



EEE 302

Microprocessors and Interfacing

Experiment 3

**Rotate, Shift and LOOPs in assembly
language**

**Department of Electrical and Electronic
Engineering, EWU**

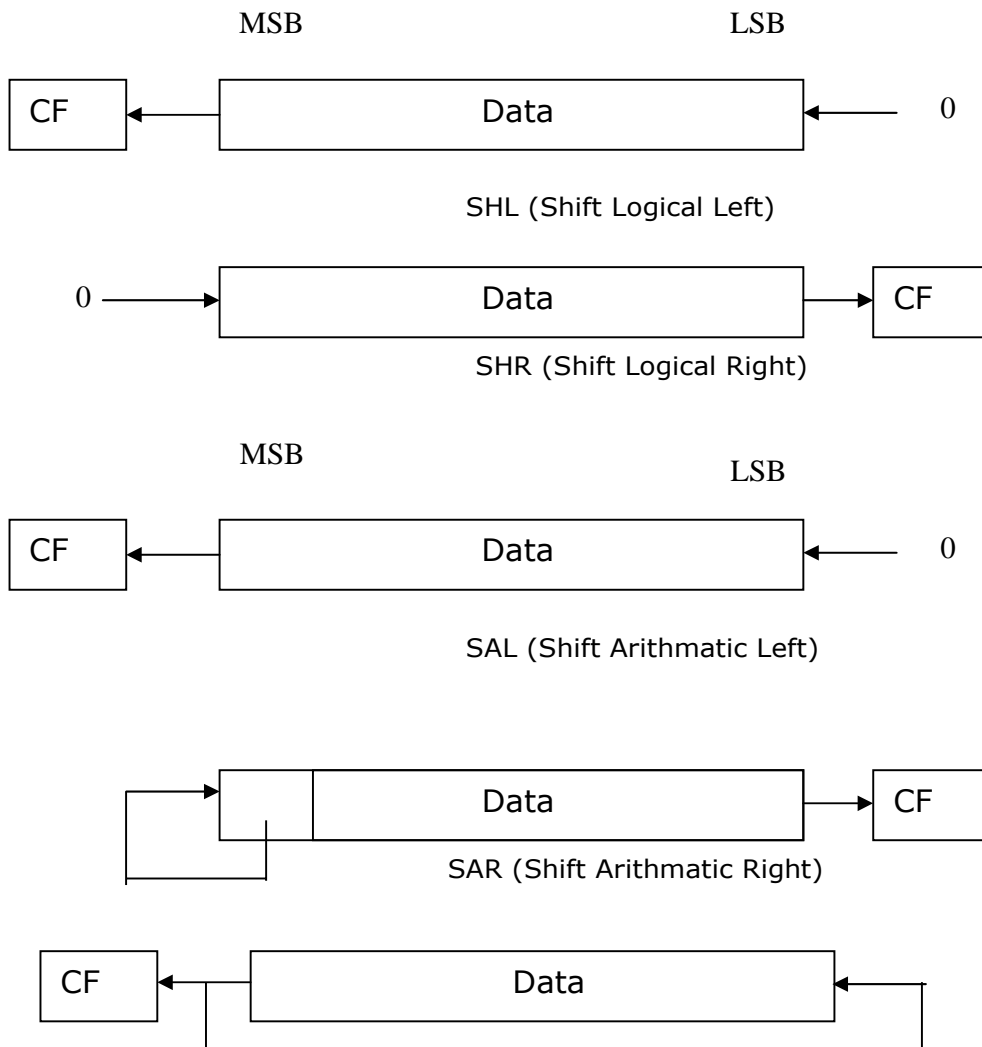
Objective:

To get familiar with Rotate and Shift commands in assembly language.
To use loops in complex problems.

Introduction:

Shift and Rotate command:

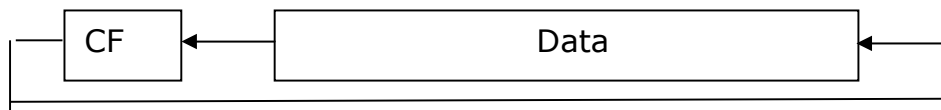
Shift and Rotate commands are used to convert a number to another form where some bits are shifted or rotated. Basic difference between shift and rotate is shift command makes "fall off" bits at the end of register. Where rotate command makes "Wrap around" at the end of the register. There are both arithmetic (SAL and SAR) and logical (SHL and SHR) shift instructions. Graphical operation for these commands are shown below.



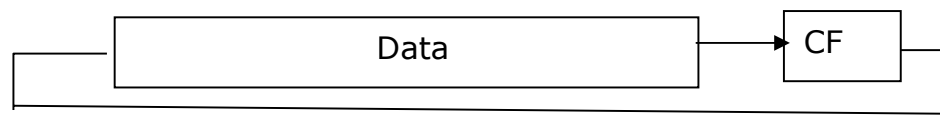
ROL (Rotate Left)



ROR (Rotate Right)



RCL (Rotate Through Carry Left)



RCR (Rotate Through Carry Right)

Some simple codes can be given to clarify the idea.

```
MOV CL,03H      ;  
MOV AX,02F3H    ; In binary 0000 0010 1111 0011  
SHR AX,CL       ; In binary 0000 0000 0101 1110
```

