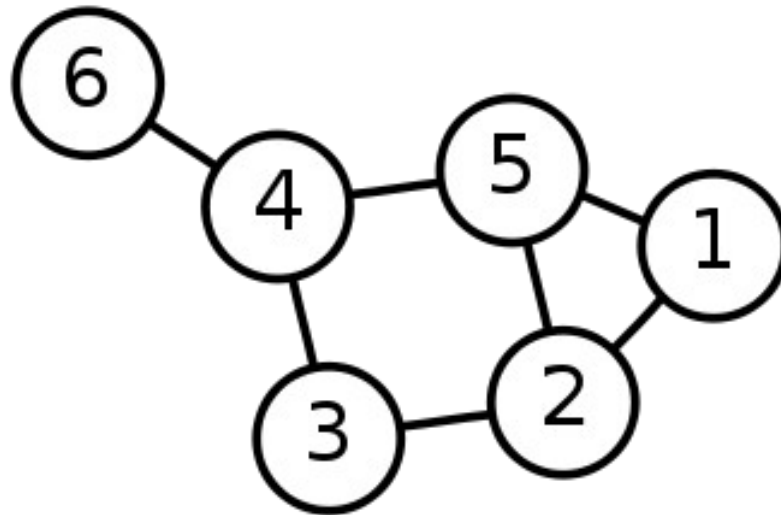


Dijkstra's, Kruskals and Floyd-Warshall Algorithms

Single-Source Shortest Path Problem

Single-Source Shortest Path Problem - The problem of finding shortest paths from a source vertex v to all other vertices in the graph.



Dijkstra's algorithm

Dijkstra's algorithm - is a solution to the single-source shortest path problem in graph theory.

Works on both directed and undirected graphs. However, all edges must have nonnegative weights.

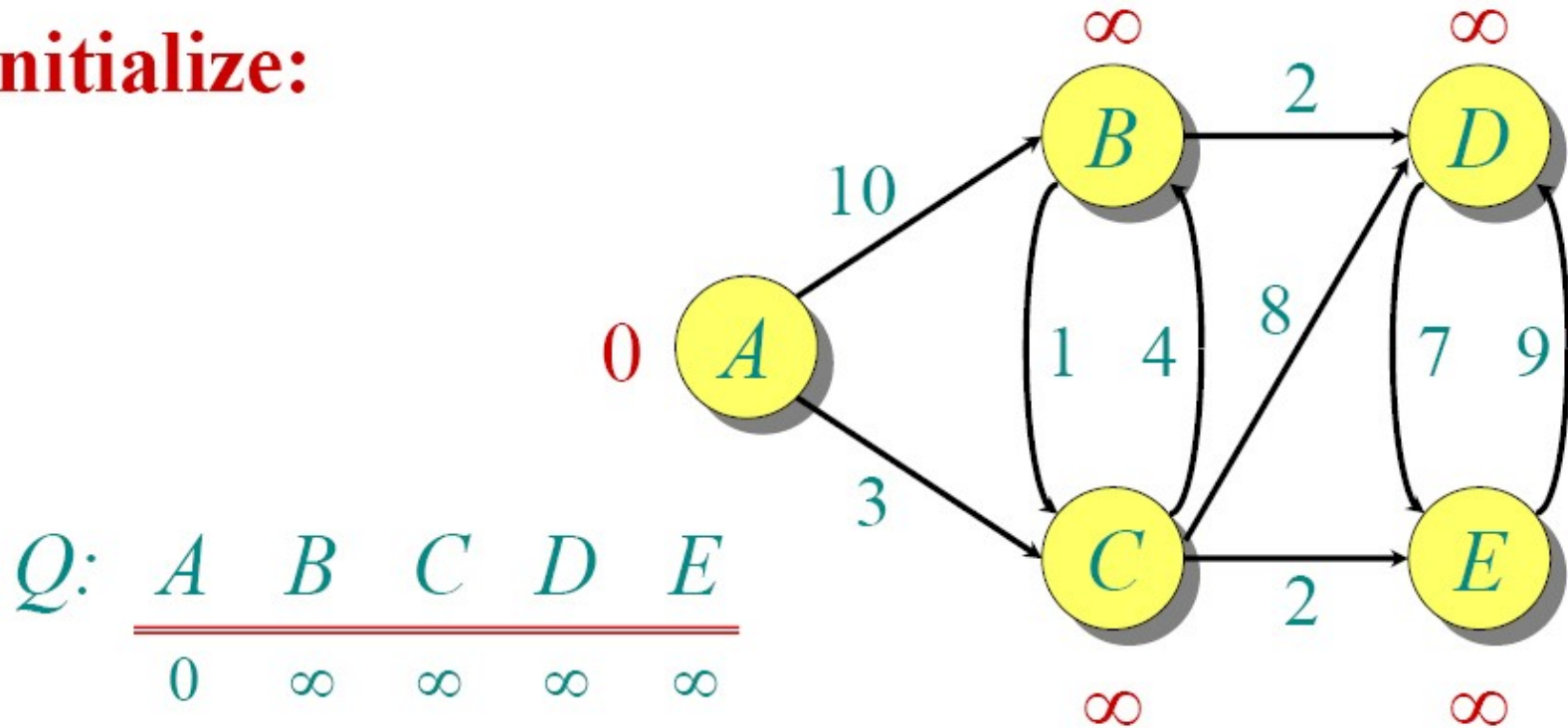
Approach: Greedy

Dijkstra's algorithm - Pseudocode

```
dist[s] ← 0                (distance to source vertex is zero)
for all v ∈ V - {s}
    do dist[v] ← ∞          (set all other distances to infinity)
S ← ∅                       (S, the set of visited vertices is initially empty)
Q ← V                       (Q, the queue initially contains all vertices)
while Q ≠ ∅                 (while the queue is not empty)
do u ← mindistance(Q, dist) (select the element of Q with the
min. distance)
    S ← S ∪ {u}             (add u to list of visited vertices)
    for all v ∈ neighbors[u]
        do if dist[v] > dist[u] + w(u, v) (if new shortest path
found)
            then d[v] ← d[u] + w(u, v) (set new value of shortest
path)
            (if desired, add traceback code)
return dist
```

Dijkstra Animated Example

Initialize:

