### February 16, 2024

MOUNTAINS OF THE MOON UNIVERSITY FACULTY OF SCIENCE, TECHNOLOGY AND INNOVATION DEPARTMENT OF COMPUTER SCIENCE YEAR ONE SEMESTER TWO

COURSE NAME: LINEAR PROGRAMMING

COURSE CODE: BCS 1201

LECTURERS NAME: SAMUEL OCEN

INDIVIDUAL COURSE WORK NAME: TUMUHAISE DAVID

REG NO: 2023/U/MMU/BCS/00846

```
NO 1 BASIC RESOURCE ALLOCATION

from pulp import LpProblem, LpVariable, LpMinimize

model = LpProblem(name="Minimize_cost_of_Resource_Allocation", sense=LpMinimize)

# definiing the objective variables of linear programming problem

x = LpVariable(name=("x"), lowBound=0)

y = LpVariable(name=("y"), lowBound=0)

#defining the objective function of the linear programming problem

model += 4 * x + 5 * y

model += 2 * x + 3 * y >= 10 # CPU

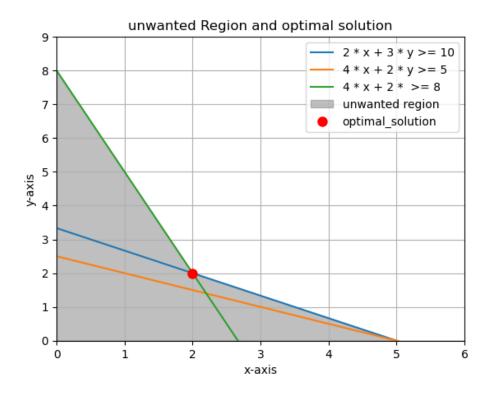
model += x + 2 * y >= 5 # memory

model += 3 * x + y >= 8 # storage

#solve the proble

model.solve()
```

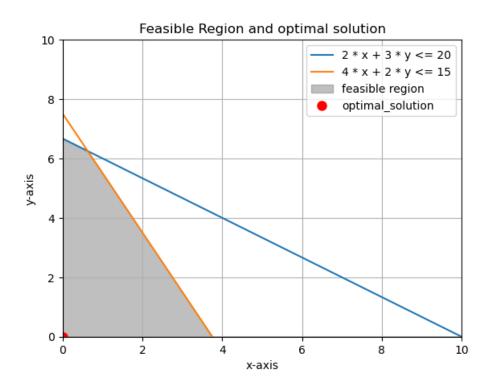
```
#display the result
print("Optimal value:")
print(f"optimal value (x): {x.varValue}")
print(f"optimal value (y): {y.varValue}")
print(f"minimum_cost (Z): {model.objective.value()}")
Optimal value:
optimal value (x): 2.0
optimal value (y): 2.0
minimum_cost (Z): 18.0
#graph for no1 resource allocation*
import numpy as np
import matplotlib.pyplot as plt
#converting constraints to inqualities
x = np.linspace(0,6,400)
#convert constraints into inqualities
y1 = (10 - 2 * x)/3
y2 = (5 - x)/2
y3 = (8 - 3 * x)
#plot constraints
plt.plot(x, y1, label = "2 * x + 3 * y >= 10") #CPU
plt.plot(x, y2, label = "4 * x + 2 * y >= 5") #Memory
plt.plot(x, y3, label = "4 * x + 2 * >= 8") #storage
#defining the unwanted region
y4 = np.maximum.reduce([y1, y2, y3])
plt.fill_between(x, y4, 0, color = "gray", alpha = 0.5, label="unwanted region")
#plot the optimal solution point
optimal_x=2.0
optimal_y=2.0
plt.plot(2, 2, "ro", markersize=8, label="optimal_solution")
plt.xlim(0, 6)
plt.ylim(0, 9)
plt.grid(True)
plt.legend()
plt.xlabel("x-axis")
plt.ylabel("y-axis")
plt.title("unwanted Region and optimal solution")
```



