Heap Sort

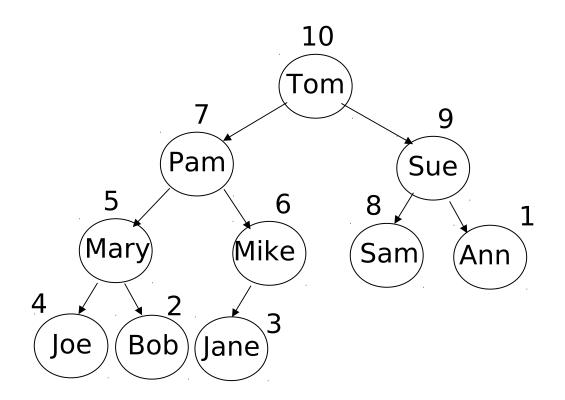
Heaps

A **heap** is a **complete** binary tree that is either:

- empty, or
- consists of a root and two subtrees, such that
 - both subtrees are heaps, and
 - the root contains a search key that is ≥
 the search key of each of its children.

Array-Based Representation of a Heap

Search	Ite	
Key		
10	To	
7	Par	
9	Suc	
5	Ma	
6	Mi	
8	Sar	
1	An	
4	Joe	
2	Bo	
3	Jan	



Array-Based Representation of a Heap

- Note that, for any node, the search key of its left child is not necessarily ≤ or ≥ the search key of its right child.
- The only constraint is that any *parent* node must have a search key that is ≥ the search key of both of its children.
- Note that this is sufficient to ensure that the item with the greatest search key in the heap is stored at the root.

The ADT Priority Queue

- A *priority queue* is an ADT in which items are ordered by a priority value. The item with the *highest priority* is always the *next* to be removed from the queue. (Highest Priority In, First Out: *HPIFO*)
- Supported operations include:
 - Create an empty priority queue
 - Destroy a priority queue
 - Determine whether a priority queue is empty
 - Insert a new item into a priority queue
 - Retrieve, and then delete from the priority queue the item with the highest priority value

PriorityQ: Retrieve & Delete

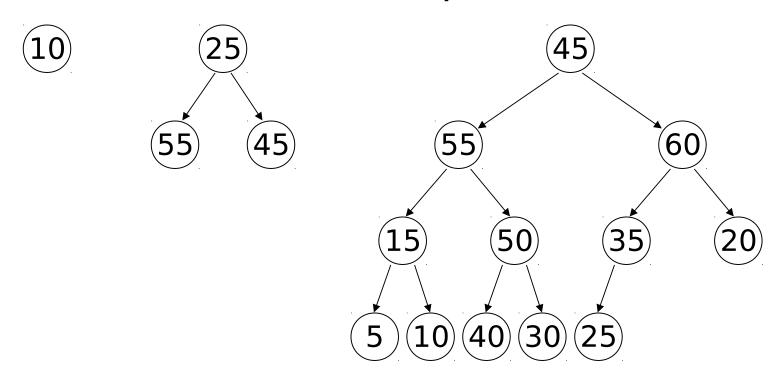
- Consider the operation, "Retrieve, and then delete from the priority queue the item with the highest priority value."
- In a heap where search keys represent the *priority* of the items, the item with the highest priority is stored at the *root*.
- Consequently, *retrieving* the item with the highest priority value is trivial.
- However, if the root of a heap is deleted we will be left with two separate heaps.
- We need a way to transform the remaining nodes back into a single heap.

PriorityQ: Retrieve

```
bool PriorityQ::pqRetrieve(pq)
   if( pq IsEmpty( ) ) return false;
  priorityItem = items[ 0 ];
   items[0] = items[--size];
   heapRebuild(0);
   return true;
```

Semiheap

A **semiheap** is a **complete** binary tree in which the root's left and right subtrees are both **heaps**.



Rebuilding a Heap: Basic Idea

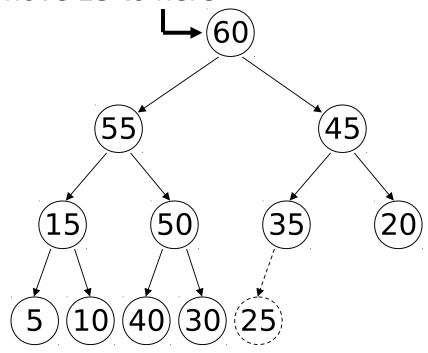
Problem: Transform a *semiheap* with given root into a *heap*.

Let *key(n)* represent the search key value of node *n*.

