

# Methods of Variation of Parameters

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### 7.1 Method of variation of parameters for solving $dy/dx + P(x)y = Q(x)$

Consider a first order linear differential equation

$$dy/dx + Py = Q, \quad \text{i.e.,} \quad y_1 + Py = Q, \quad \text{where} \quad y_1 = dy/dx \quad \dots (1)$$

and  $P$  and  $Q$  are functions of  $x$  or constants. Suppose that the general solution of

$$y_1 + Py = 0, \quad \dots (2)$$

be given by

$$y = au, \quad \dots (3)$$

where  $a$  is an arbitrary constant and  $u$  is a function of  $x$ . Since  $u$  must be a solution of (2), we have

$$u_1 + Pu = 0 \quad \text{where} \quad u_1 = du/dx. \quad \dots (4)$$

When  $Q \neq 0$ , (3) cannot be the general solution of (1).

Now assume that

$$y = Au \quad \dots (5)$$

is the general solution of (1), where  $A$  is no longer constant but function of  $x$  to be so chosen that (1) is satisfied.

From (3) and (5), we note that the form of  $y$  is the same for two equations (1) and (2), but the constant which occurs in the former case is changed in the latter into a function of the independent variable  $x$ . For this reason, the present method is known as *variation of parameters*.

Differentiating (5) w.r.t. ' $x$ ', we have

$$y_1 = A_1u + Au_1, \quad \text{where} \quad A_1 = dA/dx \quad \dots (6)$$

Putting the values of  $y$  and  $y_1$  given by (5) and (6) in (1), we get

$$A_1u + Au_1 + PAu = Q \quad \text{or} \quad A_1u + A(u_1 + Pu) = Q$$

or

$$A_1u = Q, \text{ using (4)} \quad \dots (7)$$

$$\text{From (7),} \quad A_1 = Q/u \quad \text{or} \quad dA/dx = Q/u \quad \text{or} \quad dA = (Q/u) dx$$

$$\text{Integrating,} \quad A = \int (Q/u) dx + c, \text{ where } c \text{ is an arbitrary constant} \quad \dots (8)$$

Using (8) in (5), the general solution of (1) is given by

$$y = u(x)\{c + \int (Q/u) dx\} \quad \text{or} \quad y = c u(x) + u(x) \int (Q/u) dx \quad \dots (9)$$

**Ex. 1.** Apply the method of variation of parameters to solve

(i)  $y_2 + n^2 y = \sec nx$  [Agra 2006, Madras 2005; Gulbarga 2005; Delhi Maths 99, 2004; Bundelhand 2001; Himachal 2004; Kanpur 2007; Meerut 2008, 09; Madurai 2001; Rohilkhand

2004; Ravishanka 2002, 2004; Purvanchal 2007, I.A.S. 99 Venkenkateshwar 2003]

(ii)  $y_2 + y = \sec x$  [Mysore 2004; Delhi Maths (P) 2001; 02, Delhi Maths (G) 2002]

(iii)  $y_2 + 4y = \sec 2x$

(iv)  $y_2 + 9y = \sec 3x$  [Meerut 2007; Delhi Maths (H) 1999]

**Sol.** (i) Given  $y_2 + n^2 y = \sec nx$  ... (1)

Comparing (1) with  $y_2 + Py_1 + Qy = R$ , we have  $R = \sec nx$

Consider  $y_2 + n^2 y = 0$  or  $(D^2 + n^2) y = 0$ , where  $D \equiv d/dx$  ... (2)

Auxiliary equation of (2) is  $D^2 + n^2 = 0$  so that  $D = \pm in$ .

C.F. of (1) =  $C_1 \cos nx + C_2 \sin nx$ ,  $C_1$  and  $C_2$  being arbitrary constants ... (3)

Let  $u = \cos nx$ ,  $v = \sin nx$  Also, here  $R = \sec nx$  ... (4)

Here  $W = \begin{vmatrix} u & v \\ u_1 & v_1 \end{vmatrix} = \begin{vmatrix} \cos nx & \sin nx \\ -n \sin nx & n \cos nx \end{vmatrix} = n \neq 0$  ... (5)

Then, P.I. of (1) =  $u f(x) + v g(x)$  ... (6)

where  $f(x) = - \int \frac{vR}{W} dx = - \int \frac{\sin nx \sec nx}{n} dx = \frac{1}{n^2} \log \cos nx$ , by (4) and (5)

and  $g(x) = \int \frac{uR}{W} dx = \int \frac{\cos nx \sec nx}{n} dx = \frac{x}{n}$ , by (4) and (5)

