# Final\_Project

March 23, 2024

# 1 Illustration of a sample data from Argoverse 2 Motion Forecasting Dataset

```
[1]: import pandas as pd
     import matplotlib.pyplot as plt
     from google.colab import drive
     drive.mount('/content/drive', force_remount=False)
     parquet_file = '/content/drive/MyDrive/ME343/Final_Project/test/
      \hookrightarrow0b3b4036-d003-4caf-a387-1bf069f0810d/
      ⇔scenario_0b3b4036-d003-4caf-a387-1bf069f0810d.parquet'
     df = pd.read_parquet(parquet_file)
     print(df.head())
     print(df.columns)
     unique_tracks = df['track_id'].unique()
     plt.figure(figsize=(12, 6))
     # Plot position_x over time for each track_id
     for track_id in unique_tracks:
         track_data = df[df['track_id'] == track_id]
         plt.plot(track_data['timestep'], track_data['position_x'], marker='o',_
      ⇔linestyle='-', label=f'Track {track id}')
     plt.xlabel('Time Step')
     plt.ylabel('Position X')
     plt.title('Vehicle Position X Over Time by Track ID')
     plt.legend()
     plt.grid(True)
     plt.show()
```

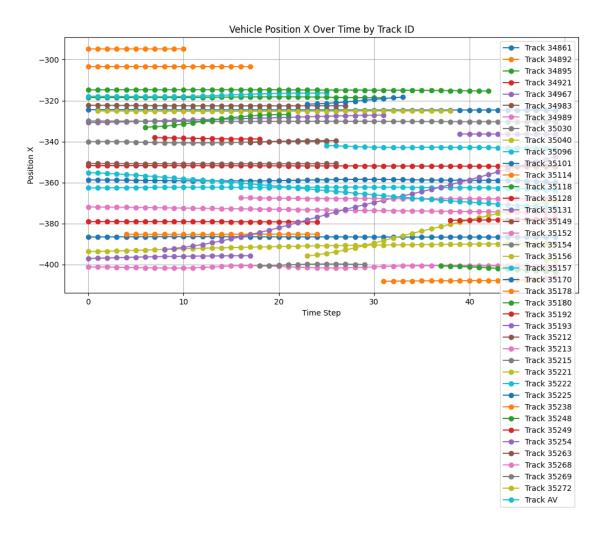
```
Drive already mounted at /content/drive; to attempt to forcibly remount, call drive.mount("/content/drive", force_remount=True).

observed track_id object_type object_category timestep position_x \

True 34861 vehicle 0 0 -324.467841

True 34861 vehicle 0 1 -324.469266
```

```
2
       True
               34861
                         vehicle
                                                0
                                                          2 - 324.471939
3
       True
               34861
                         vehicle
                                                0
                                                          3 -324.474907
                                                          4 -324.478024
      True
               34861
                         vehicle
                                                0
   position_y
                heading
                            velocity x
                                          velocity y \
0 -1153.480477
                2.860113 -2.360225e-16 -2.589164e-18
1 -1153.477966
               2.860182 -2.750969e-16 -5.923612e-17
2 -1153.474094 2.860252 -3.336415e-16 -3.864316e-17
3 -1153.469879 2.860321 -3.559718e-16 -2.743535e-18
4 -1153.464355 2.860572 -3.814046e-16 3.039250e-18
                                                          end_timestamp
                            scenario_id start_timestamp
0 0b3b4036-d003-4caf-a387-1bf069f0810d
                                            3.159739e+17
                                                           3.159739e+17
1 0b3b4036-d003-4caf-a387-1bf069f0810d
                                            3.159739e+17
                                                           3.159739e+17
2 0b3b4036-d003-4caf-a387-1bf069f0810d
                                            3.159739e+17
                                                           3.159739e+17
3 0b3b4036-d003-4caf-a387-1bf069f0810d
                                            3.159739e+17
                                                           3.159739e+17
4 0b3b4036-d003-4caf-a387-1bf069f0810d
                                            3.159739e+17
                                                           3.159739e+17
  num_timestamps focal_track_id
                                    city
0
              110
                           34989 austin
                           34989
1
              110
                                  austin
2
                           34989 austin
              110
3
              110
                           34989
                                  austin
4
              110
                           34989 austin
Index(['observed', 'track_id', 'object_type', 'object_category', 'timestep',
       'position_x', 'position_y', 'heading', 'velocity_x', 'velocity_y',
       'scenario_id', 'start_timestamp', 'end_timestamp', 'num_timestamps',
       'focal_track_id', 'city'],
      dtype='object')
```



It should be noticed in this task, we will focus on the motion of vehicle with a focal\_track\_id, which is 34989 in this example. focal\_track\_id is The track ID associated with the focal agent of the scenario.

# 2 Import the data

```
[2]: import os
import pandas as pd

base_dir = '/content/drive/MyDrive/ME343/Final_Project/test/'
focal_tracks_data = []

# Iterate through each directory in the base directory
for scenario_dir in os.listdir(base_dir):
    scenario_path = os.path.join(base_dir, scenario_dir)
    if os.path.isdir(scenario_path):
```

```
parquet_file_path = os.path.join(scenario_path,__
f'scenario_{scenario_dir}.parquet')

if os.path.exists(parquet_file_path):
    df = pd.read_parquet(parquet_file_path)

# Extract data for the focal track ID

if 'focal_track_id' in df.columns and 'track_id' in df.columns:
    focal_track_id = df['focal_track_id'].iloc[0]

    focal_track_data = df[df['track_id'] == focal_track_id]
    focal_tracks_data.append(focal_track_data)

all_focal_tracks_df = pd.concat(focal_tracks_data)

save_csv_path = '/content/drive/MyDrive/ME343/Final_Project/all_focal_tracks.

csv'

all_focal_tracks_df.to_csv(save_csv_path, index=False)
```