- 1) If the *root* of the *semiheap* is not a leaf, and key(*root*) < key(child of *root* with larger search key value) then swap the item in the root with the child containing the larger search key value.
- 2) If any items were swapped in step 1, then repeat step 1 with the subtree rooted at the node whose item was swapped with the root. If no items were swapped, then we are done: the resulting tree is a heap.

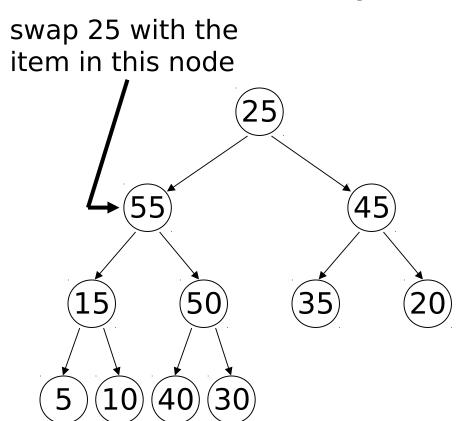
Retrieve & Delete: Example

move 25 to here



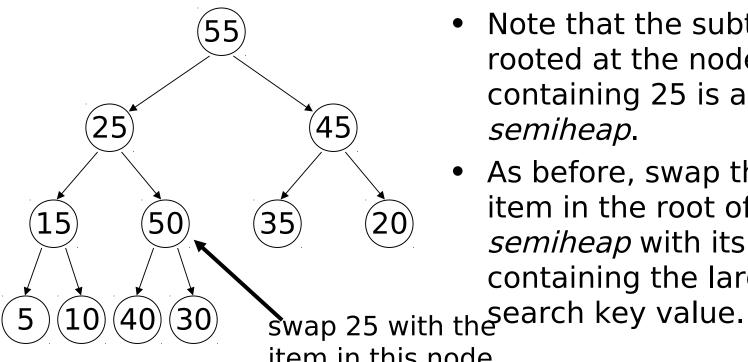
- Retrieve the item with the highest priority value (= 60) from the root.
- Move the item from the *last* node in the heap (= 25) to the *root*, and delete the last node.

Rebuilding a Heap: *Example* (Cont'd.)



- The resulting data structure is a semiheap, a complete binary tree in which the root's left and right subtrees are both heaps.
- To transform this semiheap into a heap, start by swapping the item in the root with its child containing the larger search key value.

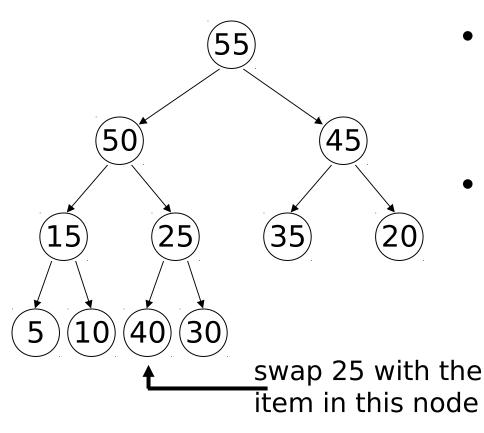
Rebuilding a Heap: *Example* (Cont'd.)



- Note that the subtree rooted at the node containing 25 is a semiheap.
- As before, swap the item in the root of this semiheap with its child containing the larger

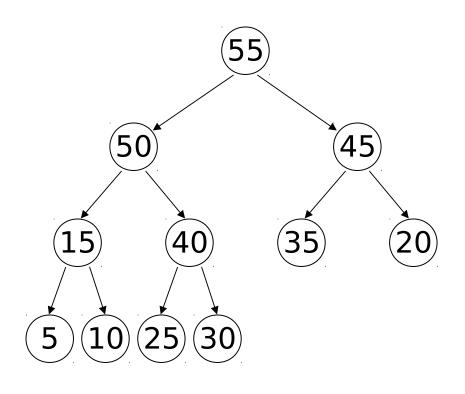
item in this node

Rebuilding a Heap: *Example* (Cont'd.)



- Note that the subtree rooted at the node containing 25 is a semiheap.
- As before, swap the item in the root of this semiheap with its child containing the larger search key value.

Rebuilding a Heap: *Example* (Cont'd.)



- Note that the subtree rooted at the node containing 25 is a semiheap with two empty subtrees.
- Since the root of this semiheap is also a leaf, we are done.
- The resulting tree rooted at the node containing 55 is a heap.