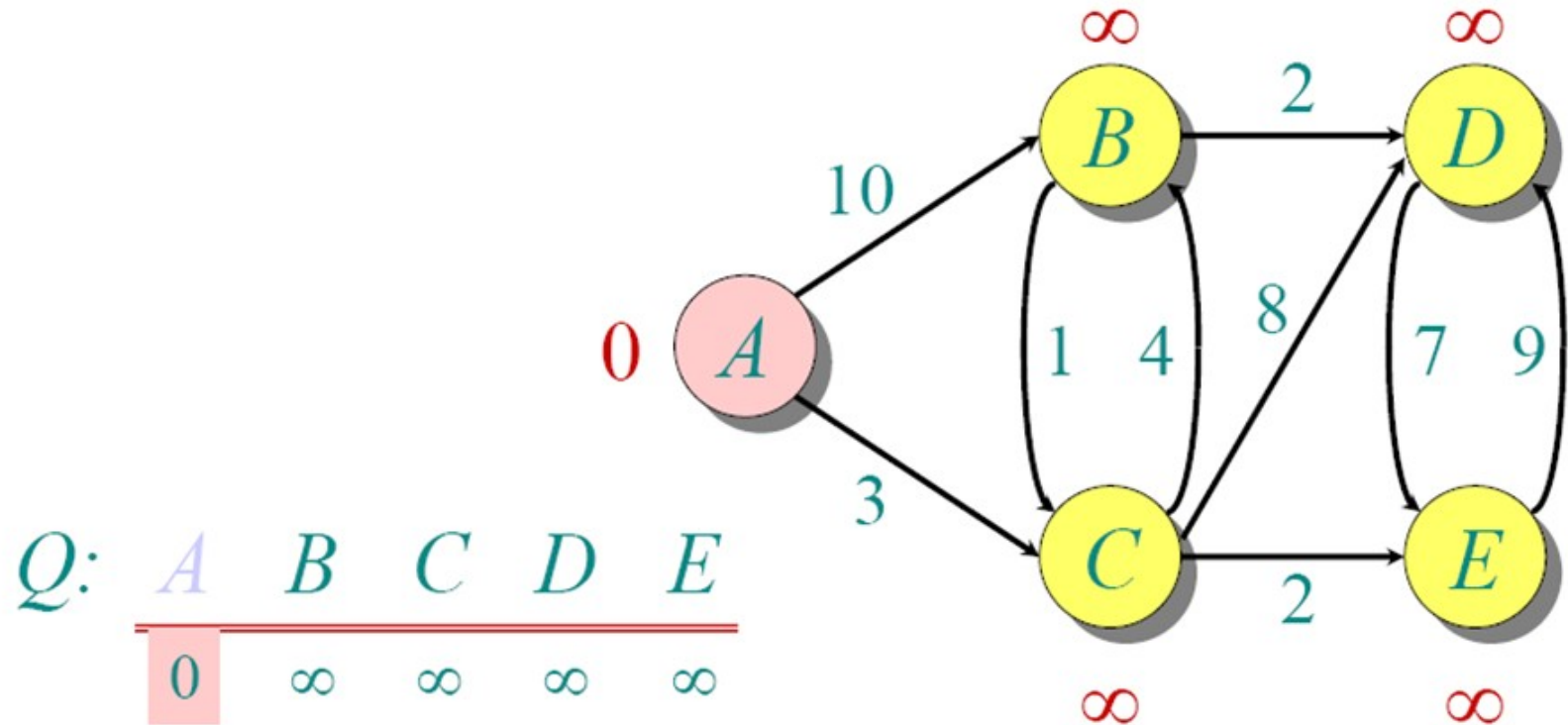


$Q:$

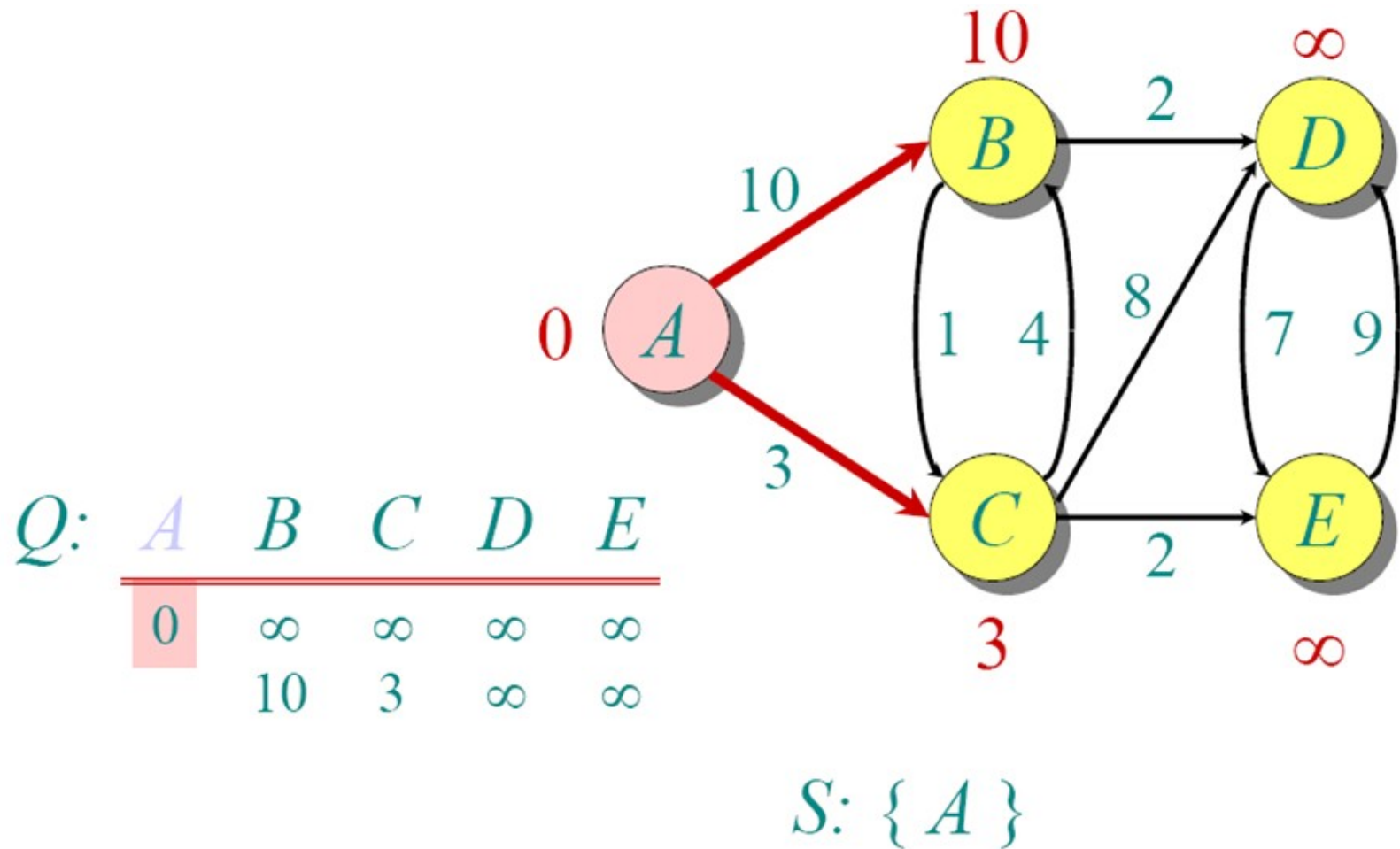
A	B	C	D	E
0	∞	∞	∞	∞

$S: \{\}$

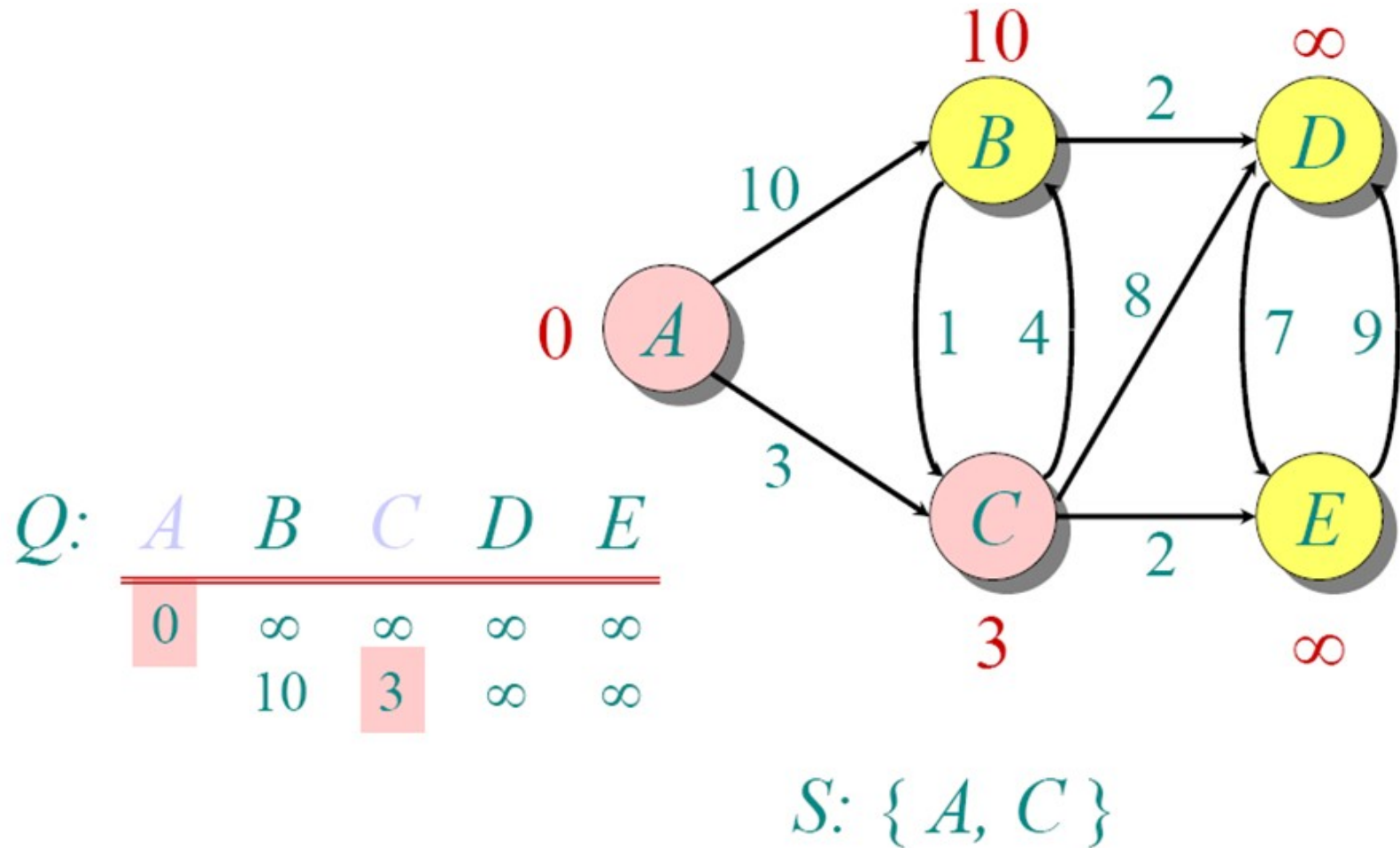
Dijkstra Animated Example



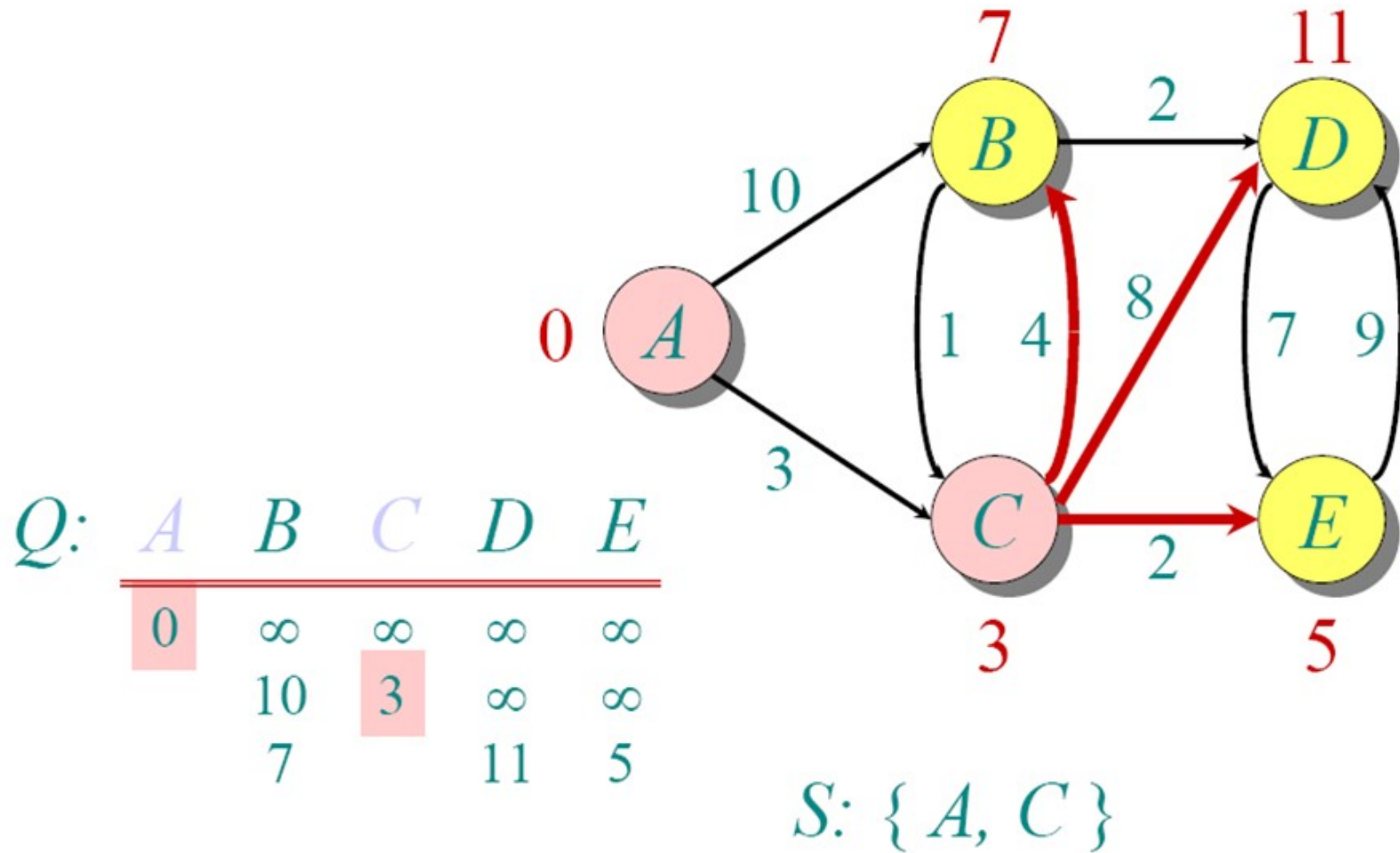
Dijkstra Animated Example



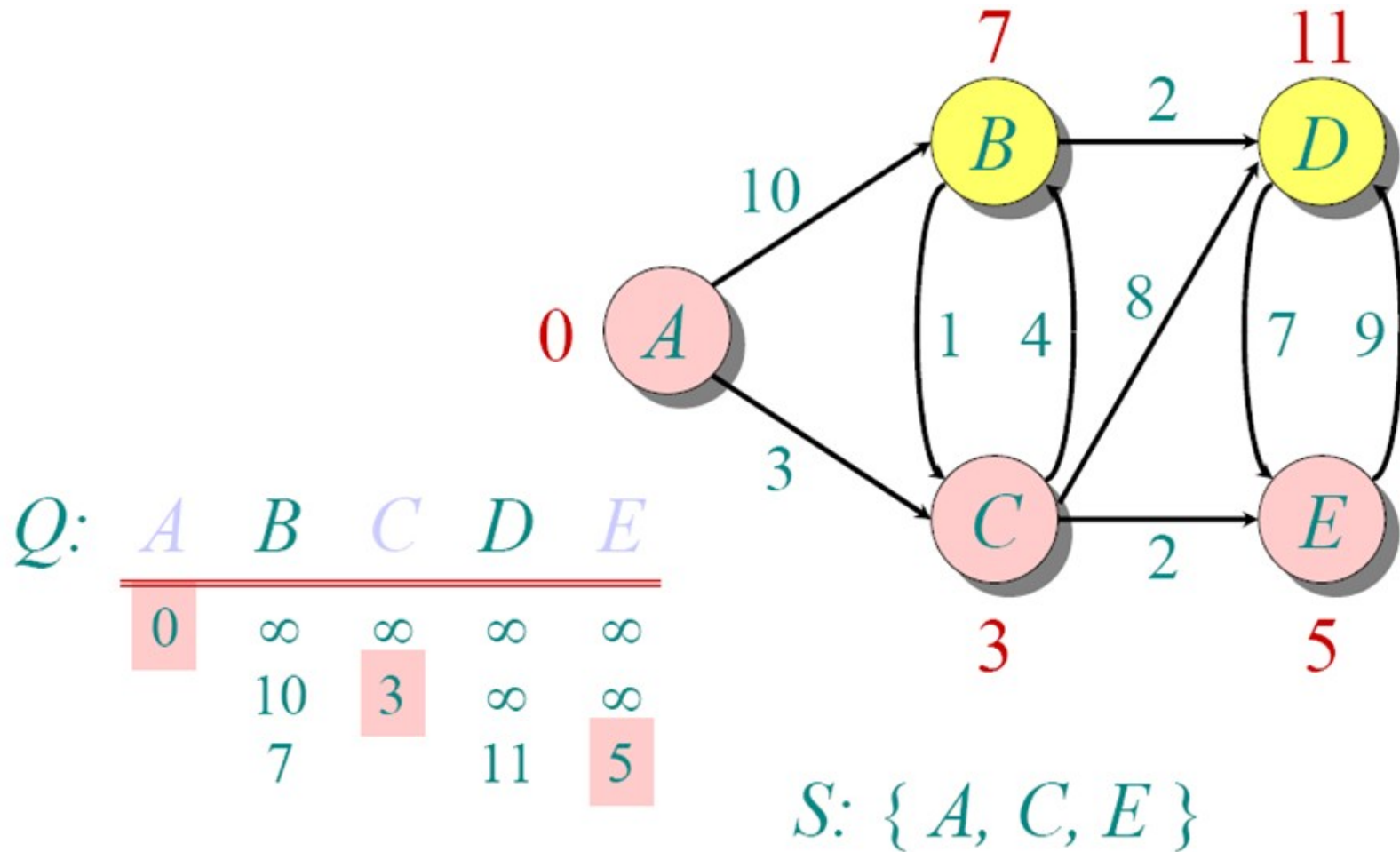
Dijkstra Animated Example



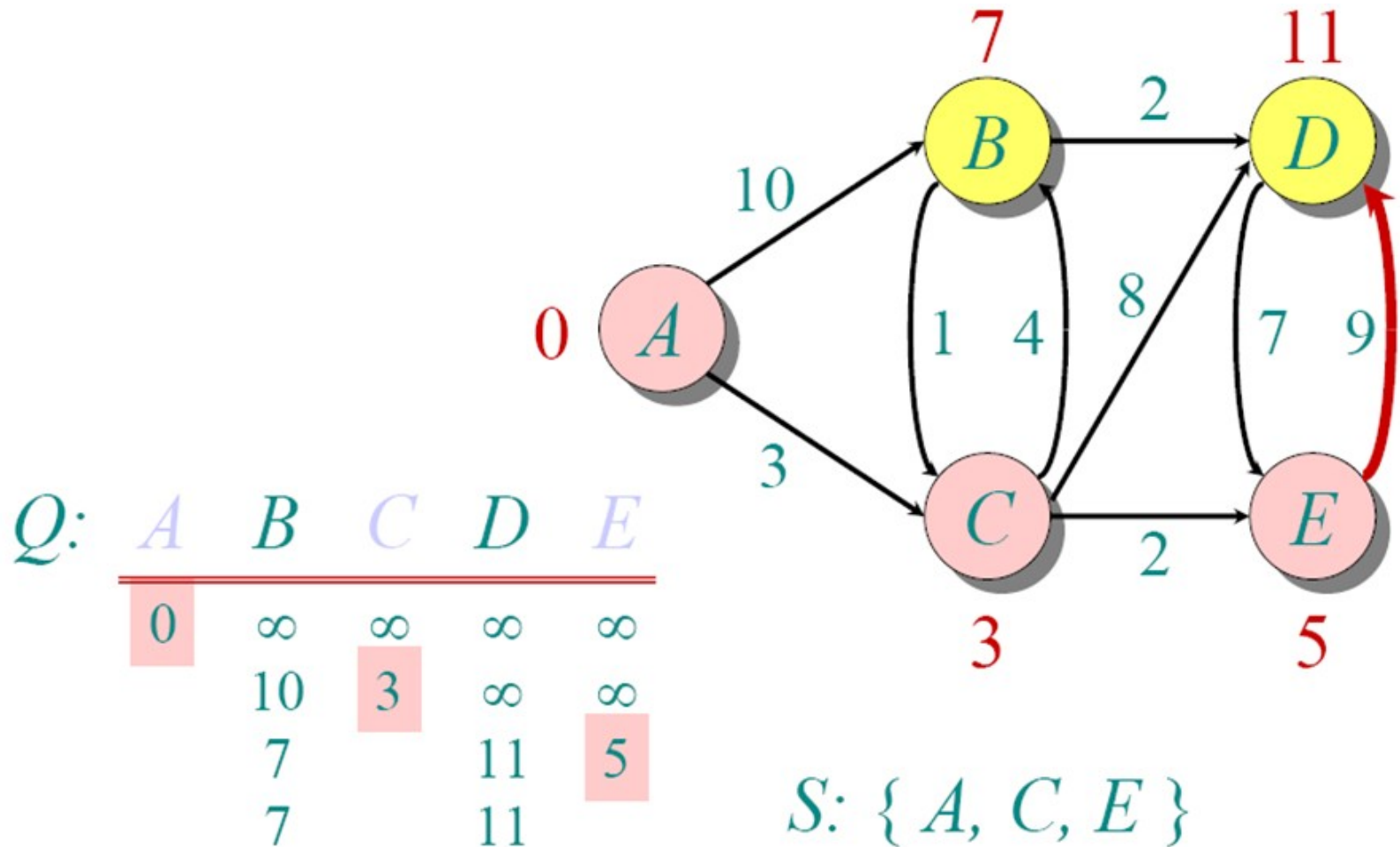
Dijkstra Animated Example



