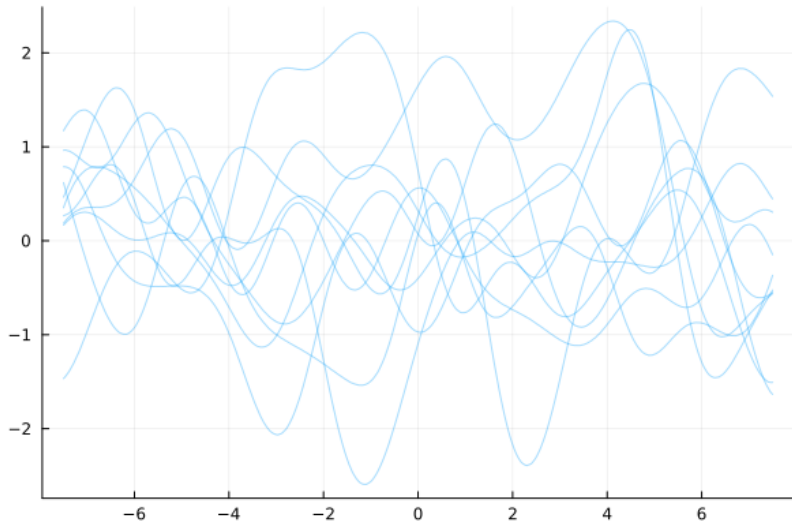


# TODO

- ▶ Tidy up formatting / make figures consistent
- ▶ Allude to use in non-Gaussian setting

$$f \sim \mathcal{GP}(0, \kappa_\theta)$$





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$$\mathbf{f} := [f(\tau_1), \dots, f(\tau_N)]^\top$$

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$$\mathbf{f} := [f(\tau_1), \dots, f(\tau_N)]^\top$$

$$\mathbf{y} \mid \mathbf{f} \sim \mathcal{N}(\mathbf{f}, \sigma^2 \mathbf{I})$$