#### NO2 LOAD BALANCING

```
#importing necessary libraries
from pulp import LpProblem, LpVariable, LpMinimize
# creating a linear programming minimization problem
model = LpProblem(name="minimize_the_overall_response_time", sense=LpMinimize)
# definiing the objective variables of linear programming problem
x = LpVariable(name=("x"), lowBound=0)
y = LpVariable(name=("y"), lowBound=0)
#defining the objective function of the linear programming problem
model += 5 * x + 4 * y
#defining the constraints of the linear programing problem
model += 2 * x + 3 * y \le 20 #server 1 capacity
model += 4 * x + 2 * y <= 15 # server2 capcity
#solve the problem
model.solve()
#display the result
print("Optimal value:")
print(f"optimal value (x): {x.varValue}")
print(f"optimal value (y): {x.varValue}")
print(f"minimum_overall_time (Z): {model.objective.value()}")
Optimal value:
optimal value (x): 0.0
optimal value (y): 0.0
minimum_overall_time (Z): 0.0
code for graph of loading balancing
  import numpy as np
import matplotlib.pyplot as plt
#converting constraints to inqualities
x = np.linspace(0,15,400)
y1 = (20 - 2* x)/3
```

```
y2 = (15 - 4 * x)/2
#plot constraints
plt.plot(x, y1, label = "2 * x + 3 * y \le 20")
plt.plot(x, y2, label = "4 * x + 2 * y <= 15")
#define the feasible region
y3 = np.minimum(y1, y2)
plt.fill_between(x, y3, color = "gray", alpha = 0.5, label="feasible region")
#plot the optimal solution point
optimal_x=0
optimal_y=0
plt.plot(0, 0, "ro", markersize=8, label="optimal_solution")
#define the limits
plt.xlim(0, 10)
plt.ylim(0, 10)
plt.grid(True)
plt.legend()
plt.xlabel("x-axis")
plt.ylabel("y-axis")
plt.title("Feasible Region and optimal solution")
```

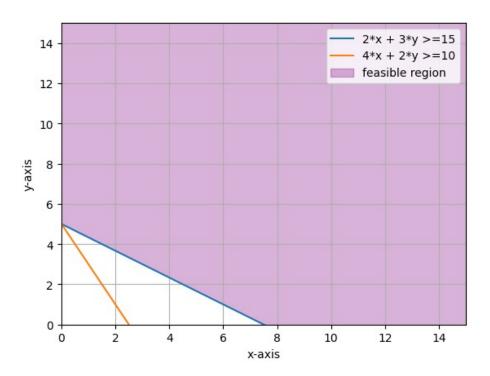


```
NO.3 ENERGY EFFICIENT RESOURCE ALLOCATION
from pulp import LpProblem, LpMinimize, LpVariable
import matplotlib.pyplot as plt
import numpy as np
#LpProblem
model = LpProblem(name="Energy-Efficient_resource_allocation",sense=LpMinimize)
#variables
x=LpVariable("x",0)
y=LpVariable("y",0)
#objective function
model+= 3*x + 2*y
#Constraints
model+= 2*x + 3*y >= 15, "CPU Allocation Constraint"
model+= 4*x + 2*y >= 10," Memory Allocation Constraint"
#Solving
model.solve()
#resluts
optimal_x=x.varValue
optimal_y=y.varValue
optimal_value = model.objective.value()
print("optimal solution:")
print("x:",optimal_x)
print("y:",optimal_y)
print("z:",optimal_value)
optimal solution:
x: 0.0
y: 5.0
z: 10.0
\[CODES FOR GRAPH\]
import matplotlib.pyplot as plt
import numpy as np
#define x array
x=np.linspace(0,17,15000)
#convert constraints to inequalities
y1=(15-2*x)/3
```