### 3 Construction of Dataset for LSTM

In the code below processes trajectory including position, velocity, heading from a dataset grouped by track ID, normalizes these features and labels using MinMax scaling, creates fixed-length sequences, which is 5. Finally, all data are converted into separate tensor for training, validation and testing

```
[3]: import numpy as np
     import pandas as pd
     from sklearn.preprocessing import MinMaxScaler
     from sklearn.model_selection import train_test_split
     import torch
     from torch.utils.data import TensorDataset, DataLoader
     # Function to create sequences for LSTM
     def create_sequences(features, labels, seq_length):
         sequences, seq_labels = [], []
         for i in range(len(features) - seq_length):
             seq = features[i:(i + seq length)]
             label = labels[i + seq_length]
             sequences.append(seq)
             seq labels.append(label)
         return np.array(sequences), np.array(seq_labels)
     segmented_data = []
     scaler = MinMaxScaler()
     # Group by 'track_id' to separate different trajectories
     for _, group in all_focal_tracks_df.groupby('track_id'):
```

```
group_features = group[['position_x', 'position_y', 'heading', __
 group_labels = group[['position_x', 'position_y']].values
   # Normalize features within each group
   normalized_features = scaler.fit_transform(group_features)
   labels_scaler = MinMaxScaler()
   normalized_labels = labels_scaler.fit_transform(group_labels)
   seq_length = 5
   X, Y = create_sequences(normalized_features, normalized_labels, seq_length)
    segmented_data.append((X, Y))
X_all = np.concatenate([data[0] for data in segmented_data])
Y_all = np.concatenate([data[1] for data in segmented_data])
total_samples = len(X_all)
train_end_idx = int(total_samples * 0.8)
val_end_idx = train_end_idx + int(total_samples * 0.1)
X_train = X_all[:train_end_idx]
Y_train = Y_all[:train_end_idx]
X_val = X_all[train_end_idx:val_end_idx]
Y_val = Y_all[train_end_idx:val_end_idx]
X_test = X_all[val_end_idx:]
Y_test = Y_all[val_end_idx:]
device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
X_train_tensor = torch.tensor(X_train, dtype=torch.float).to(device)
Y_train_tensor = torch.tensor(Y_train, dtype=torch.float).to(device)
X_val_tensor = torch.tensor(X_val, dtype=torch.float).to(device)
Y_val_tensor = torch.tensor(Y_val, dtype=torch.float).to(device)
X_test_tensor = torch.tensor(X_test, dtype=torch.float).to(device)
Y_test_tensor = torch.tensor(Y_test, dtype=torch.float).to(device)
batch_size = 32
train_dataset = TensorDataset(X_train_tensor, Y_train_tensor)
val_dataset = TensorDataset(X_val_tensor, Y_val_tensor)
test_dataset = TensorDataset(X_test_tensor, Y_test_tensor)
```

## [4]: !pip install wandb

```
Requirement already satisfied: wandb in /usr/local/lib/python3.10/dist-packages (0.16.4)
Requirement already satisfied: Click!=8.0.0,>=7.1 in
```

```
/usr/local/lib/python3.10/dist-packages (from wandb) (8.1.7)
Requirement already satisfied: GitPython!=3.1.29,>=1.0.0 in
/usr/local/lib/python3.10/dist-packages (from wandb) (3.1.42)
Requirement already satisfied: requests<3,>=2.0.0 in
/usr/local/lib/python3.10/dist-packages (from wandb) (2.31.0)
Requirement already satisfied: psutil>=5.0.0 in /usr/local/lib/python3.10/dist-
packages (from wandb) (5.9.5)
Requirement already satisfied: sentry-sdk>=1.0.0 in
/usr/local/lib/python3.10/dist-packages (from wandb) (1.43.0)
Requirement already satisfied: docker-pycreds>=0.4.0 in
/usr/local/lib/python3.10/dist-packages (from wandb) (0.4.0)
Requirement already satisfied: PyYAML in /usr/local/lib/python3.10/dist-packages
(from wandb) (6.0.1)
Requirement already satisfied: setproctitle in /usr/local/lib/python3.10/dist-
packages (from wandb) (1.3.3)
Requirement already satisfied: setuptools in /usr/local/lib/python3.10/dist-
packages (from wandb) (67.7.2)
Requirement already satisfied: appdirs>=1.4.3 in /usr/local/lib/python3.10/dist-
packages (from wandb) (1.4.4)
Requirement already satisfied: protobuf!=4.21.0,<5,>=3.19.0 in
/usr/local/lib/python3.10/dist-packages (from wandb) (3.20.3)
Requirement already satisfied: six>=1.4.0 in /usr/local/lib/python3.10/dist-
packages (from docker-pycreds>=0.4.0->wandb) (1.16.0)
Requirement already satisfied: gitdb<5,>=4.0.1 in
/usr/local/lib/python3.10/dist-packages (from GitPython!=3.1.29,>=1.0.0->wandb)
(4.0.11)
Requirement already satisfied: charset-normalizer<4,>=2 in
/usr/local/lib/python3.10/dist-packages (from requests<3,>=2.0.0->wandb) (3.3.2)
Requirement already satisfied: idna<4,>=2.5 in /usr/local/lib/python3.10/dist-
packages (from requests<3,>=2.0.0->wandb) (3.6)
Requirement already satisfied: urllib3<3,>=1.21.1 in
/usr/local/lib/python3.10/dist-packages (from requests<3,>=2.0.0->wandb) (2.0.7)
Requirement already satisfied: certifi>=2017.4.17 in
/usr/local/lib/python3.10/dist-packages (from requests<3,>=2.0.0->wandb)
(2024.2.2)
Requirement already satisfied: smmap<6,>=3.0.1 in
/usr/local/lib/python3.10/dist-packages (from
gitdb<5,>=4.0.1->GitPython!=3.1.29,>=1.0.0->wandb) (5.0.1)
```

# 4 Model of simple LSTM

The SimpleLSTM class defines a simple LSTM network structure, comprising a single LSTM layer followed by a linear layer. The LSTM layer takes sequences of a specified input size and processes them using a hidden state of a defined size.