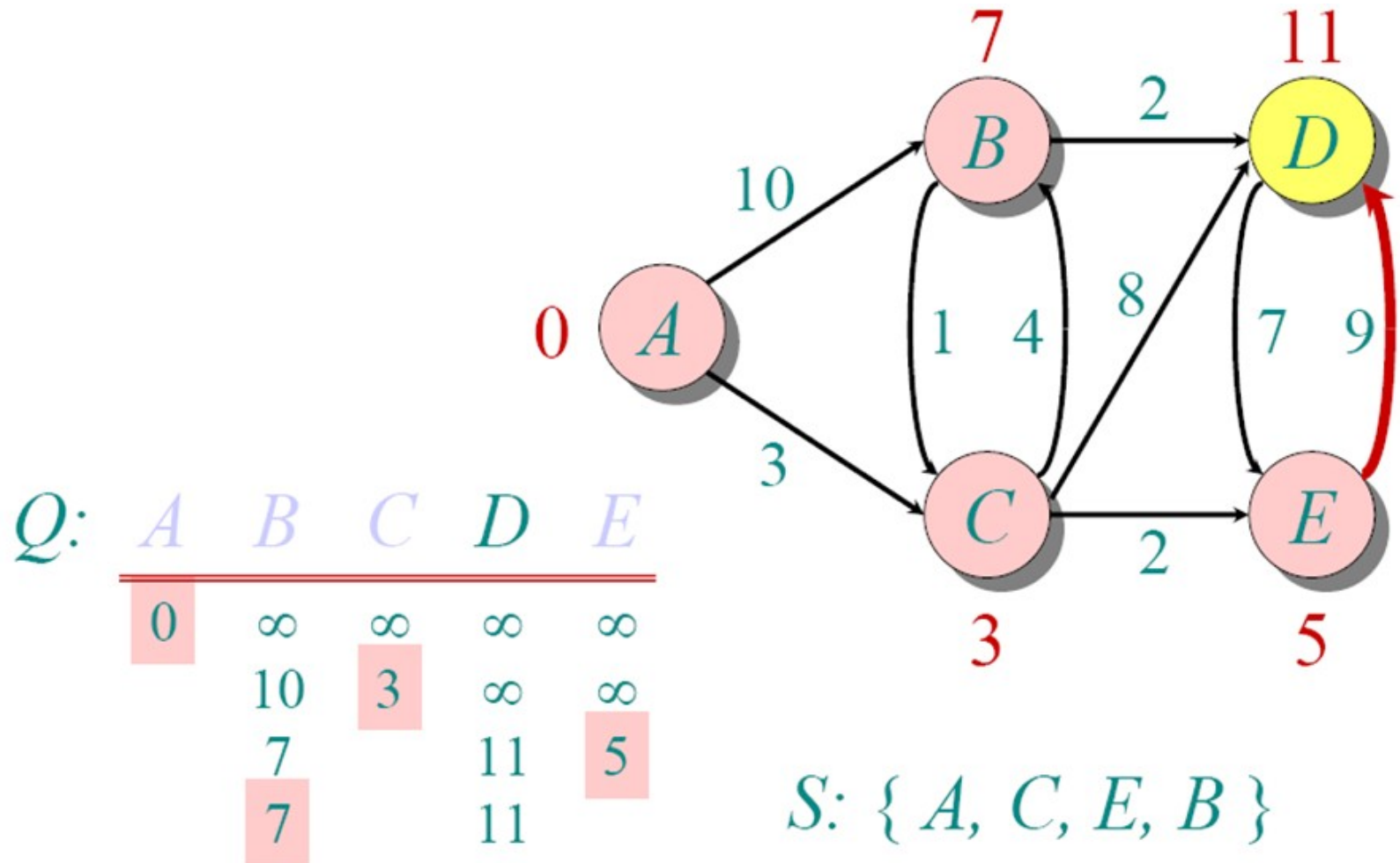
Dijkstra Animated Example



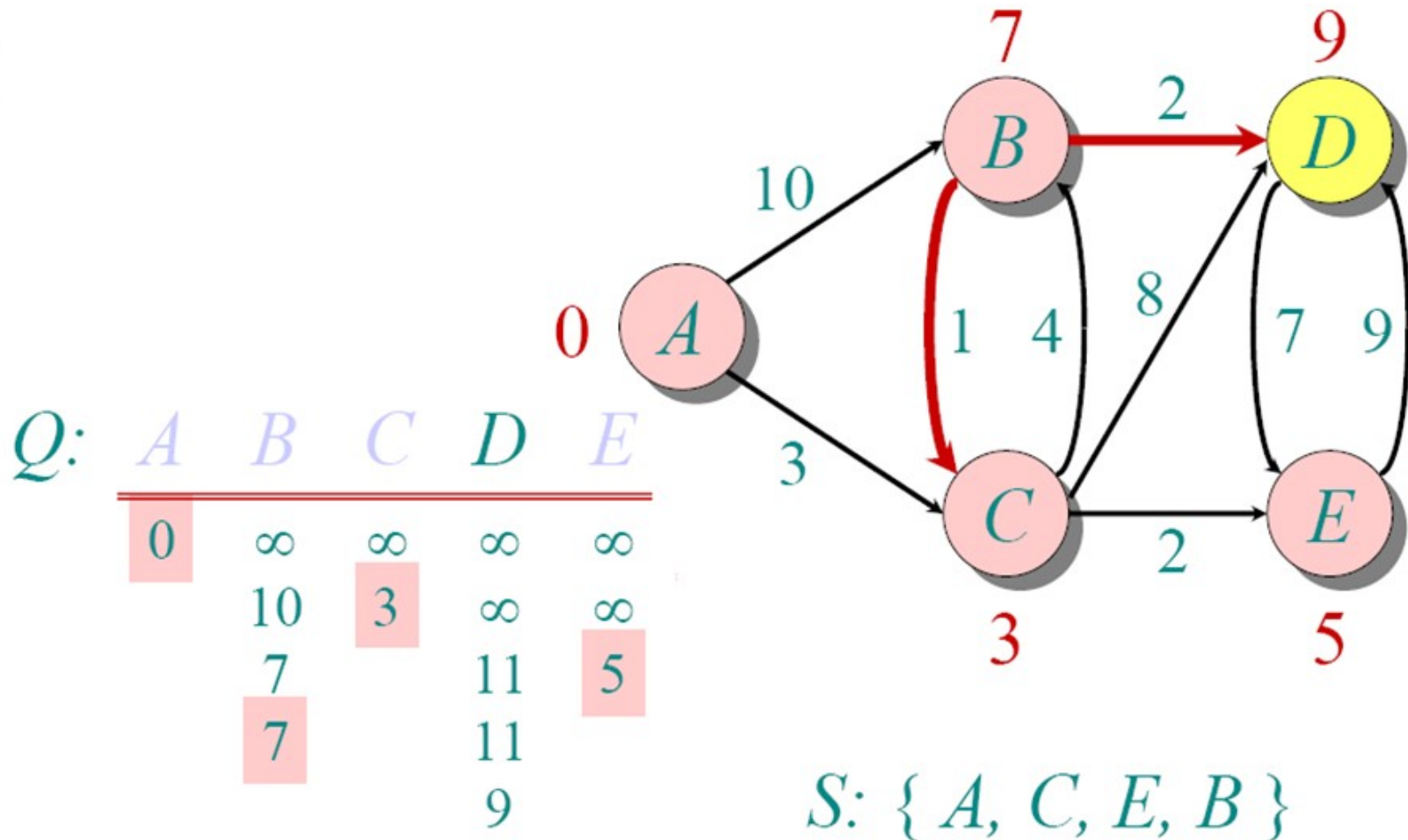
Dijkstra Animated Example



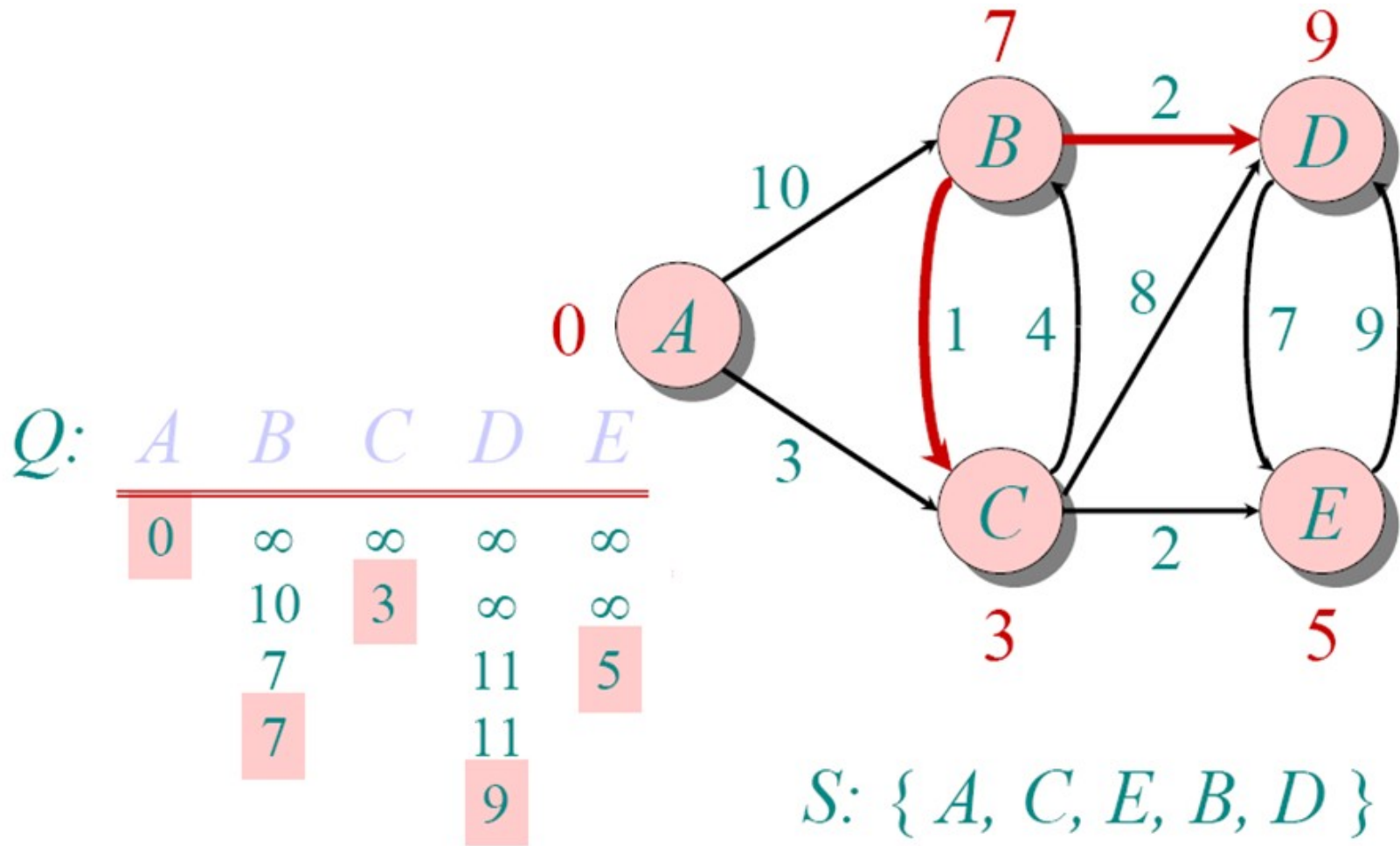
Dijkstra Animated Example



Dijkstra Animated Example



Dijkstra Animated Example

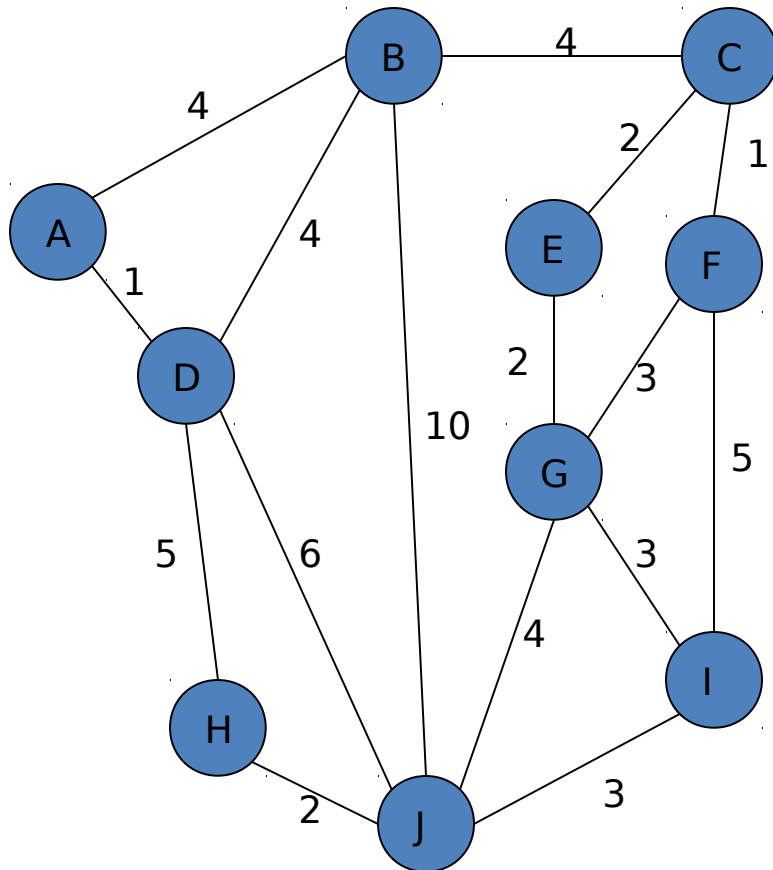


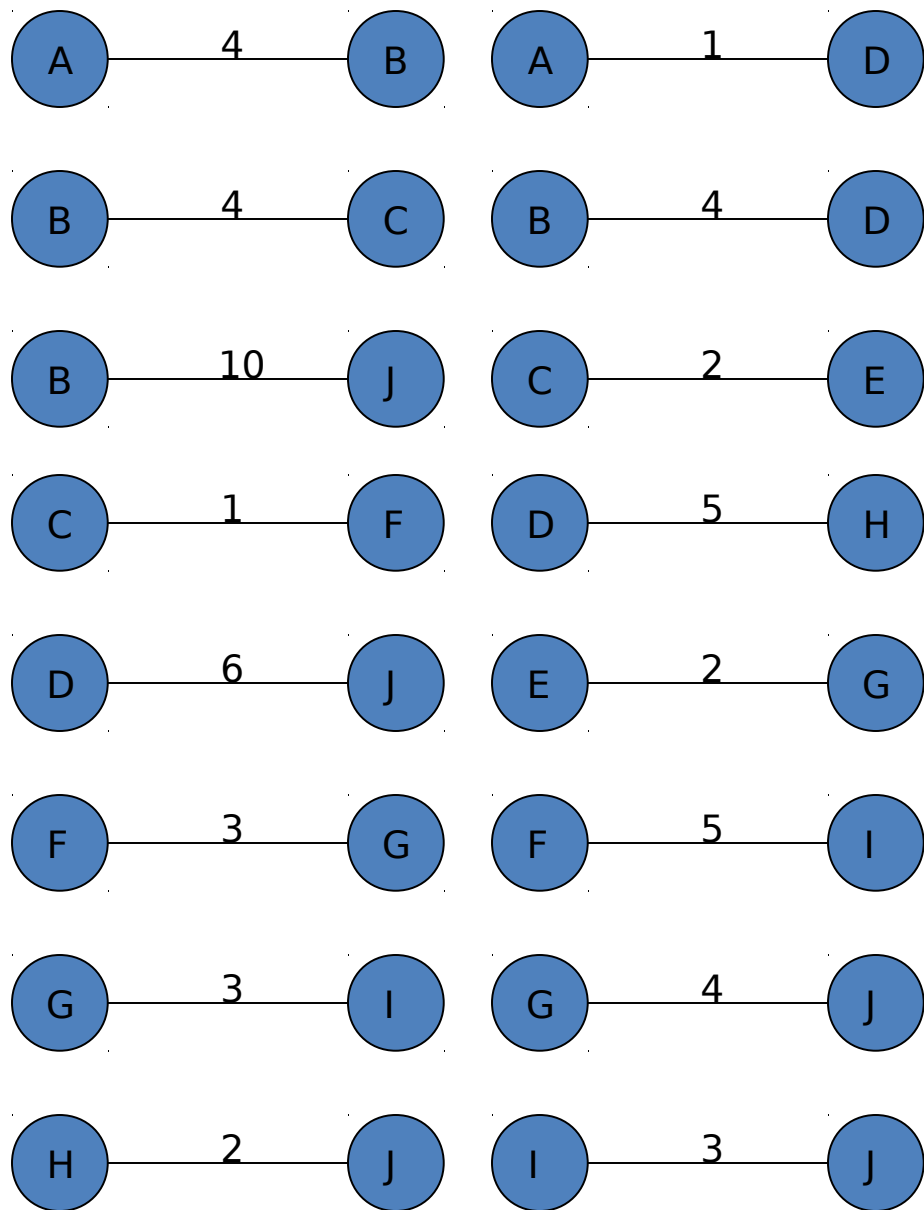
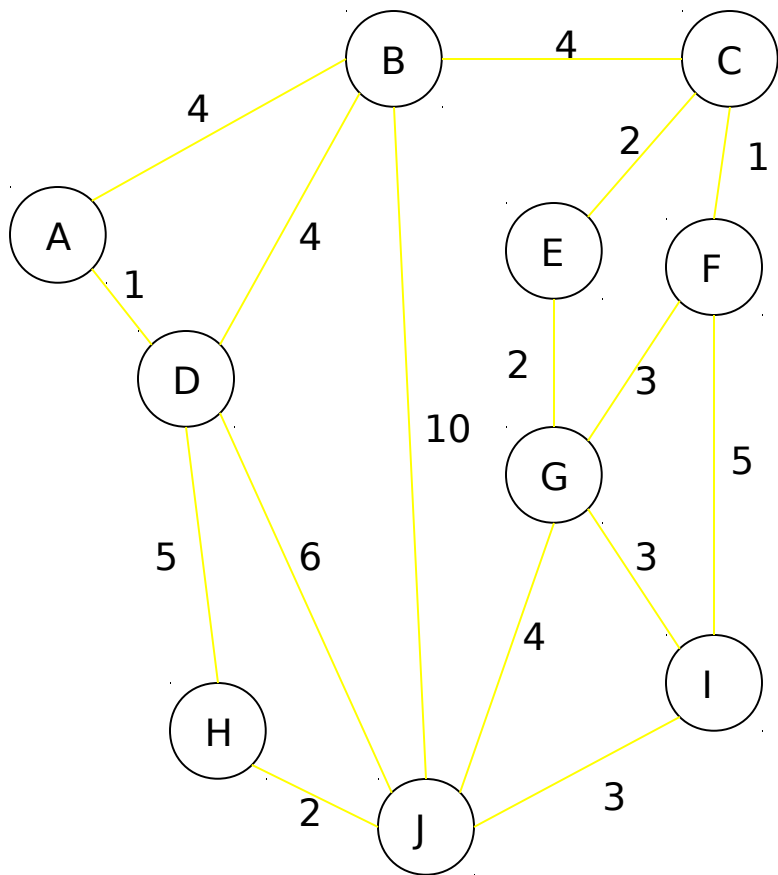
Kruskal' Algorithm