$\therefore$  P.I. of (1) =  $(\cos nx) \times (1/n^2) \log \cos nx + (\sin nx) \times (x/n)$ , by (6)

Hence the general solution of (1) is  $y = \text{C.F.} + \text{P.I.}$

i.e.,  $y = C_1 \cos nx + C_2 \sin nx + (1/n^2) \times \cos nx \log \cos nx + (x/n) \times \sin nx$

**Ex. 2.** Apply the method of variation of parameters to solve

(i)  $y_2 + a^2 y = \operatorname{cosec} ax$  [Meerut 2004, 10; Kakatiay 2003; S.V. University A.P. 199, Rajsthan 2003, 01]

(ii)  $y_2 + y = \operatorname{cosec} x$  [Meerut 2007, 11; Bangalore 1996, Delhi Maths (G) 1998, 2003] Nagpur 2002, Delhi Maths (H) 1997; Guwahati 1996; Bilaspur 2000, 04 Indore 2001, 07]

(iii)  $y_2 + 9y = \operatorname{cosec} 3x$  [Delhi Maths (Pass) 2004]

**Sol.** (i) Given  $y_2 + a^2 y = \operatorname{cosec} ax$  ... (1)

Comparing (1) with  $y_2 + Py_1 + Qy = R$ , we have  $R = \operatorname{cosec} ax$

Consider  $y_2 + a^2 y = 0$  or  $(D^2 + a^2)y = 0$ ,  $D \equiv d/dx$  ... (2)

Auxiliary equation of (2) is  $D^2 + a^2 = 0$  so that  $D = \pm ai$

$\therefore$  C.F. of (1) =  $C_1 \cos ax + C_2 \sin ax$ ,  $C_1$  and  $C_2$  being arbitrary constants ... (3)

Let  $u = \cos ax$ ,  $v = \sin ax$ . Also, here  $R = \operatorname{cosec} ax$  ... (4)

Here  $W = \begin{vmatrix} u & v \\ u_1 & v_1 \end{vmatrix} = \begin{vmatrix} \cos ax & \sin ax \\ -a \sin ax & a \cos ax \end{vmatrix} = a \neq 0$  ... (5)

Then, P.I. of (1) =  $u f(x) + v g(x)$ , ... (6)

where  $f(x) = -\int \frac{vR}{W} dx = -\int \frac{\sin ax \operatorname{cosec} ax}{a} dx = -\frac{x}{a}$ , by (4) and (5)

and  $g(x) = \int \frac{uR}{W} dx = \int \frac{\cos ax \operatorname{cosec} ax}{a} dx = (1/a^2) \times \log \sin ax$ , by (4) and (5)

$\therefore$  P.I. of (1) =  $(\cos ax) \times (-x/a) + (\sin ax) \times (1/a^2) \times \log \sin ax$ , by (6)

Hence the general solution of (1) is  $y = \text{C.F.} + \text{P.I.}$

i.e.,  $y = C_1 \cos ax + C_2 \sin ax - (x/a) \times \cos ax + (1/a^2) \times \sin ax \log \sin ax$

(ii) Proceed as in part (i). Note that here  $a = 1$ .

**Ans.**  $y = C_1 \cos x + C_2 \sin x - x \cos x + \sin x \log \sin x$

(iii) Proceed as in part (i). Note that here  $a = 3$

**Ans.**  $y = C_1 \cos 3x + C_2 \sin 3x - (x/3) \times \cos 3x + (1/9) \times \sin 3x \log \sin 3x$

**Ex. 3.** Apply the method of variation of parameters to solve

(i)  $y_2 + a^2 y = \tan ax$  [Osmania 2004]

(ii)  $y_2 + 4y = 4 \tan 2x$  [Himiachal 2002, 03; Garhwal 2005, Delhi Maths (G) 1997, 2001; Rohilkhand 2001; Delhi B.A. (Prog) II 2010; Kanpur 2002, 08; Nagpur 1996]

(iii)  $y_2 + y = \tan x$  [Delhi B.A (Prog.) H 2007, 08, 11; Delhi B.A (G) 2000; Bangalore 2005; Delhi B.Sc. (Prog.) II 2008; Delhi Maths (H.) 1996, 2002]

(iv)  $y_2 + a^2 y = \cot ax$  [Delhi Maths (G) 2005]

(v)  $y_2 + 4y = \cot 2x$

**Sol.** (i) Given  $y_2 + a^2 y = \tan ax$  ... (1)

Comparing (1) with  $y_2 + Py_1 + Qy = Q$ , we have  $R = \tan ax$

Consider  $y_2 + a^2 y = 0$  or  $(D^2 + a^2) y = 0$ , where  $D \equiv d/dx$  ... (2)