The output of the LSTM is passed through a linear layer to produce the final predictions of the vehicle position of the next time step

```
[5]: import torch
     import torch.nn as nn
     class SimpleLSTM(nn.Module):
         def __init__(self, input_size, hidden_layer_size, output_size):
             super(SimpleLSTM, self).__init__()
             self.hidden layer size = hidden layer size
             self.lstm = nn.LSTM(input_size, hidden_layer_size, batch_first=True)
             self.linear = nn.Linear(hidden_layer_size, output_size)
         def forward(self, input seq):
             batch_size = input_seq.size(0)
             hidden_cell = (torch.zeros(1, batch_size, self.hidden_layer_size).
      →to(input_seq.device),
                            torch.zeros(1, batch_size, self.hidden_layer_size).
      →to(input_seq.device))
             lstm_out, _ = self.lstm(input_seq, hidden_cell)
             predictions = self.linear(lstm_out[:, -1, :])
             return predictions
     import pprint
```

```
[6]: # Import libraries
import pprint
import numpy as np
import wandb
wandb.login(key="7e90cac615bb30d0f6ff46867fc78524840e4dd4")
import torch
import torch.nn as nn
import matplotlib.pyplot as plt
import importlib
```

```
wandb: Currently logged in as: zhiyuanl
(zhiyuan1925). Use `wandb login --relogin` to force relogin
wandb: WARNING If you're specifying your api key in code,
ensure this code is not shared publicly.
wandb: WARNING Consider setting the WANDB_API_KEY
environment variable, or running `wandb login` from the command line.
wandb: Appending key for api.wandb.ai to your netrc file:
/root/.netrc
```

## 5 Training and plotting

```
[]: import os
import numpy as np
import torch
import torch.nn as nn
```

```
from torch.utils.data import DataLoader
import wandb
import random
random.seed(150)
torch.backends.cudnn.deterministic = True
seed_no = 108
np.random.seed(hash("improves reproducibility") % seed_no)
torch.manual_seed(hash("by removing stochasticity") % seed_no)
torch.cuda.manual_seed_all(hash("so runs are repeatable") % seed_no)
device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
max_epochs = 150
log_freq = int(0.1 * max_epochs)
sweep_configuration = {
   "method": "grid",
   "metric": {"goal": "minimize", "name": "val_loss"},
   "parameters": {
       "hidden_layer_size": {"values": [64, 128]},
       "learning_rate": {"values": [0.001, 0.0005]},
       "batch_size": {"values": [32, 64]}
   }
}
project_name = "ME343_FinalProject_TrajectoryPredictions_ZhiyuanLi"
group_name = "grid_search"
sweep_id = wandb.sweep(sweep_configuration, project=project_name)
import time
t1 = time.time()
# ------
# Training
# -----
def rel_12_error(pred, true):
   """A helper function to compute the relative L2 error in percentage
   Args:
       pred (torch. Tensor): Predicted values
       true (torch. Tensor): True values
   Returns:
       torch. Tensor: Relative L2 error in percentage
   return (torch.norm(pred - true) / torch.norm(true))*100
def train(config=None):
   wandb.init(config=config, project=project_name, group=group_name)
```

```
config = wandb.config
  model = SimpleLSTM(input_size=5, hidden_layer_size=config.
⇔hidden_layer_size, output_size=2).to(device)
  criterion = nn.MSELoss()
  optimizer = torch.optim.Adam(model.parameters(), lr=config.learning rate)
  train_loader = DataLoader(train_dataset, batch_size=config.batch_size,__
⇔shuffle=False)
  val_loader = DataLoader(val_dataset, batch_size=config.batch_size,_
⇒shuffle=False)
  training loss list = []
  validation_loss_list =[]
  for epoch in range(max_epochs):
      model.train()
      total_train_loss = 0
      for train_x, train_y in train_loader:
          train_x, train_y = train_x.to(device), train_y.to(device)
          model.zero_grad()
          output = model(train_x)
          loss = criterion(output, train_y)
          loss.backward()
          optimizer.step()
      if (epoch + 1)\%15 == 0:
          training_loss_list.append(loss.item())
          model.eval()
          with torch.no_grad():
              val_pred_field = model(X_val_tensor)
              val_loss = criterion(val_pred_field, Y_val_tensor)
              MRE = rel_12_error(val_pred_field, Y_val_tensor)/
→len(Y_val_tensor)
               validation_loss_list.append(val_loss.item())
               wandb.log({"val_loss": val_loss.item(), "train_loss": loss.
→item(), "val_rel_error_pt": MRE, "epoch": epoch})
              print(f"Current Epoch: {epoch+1}/{max_epochs}")
              print(f"The training loss is {loss.item()}")
              print(f"The validation loss is {val_loss.item()}")
              print(f"The mean relative error (in percentage) for the ⊔
→validation set: {MRE}")
  model.eval()
  n plots = 10
  random_indices = random.sample(range(len(test_dataset)), n_plots)
```

```
with torch.no_grad():
        test_field = model(X_test_tensor)
       predict outputs = labels_scaler.inverse_transform(test_field.cpu().
 →numpy())
        test_outputs = labels_scaler.inverse_transform(Y_test_tensor.cpu().
 →numpy())
       num_samples, num_timesteps, num_features = X_test_tensor.shape
       X_test_reshaped = X_test_tensor.reshape(-1, num_features).cpu().numpy()
       test_inputs_transformed = scaler.inverse_transform(X_test_reshaped)
       test_inputs = test_inputs_transformed.reshape(num_samples,__
 →num timesteps, num features)
        fig, axs = plt.subplots(int(n_plots/2), 2, figsize=(n_plots*2, 4 *_
 →int(n_plots/2)))
        for i, index in enumerate(random_indices):
            actual x, actual y = test outputs[index]
            predicted_x, predicted_y = predict_outputs[index]
            input_positions = test_inputs[index, :, :2]
            ax = axs[i // 2, i % 2]
            ax.scatter(actual_x, actual_y, c='red', label='Actual Position')
            ax.scatter(predicted_x, predicted_y, c='blue', label='Predicted_u
 ⇔Position')
            for step in range(5):
                ax.scatter(input_positions[step, 0], input_positions[step, 1],__
 oc='green', alpha=0.5, label=f'Input Position at Step {step+1}' if step == 0⊔
 ⇔else "")
            ax.set_title(f'Sample {index} Positions')
            ax.set_xlabel('Position X')
            ax.set_ylabel('Position Y')
            if i == 0:
                ax.legend()
            ax.grid(True)
       plt.tight layout()
        wandb.log({"Prediction vs Actual Position": wandb.Image(fig)})
       plt.show()
    save_path = os.path.join(wandb.run.dir, "model.ckpt")
   torch.save(model.state_dict(), save_path)
wandb.agent(sweep_id, train)
```

```
t2 = time.time()
print(f"Total time taken: {t2-t1}")
wandb.finish()
Create sweep with ID: 0gnw08y5
Sweep URL: https://wandb.ai/zhiyuan1925/ME343 FinalProject_TrajectoryPredictions
_ZhiyuanLi/sweeps/0gnw08y5
wandb: Agent Starting Run: zkkmppp9 with config:
wandb:
         batch_size: 32
wandb:
          hidden_layer_size: 64
wandb:
           learning_rate: 0.001
wandb: WARNING Ignored wandb.init() arg project when
running a sweep.
VBox(children=(Label(value='Waiting for wandb.init()...\r'), FloatProgress(value=0.
 →01111334253334159, max=1.0)...
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
Current Epoch: 15/150
The training loss is 0.0013353365939110518
The validation loss is 0.001124282949604094
The mean relative error (in percentage) for the validation set:
0.007656624540686607
Current Epoch: 30/150
The training loss is 0.00025675323558971286
The validation loss is 0.0001582837285241112
The mean relative error (in percentage) for the validation set:
0.002872881479561329
Current Epoch: 45/150
The training loss is 5.425124254543334e-05
The validation loss is 9.852176299318671e-05
The mean relative error (in percentage) for the validation set:
0.002266551833599806
Current Epoch: 60/150
The training loss is 3.863553865812719e-05
The validation loss is 7.526861736550927e-05
The mean relative error (in percentage) for the validation set:
0.0019811003003269434
Current Epoch: 75/150
The training loss is 2.931419476226438e-05
```