Minimum Spanning Tree

Disjoint Sets

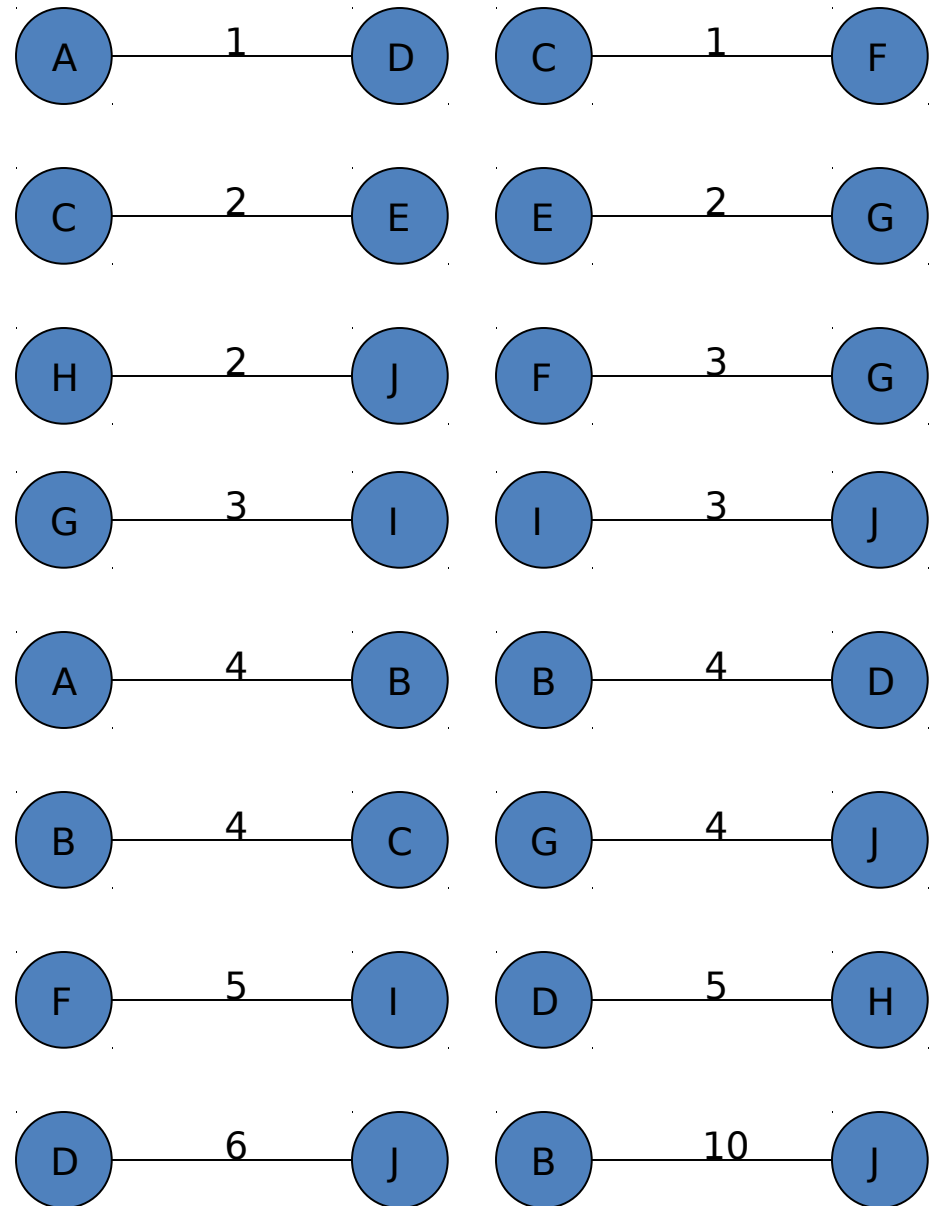
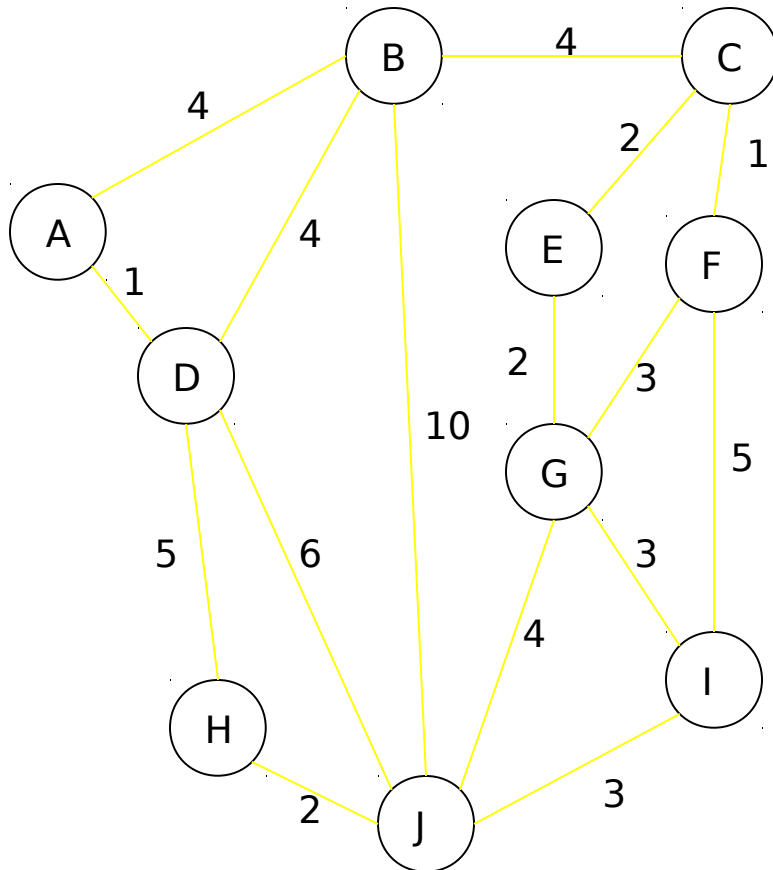
Complete Graph



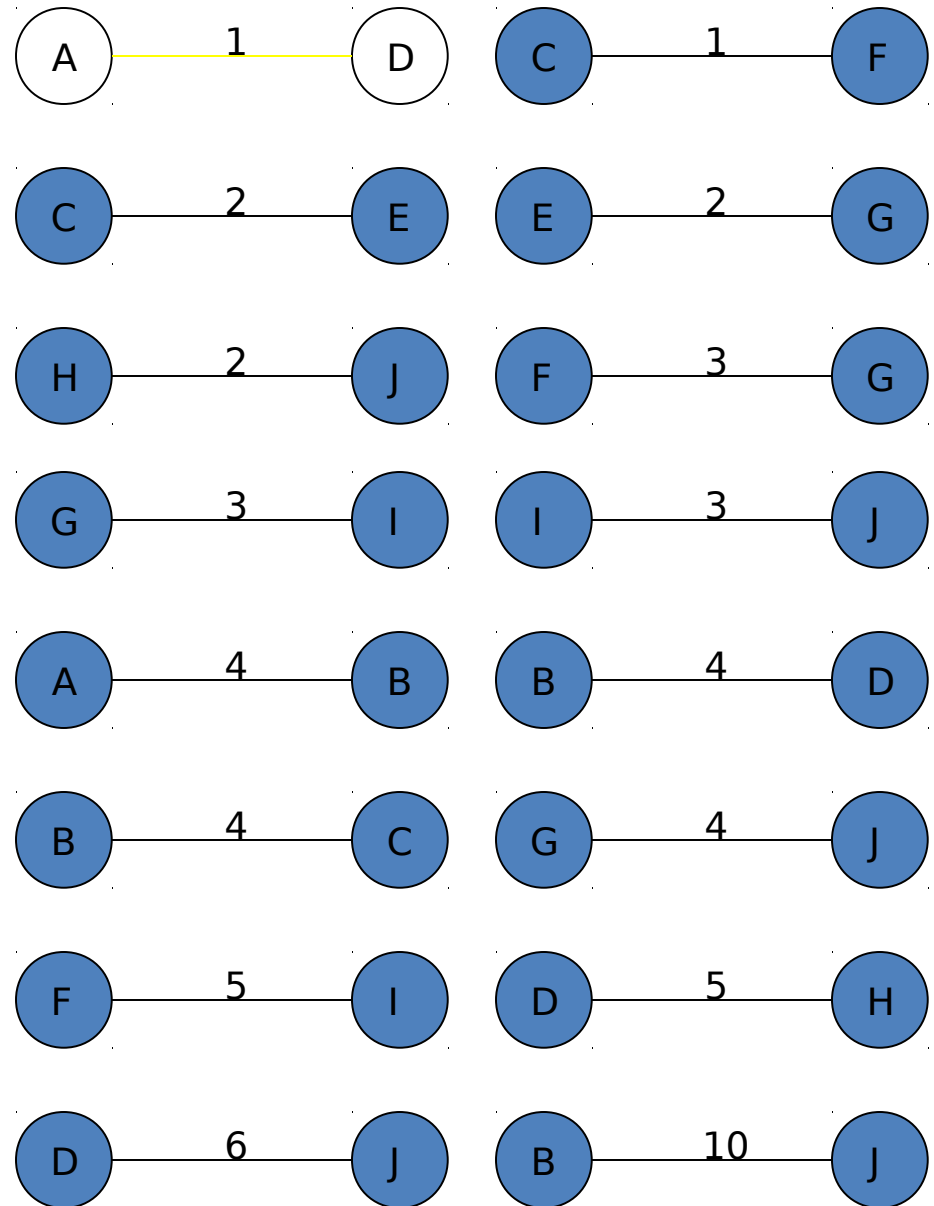
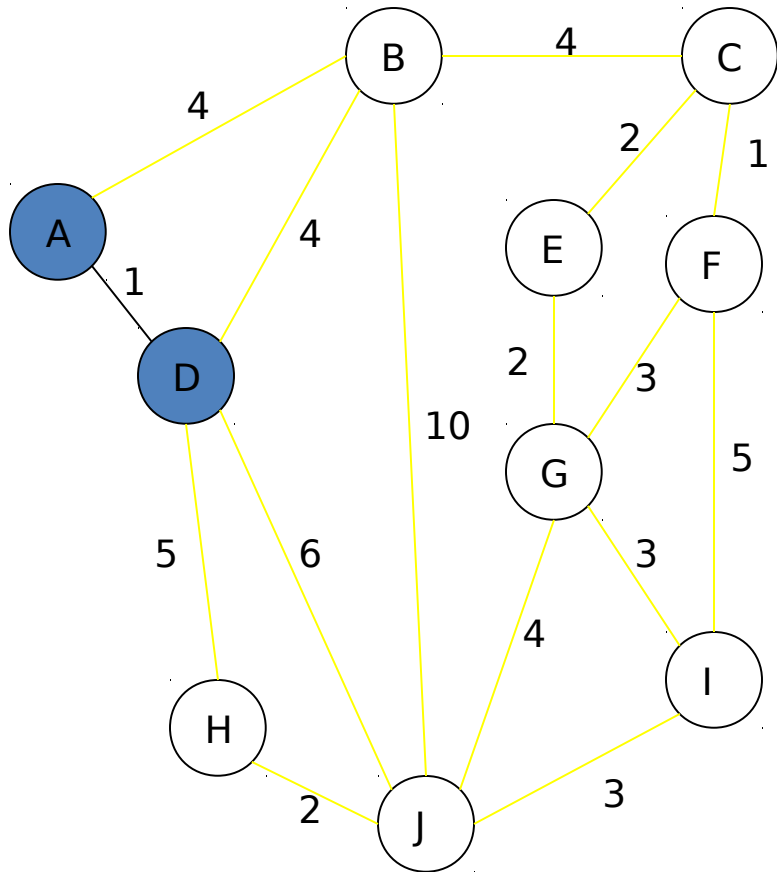


Sort Edges

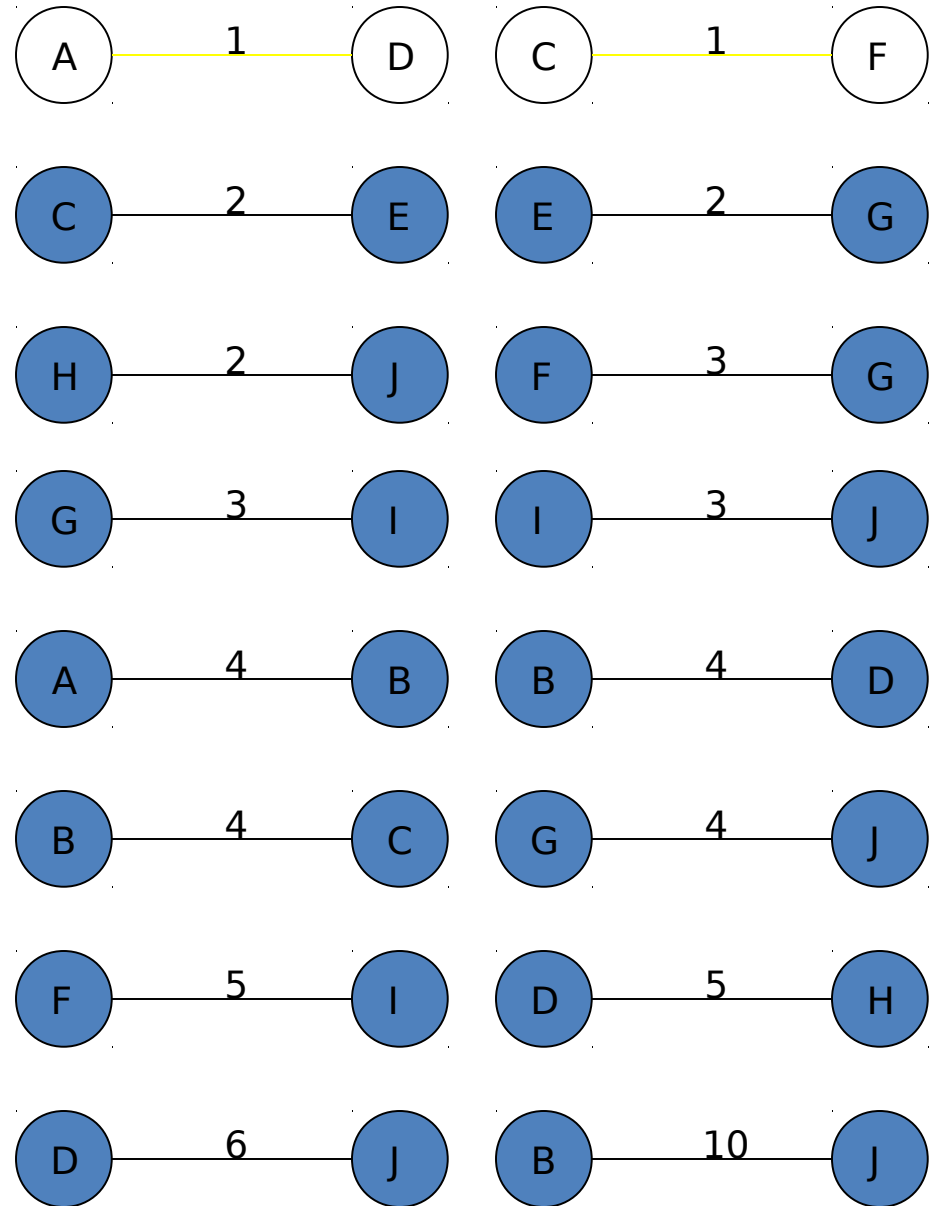
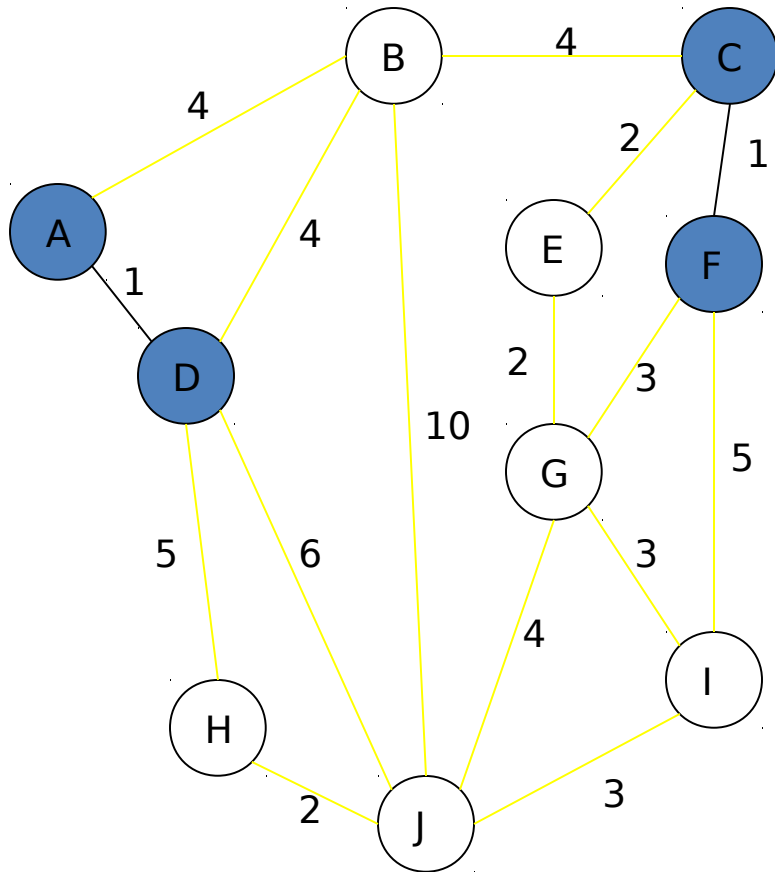
(in reality they are placed in a priority queue - not sorted - but sorting them makes the algorithm easier to visualize)