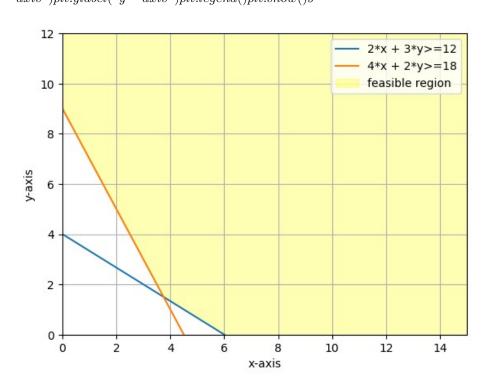
```
y2=(10-4*x)/2
#plot constraints
plt.plot(x,y1,label="2*x + 3*y >=15")
plt.plot(x,y2,label="4*x + 2*y >=10")
#define the feasible region
y3 =np.maximum.reduce([y1,y2])
plt.fill_between(x,y3,15,color="purple",label="feasible region",alpha=0.3)
# define limits
plt.xlim(0,15)
plt.ylim(0,15)
ENERGY EFFICIENT RESOURCE ALLOCATION.png
Figure 1: graph for number three
plt.grid(True)
plt.xlabel ("x-axis")
plt.ylabel("y-axis")
plt.legend()
plt.show()
NO 4.MULTI-TENANT RESOURCE SHARING
from pulp import LpProblem, LpMinimize, LpVariable
import matplotlib.pyplot as plt
import numpy as np
#LpProblem
model = LpProblem(name="Multi_Tenant_Resource_Sharing",sense=LpMinimize)
#variables
x=LpVariable("x",0)
y=LpVariable("y",0)
#objective function
model+= 5*x + 4*y
#Constraints
model+= 2*x + 3*y >= 12, "Tenant 1 Constraint"
model+= 4*x + 2*y >= 18,"Tenant 2 Constraint"
#Solving
model.solve()
#resluts
optimal_x=x.varValue
optimal_y=y.varValue
optimal_value = model.objective.value()
print("optimal solution:")
print("x:",optimal_x)
print("y:",optimal_y)
print("z:",optimal_value)
optimal solution:
x: 3.75
y: 1.5
```

```
z: 24.75
\[CODES FOR GRAPH\]
import matplotlib.pyplot as plt
import numpy as np
#define the x array
x= np.linspace(0,15,20000)
#convert constraints to inequalities
y1=(12-2*x)/3
y2=(18-4*x)/2
#=plot constraints
plt.plot(x,y1,label="2*x + 3*y>=12")
plt.plot(x,y2,label="4*x + 2*y>=18")
#define the feasible region
y3 =np.maximum.reduce([y1,y2])
plt.fill_between(x,y3,13,color="yellow",label="feasible region",alpha=0.3)
#define limits
plt.xlim(0,15)
MULTI-TENANT RESOURCE SHARING.png
Figure 2: Graph for number four
plt.ylim(0,12)
plt.grid(True)
plt.xlabel ("x-axis")
plt.ylabel ("y-axis")
plt.legend()
plt.show()
\begin{verbatim}
NO.3 ENERGY EFFICIENT RESOURCE ALLOCATION
from pulp import LpProblem, LpMinimize, LpVariable
import matplotlib.pyplot as plt
import numpy as np
#LpProblem
model = LpProblem(name="Energy-Efficient_resource_allocation",sense=LpMinimize)
#variables
x=LpVariable("x",0)
y=LpVariable("y",0)
#objective function
model+= 3*x + 2*y
#Constraints
model+= 2*x + 3*y >= 15, "CPU Allocation Constraint"
model+= 4*x + 2*y >= 10," Memory Allocation Constraint"
#Solving
model.solve()
#resluts
optimal_x=x.varValue
```

```
optimal_y=y.varValue
optimal_value = model.objective.value()
print("optimal solution:")
print("x:",optimal_x)
print("y:",optimal_y)
print("z:",optimal_value)
optimal solution:
x: 0.0
y: 5.0
z: 10.0
\[CODES FOR GRAPH\]
import matplotlib.pyplot as plt
import numpy as np
#define x array
x=np.linspace(0,17,15000)
#convert constraints to inequalities
y1=(15-2*x)/3
y2=(10-4*x)/2
#plot constraints
plt.plot(x,y1,label="2*x + 3*y >=15")
plt.plot(x,y2,label="4*x + 2*y >=10")
#define the feasible region
y3 =np.maximum.reduce([y1,y2])
plt.fill_between(x,y3,15,color="purple",label="feasible region",alpha=0.3)
# define limits
ENERGY EFFICIENT RESOURCE ALLOCATION.png
Figure 3: graph for number three
plt.xlim(0,15)
plt.ylim(0,15)
plt.grid(True)
plt.xlabel ("x-axis")
plt.ylabel("y-axis")
plt.legend()
plt.show()
```