PriorityQ: Private Member Function Definition

```
void PriorityQ::heapRebuild( int root )
{
   int child = 2 * root + 1;
   if( child < size )
     int rightChild = child + 1;
     if( rightChild < size && getKey( items[ rightChild ] ) > getKey( items[ child ] ) )
            child = rightChild; // child has the larger search key
         if( getKey( items[ root ] ) < getKey( items[ child ] ) )</pre>
            swap( items[ root ], items[ child ] );
            heapRebuild( child );
```

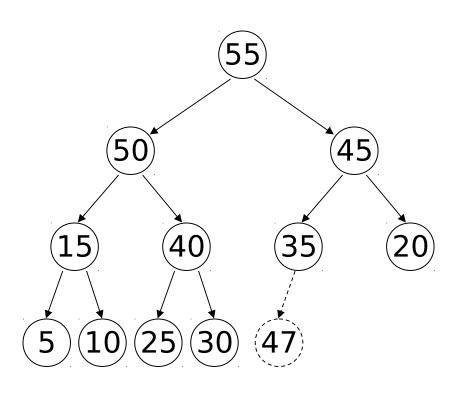
PriorityQ Insert: Basic Idea

Problem: Insert a new item into a *priority queue*, where the priority queue is implemented as a *heap*.

Let *key(n)* represent the search key value of node *n*.

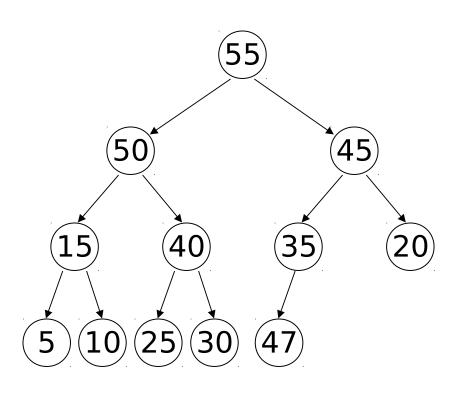
- 1) Store the new item in a new node at the end of the heap.
- 2) If the node containing the new item has a parent, and key(node containing new item) > key(node's parent) then swap the new item with the item in its parent node.
- 3) If the new item was swapped with its parent in step 2, then repeat step 2 with the new item in the parent node. If no items were swapped, then we are done: the resulting tree is a heap containing the new item.

PriorityQ Insert: Example



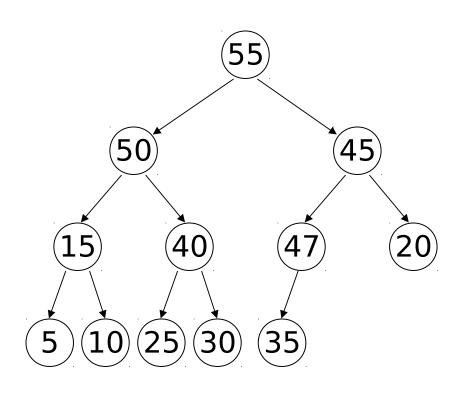
- Suppose that we wish to insert an item with search key = 47.
- First, we store the new item in a new node at the end of the heap.

PriorityQ Insert: *Example* (Cont'd.)



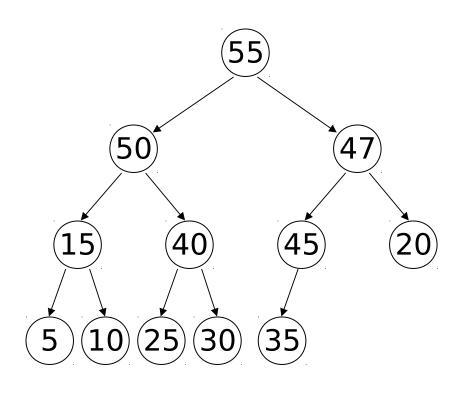
 Since the search key of the new item (= 47) > the search key of its parent (= 35), swap the new item with its parent.

PriorityQ Insert: *Example* (Cont'd.)



 Since the search key of the new item (= 47) > the search key of its parent (= 45), swap the new item with its parent.

PriorityQ Insert: *Example* (Cont'd.)



- Since the search key of the new item (= 47) ≤ the search key of its parent (= 55), we are done.
- The resulting tree is a heap containing the new item.