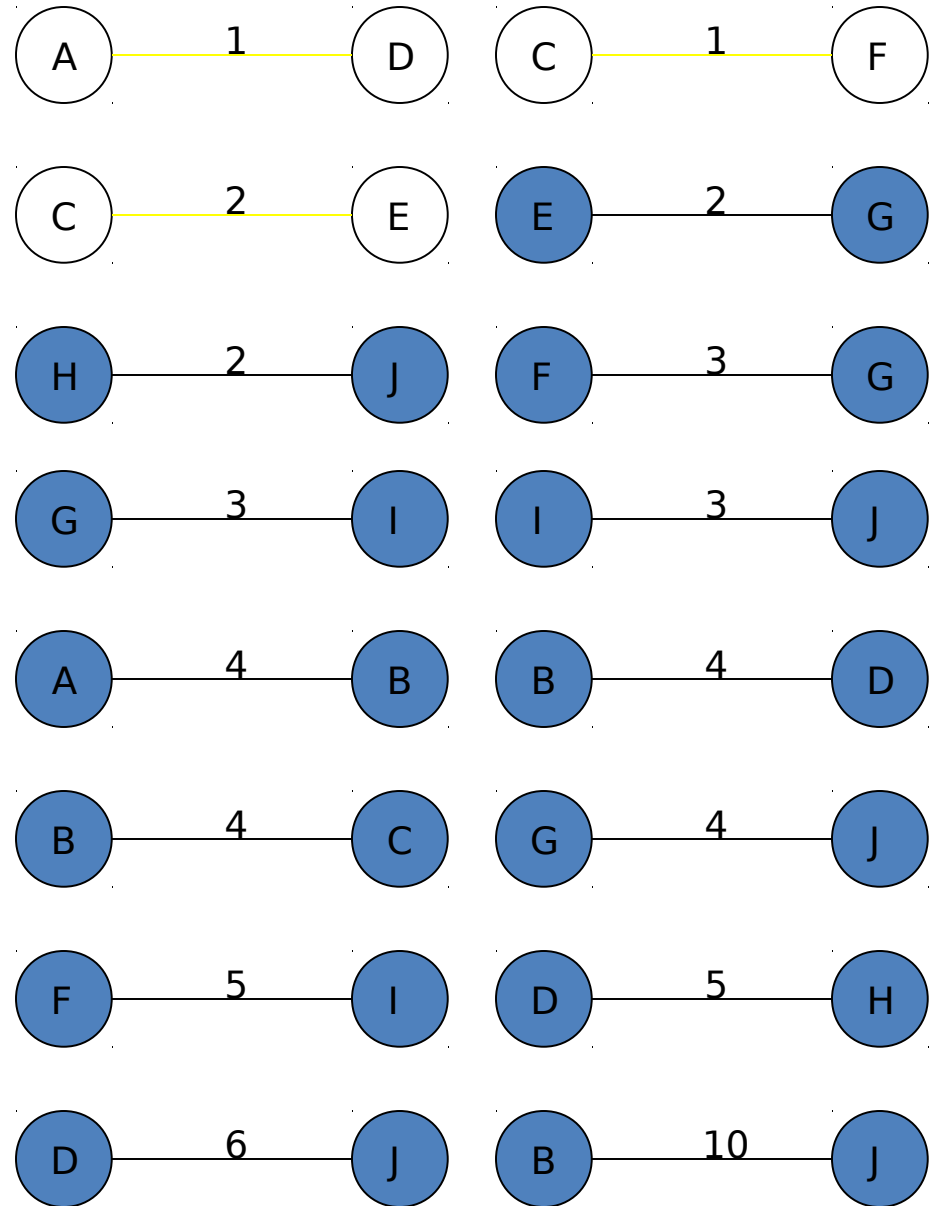
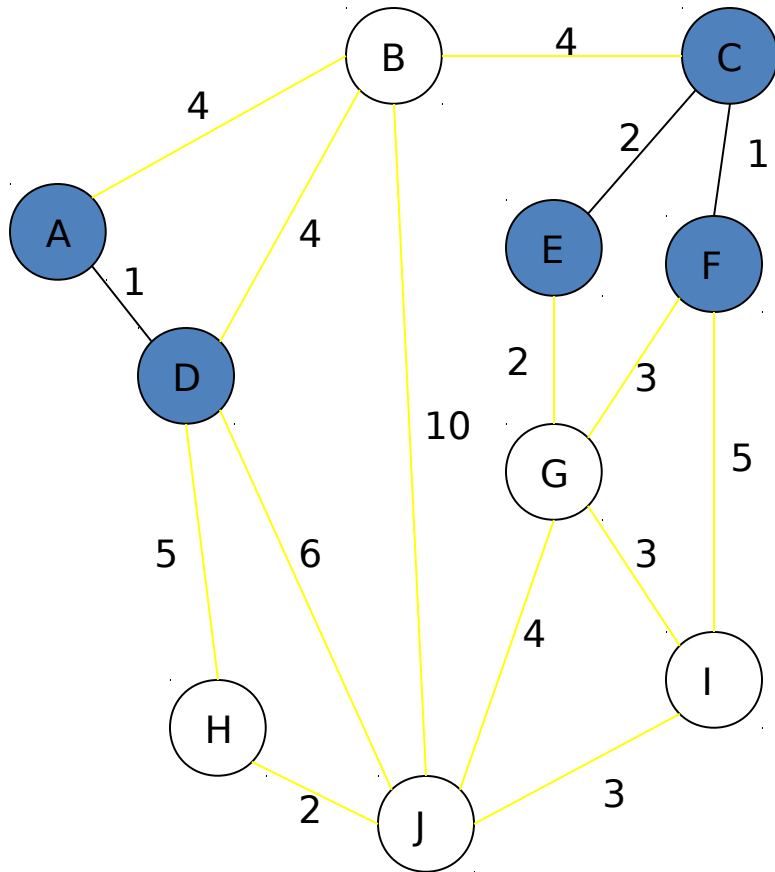
Add Edge



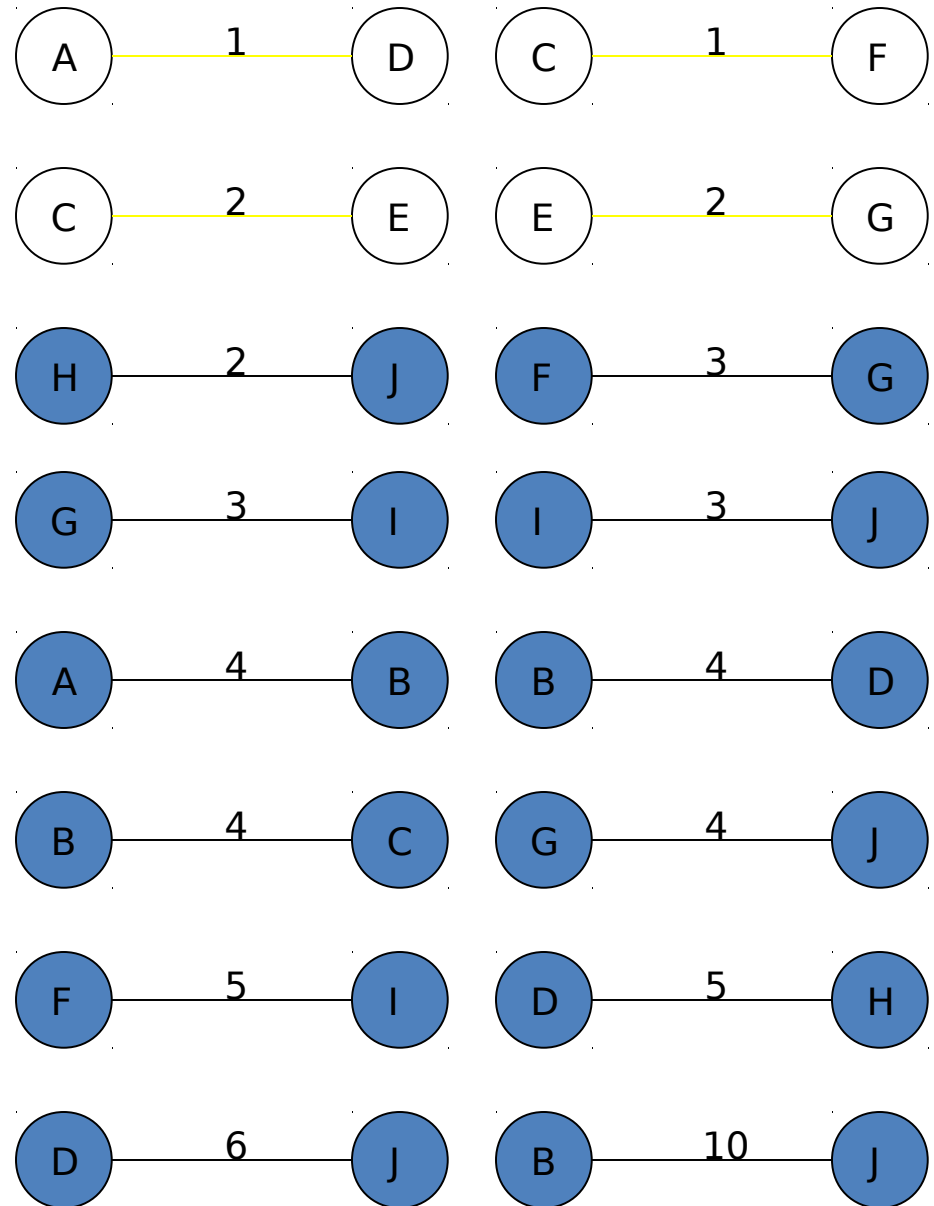
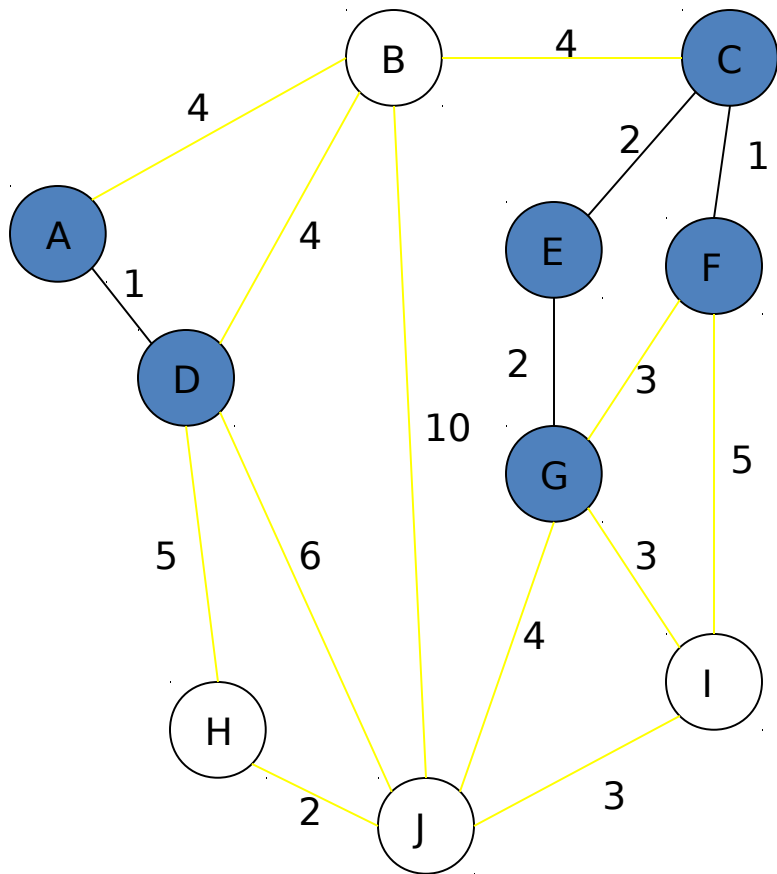
Add Edge



