \\ 5 \\ 6 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 4 - 1 \\ 5\sqrt{2}/2 + 6\sqrt{2}/2 & -\sqrt{2} - 3\sqrt{2}/2 \\ -5\sqrt{2}/2 + 6\sqrt{2}/2 & +\sqrt{2} - 3\sqrt{2}/2 \\ 1 \end{bmatrix}$$

$${}^B P = \begin{bmatrix} 3 \\ 3\sqrt{2} \\ 0 \end{bmatrix}$$



$$2. A_{R_c} = \begin{bmatrix} \cos \phi & -\sin \phi & 0 \\ \sin \phi & \cos \phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{bmatrix}$$

$$= \begin{bmatrix} \cos \phi \cos \theta & -\sin \phi \cos \theta & \sin \theta \\ \sin \phi \cos \theta & \cos \phi \cos \theta & \sin \theta \\ -\sin \theta & 0 & \cos \theta \end{bmatrix}$$

$$3. (a) {}^0 T_1 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^0 T_2 = \begin{bmatrix} 1 & 0 & 0 & -0.5 \\ 0 & 1 & 0 & 1.5 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^0 T_3 = \begin{bmatrix} 0 & 1 & 0 & -0.5 \\ 1 & 0 & 0 & 1.5 \\ 0 & 0 & -1 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$(b) {}^3 T_2 = {}^3 T_0 {}^0 T_2$$

$$= \begin{bmatrix} 0 & 1 & 0 & -1.5 \\ 1 & 0 & 0 & 0.5 \\ 0 & 0 & -1 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -0.5 \\ 0 & 1 & 0 & 1.5 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 2 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$(c) {}^0 \text{Cube} = {}^0 T_3 {}^3 \text{Cube}$$

$$= \begin{bmatrix} 0 & 1 & 0 & -0.5 \\ 1 & 0 & 0 & 1.5 \\ 0 & 0 & -1 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0.2 \\ -0.3 \\ 2 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} -0.5 - 0.5 \\ 0.2 + 1.5 \\ -2 + 3 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} -0.8 \\ 1.7 \\ 1 \end{bmatrix}$$

$$(d) {}^3 \text{Cube} = {}^3 T_0 {}^0 T_1 {}^1 \text{Cube}$$

$$= \begin{bmatrix} 0 & 1 & 0 & -1.5 \\ 1 & 0 & 0 & 0.5 \\ 0 & 0 & -1 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -0.1 \\ 0.1 \\ 0 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 1 & 0 & -0.5 \\ 1 & 0 & 0 & 0.5 \\ 0 & 0 & -1 & 2 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -0.1 \\ 0.1 \\ 0 \\ 1 \end{bmatrix}$$

$${}^3 \text{Cube} = \begin{bmatrix} -0.4 \\ 0.4 \\ 2 \end{bmatrix}$$

## 4. modified DH

$${}^{i-1} T_i = \begin{bmatrix} \cos \theta_i & -\sin \theta_i \cos \alpha_i & \sin \theta_i \cos \alpha_i & a_i \cos \theta_i \\ \sin \theta_i & \cos \theta_i \cos \alpha_i & -\cos \theta_i \cos \alpha_i & a_i \sin \theta_i \\ 0 & \sin \alpha_i & \cos \alpha_i & d_i \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



$$(a) {}^0 T_3 = {}^0 T_1 {}^1 T_2 {}^2 T_3$$

$$\begin{array}{c|c|c|c|c} i & \alpha_i & a_i & d_i & \theta_i \\ \hline 1 & 90 & 0 & L_1 & \theta_1 \\ 2 & 0 & L_2 & 0 & \theta_2 \\ 3 & 0 & L_3 & 0 & \theta_3 \end{array}$$