PriorityQ: *Public Member Function Definition*

```
bool PriorityQ::pqInsert( const PQItemType &newItem )
  if( size > MaxItems ) return false;
  items[ size ] = newItem;
  int newPos = size, parent = (newPos - 1) / 2;
  while( parent >= 0 \&\&
    getKey( items[ newPos ] ) > getKey( items[ parent ] ) )
     swap( items[ newPos ], items[ parent ] );
      newPos = parent;
      parent = (newPos - 1) / 2;
  size++; return true;
```

Heap-Based PriorityQ: *Efficiency*

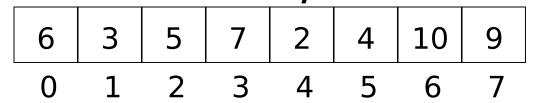
- In the *best case*, no swaps are needed after an item is inserted at the end of the heap. In this case, *insertion* requires constant time, which is O(1).
- In the *worst case*, an item inserted at the end of a heap will be swapped until it reaches the root, requiring O(height of tree) swaps. Since heaps are *complete binary trees*, and hence, *balanced*, the height of a heap with n nodes is \[\log_2 \left(n + 1 \right) \]. Therefore, in this case, *insertion* is O(log n).
- In the average case, the inserted item will travel halfway to the root, which makes *insertion* in this case also O(log n).
- The "retrieve & delete" operation spends most of its time rebuilding a heap. A similar analysis shows that this is O(log n) in the best, average, and worst cases.

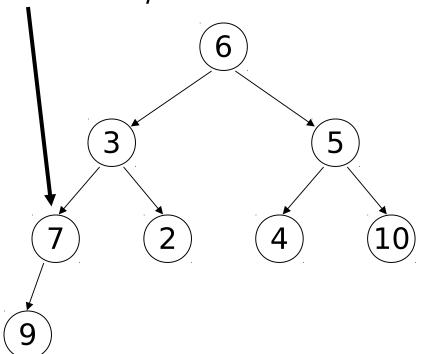
Heapsort: Basic Idea

Problem: Arrange an array of items into sorted order.

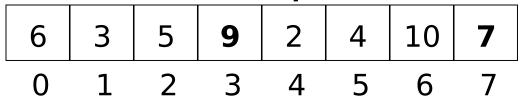
- 1) Transform the array of items into a *heap*.
- 2) Invoke the "retrieve & delete" operation repeatedly, to extract the largest item remaining in the heap, until the heap is empty. Store each item retrieved from the heap into the array from back to front.

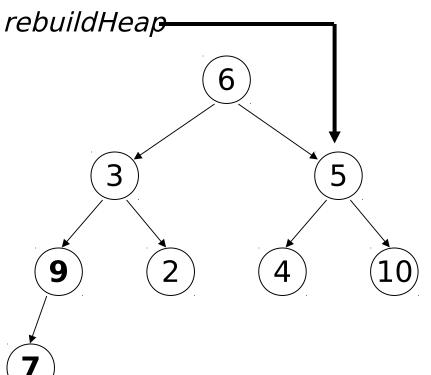
Note: We will refer to the version of *heapRebuild* used by *Heapsort* as *rebuildHeap*, to distinguish it from the version implemented for the class *PriorityQ*.



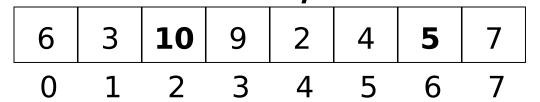


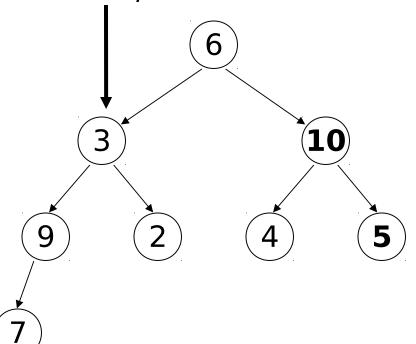
- The items in the array, above, can be considered to be stored in the complete binary tree shown at right.
- Note that leaves 2, 4, 9 & 10 are heaps; nodes 5 & 7 are roots of semiheaps.
- rebuildHeap is invoked on the parent of the last node in the array (= 9).





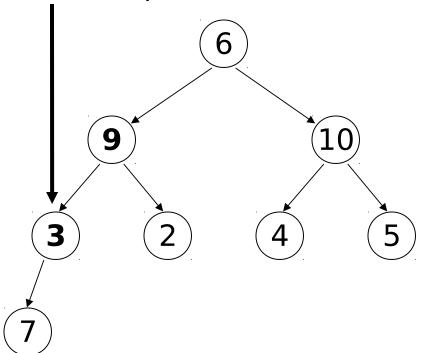
- Note that nodes 2, 4, 7, 9 & 10 are roots of heaps; nodes 3 & 5 are roots of semiheaps.
- rebuildHeap is invoked on the node in the array preceding node 9.