The validation loss is 6.911534001119435e-05

The mean relative error (in percentage) for the validation set:

0.0018983958289027214

Current Epoch: 90/150

The training loss is 4.474477827898227e-05

The validation loss is 7.04324193065986e-05

The mean relative error (in percentage) for the validation set:

0.001916398643516004 Current Epoch: 105/150

The training loss is 5.5505955970147625e-05

The validation loss is 6.587956886505708e-05

The mean relative error (in percentage) for the validation set:

0.0018534245900809765 Current Epoch: 120/150

The training loss is 7.567399006802589e-05

The validation loss is 6.706403655698523e-05

The mean relative error (in percentage) for the validation set:

0.0018700117943808436 Current Epoch: 135/150

The training loss is 7.634733628947288e-05

The validation loss is 7.801056926837191e-05

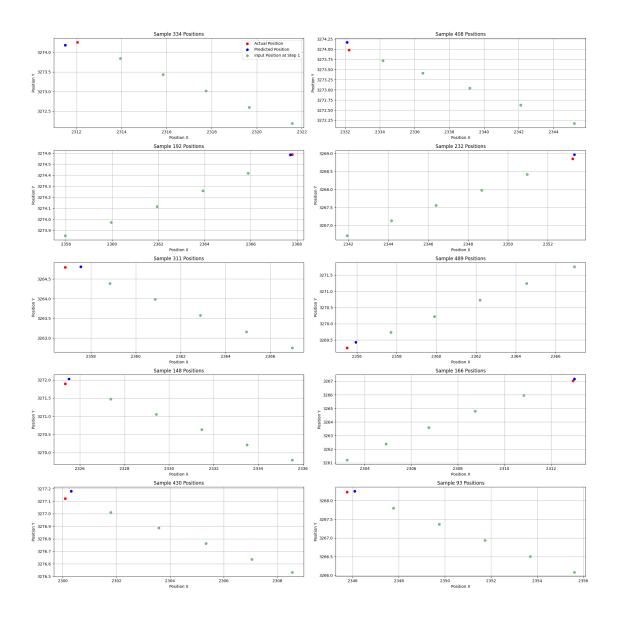
The mean relative error (in percentage) for the validation set:

0.002016862388700247 Current Epoch: 150/150

The training loss is 7.432968413922936e-05

The validation loss is 7.177478255471215e-05

The mean relative error (in percentage) for the validation set:



```
VBox(children=(Label(value='0.183 MB of 0.183 MB uploaded\r'), GFloatProgress(value=1.0, max=1.0)))

<IPython.core.display.HTML object>

<IPython.core.display.HTML object>

wandb: Agent Starting Run: ys9uwj42 with config:
wandb: batch_size: 32
wandb: hidden_layer_size: 64
wandb: learning_rate: 0.0005
wandb: WARNING Ignored wandb.init() arg project when running a sweep.
```

```
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
```

<IPython.core.display.HTML object>

<IPython.core.display.HTML object>

<IPython.core.display.HTML object>

<IPython.core.display.HTML object>

Current Epoch: 15/150

The training loss is 0.0025550040882080793 The validation loss is 0.004850317258387804

