

## CS 208 - Applied Privacy for Data Science Homework 2

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The public Github repo containing all work is at <https://github.com/TurboFreeze/cs208hw>. All code has also been included in the appendix of this PDF as specified.

### Problem 1

(a)

- (i) The clamping function is effectively applying a post-processing function to the noisy query result. In other words, Laplace noise is added to the true mean  $\bar{x}$ , which must be  $(\epsilon, 0)$ -DP. The following clamping function does not change the privacy characteristics guaranteed by differential privacy, meaning that this mechanism **meets the definition** of  $(\epsilon, 0)$ -DP (following directly by privacy under post-processing and the proof of Laplace DP).

Note that the scale factor parameter of the Laplace distribution should be set to  $s = GS_q/\epsilon$  for differential privacy, meaning that  $\epsilon = GS_q/s$ . In this case, the global sensitivity  $GS_q$  is the maximum change that can be affected to the statistic by a single entry's change, which in this case would be  $1/n$  for the mean. Furthermore  $s = 2/n$ . The  $\epsilon = (1/n)/(2/n) \implies \boxed{\epsilon = 0.5}$ .

- (ii) Constant ratios of Laplace mechanisms

(iii)

$$\frac{P[M(x', q) = r]}{P[M(x, q) = r]} =$$

(iv)

$$\begin{aligned} P[M(x, q) = r] &= P[\bar{x} + Z]_0^1 = r] \\ &= \\ \frac{P[M(x, q) = r]}{P[M(x', q) = r]} &= \\ P[M(x, q) = r] &= P[\bar{x} + [Z]_{-1}^1 = r] \\ &= \end{aligned}$$

### Problem 2

(a) The DGP is the following likelihood of some data vector  $k \in \mathbb{N}^n$ :

$$P(\mathbf{x} = \mathbf{k}) = \prod_{i=1}^n \frac{10^{\mathbf{k}_i} e^{-10}}{\mathbf{k}_i!}$$

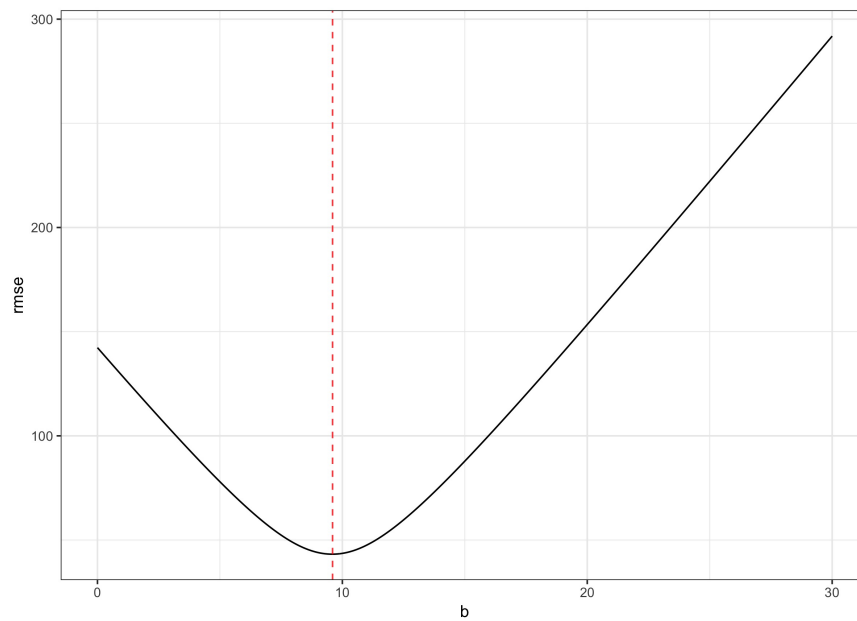
The DGP function was implemented using a Poisson random draw.

*See the attached R script `q2.R` for the implementation.*

(b) The first mechanism was chosen, involving clamping after Laplace noise has been added.

*See the attached R script `q2.R` for the implementation.*

(c) The optimal value  $b^*$  for  $b$  is  $b^* \approx 10$ . As expected, root mean squared error is indeed high with small clamping regions and decreases as it becomes more appropriate, with large clamping regions yielding high RMSE again.



*See the attached R script `q2.R` for the implementation.*

(d)

(e)

### Problem 3

(a) There are differentially private techniques to release the means  $\bar{y}$  and  $\bar{x}$  as well as the slope  $\hat{\beta}$ . However, given the careful considerations needed for the slope  $\hat{\beta}$ , it may be challenging to come up with a single differentially private mechanism to derive the intercept estimate. However  $\hat{\alpha} = \bar{y} - \hat{\beta}\bar{x}$  lends itself nicely to privacy preservation under composition and post-processing. Since there are three differentially private statistics needed here of  $\bar{x}, \bar{y}, \hat{\beta}$ , for a total epsilon budget of  $\epsilon_t$ , then calculate differentially private releases of each

statistic with  $\epsilon = \epsilon_t/3$  to yield  $(\epsilon_t/3, 0)$ -DP statistics. Since post-processing is allowed without affecting privacy, then this three differentially private statistics will lead to  $\epsilon_t/3 + \epsilon_t/3 + \epsilon_t/3 = \epsilon_t$  differential privacy for  $\hat{\alpha}$  by composition and  $\epsilon_t/3$  differential privacy for  $\hat{\beta}$  (which is used in  $\hat{\alpha}$  and does not require separate consumption of the budget). Therefore, the overall method for computing both  $\hat{\alpha}$  and  $\hat{\beta}$  would be  $\epsilon_t$ -DP, as desired.

Since the data  $x_i$  is generated by a Poisson process according to the previous problem, it can be clamped using the optimal value of  $b^* \approx 10$  found before. Since there is a linear relationship between  $x_i$  and  $y_i$  here (and it is known in the following part that the slope is simply 1), then similarly clamp  $y_i$  by  $b^* \approx 10$ .

*See the attached R script `q3.R` for the implementation.*

(b)

*See the attached R script `q3.R` for the implementation.*

(c)

*See the attached R script `q3.R` for the implementation.*

#### Problem 4

Use linearity of expectations and fundamental bridge to convert between probabilities and expectation of indicators.

$$\begin{aligned} \mathbb{E}[\#\{i \in [n] : A(M(X))_i = X_i\}/n] &= \mathbb{E}[\mathbb{1}\{i \in [n] : A(M(X))_i = X_i\}/n] \\ &= \mathbb{E}\left[\sum_{i=1}^n \mathbb{1}(A(M(X))_i = X_i)/n\right] \\ &= \frac{1}{n} \sum_{i=1}^n \mathbb{E}[\mathbb{1}(A(M(X))_i = X_i)] \\ &= \frac{1}{n} \sum_{i=1}^n P(A(M(X))_i = X_i) \end{aligned}$$

Use the definition of  $(\epsilon, \delta)$ -DP

## **Appendix**

### **Code for Problem 1**

**Code for Problem 2**

### **Code for Problem 3**