```
Sensor< float >

+ getOutput()
+ process()
+ isAlive()
```

```
UltrasonicSensor

- max_distance_
- output_current_distance_
- is_running_
- seed_

+ UltrasonicSensor()
+ ~UltrasonicSensor()
+ setSeed()
+ process()
+ isAlive()
+ setMaxDistance()
+ getMaxDistance()
+ getOutput()
```