The mean relative error (in percentage) for the validation set:

0.015903204679489136 Current Epoch: 30/150

The training loss is 0.0009175420273095369 The validation loss is 0.0005491080810315907

The mean relative error (in percentage) for the validation set:

0.005350919906049967 Current Epoch: 45/150

The training loss is 0.0002698661701288074 The validation loss is 0.00017522502457723022

The mean relative error (in percentage) for the validation set:

0.003022718010470271 Current Epoch: 60/150

The training loss is 7.026762614259496e-05 The validation loss is 0.00013214950740803033

The mean relative error (in percentage) for the validation set:

0.002625018125399947 Current Epoch: 75/150

The training loss is 7.258874393301085e-05 The validation loss is 0.0001198315731016919

The mean relative error (in percentage) for the validation set:

0.002499684225767851 Current Epoch: 90/150

The training loss is 6.864216993562877e-05 The validation loss is 9.84199286904186e-05

The mean relative error (in percentage) for the validation set:

0.0022653802298009396 Current Epoch: 105/150

The training loss is 5.732291901949793e-05 The validation loss is 7.914024172350764e-05

The mean relative error (in percentage) for the validation set:

0.0020314131397753954 Current Epoch: 120/150

The training loss is 9.019093704409897e-05 The validation loss is 5.265568688628264e-05

The mean relative error (in percentage) for the validation set:

### 0.0016569987637922168 Current Epoch: 135/150

The training loss is 0.00012280191003810614 The validation loss is 5.789498027297668e-05

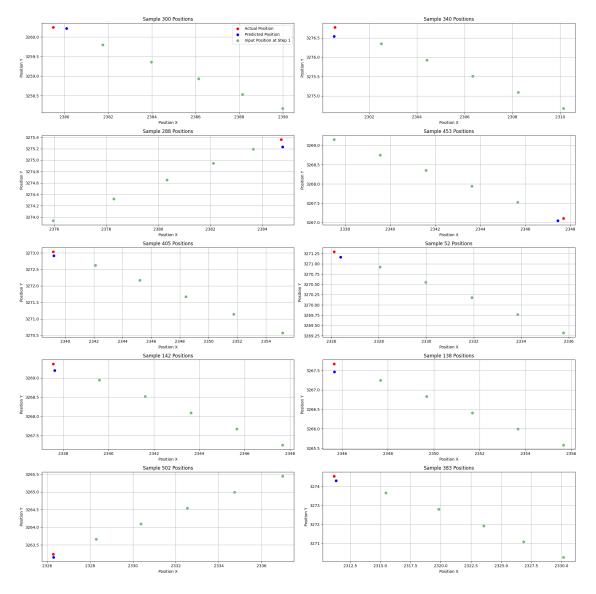
The mean relative error (in percentage) for the validation set:

0.001737480633892119 Current Epoch: 150/150

The training loss is 0.0001316090056207031 The validation loss is 6.910732918186113e-05

The mean relative error (in percentage) for the validation set:

### 0.0018982857000082731



VBox(children=(Label(value='0.249 MB of 0.259 MB uploaded\r'), U\$\ightarrow{FloatProgress(value=0.9624956651983679, max=1.0...}

```
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
wandb: Agent Starting Run: 8vyzyaxf with config:
wandb:
          batch_size: 32
wandb:
          hidden_layer_size: 128
wandb:
           learning_rate: 0.001
wandb: WARNING Ignored wandb.init() arg project when
running a sweep.
VBox(children=(Label(value='Waiting for wandb.init()...\r'), FloatProgress(value=0.
 →011113172655556506, max=1.0...
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
Current Epoch: 15/150
The training loss is 0.0009148058015853167
The validation loss is 0.0009852161165326834
The mean relative error (in percentage) for the validation set:
0.007167460396885872
Current Epoch: 30/150
The training loss is 0.00025865258066914976
The validation loss is 0.00014451955212280154
The mean relative error (in percentage) for the validation set:
0.002745129633694887
Current Epoch: 45/150
The training loss is 9.780436812434345e-05
The validation loss is 8.687340596225113e-05
The mean relative error (in percentage) for the validation set:
0.002128349617123604
Current Epoch: 60/150
The training loss is 5.7506971643306315e-05
The validation loss is 0.00010034042497863993
The mean relative error (in percentage) for the validation set:
0.0022873757407069206
Current Epoch: 75/150
The training loss is 3.9545873733004555e-05
The validation loss is 8.644105400890112e-05
The mean relative error (in percentage) for the validation set:
0.002123046899214387
```

Current Epoch: 90/150

The training loss is 3.3808966691140085e-05 The validation loss is 7.445089431712404e-05

The mean relative error (in percentage) for the validation set:

0.001970309764146805 Current Epoch: 105/150

The training loss is 3.214710159227252e-05 The validation loss is 7.769669173285365e-05

The mean relative error (in percentage) for the validation set:

0.0020128008909523487 Current Epoch: 120/150

The training loss is 3.21287261613179e-05 The validation loss is 7.960392395034432e-05

The mean relative error (in percentage) for the validation set:

0.0020373554434627295 Current Epoch: 135/150

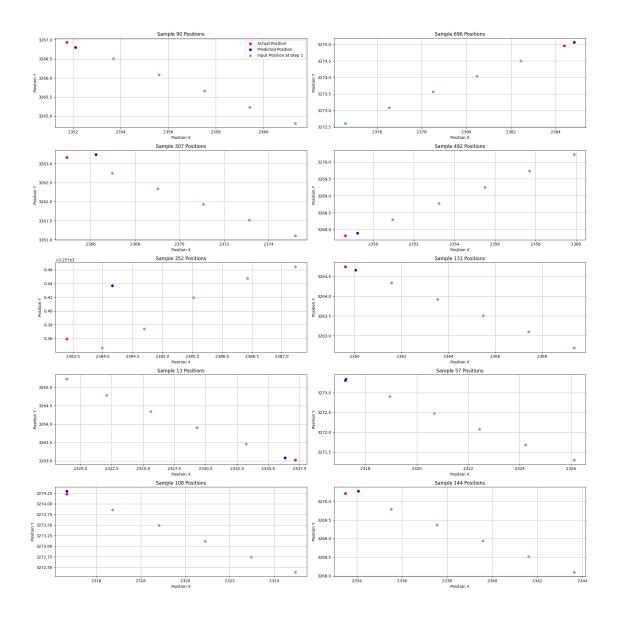
The training loss is 4.323721077525988e-05 The validation loss is 7.52047635614872e-05