No 4.MULTI-TENANT RESOURCE SHARING from pulp import LpProblem, LpMinimize, LpVariable import matplotlib.pyplot as plt import numpy as np LpProblem model = LpProblem (name="Multi\_renant\_Resource\_sharing", sense = LpMinimize) variablesx = LpVariable("x",0)y = LpVariable("y",0) objective function model + = 5\*x+4\*yConstraintsmodel + 2\*x+3\*y >= 12, "Tenant1Constraint" model + 4\*x+2\*y >= 18, "Tenant2Constraint" Solving model. solve() resluts optimal\_x = 4\*x+2\*y >= 18, "Tenant2Constraint" solving model. solve() resluts optimal\_x = 4\*x+2\*y >= 18, "Tenant2Constraint" y: ", optimal\_y print("z: ", optimal\_value) optimal solution: 4\*x+2\*y >= 18, "optimal\_y print("y: ", optimal\_y) print("z: ", optimal\_value) optimal solution: 4\*x+2\*y >= 18, "optimal\_y print("z: ", optimal\_value) optimal solution: 4\*x+2\*y >= 18, "optimal\_y print("z: ", optimal\_value) optimal solution: 4\*x+2\*y >= 18, "optimal\_y print("z: ", optimal\_value) optimal solution: 4\*x+2\*y >= 18, "optimal\_y print("z: ", optimal\_value) optimal solution: 4\*x+2\*y >= 18, "optimal\_y print("z: ", optimal\_value) optimal solution: 4\*x+2\*y >= 18, "optimal\_y print("z: ", optimal\_value) optimal solution: 4\*x+2\*y >= 18, "optimal\_y print("z: ", optimal\_value) optimal\_value) optimal\_y print("z: ", optimal\_value) optimal\_value) optimal\_y optimal\_value) optimal\_y optimal\_value) optimal\_y optimal\_value) optimal



# NO 5 PRODUCTION PLANNING MANUFACTURING from pulp import LpProblem, LpVariable, LpMinimize model = LpProblem(name="Minimizing\_the\_production\_cost", sense=LpMinimize) # definiing the objective variables x1 = LpVariable(name=("x1"), lowBound=0) x2 = LpVariable(name=("x2"), lowBound=0) x3 = LpVariable(name=("x3"), lowBound=0) #defining the objective function model += 5 \* x1 + 3 \* x2 + 4 \* x3#defining the constraints model += 2 \* x1 +3 \* x2 + x3 <= 1000 #available raw material model += 4 \* x1 + 2 \* x2 + 5 \* x3 <= 120 # Available hours model += x1 >= 200 #demand constraint, minimum product constrains model += x2 >= 300 #demand constraint, minimum product constrains model += x3 >= 150 #demand constraint, minimum product constrains #solve the proble model.solve() #display the result print("Optimal value:") print(f"Quantity of product (x1): {x1.varValue}") print(f"Quantity of product (x2): {x2.varValue}") print(f"Quantity of product (x2): {x3.varValue}") print(f"minimum value(Z): {model.objective.value()}") Optimal value: Quantity of product (x1): 200.0 Quantity of product (x2): 300.0 Quantity of product (x2): 0.0