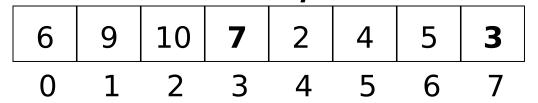


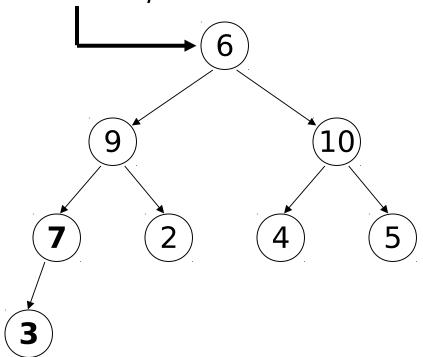
- Note that nodes 2, 4, 5, 7, 9 & 10 are roots of heaps; node 3 is the root of a semiheap.
- rebuildHeap is invoked on the node in the array preceding node 10.





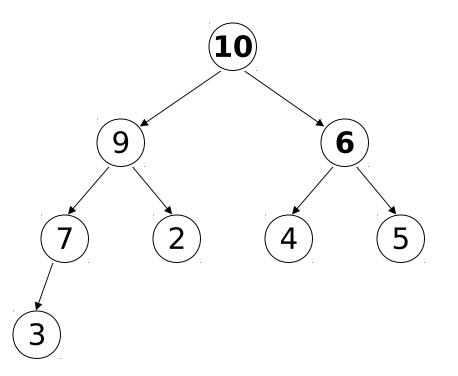
- Note that nodes 2, 4, 5, 7 & 10 are roots of heaps; node 3 is the root of a semiheap.
- rebuildHeap is invoked recursively on node 3 to complete the transformation of the semiheap rooted at 9 into a heap.





- Note that nodes 2, 3, 4, 5, 7, 9 & 10 are roots of heaps; node 6 is the root of a semiheap.
- The recursive call to rebuildHeap returns to node 9.
- rebuildHeap is invoked on the node in the array preceding node 9.

10	9	6	7	2	4	5	3
0	1	2	3	4	5	6	7



- Note that node 10 is now the root of a *heap*.
- The transformation of the array into a heap is complete.

Transform an Array Into a Heap (Cont'd.)

- Transforming an array into a heap begins by invoking rebuildHeap on the parent of the last node in the array.
- Recall that in an array-based representation of a complete binary tree, the *parent* of any node at array position, i, is

$$\lfloor (i-1)/2 \rfloor$$

• Since the last node in the array is at position n-1, it follows that transforming an array into a heap begins with the node at position

$$\lfloor (n-2)/2 \rfloor = \lfloor n/2 \rfloor - 1$$

and continues with each preceding node in the array.

Transform an Array Into a Heap: C++

```
for( int root = n/2 - 1; root >= 0; root - - )
  {
  rebuildHeap( a, root, n );
  }
```

Transform a Heap Into a Sorted Array: *Basic Idea*

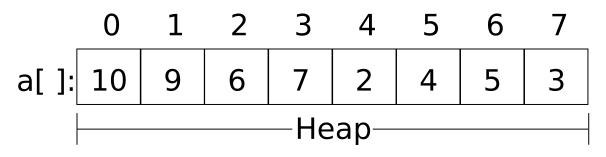
- **Problem:** Transform array a[] from a heap of *n* items into a sequence of *n* items in sorted order.
- Let *last* represent the position of the last node in the heap. Initially, the heap is in a[0 .. *last*], where last = n 1.
- 1) Move the largest item in the heap to the beginning of an (initially empty) sorted region of a[] by swapping a[0] with a[*last*].
- 2) Decrement *last*. a[0] now represents the root of a semiheap in a[0.. *last*], and the sorted region is in a[last + 1...n 1].
- 3) Invoke *rebuildHeap* on the semiheap rooted at a[0] to transform the semiheap into a heap.
- 4) Repeat steps 1 3 until last = -1. When done, the items in array a[] will be arranged in sorted order.