The mean relative error (in percentage) for the validation set:

0.0019802600145339966 Current Epoch: 150/150

The training loss is 5.6040291383396834e-05 The validation loss is 7.364417979260907e-05

The mean relative error (in percentage) for the validation set:



```
VBox(children=(Label(value='0.178 MB of 0.178 MB uploaded\r'),

→FloatProgress(value=1.0, max=1.0)))

<IPython.core.display.HTML object>

<IPython.core.display.HTML object>

wandb: Sweep Agent: Waiting for job.

wandb: Job received.

wandb: Agent Starting Run: jlwci1v4 with config:

wandb: batch_size: 32

wandb: hidden_layer_size: 128

wandb: learning_rate: 0.0005
```

wandb: WARNING Ignored wandb.init() arg project when running a sweep. <IPython.core.display.HTML object> <IPython.core.display.HTML object> <IPython.core.display.HTML object> <IPython.core.display.HTML object> <IPython.core.display.HTML object> <IPython.core.display.HTML object> Current Epoch: 15/150 The training loss is 0.0037105598021298647 The validation loss is 0.004585742950439453 The mean relative error (in percentage) for the validation set: 0.01546337828040123 Current Epoch: 30/150 The training loss is 0.0010222438722848892 The validation loss is 0.0004610525502357632 The mean relative error (in percentage) for the validation set: 0.004903145134449005 Current Epoch: 45/150 The training loss is 0.00020402981317602098 The validation loss is 0.00016038278408814222 The mean relative error (in percentage) for the validation set: 0.0028918678872287273 Current Epoch: 60/150 The training loss is 9.7375683253631e-05 The validation loss is 0.00011192820238647982 The mean relative error (in percentage) for the validation set: 0.002415846101939678 Current Epoch: 75/150 The training loss is 7.084876415319741e-05 The validation loss is 7.829878450138494e-05 The mean relative error (in percentage) for the validation set: 0.0020205846522003412 Current Epoch: 90/150 The training loss is 5.60243206564337e-05 The validation loss is 8.097964018816128e-05 The mean relative error (in percentage) for the validation set: 0.0020548845641314983 Current Epoch: 105/150 The training loss is 4.33809073001612e-05 The validation loss is 7.18083101673983e-05 The mean relative error (in percentage) for the validation set: 0.0019350263755768538

Current Epoch: 120/150

The training loss is 7.8968980233185e-05

The validation loss is 5.0621823902474716e-05

The mean relative error (in percentage) for the validation set:

0.001624682336114347 Current Epoch: 135/150

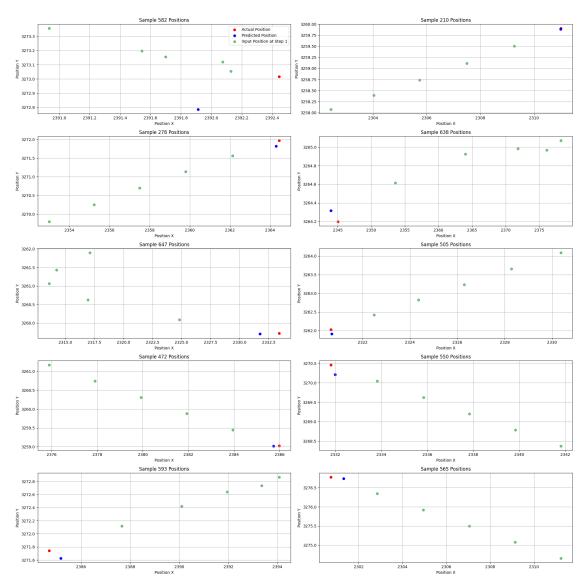
The training loss is 0.000122372672194615 The validation loss is 5.889020030735992e-05

The mean relative error (in percentage) for the validation set:

0.0017523509450256824 Current Epoch: 150/150

The training loss is 0.00013009874965064228 The validation loss is 6.534773274324834e-05

The mean relative error (in percentage) for the validation set:



```
VBox(children=(Label(value='0.183 MB of 0.183 MB uploaded\r'),
 →FloatProgress(value=1.0, max=1.0)))
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
wandb: Sweep Agent: Waiting for job.
wandb: Job received.
wandb: Agent Starting Run: x23ym73a with config:
wandb:
          batch_size: 64
wandb:
          hidden layer size: 64
           learning_rate: 0.001
wandb:
wandb: WARNING Ignored wandb.init() arg project when
running a sweep.
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
Current Epoch: 15/150
The training loss is 0.0013117719208821654
The validation loss is 0.003025824436917901
The mean relative error (in percentage) for the validation set:
0.012560918927192688
Current Epoch: 30/150
The training loss is 0.00037465442437678576
The validation loss is 0.000567099719773978
The mean relative error (in percentage) for the validation set:
0.0054378751665353775
Current Epoch: 45/150
The training loss is 0.00018817218369804323
The validation loss is 0.00033277401234954596
The mean relative error (in percentage) for the validation set:
0.0041655683889985085
Current Epoch: 60/150
The training loss is 0.0001328177168034017
The validation loss is 0.0002016642247326672
The mean relative error (in percentage) for the validation set:
0.0032427539117634296
Current Epoch: 75/150
```