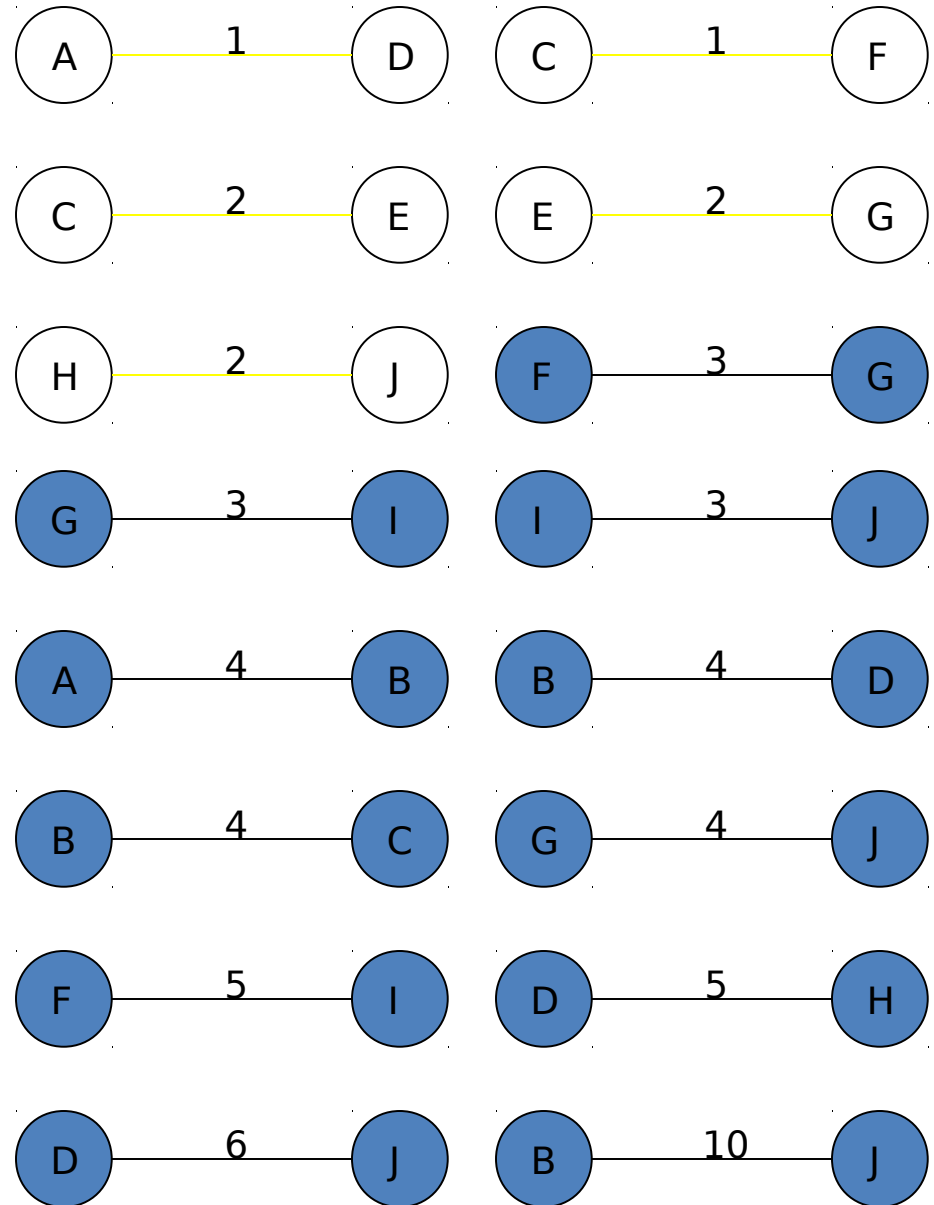
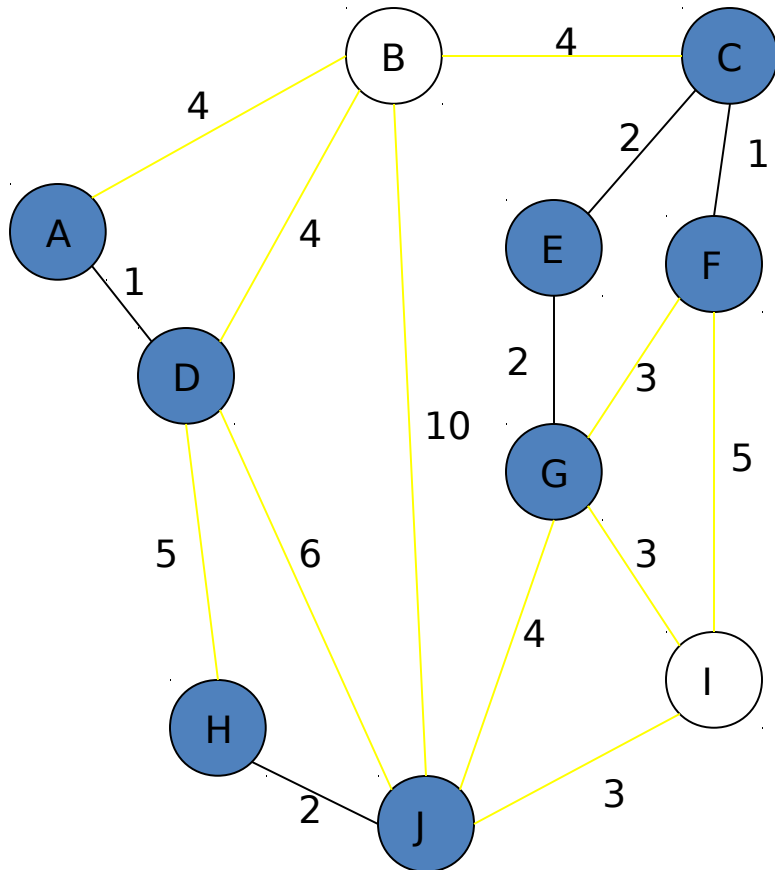
Add Edge



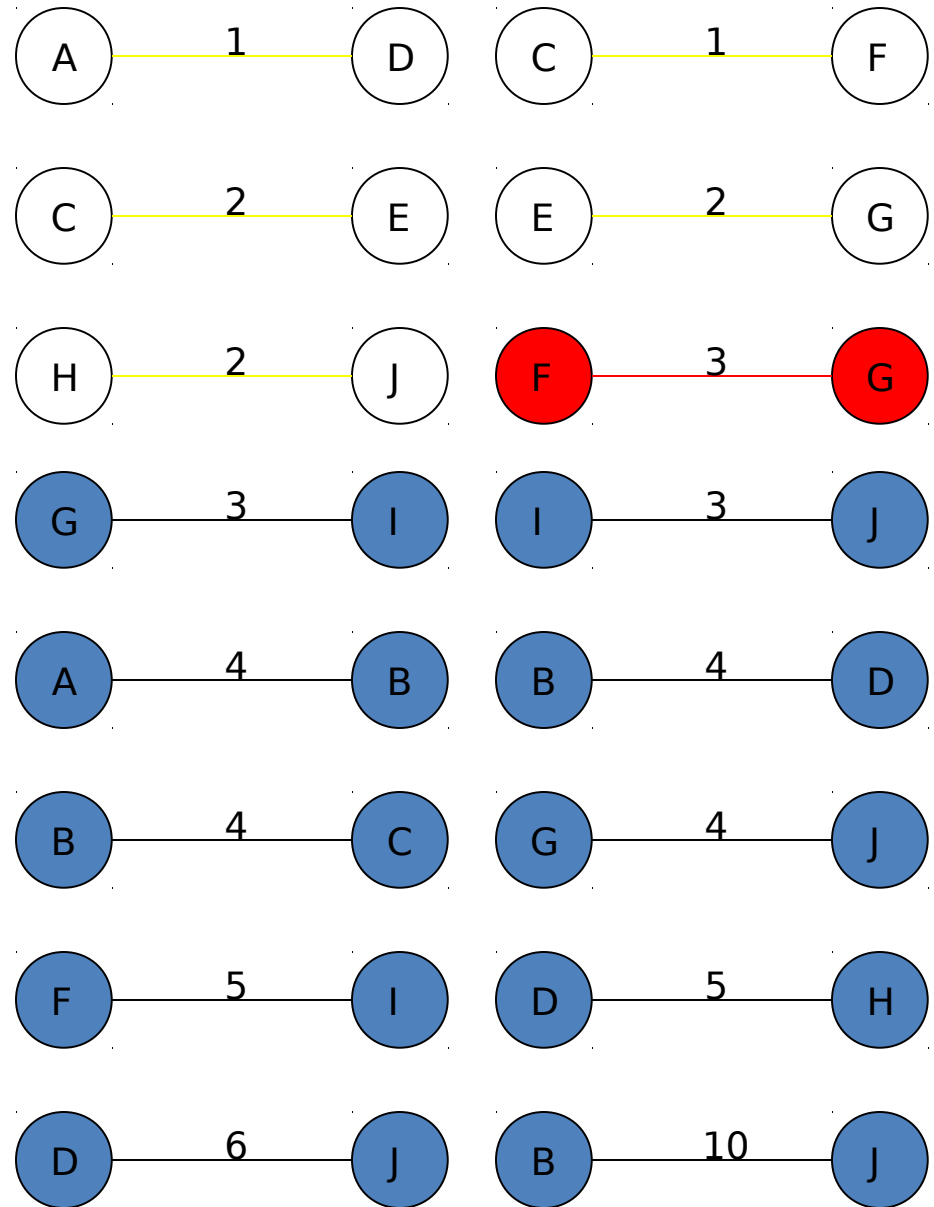
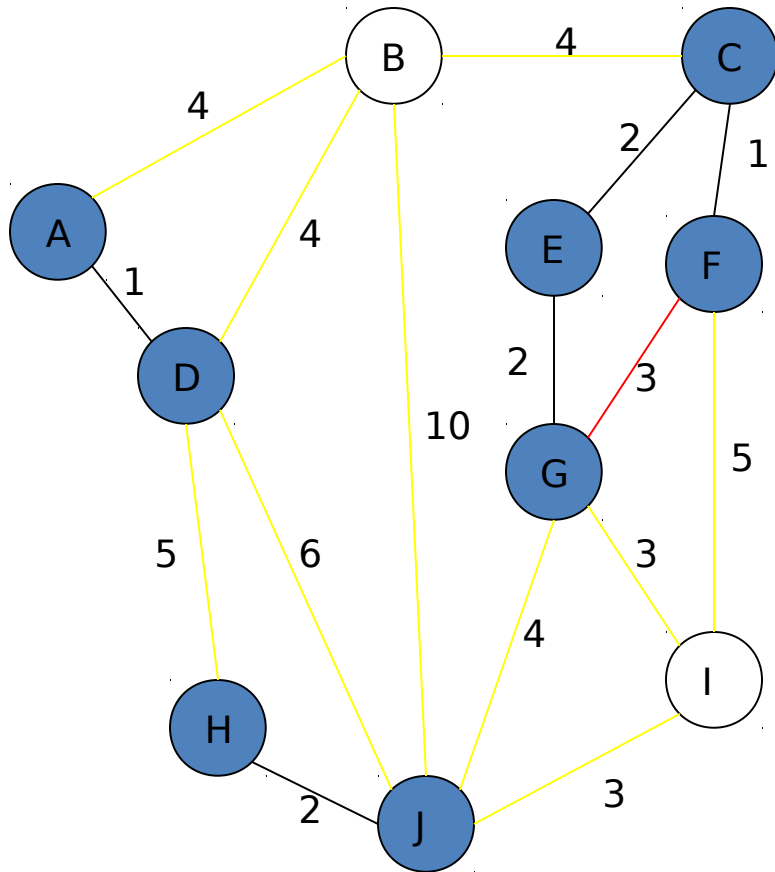
Add Edge



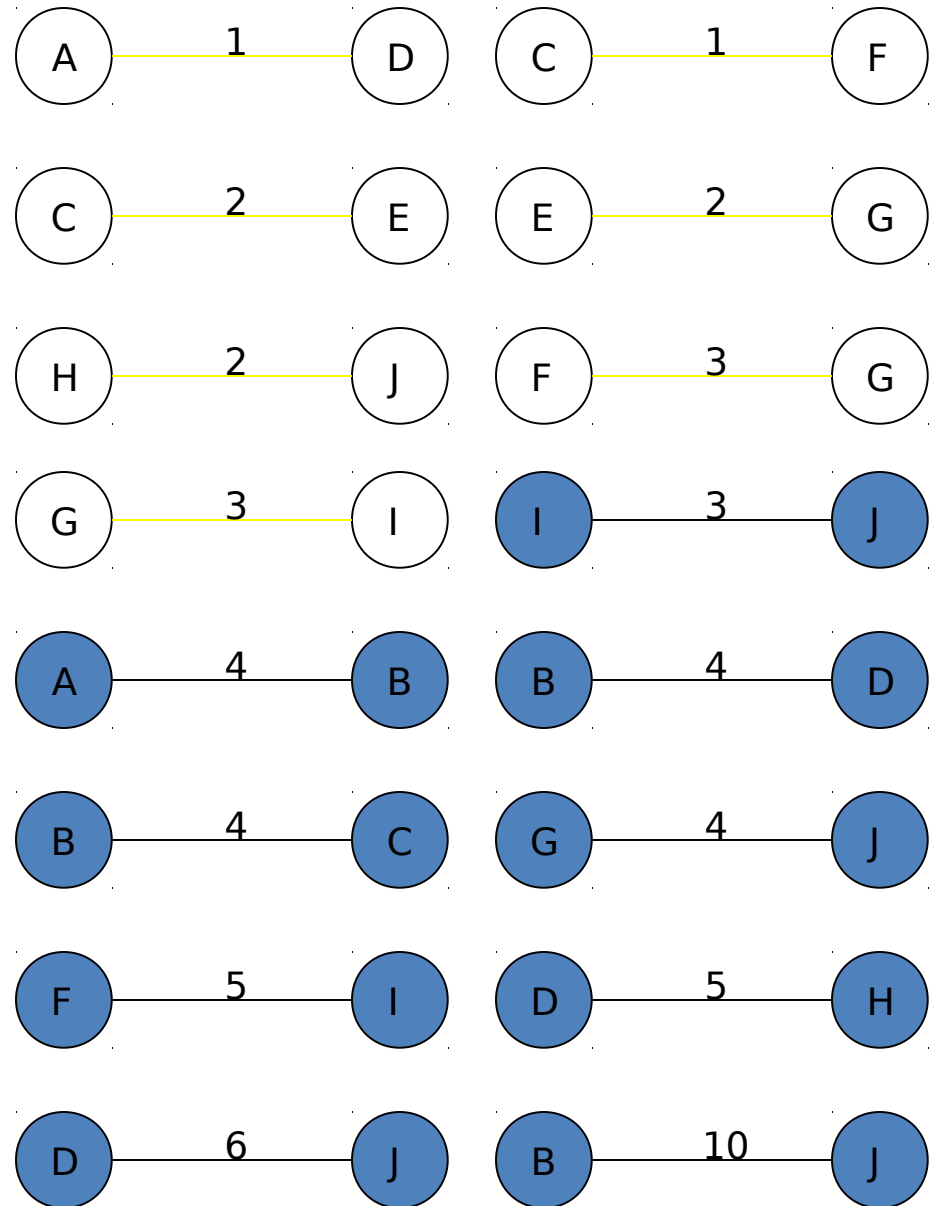
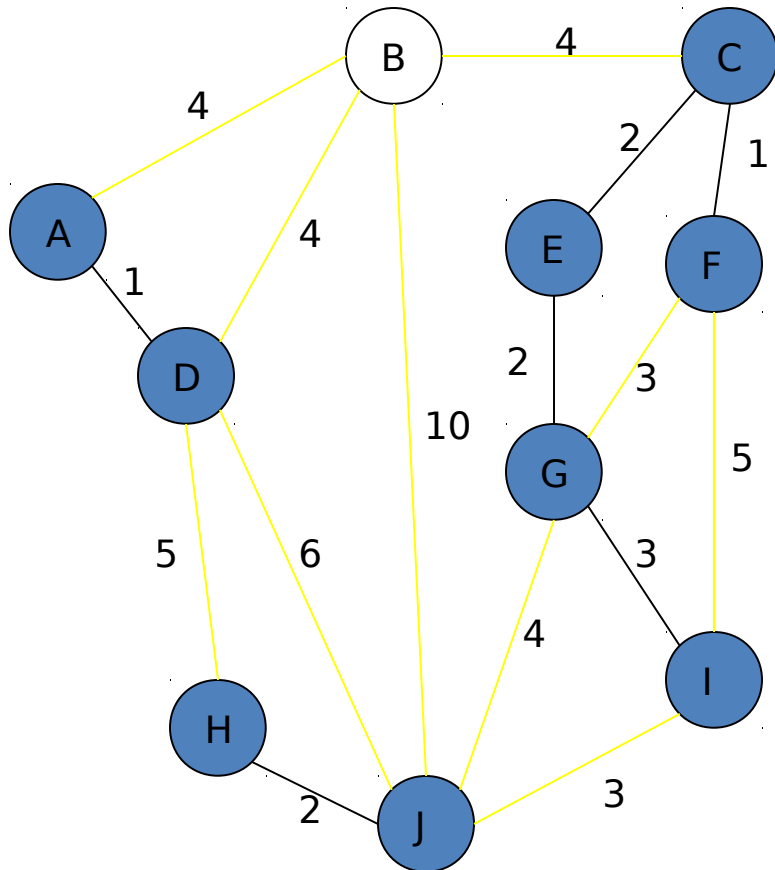
Add Edge