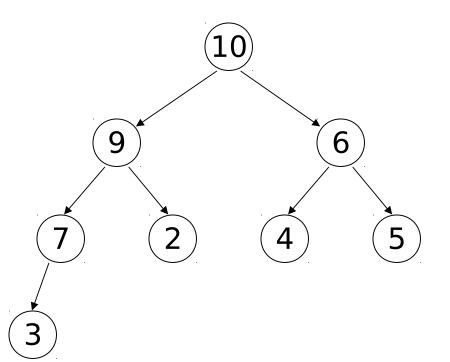
Heapsort: *C++*

```
void heapsort(ItemType a[], int n)
{
    for(int root = n/2 - 1; root >= 0; root --)
        rebuildHeap(a, root, n);

for(int last = n - 1; last > 0; )
      {
        swap(a[0], a[last]); last --;
        rebuildHeap(a, 0, last);
      }
}
```

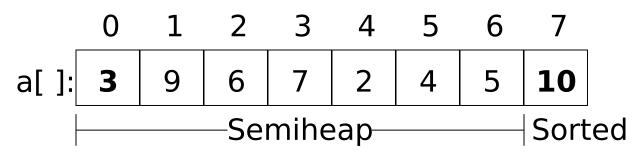
Transform a Heap Into a Sorted Array: Example

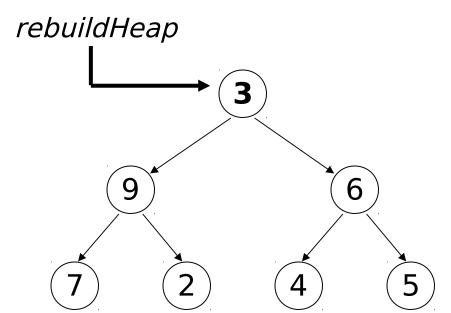




- We start with the heap that we formed from an unsorted array.
- The heap is in a[0..7] and the sorted region is empty.
- We move the largest item in the heap to the beginning of the sorted region by swapping a[0] with a[7].

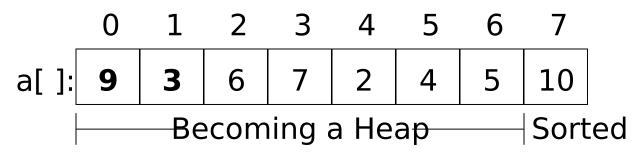
Transform a Heap Into a Sorted Array: Example

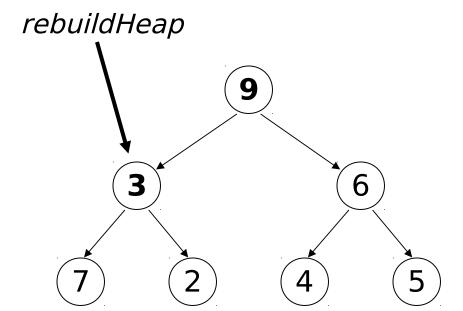




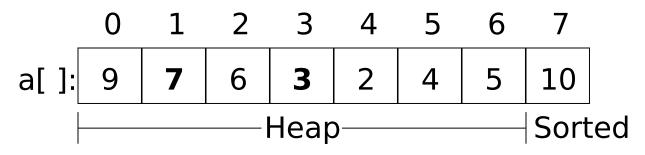
- a[0..6] now represents a semiheap.
- a[7] is the sorted region.
- Invoke rebuildHeap on the semiheap rooted at a[0].

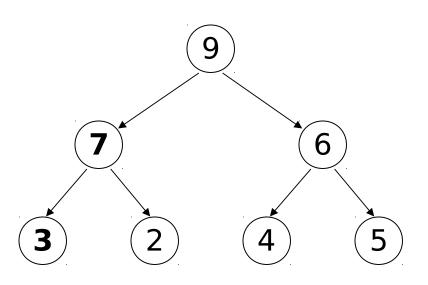
Transform a Heap Into a Sorted Array: Example



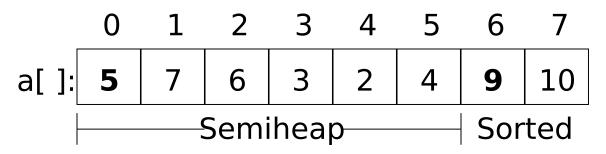


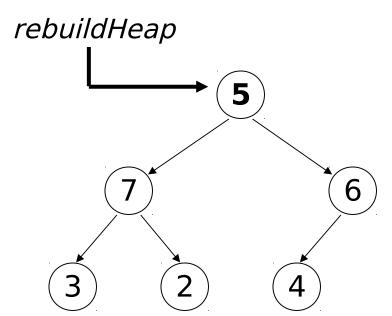
 rebuildHeap is invoked recursively on a[1] to complete the transformation of the semiheap rooted at a[0] into a heap.