minimum value(Z): 1900.0

codes for production planning no 5

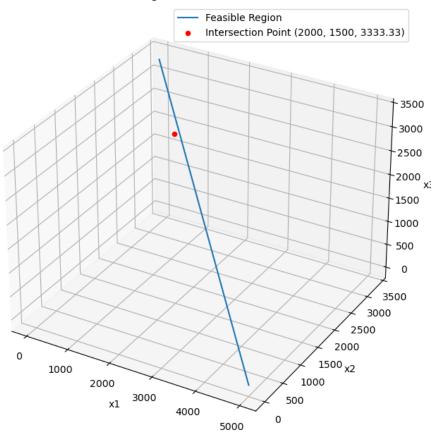
```
# importing necessary libraries
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
# coverting the constraints into inequalities
def constraint1(x1):
   return (1000 - 2 * x1) / 3
def constraint2(x1):
   return (25 - 4 * x1) / 5
def constraint3(x1):
    return 300
def constraint4(x1):
   return 150
# Create arrays of x1 values for plotting
x1\_values = np.linspace(0, 400, 100)
# Calculate corresponding x2 and x3 values based on the constraints
x2_values = constraint1(x1_values)
x3_values = constraint2(x1_values)
fig = plt.figure(figsize=(10, 8))
ax = fig.add_subplot(111, projection='3d')
# Plot the feasible region surface
ax.plot_surface(x1_values.reshape(-1, 1), np.full_like(x1_values, 300), x3_values.reshape(-
# Define the unwanted region
x1_unwanted = np.linspace(200, 40, 100)
x3_unwanted = np.full_like(x1_unwanted, 150)
x2_unwanted = constraint1(x1_unwanted)
# Plot the unwanted region surface
```

```
ax.plot_surface(x1_unwanted.reshape(-1, 1), x2_unwanted.reshape(-1, 1), x3_unwanted.reshape

optimal_x1 = 200.0
optimal_x2 = 300.0
optimal_x3 = 0.0
ax.scatter(optimal_x1, optimal_x2, optimal_x3, color='red', s=100, label='Optimal Solution')
ax.set_xlabel('x1')
ax.set_ylabel('x2')
ax.set_zlabel('x3')
ax.set_zlabel('Feasible Region with Optimal Solution')
```

#### Feasible Region and Intersection Point

plt.show()



#### NO 6 FINANCIAL PORTFOLIO OPTIMIZATION

```
#importing necessary libraries
from pulp import LpProblem, LpVariable, LpMaximize
# creating a linear programming minimization problem
model = LpProblem(name="Maximize_the_return_on_investment", sense=LpMaximize)
# definiing the objective variables
x1 = LpVariable(name=("x1"), lowBound=0)
                                           #investment in stock A
x2 = LpVariable(name=("x2"), lowBound=0)
                                           #investment in stock B
x3 = LpVariable(name=("x3"), lowBound=0)
                                           #investment in stock C
#defining the objective function
model += 0.08 * x1 + 0.1 * x2 + 0.12 * x3
#defining the constraints
model += 2 * x1 + 3 * x2 + x3 <= 10000 # bubget constraint (maximum Budget for investment)
model += x1 >= 2000
                                         # minimum investment constraints
model += x2 >= 1500
                                         # minimum investment constraints
                                         # minimum investment constraints
model += x3 >= 1000
#solve the problem
model.solve()
#display the result
print("Optimal value:")
print(f"optimal value (x1): {x1.varValue}")
print(f"optimal value (x2): {x2.varValue}")
print(f"optimal value (x3): {x3.varValue}")
print(f"maximum_return_on_investment (Z): {model.objective.value()}")
Optimal value:
optimal value (x1): 2000.0
optimal value (x2): 1500.0
optimal value (x3): 1500.0
maximum_return_on_investment (Z): 490.0
codes for no 6 in 3D
import numpy as np
import matplotlib.pyplot as plt
```

```
from mpl_toolkits.mplot3d import Axes3D
# Define the constraints
def constraint1(x1):
    return (10000 - 2 * x1) / 3
def constraint2(x1):
   return (10000 - 2 * x1) / 3
def constraint3(x1):
    return (10000 - 2 * x1) / 3
# Create arrays of x1 values for plotting
x1\_values = np.linspace(0, 5000, 1000)
# Calculate corresponding x2 and x3 values based on the constraints
x2_values = constraint1(x1_values)
x3_values = constraint2(x1_values)
# Plot the constraints
fig = plt.figure(figsize=(10, 8))
ax = fig.add_subplot(111, projection='3d')
ax.plot(x1_values, x2_values, x3_values, color='b', alpha=0.3)
# Plot the feasible region surface
X1, X3 = np.meshgrid(x1_values, x3_values)
X2 = constraint1(x1_values)
ax.plot_surface(X1, X2, X3, color='gray', alpha=0.5, label='Feasible Region')
# Plot the optimal solution point
optimal_x1 = 2000 # Optimal value for x1
optimal_x2 = 1500 # Optimal value for x2
optimal_x3 = 1500 # Optimal value for x3
ax.scatter(optimal_x1, optimal_x2, optimal_x3, color='red', s=100, label='Optimal Solution'
# Plot the point of intersection
ax.scatter(2000, 1500, 1500, color='red', s=100, label='Point of Intersection (2000, 1500,
ax.set_xlabel('x1')
ax.set_ylabel('x2')
ax.set_zlabel('x3')
ax.set_title('Feasible Region with Optimal Solution')
plt.show()
```