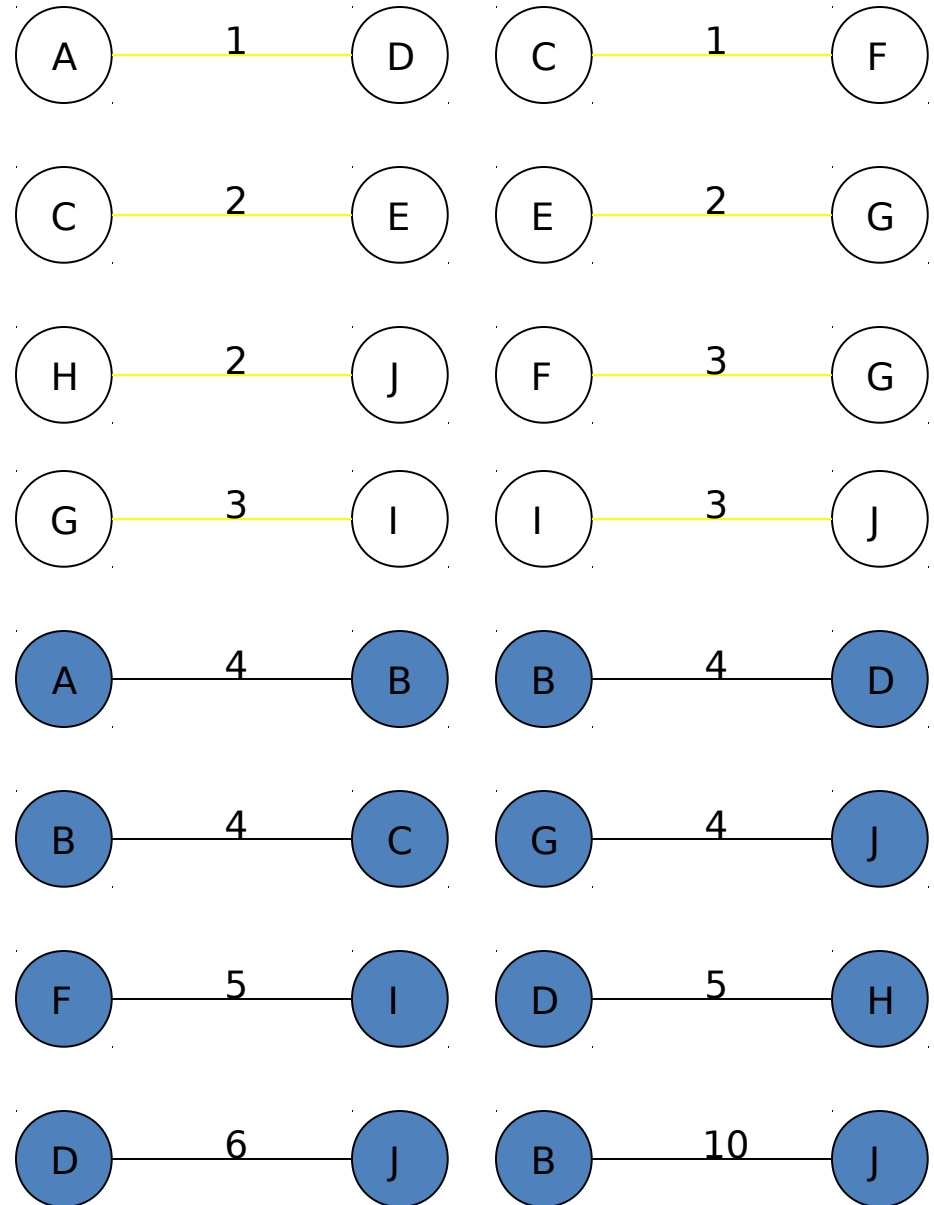
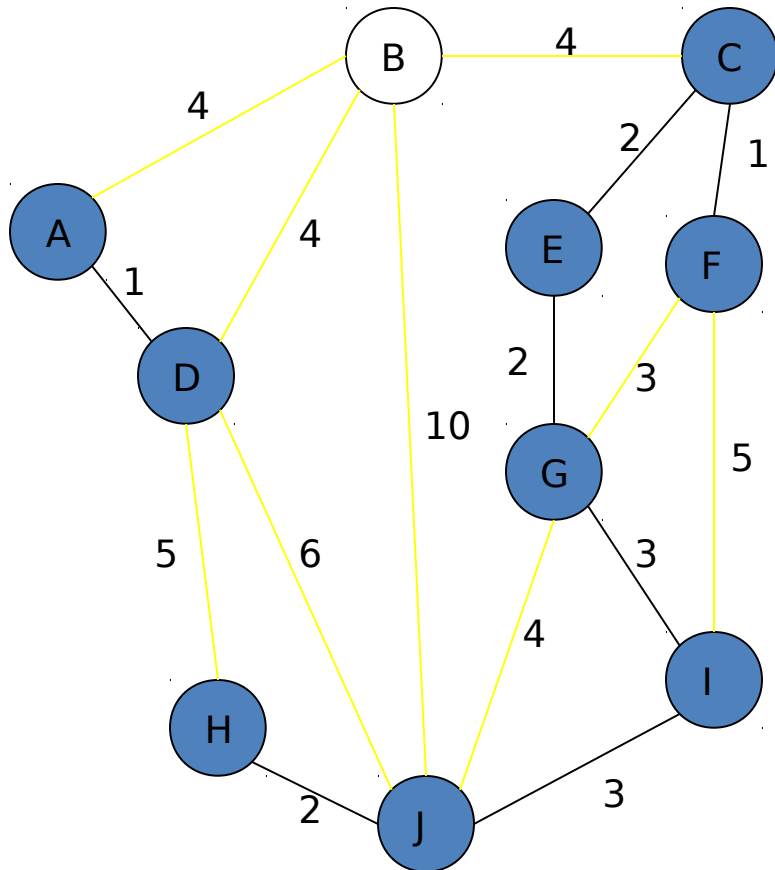
Cycle
Don't Add Edge



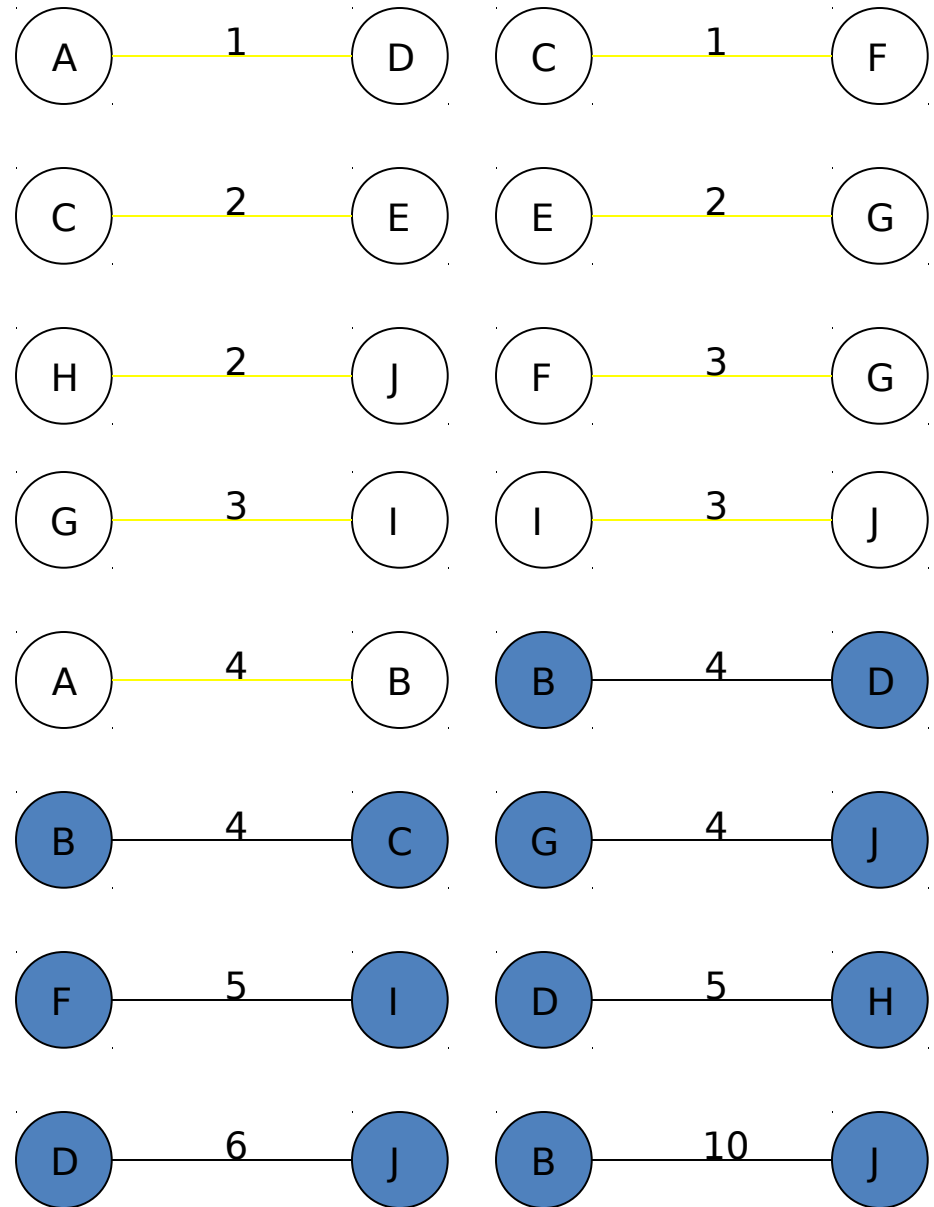
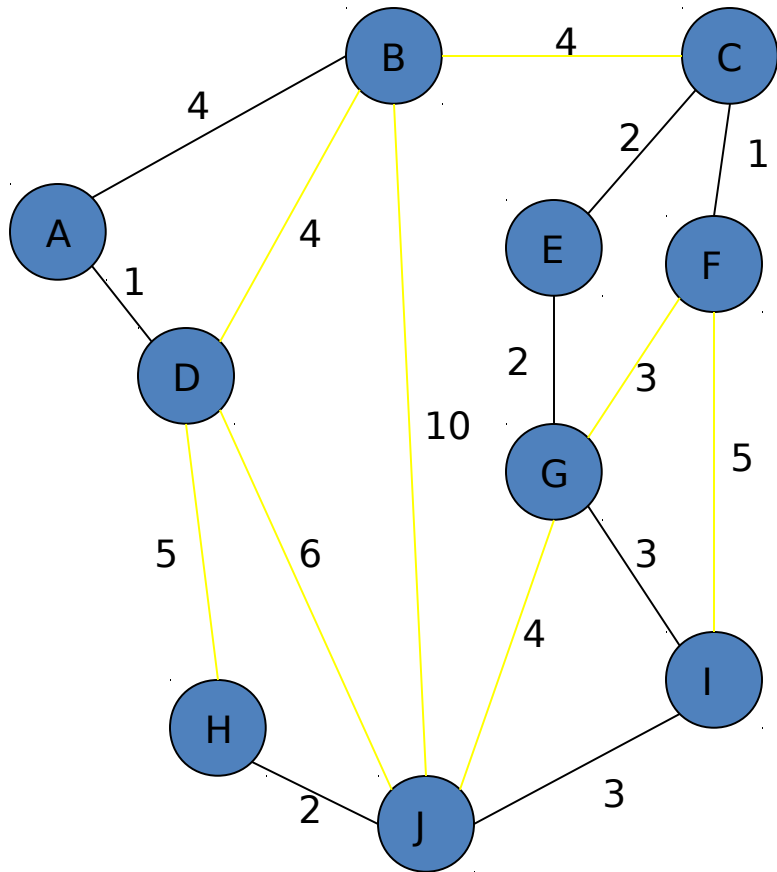
Add Edge



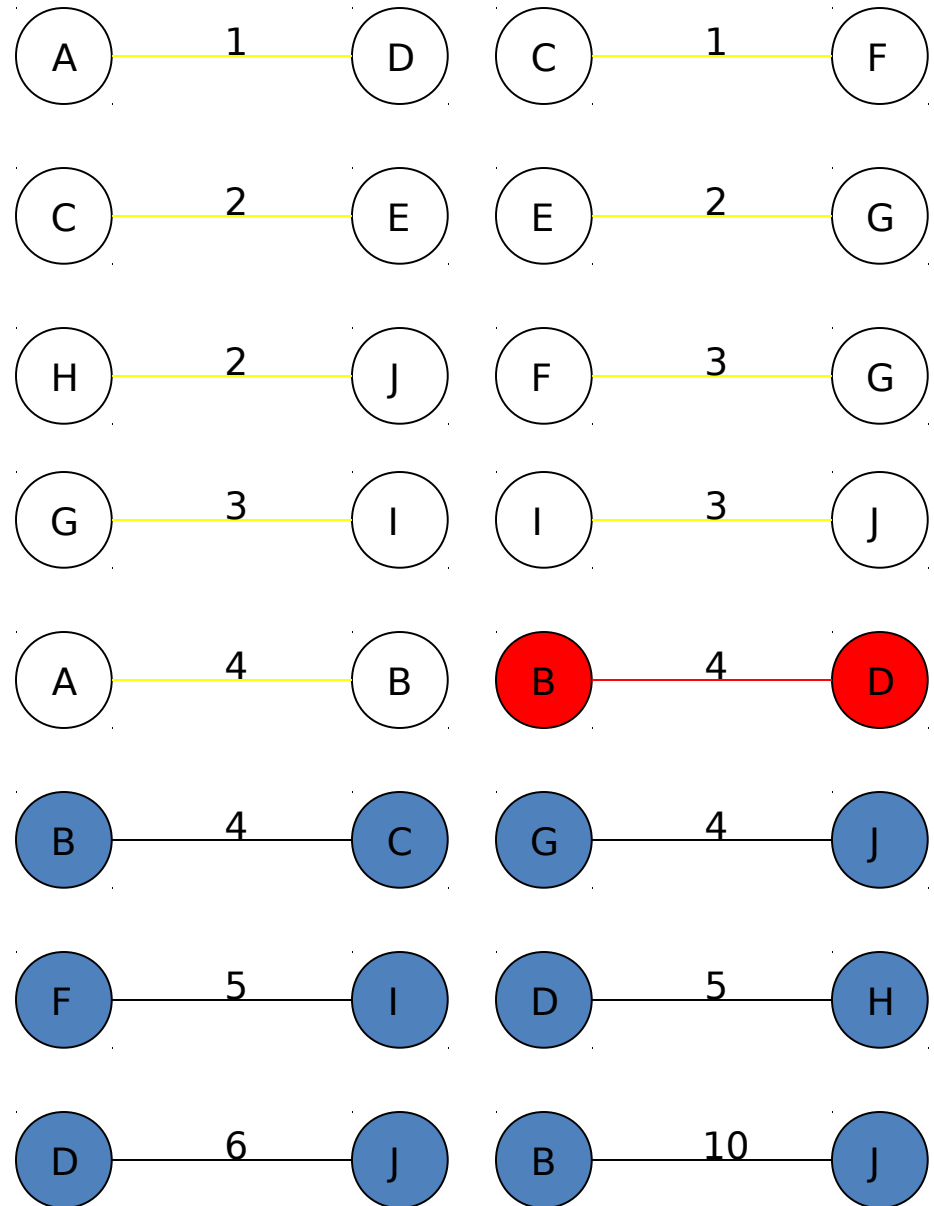
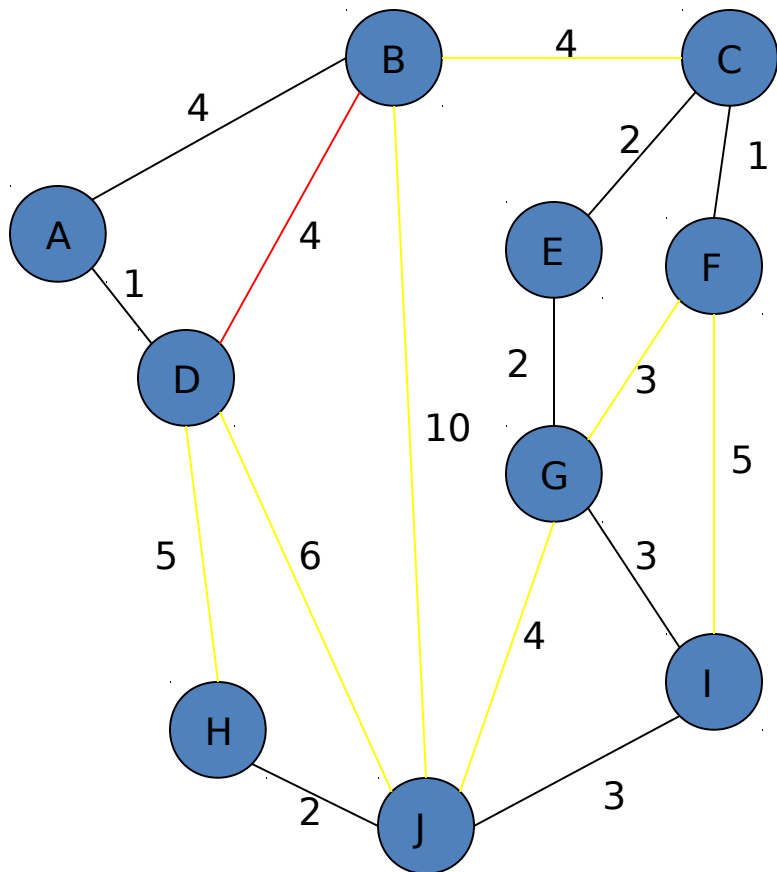
Add Edge



