CCF-LAS5Series Laser Obstacle Avoidance Sensor Instructions

ModbusCommunication protocol output

This manual is applicable to the following sensor models:CCF-LAS5-4M





1 . Product Introduction:

7 High sensitivity laser probe;

Support detection distance output through serial port;

Support baud rate setting;

Support free setting of device address;

Power status indicator light display;

 $Working\ status\ indicator\ light\ display;$

Signal output status display;

Industrial-grade three-proof design, wide voltage, low power consumption;

2 . Electrical parameter description:

Supply voltage:DC 9 - 3 0 V;

Maximum current consumption: 1 0 0 mA;

 ${\bf Output\,interface:} RS485 interface, Modbus-RTU protocol;$

Effective detection distance: 1 -400CM;

Horizontal detection angle: less than or equal to 1 8 0 degrees;

Vertical detection angle: less than or equal to $\,$ 1 $\,$ 5 $\,$ degrees;

Recommended installation height: greater than 1 0 MM, TO avoid induction

It is recommended to install it at an everation angle

Response speed: 3 0 ms;

Operating temperature range: -40°C — +85°C;

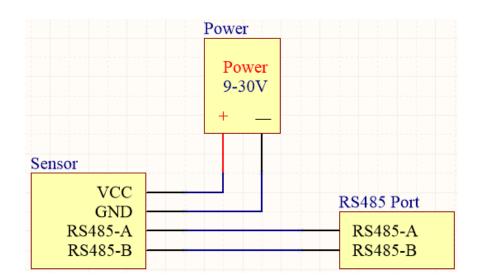
Working humidity: 1 0 % - 9 0 % relative humidity;

3 . Interface definition:

RS485接线定义:



4 . Product electrical connection:



5 . Indicator Light Description:

serial number 1 -7:Respectively 1 No. to 7 The indicator light of the probe working status flashes once

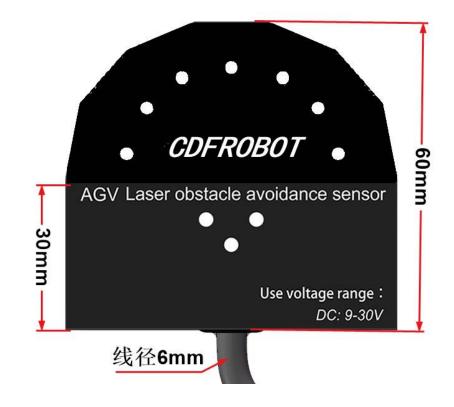
Indicates that the corresponding probe measures the distance once;

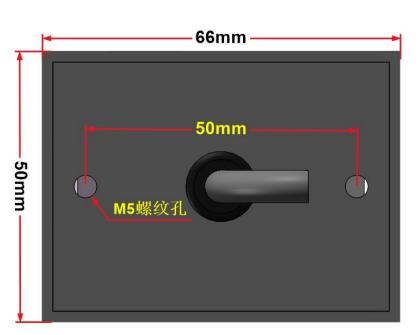
serial number 8 and 9 :none;

serial number 1 0 :Power indicator light;

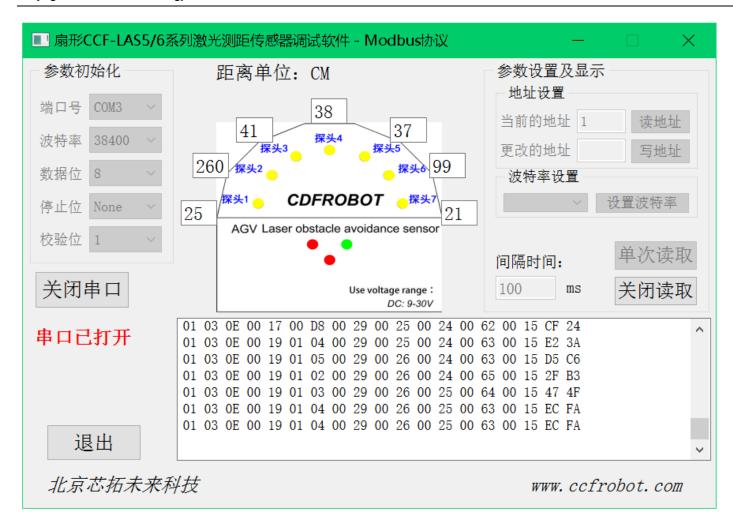


6 . Size description:





^{7 .} Instructions for using the host computer setting software:



- Parameter initialization: default as shown in the figure;
- Open serial port/Close serial port: Select the correctcomSlogan, you can open the serial port normally, otherwise an error will be reported; plug and unplugUSBSerial Port

 Before opening the line, close the serial port first;
- Current address: Click the Read Address button to display the current address of the sensor (The physical address of the sensor, as Slave address of the slave);
- Change the address: first enter the address number to be set, then click Write Address to change the sensor address (Sensor
 Physical address, used as slave address of slave machine);
- Baud rate setting: Select the baud rate you want to set and click the Set Baud Rate button to change the baud rate of the sensor (Heavy After power-on, a new baud rate is required for communication);
- Single distance reading: Click once, the sensor returns one distance data;

The sensor returns distance data upon receiving the command;