# Feasible Region with Optimal Solution

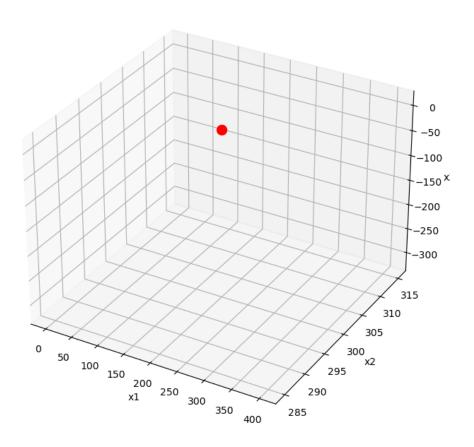


Figure 1: graph for portfolio optimization no 6 feasible region

#### NO 7 DIET OPTIMIZATION

```
from pulp import LpProblem, LpVariable, LpMinimize#my codes
# creating a linear programming minimization problem
model = LpProblem(name="Minimizing_the_cost_of_daily", sense=LpMinimize)
# definiing the objective variableS
x1 = LpVariable(name=("x1"), lowBound=0)
x2 = LpVariable(name=("x2"), lowBound=0)
#defining the objective function
model += 3 * x1 + 2 * x2
#defining the constraints of the linear programing problem
model += 2 * x1 + x2 >= 20 #proteins in grams
model += 3 * x1 + 2 * x2 >= 25 # vitamin in units
#solve the problem
model.solve()
#display the result
print("Optimal value:")
print(f"Quantity of product (x1): {x1.varValue}")
print(f"Quantity of product (x2): {x2.varValue}")
print(f"minimum value(Z): {model.objective.value()}")
Optimal value:
Quantity of product (x1): 10.0
Quantity of product (x2): 0.0
minimum value(Z): 30.0
codes for graph of no 7 unwanted region
from pulp import LpProblem, LpVariable, LpMinimize
import numpy as np
import matplotlib.pyplot as plt
```