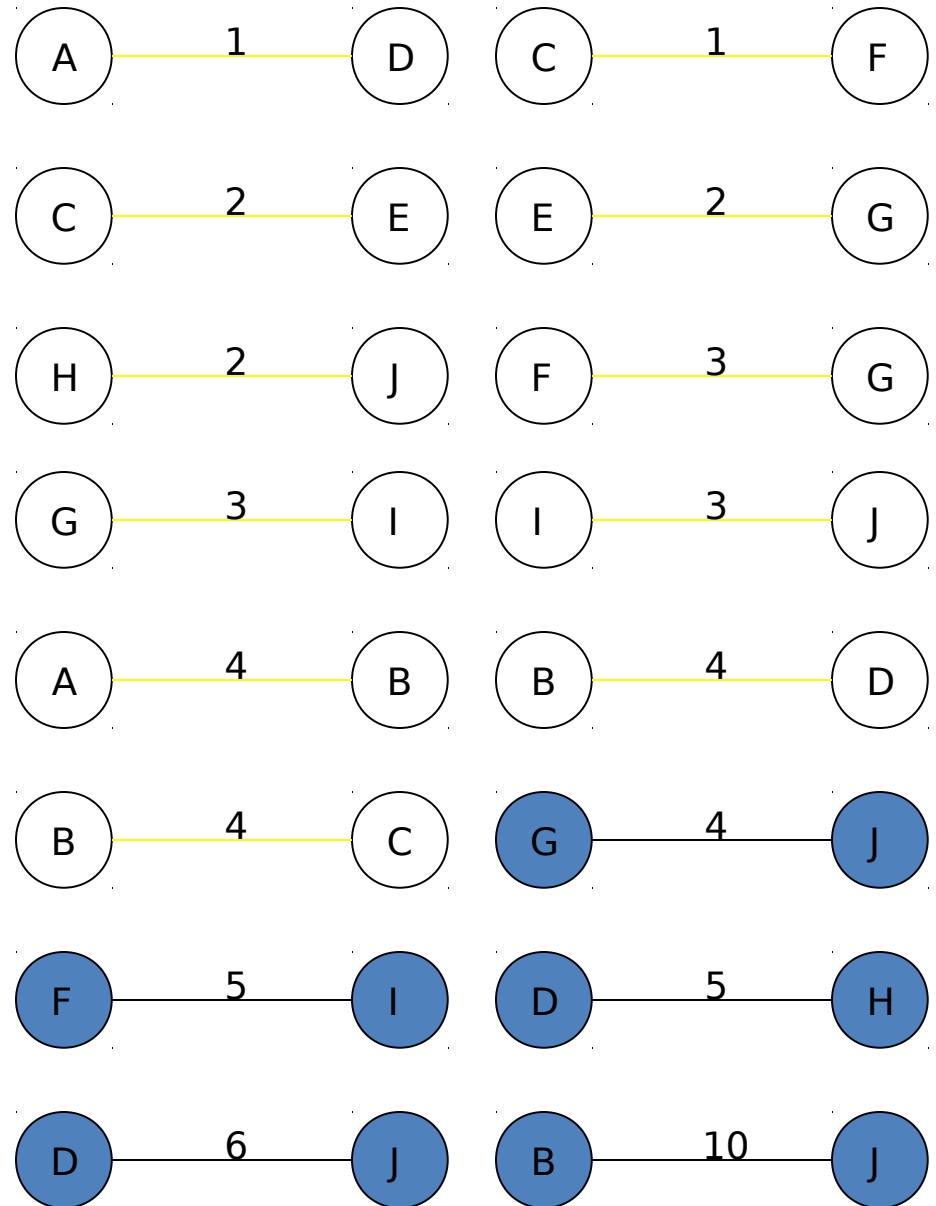
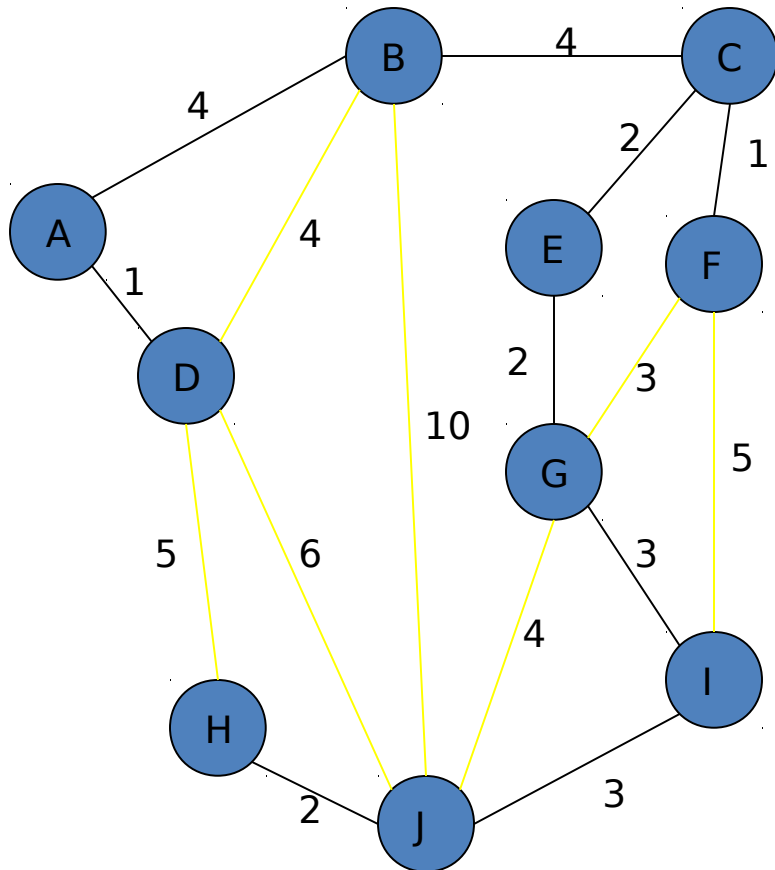
Add Edge



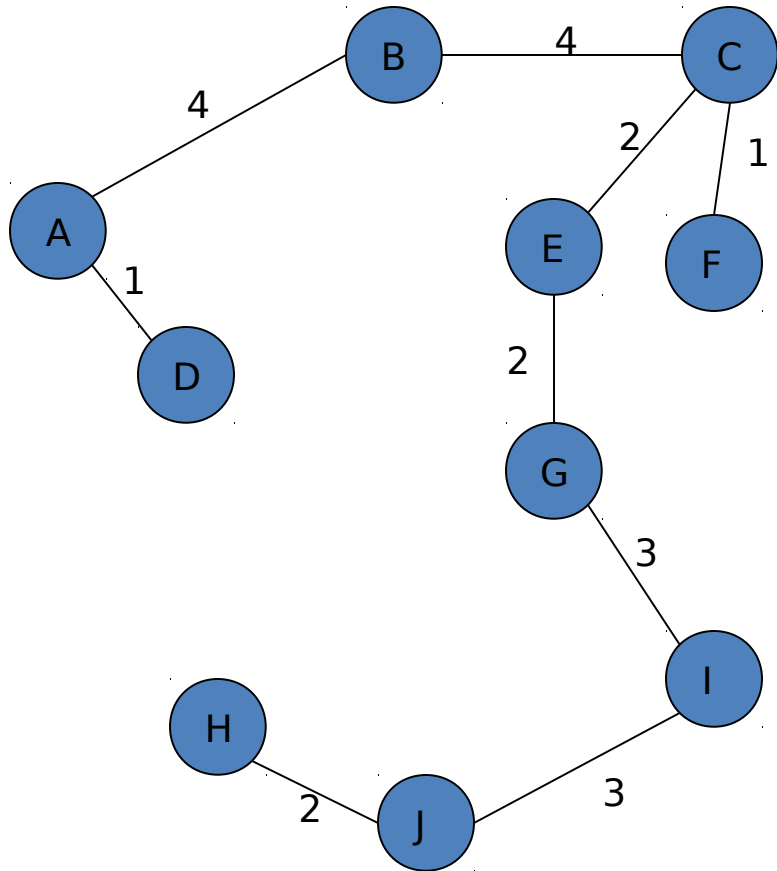
Cycle
Don't Add Edge



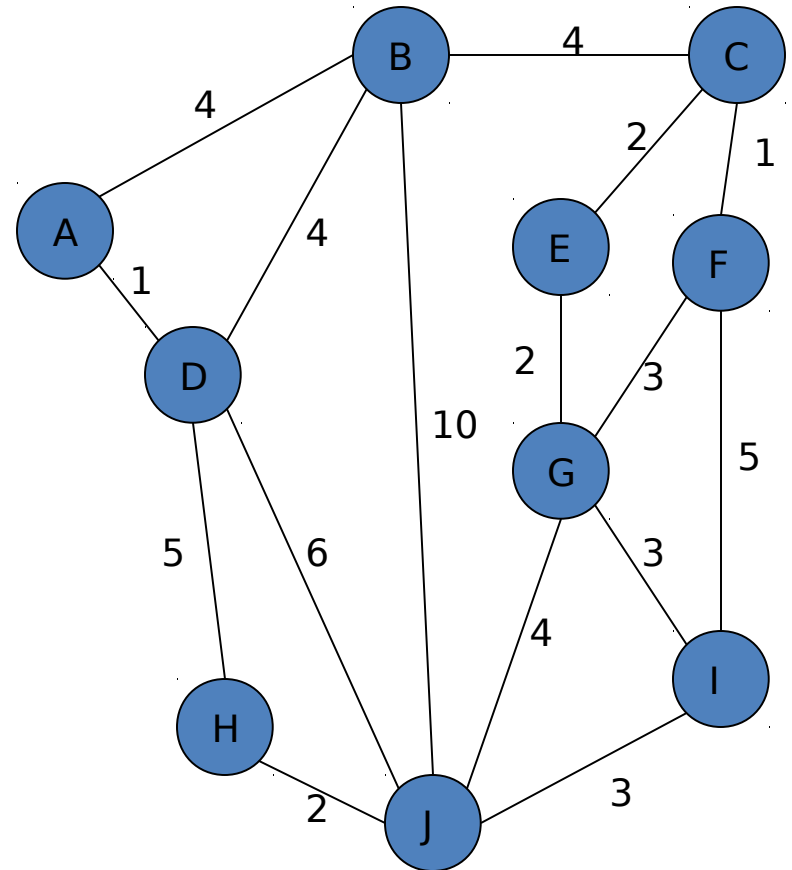
Add Edge



Minimum Spanning Tree



Complete Graph



MST-KRUSKAL(G, w)

```
1   $A \leftarrow \emptyset$ 
2  for each vertex  $v \in V[G]$ 
3      do MAKE-SET( $v$ )
4  sort the edges of  $E$  into nondecreasing order by weight  $w$ 
5  for each edge  $(u, v) \in E$ , taken in nondecreasing order by weight
6      do if FIND-SET( $u$ )  $\neq$  FIND-SET( $v$ )
7          then  $A \leftarrow A \cup \{(u, v)\}$ 
8              UNION( $u, v$ )
9  return  $A$ 
```

MAKE-SET(x)

1 $p[x] \leftarrow x$

2 $rank[x] \leftarrow 0$

UNION(x, y)

1 LINK(FIND-SET(x), FIND-SET(y))

LINK(x, y)

1 **if** $rank[x] > rank[y]$

2 **then** $p[y] \leftarrow x$

3 **else** $p[x] \leftarrow y$

4 **if** $rank[x] = rank[y]$

5 **then** $rank[y] \leftarrow rank[y] + 1$

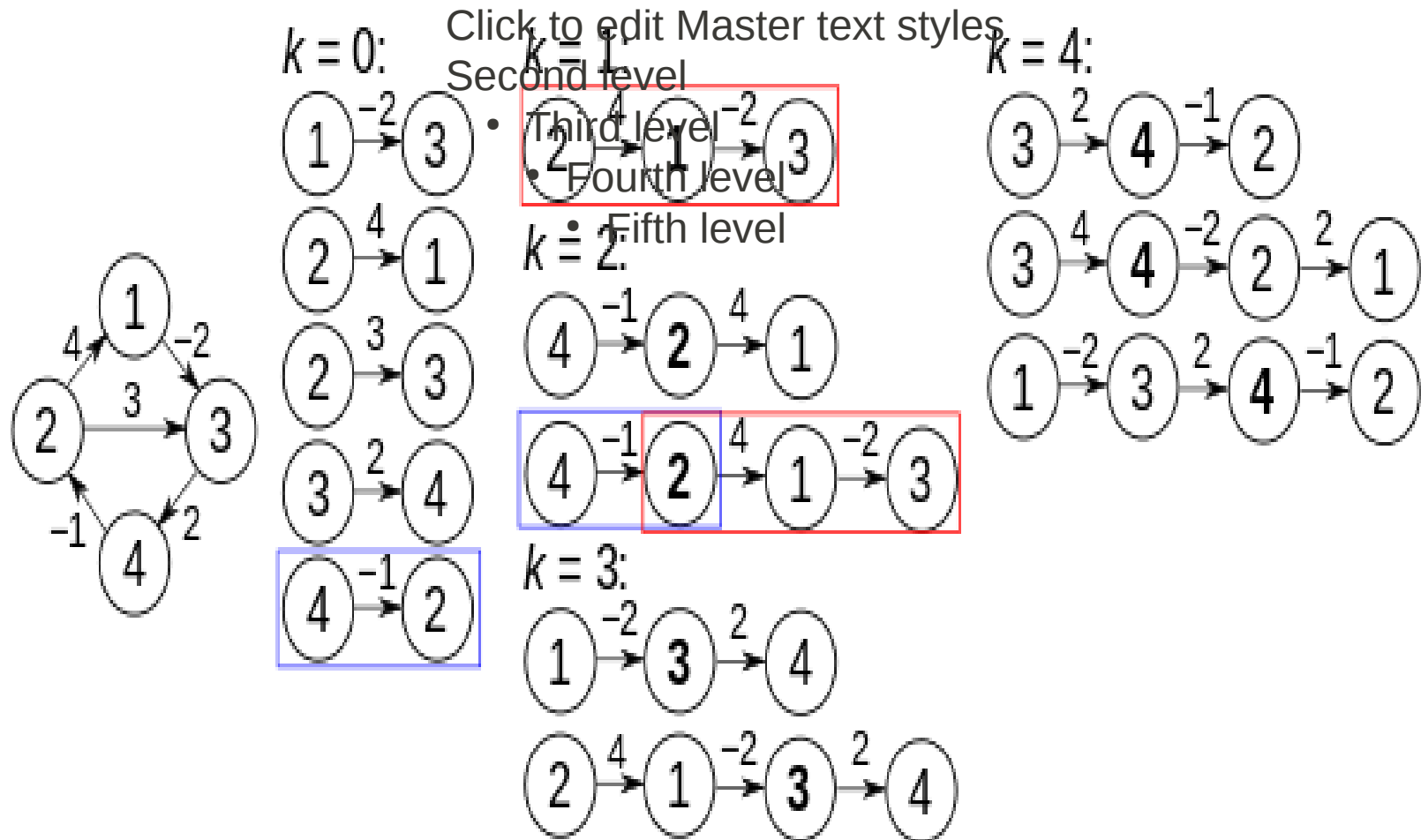
FIND-SET(x)

1 **if** $x \neq p[x]$

2 **then** $p[x] \leftarrow \text{FIND-SET}(p[x])$

3 **return** $p[x]$

Floyd-Warshall algorithm



Click to edit Master text styles
Second level

let dist be a $|V| \times |V|$ array of minimum distances initialized to ∞ (infinity)

for each vertex v

$\text{dist}[v][v] \leftarrow 0$

for each edge (u,v)

$\text{dist}[u][v] \leftarrow w(u,v)$ // the weight of the edge (u,v)

for k from 1 to $|V|$

 for i from 1 to $|V|$

 for j from 1 to $|V|$

 if $\text{dist}[i][k] + \text{dist}[k][j] < \text{dist}[i][j]$ then

$\text{dist}[i][j] \leftarrow \text{dist}[i][k] + \text{dist}[k][j]$

- Third level
- Fourth level
- Fifth level

Thank You