- Continuous Read: Click once, the host computer will continuously send distance reading instructions to the sensor at the input interval time, and transmit
- Input interval: Set the interval time for continuous reading (unit:ms);
- 1 Probe distance value: real-time display 1 The distance value of the probe, unit:CM;
- Probe distance value: real-time display 2 The distance value of the probe, unit:CM;
- Probe distance value: real-time display 3 The distance value of the probe, unit:CM;
- 4 Probe distance value: real-time display 4 The distance value of the probe, unit:CM;
- 5 Probe distance value: real-time display 5 The distance value of the probe, unit:CM;
- 6 Probe distance value: real-time display 6 The distance value of the probe, unit:CM;
- 7 Probe distance value: real-time display 7 The distance value of the probe, unit:CM;
- Note: After all the above functions are set successfully, the sensor will automatically save the latest settings after powering on again;

- 8 . Communication format and communication protocol description:
- 1. Communication format: (8 data bits, 1 stop bit, no parity, default rate 9 6 0 0)

This product adopts standardModbus RTUCommunication protocol, this product supports 0 3 0 6 Function code, address: 1 ~ 2 5 4 Can be set (The factory default address is 1)

two, Host requests sensor data

For example: The host request address is 1 Sensor data (Must be operated in answer mode)

Host red	Host request: Send data as 0 1 0 3 0 0 0 2 0 0 0 7 A5 C8																	
0 1	0 3		0	0			0 2			0 0		0 7		A5	C8			
equipment address		Character	ng register address high section Character Starting register address low section Character Number of registers read High Byte The low byte of the register number to read			CRCL	CRCH											
Slave resp	onse: The	returned dat	ais 0 1 0 3	0 E 0 0 0	0 0 0 0 0	00000	00000	0 0 0 0 0	0 0 0 0 0	0 EF 1 5								
0 1	0 3	0 E	0 0	0 0	0 0	0 0	0 0	0 0	0 0	0 0	0 0	0 0	0 0	0 0	0 0	0 0	EF	1 5
equipment	achievem	en 6 torage	1 Number	1 Number	2 Number	2 Number	3 Number	3 Number	4 Number	4 Number	5 Number	5 Number	6 Number	6 Number	7 Number	7 Number	CRCL	CRCH
address	able	Number of d	evi P e K obe	Probe	Probe	Probe	Probe	Probe	Probe	Probe	Probe	Probe	Probe	Probe	Probe	Probe		
	cod	Quantity	distance	distance	distance	distance	distance	distance	distance	distance	distance	distance	distance	distance	distance	distance		
		Should	High Word	Low Word	High Word	Low Word	High Word	Low Word	High Word	Low Word	High Word	Low Word	High Word	Low Word	High Word	Low Word		
		byte	Festival	Festival	Festival	Festival	Festival	Festival	Festival	Festival	Festival	Festival	Festival	Festival	Festival	Festival		
		number																

3 . Address range 1 ~ 2 5 4 Can be set (The factory default address is 1) . The address modification needs to be powered on again to take effect.

After the address is modified, the new address is required for communication.

For example: Set the device address to 1 Sensor address 1 Change to address 2

Host request: S	Host request: Send data as 0 1 0 6 0 0 0 0 0 0 2 0 8 0 B(address 1 Change to 2)											
0 1	0 6	0 0	0 0	0 0	0 2	0 8	0 B					
Equipment Location	Function code	Preset register address high	Preset register address low bit	Place data high word	Place data low word	CRCL	CRCH					
Slave response: T	he returned data	ais 0 1 0 6 0 0 0 0 0 0 0 2 0 8 0	В		1	1	I					
0 1	0 6	0 0	0 0	0 0	0 2	0 8	0 B					
Equipment Location	Function code	Preset register address high byte	Preset register address low bit	Place data high word	Place data low word	CRCL	CRCH					

4. When modifying the baud rate, you should first use the baud rate of the current module for communication. After the baud rate is modified, you need to power on the sensor again.

Currently supported 2 4 0 0, 4 8 0 0, 9 6 0 0, 1 9 2 0 0, 3 8 4 0 0, 5 7 6 0 0, 1 1 5 2 0 0 Baud rate, Module factory default baud

The rate is 3 8 4 0 0; 2 4 0 0 correspond 0 x0001; 4 8 0 0 correspond 0 x0002; 9 6 0 0 correspond 0 x0003; 1 9 2 0 0 correspond 0 x0004; 3 8 4 0 0

correspond 0 x0005; 5 7 6 0 0 correspond 0 x0006; 1 1 5 2 0 0 correspond 0 x0007;

For example: Set the device address to 1 The sensor baud rate is changed to 3 8 4 0 0 (3 8 4 0 0 correspond 0 \times 0005)

Host request: Send data as 0 1 0 6 0 0 0 1 0 0 0 5 1 8 0 9											
0 1	0 6	0 0	0 1	0 0	0 5	1 8	0 9				
Device Address	Function code	Preset register address high word	Preset register address bit word	Place data high word	Place data low word	CRCL	CRCH				
Slave response: T	Slave response: The returned data is 0 1 0 6 0 0 0 1 0 0 0 5 1 8 0 9										

0 1	0 6	0 0	0 1	0 0	0 5	1 8	0 9
Device Address	Function code	Preset register address high word	Preset register address bit word	Place data high word	Place data low word	CRCL	CRCH
		Festival	Festival	Festival	Festival		

9. If you forget the address after setting it, you can use the unconditional query address command. This command is a special command.

The sensor and computer are connected separately.

Get the module's address information.

Frame format: Send

	byte 1	byte 2	byte 3	byte 4	byte 5	byte 6	CRCL	CRCH
•	FF	0 3	0 0	0 0	0 0	0 1	9 1	D4

return

byte 1	byte 2	byte 3	byte 4	byte 5	CRCL	CRCH
FF	0 3	0 2	0 0	ADDR	*	*