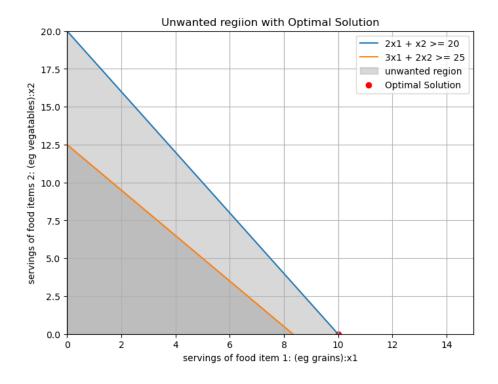
```
# creating a linear programming minimization problem
model = LpProblem(name="Minimizing_the_cost_of_daily", sense=LpMinimize)
# defining the objective variables
x1 = LpVariable(name="x1", lowBound=0)
x2 = LpVariable(name="x2", lowBound=0)
# defining the objective function
model += 3 * x1 + 2 * x2
# defining the constraints of the linear programming problem
model += 2 * x1 + x2 >= 20
                                # proteins in grams
model += 3 * x1 + 2 * x2 >= 25 # vitamin in units
# solve the problem
model.solve()
# display the result
print("Optimal value:")
print(f"Quantity of product (x1): {x1.varValue}")
print(f"Quantity of product (x2): {x2.varValue}")
print(f"Minimum value(Z): {model.objective.value()}")
# Create a grid of points
x1_values = np.linspace(0, 15, 400)
x2\_values = np.linspace(0, 15, 400)
#X1, X2 = np.meshgrid(x1_values, x2_values)
# Plot the constraints
plt.figure(figsize=(8, 6))
plt.plot(x1\_values, 20 - 2*x1\_values, label="2x1 + x2 >= 20")
plt.plot(x1_values, (25 - 3*x1_values)/2, label="3x1 + 2x2 >= 25")
# Shade the unwanted region
plt.fill_between(x1_values, 0,(20 - 2*x1_values), where=((20-2*x1_values) >= 0),color='gray'
plt.fill_between(x1_values, 0,(25 - 3*x1_values)/2, where=((25 - 3*x1_values)/2 >= 0), color=
```

## # Plot the optimal solution point

```
plt.scatter(x1.varValue, x2.varValue, color='red', label="Optimal Solution")
plt.xlabel("servings of food item 1: (eg grains):x1")
plt.ylabel("servings of food items 2: (eg vegatables):x2")
plt.title("Unwanted region with Optimal Solution")
plt.legend()
plt.grid(True)
plt.xlim(0, 15)
plt.ylim(0, 20)
plt.show()
```

#### Optimal value:

Quantity of product (x1): 10.0 Quantity of product (x2): 0.0 Minimum value(Z): 30.0



```
NO 8
```

```
from pulp import LpProblem, LpVariable, LpMaximize
```

```
model = LpProblem(name="Maximize_the_profit_in_production_process", sense=LpMaximize)
x1 = LpVariable(name=("x1"), lowBound=0)
x2 = LpVariable(name=("x2"), lowBound=0)
#defining the objective function
model += 5 * x1 + 3 * x2
#defining the constraints
model += 2 * x1 + 3 * x2 <= 60 #labors in hours
model += 4 * x1 + 2 * x2 \le 80 \# Raw materials in units
#solve the probleM
model.solve()
print("Optimal value:")
print(f"Quantity of product 1 to produce (x1): {x1.varValue}")
print(f"Quantity of product 2 to produce (x2): {x2.varValue}")
print(f"maximum value(Z): {model.objective.value()}")
Optimal value:
Quantity of product 1 to produce (x1): 15.0
Quantity of product 2 to produce (x2): 10.0
maximum value(Z): 105.0
import matplotlib.pyplot as plt
import numpy as np
# defining the x array
```

x = np.linspace(0,50,20000)

```
# convert the constraints to inequalities
y1 = (60-2*x)/3
y2 = (80-4*x)/2
# plot the the constraints
plt.plot(x,y1,label="2 * x1 + 3 * x2 <= 60")
plt.plot(x,y2,label="4 * x1 + 2 * x2 <= 80")
# shading the feasible region
y3 = np.minimum.reduce([y1,y2])
plt.fill_between(x,y3,0 ,label="feasible region", color="gray",alpha=0.5)
#optimal solution
optimal_x1 = 15.0
optimal_x2 = 10.0
plt.plot(optimal_x1, optimal_x2, "ro", markersize=8, label="optimal_solution")
# plt.plot(15,10,"ro", markersize=8, color="red", label="optimal point")
plt.xlabel("Quantity of product 1 to produce: x-axis")
plt.ylabel("Quantity of product 1 to produce: y-axis")
plt.title("feasible region and optimal solution")
plt.xlim(0,40)
plt.ylim(0,50)
plt.grid(True)
plt.legend()
plt.show()
```