The training loss is 0.00013182673137634993

The validation loss is 0.00013640148972626776

The mean relative error (in percentage) for the validation set:

0.002666914602741599 Current Epoch: 90/150

The training loss is 0.00015181154594756663

The validation loss is 0.00011210349475732073

The mean relative error (in percentage) for the validation set:

0.002417737152427435 Current Epoch: 105/150

The training loss is 0.00013085652608424425

The validation loss is 0.00010322860180167481

The mean relative error (in percentage) for the validation set:

0.002320061670616269 Current Epoch: 120/150

The training loss is 0.0001215175143443048 The validation loss is 0.0001052723964676261

The mean relative error (in percentage) for the validation set:

0.002342916326597333 Current Epoch: 135/150

The training loss is 0.0001066750191967003

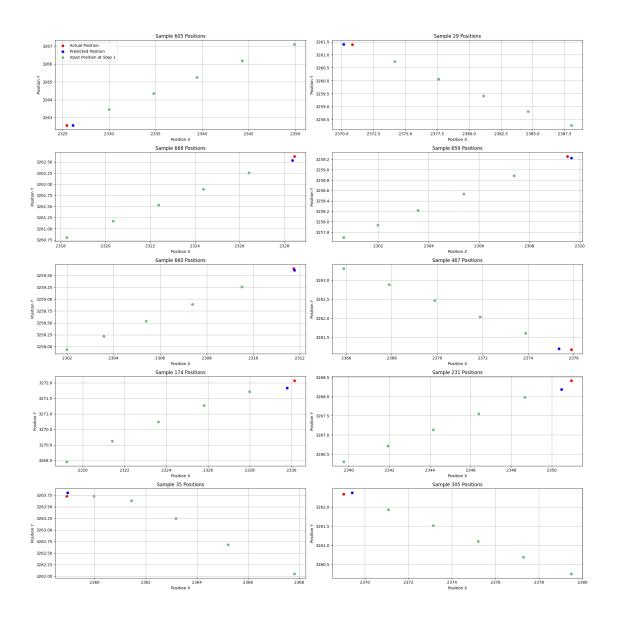
The validation loss is 0.00010659587860573083

The mean relative error (in percentage) for the validation set:

0.002357597928494215 Current Epoch: 150/150

The training loss is 8.082116255536675e-05 The validation loss is 0.00010585983545752242

The mean relative error (in percentage) for the validation set:



```
VBox(children=(Label(value='0.193 MB of 0.276 MB uploaded\r'), GFloatProgress(value=0.6987462719540484, max=1.0...)

<IPython.core.display.HTML object>

<IPython.core.display.HTML object>

wandb: Agent Starting Run: 2c7793nf with config: wandb: batch_size: 64
wandb: hidden_layer_size: 64
wandb: learning_rate: 0.0005
wandb: WARNING Ignored wandb.init() arg project when
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running a sweep.

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Current Epoch: 15/150

The training loss is 0.0025081071071326733 The validation loss is 0.005544864572584629

The mean relative error (in percentage) for the validation set:

0.01700376160442829 Current Epoch: 30/150

The training loss is 0.0008715858566574752 The validation loss is 0.0022509226109832525

The mean relative error (in percentage) for the validation set:

0.010833775624632835 Current Epoch: 45/150

The training loss is 0.0004895020392723382 The validation loss is 0.000691032677423209

The mean relative error (in percentage) for the validation set:

0.006002729758620262 Current Epoch: 60/150

The training loss is 0.0002981290454044938 The validation loss is 0.00040925992652773857

The mean relative error (in percentage) for the validation set:

0.00461954390630126 Current Epoch: 75/150

The training loss is 0.00016810167289804667 The validation loss is 0.0002779311907943338

The mean relative error (in percentage) for the validation set:

0.0038068711291998625 Current Epoch: 90/150

The training loss is 0.00015404439182020724 The validation loss is 0.00022719052503816783

The mean relative error (in percentage) for the validation set:

0.00344187137670815 Current Epoch: 105/150

The training loss is 0.00011488471500342712 The validation loss is 0.00014160401769913733

The mean relative error (in percentage) for the validation set:

0.002717298222705722 Current Epoch: 120/150

The training loss is 9.129035606747493e-05 The validation loss is 0.00011645222548395395

The mean relative error (in percentage) for the validation set:

### 0.0024641859345138073 Current Epoch: 135/150

The training loss is 9.030791989061981e-05 The validation loss is 0.00010227553138975054

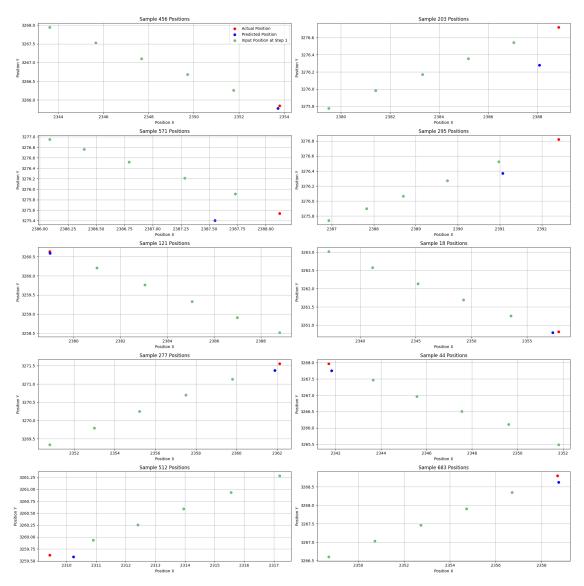
The mean relative error (in percentage) for the validation set:

0.002309326780959964 Current Epoch: 150/150

The training loss is 8.687983790878206e-05 The validation loss is 8.748780965106562e-05

The mean relative error (in percentage) for the validation set:

### 0.0021358623635023832



VBox(children=(Label(value='0.190 MB of 0.190 MB uploaded\r'), U\$\times\text{FloatProgress(value=1.0, max=1.0)})

