



Probability Revisited

Discrete Random Variable, Continuous Random Variable, Joint Probability, Conditional Probability, Probability

Distribution



Discrete Random Variable

- Discrete random variable: the expression p(A) denotes the probability that the event A is true.
- A discrete random variable take any value from a finite or countably infinite set X.
- p(X = x) denotes the probability mass function for the rv X and $\sum p(x) = 1$



Joint Probability

- We define probability of the joint event A and B as follows:
- $p(A,B) = p(A \cap B) = p(A|B)p(B)$
- This is sometimes called product rule.
- Given a joint distribution on two events p(A,B), the marginal distribution is
- $p(A) = \sum_{b} p(A, B) = \sum_{b} p(A|B = b)p(B = b)$
- This is called sum rule or rule of total probability.



Joint Probability

- The product rule or chain probability can be written as
- $p(X_{1:N}) = p(X_1)p(X_2|X_1)p(X_3|X_2,X_1) \dots p(X_N|X_1,X_2 \dots X_{N-1})$



Conditional Probability

ullet The conditional probability for the event A, given that the event B is true

•
$$p(A|B) = \frac{p(AB)}{p(B)}$$
 if $p(B) > 0$

Bayes Rule:

•
$$p(X = x | Y = y) = \frac{p(X = x, Y = y)}{p(Y = y)} = \frac{p(Y = y | X = x)p(X = x)}{\sum_{\widehat{X}} p(Y = y | X = \widehat{X})p(X = \widehat{X})}$$



Example:

• Suppose you are a woman in your 40s, and you decide to have a medical test for breast cancer called a mammogram. If the test is positive, what is the probability you have cancer? Suppose you are told the test has a sensitivity of 80%, which means, if you have cancer, the test will be positive with probability 0.8. the prior probability of having breast cancer is 0.004.



Generative Classifier

 We can generalize the medical diagnosis example to classify feature vectors x of arbitrary type as follows:

•
$$p(y = c|x, \theta) = \frac{p(x|y = c, \theta)p(y=c|\theta)}{\sum_{\hat{c}} \hat{c}p(x|y = \hat{c}, \theta)p(y=\hat{c}|\theta)}$$



Mean and Variance

- The mean or expected value of X is denoted as E(X) or μ
- $E(x) = \sum x p(x)$
- $E(x) = \int x p(x) dx$
- The variance of X is a measure of dispersion, denoted as σ^2
- $E[(X \mu)^2] = \int (x \mu)^2 p(x) dx$



Continuous Random Variable

- If X is some uncertain continuous quantity. The probability that X lies in any interval can be written as $P(a \le X \le b)$
- We define the cumulative density function of X as F(a)
- $P(a \le X \le b) = F(b) F(a)$
- $p(a \le x \le b) = \int_a^b f(x)dx$, where f(x) is pdf of X



Discrete Distribution

- Bernoulli Distribution
- Binomial Distribution
- Poisson Distribution
- The empirical Distribution



Bernouli Distribution

 A discrete random variable only having two outcome success with probability \$p\$ and failure with probability \$(1-p)\$ follows Bernoulli distribution.

•
$$P(X = 1) = p$$

• And
$$P(X = 0) = 1 - p$$

•



Binomial Distribution

• The binomial distribution is n repetition of the identical experiment, each experiment has only two outcomes: success and failure.

•
$$P(X = x) = {}^{n} C_{x} p^{x} (1 - p)^{n - x}$$



Poisson Distribution

•
$$P(X = x) = \frac{\lambda^x e^{-\lambda}}{x!}$$

- Where x = 0,1,2,3,4,...
- And λ is the long-run average



Empirical Distribution

• The empirical distribution for the dataset $D = \{x_1, x_2, ..., x_n\}$ of n observation is the function $[0,1] \to \mathbb{R}$

•
$$F(x) = \frac{1}{n} \sum_{n=1}^{\infty} \mathbb{I}_n$$



Gaussian Distribution

• The widely used distribution in machine learning is the Gaussian distribution. The probability distribution of x is

•
$$(x|\mu,\sigma^2) = \frac{1}{\sqrt{(2\pi\sigma^2)}} \exp(-\frac{(x-\mu)^2}{2\sigma^2})$$

• Where $\mu = E[x]$ and $\sigma^2 = var(x)$



Some Continuous Distribution

- Gaussian(Normal) Distribution
- Degenerate pdf
- The Laplace Distribution
- The gamma distribution
- Beta Distribution



Covariance and Correlation

•
$$COV(X,Y) = E[(X - E(X))(Y - E(Y))] = E(XY) - E(X)E(Y)$$

•
$$Corr(X,Y) = \frac{COV(X,Y)}{\sqrt{(var(X)Var(Y))}}$$



Multivariate Gaussian

 The probability distribution function(pdf) for the multivariate Gaussian in \$D\$ dimension is defined as

•
$$\mathcal{N}(x|\mu,\Sigma) = \frac{1}{(2\pi)^{\frac{D}{2}}|\Sigma|^{1/2}} \exp\left[-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)\right]$$