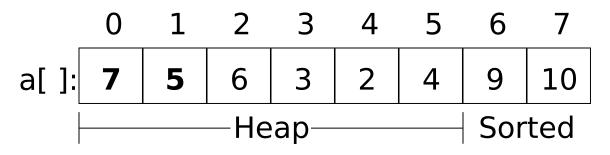


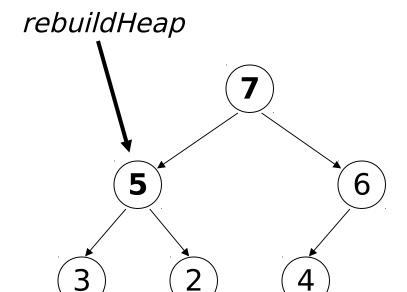
- a[0] is now the root of a heap in a[0..6].
- We move the largest item in the heap to the beginning of the sorted region by swapping a[0] with a[6].



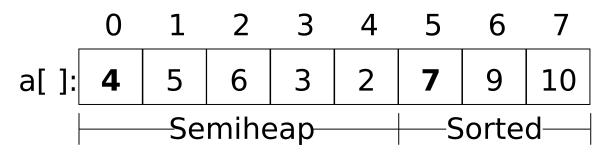


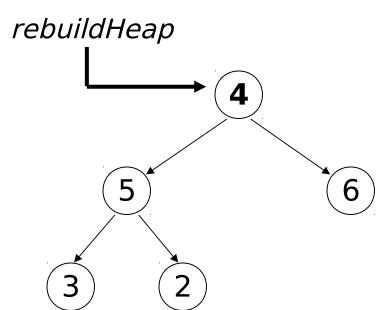
- a[0..5] now represents a semiheap.
- a[6..7] is the sorted region.
- Invoke rebuildHeap on the semiheap rooted at a[0].



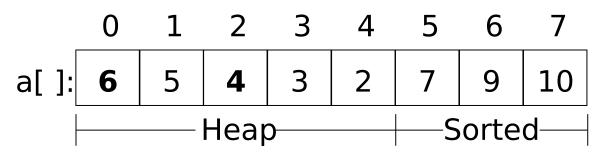


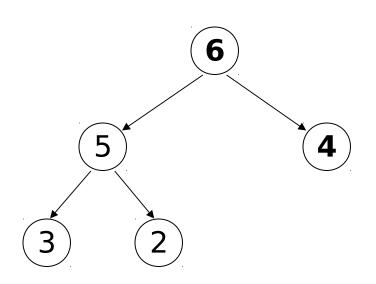
- Since a[1] is the root of a heap, a recursive call to rebuildHeap does nothing.
- a[0] is now the root of a heap in a[0..5].
- We move the largest item in the heap to the beginning of the sorted region by swapping a[0] with a[5].



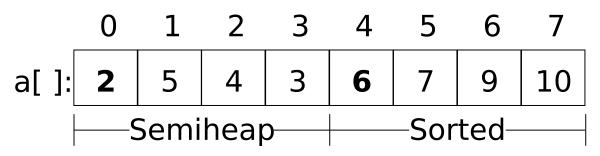


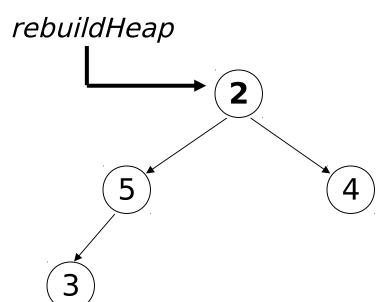
- a[0..4] now represents a semiheap.
- a[5..7] is the sorted region.
- Invoke rebuildHeap on the semiheap rooted at a[0].



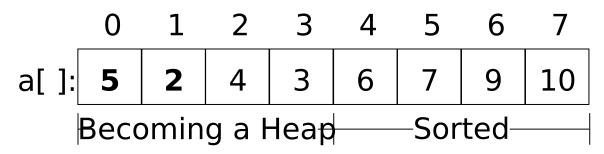


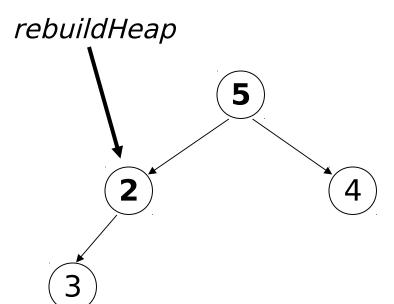
- a[0] is now the root of a heap in a[0..4].
- We move the largest item in the heap to the beginning of the sorted region by swapping a[0] with a[4].