```
<IPython.core.display.HTML object>
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<IPython.core.display.HTML object>
wandb: Agent Starting Run: 193pk3z4 with config:
wandb:
         batch_size: 64
wandb:
          hidden_layer_size: 128
           learning_rate: 0.001
wandb:
wandb: WARNING Ignored wandb.init() arg project when
running a sweep.
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
Current Epoch: 15/150
The training loss is 0.001166482805274427
The validation loss is 0.0021155672147870064
The mean relative error (in percentage) for the validation set:
0.010502989403903484
Current Epoch: 30/150
The training loss is 0.0002184532058890909
The validation loss is 0.0004536488268058747
The mean relative error (in percentage) for the validation set:
0.004863617941737175
Current Epoch: 45/150
The training loss is 0.00010518702038098127
The validation loss is 0.0001651886268518865
The mean relative error (in percentage) for the validation set:
0.002934874966740608
Current Epoch: 60/150
The training loss is 0.00010242682037642226
The validation loss is 0.0001206565139000304
The mean relative error (in percentage) for the validation set:
0.0025082738138735294
Current Epoch: 75/150
The training loss is 0.00015709048602730036
The validation loss is 0.00010427756933495402
The mean relative error (in percentage) for the validation set:
0.002331819850951433
Current Epoch: 90/150
The training loss is 0.00013516083708964288
The validation loss is 9.731302998261526e-05
```

The mean relative error (in percentage) for the validation set:

0.0022526050452142954 Current Epoch: 105/150

The training loss is 0.00011984664888586849 The validation loss is 9.619276534067467e-05

The mean relative error (in percentage) for the validation set:

0.0022396014537662268 Current Epoch: 120/150

The training loss is 0.00011049374006688595 The validation loss is 9.899142605718225e-05

The mean relative error (in percentage) for the validation set:

0.0022719476837664843 Current Epoch: 135/150

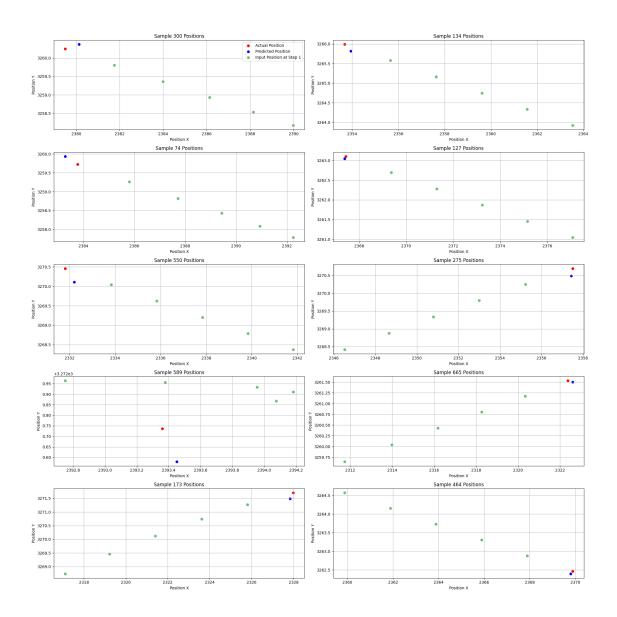
The training loss is 9.222002699971199e-05The validation loss is 0.00010345938062528148

The mean relative error (in percentage) for the validation set:

0.0023226537741720676 Current Epoch: 150/150

The training loss is 6.743345875293016e-05 The validation loss is 9.801196574699134e-05

The mean relative error (in percentage) for the validation set:



```
VBox(children=(Label(value='0.185 MB of 0.185 MB uploaded\r'), GFloatProgress(value=1.0, max=1.0)))

<IPython.core.display.HTML object>

<IPython.core.display.HTML object>

wandb: Agent Starting Run: yj8q15we with config:
wandb: batch_size: 64
wandb: hidden_layer_size: 128
wandb: learning_rate: 0.0005
wandb: WARNING Ignored wandb.init() arg project when
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running a sweep.

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<IPython.core.display.HTML object>
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<IPython.core.display.HTML object>

Current Epoch: 15/150

The training loss is 0.0031093615107238293 The validation loss is 0.005619566421955824

The mean relative error (in percentage) for the validation set:

0.01711791753768921 Current Epoch: 30/150

The training loss is 0.0007850875845178962 The validation loss is 0.0012562599731609225

The mean relative error (in percentage) for the validation set:

0.008093554526567459 Current Epoch: 45/150

The training loss is 0.0003556630981620401 The validation loss is 0.0005996702238917351

The mean relative error (in percentage) for the validation set:

0.005591853521764278 Current Epoch: 60/150

The training loss is 0.0001920072827488184 The validation loss is 0.00042599253356456757

The mean relative error (in percentage) for the validation set:

0.004713033325970173 Current Epoch: 75/150

The training loss is 0.00015969692321959883 The validation loss is 0.00028795498656108975

The mean relative error (in percentage) for the validation set:

0.0038749119266867638 Current Epoch: 90/150

The training loss is 0.00011291784176137298 The validation loss is 0.00017098993703257293

The mean relative error (in percentage) for the validation set:

0.002985965460538864 Current Epoch: 105/150

The training loss is 0.00015754283231217414

The validation loss is 0.00017559886327944696

The mean relative error (in percentage) for the validation set:

0.0030259406194090843 Current Epoch: 120/150

The training loss is 0.0001652678329264745 The validation loss is 0.00016684741422068328

The mean relative error (in percentage) for the validation set:

```
[]: # !pip install nbconvert

# !apt-get install texlive texlive-xetex texlive-latex-extra pandoc

!jupyter nbconvert --to pdf /content/drive/MyDrive/Colab\ Notebooks/

→Final_Project.ipynb
```