$${}^0 T_1 = \begin{bmatrix} \cos \theta_1 & 0 & \sin \theta_1 & 0 \\ \sin \theta_1 & 0 & -\cos \theta_1 & 0 \\ 0 & 1 & 0 & L_1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^1 T_2 = \begin{bmatrix} \cos \theta_2 & -\sin \theta_2 & 0 & L_2 \cos \theta_2 \\ \sin \theta_2 & \cos \theta_2 & 0 & L_2 \sin \theta_2 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^2 T_3 = \begin{bmatrix} \cos \theta_3 & -\sin \theta_3 & 0 & L_3 \cos \theta_3 \\ \sin \theta_3 & \cos \theta_3 & 0 & L_3 \sin \theta_3 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$(b) {}^0 T_3 = {}^0 T_1 {}^1 T_2 {}^2 T_3$$

$$\begin{array}{c|c|c|c|c} i & \alpha_i & a_i & d_i & \theta_i \\ \hline 1 & 90 & 0 & L_1 & \theta_1 \\ 2 & 0 & L_2 & 0 & \theta_2 \\ 3 & 90 & 0 & \theta_3 & 0 \end{array}$$

$${}^0 T_1 = \begin{bmatrix} \cos \theta_1 & 0 & \sin \theta_1 & 0 \\ \sin \theta_1 & 0 & -\cos \theta_1 & 0 \\ 0 & 1 & 0 & L_1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^1 T_2 = \begin{bmatrix} \cos \theta_2 & -\sin \theta_2 & 0 & L_2 \cos \theta_2 \\ \sin \theta_2 & \cos \theta_2 & 0 & L_2 \sin \theta_2 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^2 T_3 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & \theta_3 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$5. (a) r^2 = l_1^2 + l_2^2 - 2 l_1 l_2 \cos \beta$$

$$\cos \beta = \frac{l_1^2 + l_2^2 - r^2}{2 l_1 l_2}$$

$$(b) \theta_2 = 180 - \beta$$

$$\theta_2 = 180 - \cos^{-1} \left( \frac{l_1^2 + l_2^2 - r^2}{2 l_1 l_2} \right)$$

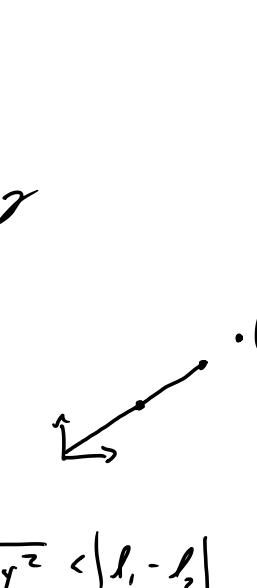
$$(c) \frac{\sin A}{a} = \frac{\sin B}{b} = \frac{\sin C}{c}$$

$$\frac{\sin \theta_2}{d} = \frac{\sin 90}{l_2}$$

$$d = l_2 \sin \theta_2$$

$$\gamma = \sin^{-1} \left( \frac{d}{r} \right)$$

$$\gamma = \sin^{-1} \left( \frac{l_2 \sin \theta_2}{r} \right)$$



$$(d) \alpha = \sin^{-1} \left( \frac{y_w}{r} \right)$$

$$\theta_1 = \alpha - \gamma$$

$$= \sin^{-1} \left( \frac{y_w}{r} \right) - \gamma$$

$$(e) \text{zero solutions if: } \sqrt{x^2 + y^2} > (l_1 + l_2)$$

$$\text{or}$$

$$l_2 \neq l_1 \text{ AND } \sqrt{x^2 + y^2} < |l_1 - l_2|$$

$$\text{one solution if } \sqrt{x^2 + y^2} = l_1 + l_2$$

$$\text{two solutions if } 0 < \sqrt{x^2 + y^2} < l_1 + l_2$$

$$\text{inf solutions if } \sqrt{x^2 + y^2} = 0 \text{ and } l_1 = l_2$$

$$0 \leq \theta_1 \leq 360^\circ$$

$$\theta_2 = 180^\circ$$