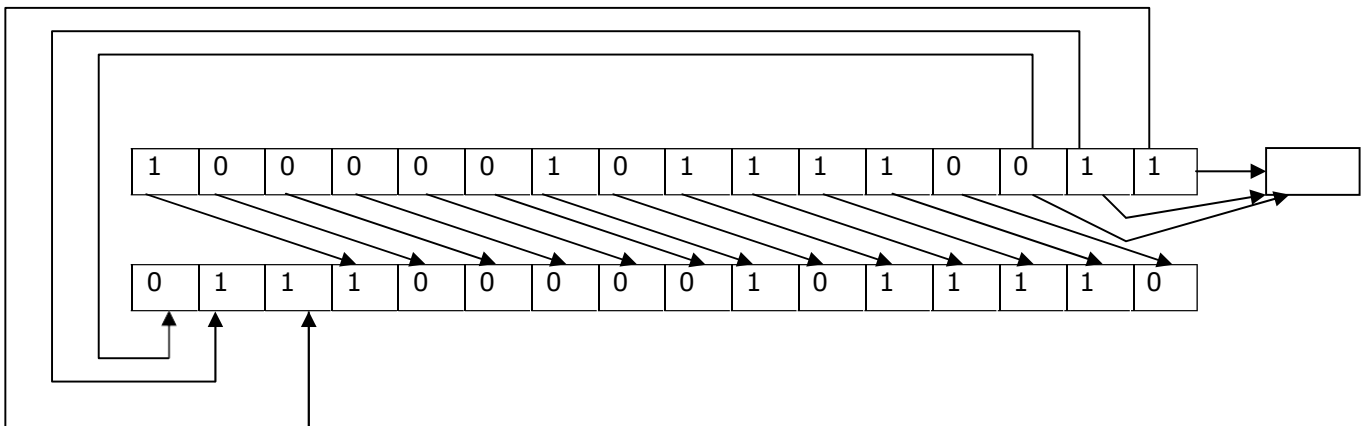
In this procedure, SHR commands inserts 0's from right side. Each time a 0 is inserted left most bit is vanished from register content.

```
MOV CL,03H      ;  
MOV AX,82F3H    ; In binary 1000 0010 1111 0011  
SAR AX,CL       ; In binary 1111 0000 0101 1110
```

In this procedure, SAR commands inserts MSB content from right side. Each time it is inserted left most bit is vanished from register content.

```
MOV CL,03H      ;  
MOV AX,82F3H    ; In binary 1000 0010 1111 0011  
ROR AX,CL       ; In binary 0111 0000 0101 1110
```

The whole procedure can be visualized as follows.



Here rotate by 3 operation is shown. It is clearly seen that every bit is assigned to a new position that is 3 places away from previous one. Unlike the shift command no right bit is destroyed. It is placed in the leftmost position.

Exercise part 1:

(a) Program 1:

```
CODE SEGMENT
    ASSUME CS:CODE

    MOV CL,02H
    MOV AX,105AH
    SHL AX,CL
    HLT

CODE ENDS
END
```

Obtain AX register value in write the previous value and present value in binary form. What type of operation is this?_____

(b) Program 2:

```
CODE SEGMENT
    ASSUME CS:CODE

    MOV CL,04H
    MOV AX,564AH
    SAL AX,CL
    HLT

CODE ENDS
END
```

Obtain AX register value in write the previous value and present value in binary form. What type of operation is this?_____

(c) Perform for similar values of AX and CL with ROL, ROR. RCL, RCR command.

LOOP in assembly language:

Loop commands are used to perform same operation again and again. This is like for, while type instructions in 'C' or 'MATLAB'. A common example can be shown as,

```
MOV CX,0100D
MOV AX,564AH
Lev: DEC AX
     Loop LEV
     HLT
```

Here CX acts as a count register. Loop Lev instruction leads instruction to go back to Lev level until CX is zero. Each time Lev level is executed CX is decreased by 1. Loop command can be used for waiting purposes. Such as,

```
MOV CX,0100D
Wt:  NOP
     Loop Wt
     HLT
```

Here the loop is executed until CX is zero. If 1 loop takes 1ms, the program will wait for 100ms.

Exercise part 2:

(a) Program 1:

```
CODE SEGMENT
     ASSUME CS:CODE

     MOV AX,1025H
     MOV BX,475AH
     MOV CX,50H
Lev:  INC AX
     DEC BX
     LOOP Lev
     HLT

CODE ENDS
     END
```

Observe the operation of this code. What happens when the loop is executed again and again.

(b) Program 2: This code is to find GCD of two numbers.

```
CODE SEGMENT
    ASSUME CS:CODE

    MOV AX,5H
    MOV BX,3H
Lev: XOR DX,DX
    DIV BX
    MOV AX,BX
    MOV BX,DX
    TEST DX,0H
    JNZ Lev
    HLT
CODE ENDS
END
```

Here GCD of 5 and 3 are found. You can change the values of AX and BX and obtain the result for any other values. Find GCD of 08D4H and 235H.

Result:_____

(c) Find Least Common Multiplier of 12H and 25H.

Report:

1. Suppose $x = 20$ and $y = 28$. Add y with x for 30 times.
2. Multiply 12 by 6 until result is below 3000H. If result is greater than this, divide the result by 2 for 3 times.
3. You can get input into microprocessor via following code.

```
MOV AH, 1H ; keyboard input subprogram
INT 21H
HLT
```

Take input from the keyboard until b is pressed.