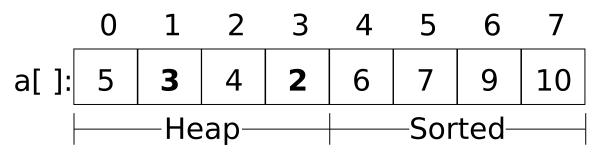


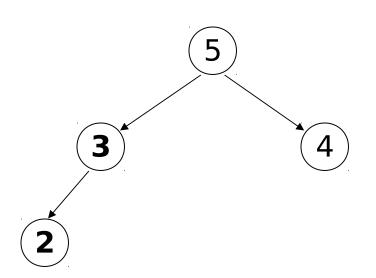
- a[0..3] now represents a semiheap.
- a[4..7] is the sorted region.
- Invoke rebuildHeap on the semiheap rooted at a[0].



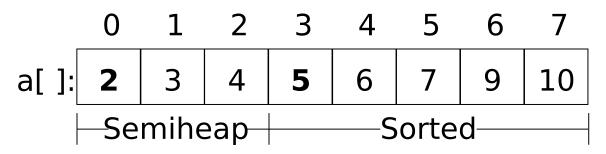


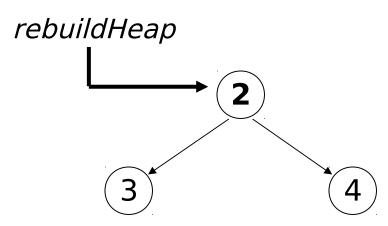
 rebuildHeap is invoked recursively on a[1] to complete the transformation of the semiheap rooted at a[0] into a heap.



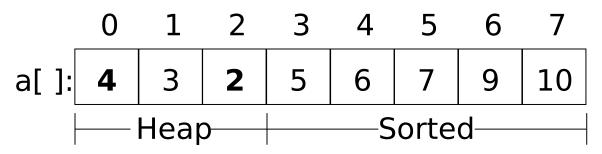


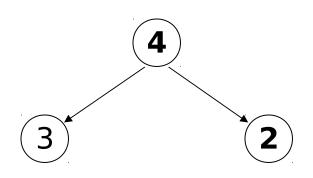
- a[0] is now the root of a heap in a[0..3].
- We move the largest item in the heap to the beginning of the sorted region by swapping a[0] with a[3].



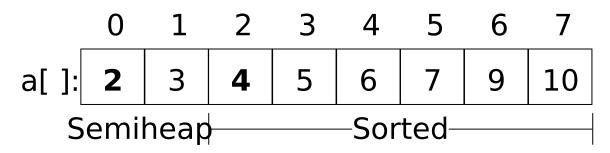


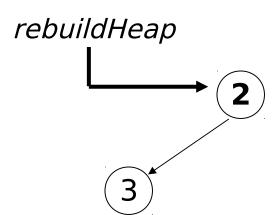
- a[0..2] now represents a semiheap.
- a[3..7] is the sorted region.
- Invoke rebuildHeap on the semiheap rooted at a[0].



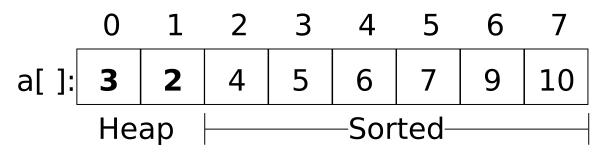


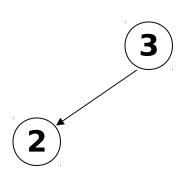
- a[0] is now the root of a heap in a[0..2].
- We move the largest item in the heap to the beginning of the sorted region by swapping a[0] with a[2].



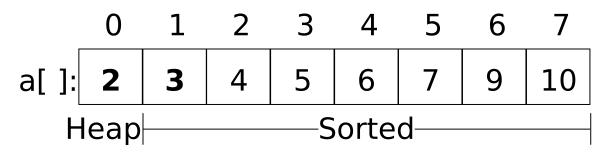


- a[0..1] now represents a semiheap.
- a[2..7] is the sorted region.
- Invoke rebuildHeap on the semiheap rooted at a[0].



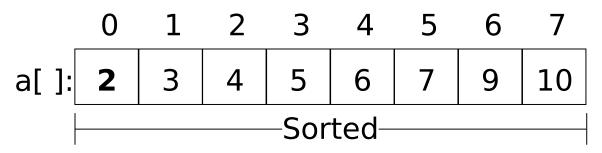


- a[0] is now the root of a heap in a[0..1].
- We move the largest item in the heap to the beginning of the sorted region by swapping a[0] with a[1].





- a[1..7] is the sorted region.
- Since a[0] is a heap, a recursive call to rebuildHeap does nothing.
- We move the only item in the heap to the beginning of the sorted region.



 Since the sorted region contains all the items in the array, we are done.

Thank You