Auxiliary equation of (2) is  $D^2 + a^2 = 0$  so that  $D = \pm ia$

$\therefore$  C.F. of (1) =  $c_1 \cos ax + c_2 \sin ax$ ,  $c_1$  and  $c_2$  being arbitrary constants ... (3)

Let  $u = \cos ax$ ,  $v = \sin ax$ . Also, here  $R = \tan ax$  ... (4)

Here  $W = \begin{vmatrix} u & v \\ u_1 & v_1 \end{vmatrix} = \begin{vmatrix} \cos ax & \sin ax \\ -a \sin ax & a \cos ax \end{vmatrix} = a \neq 0$  ... (5)

Then P.I. of (1) =  $u f(x) + v g(x)$ , ... (6)

where 
$$f(x) = -\int \frac{vR}{W} dx = -\int \frac{\sin ax \tan ax}{a} dx = -\frac{1}{a} \int \frac{1 - \cos^2 ax}{\cos ax} dx, \text{ using (4) and (5)}$$

$$= -\frac{1}{a} \int (\sec ax - \cos ax) dx = -\frac{1}{a} \left[ \frac{1}{a} \log (\sec ax + \tan ax) - \frac{\sin ax}{a} \right]$$

$$= (1/a^2) \times \{\sin ax - \log (\sec ax + \tan ax)\}$$

and 
$$g(x) = \int \frac{uR}{W} dx = \int \frac{\cos ax \tan ax}{a} dx = \frac{1}{a} \int \sin ax dx = -\frac{1}{a^2} \cos ax, \text{ using (4) and (5)}$$

Using (6), P.I. of (1) =  $\cos ax \times (1/a^2) \{\sin ax - \log (\sec ax + \tan ax)\} + \sin ax \times (-1/a^2) \cos ax$   
 $= -(1/a^2) \times \cos ax \log (\sec ax + \tan ax)$

Hence the general solution of (1) is  $y = \text{C.F.} + \text{P.I.}$

i.e., 
$$y = c_1 \cos ax + c_2 \sin ax - (1/a^2) \times \cos ax \log (\sec ax + \tan ax)$$

(ii) Given 
$$y_2 + 4y = 4 \tan 2x \quad \dots (1)$$

Comparing (1) with  $y_2 + Py_1 + Qy = R$ , here  $R = 4 \tan 2x$

Consider  $y_2 + 4y = 0$  or  $(D^2 + 4)y = 0$ ,  $D \equiv d/dx \dots (2)$

Auxiliary equation of (2) is  $D^2 + 4 = 0$  so that  $D = \pm 2i$ .

C.F. of (1) =  $C_1 \cos 2x + C_2 \sin 2x$ ,  $C_1$  and  $C_2$  being arbitrary constants  $\dots (3)$

Let  $u = \cos 2x$ ,  $v = \sin 2x$ . Also, here  $R = 4 \tan 2x \quad \dots (4)$

Here 
$$W = \begin{vmatrix} u & v \\ u_1 & v_1 \end{vmatrix} = \begin{vmatrix} \cos 2x & \sin 2x \\ -2 \sin 2x & 2 \cos 2x \end{vmatrix} = 2 \neq 0 \quad \dots (5)$$

Then, 
$$\text{P.I. of (1)} = uf(x) + vg(x), \quad \dots (6)$$

where 
$$f(x) = -\int \frac{vR}{W} dx = -4 \int \frac{\sin 2x \tan 2x}{2} dx = -2 \int \frac{1 - \cos^2 2x}{\cos 2x} dx, \text{ using (4) and (5)}$$
$$= 2 \int (\cos 2x - \sec 2x) dx = \sin 2x - \log(\sec 2x + \tan 2x)$$

and 
$$g(x) = \int \frac{uR}{W} dx = 4 \int \frac{\cos 2x \tan 2x}{2} dx = -\cos 2x, \text{ by (4) and (5)}$$

$\therefore$  P.I of (1) =  $(\cos 2x)\{\sin 2x - \log(\sec 2x + \tan 2x)\} + (\sin 2x)(-\cos 2x)$ , by (6)

or 
$$\text{P.I. of (1)} = -\cos 2x \log(\sec 2x + \tan 2x)$$

Hence the general solution of (1) is 
$$y = \text{C.F.} + \text{P.I.}$$

i.e., 
$$y = C_1 \cos 2x + C_2 \sin 2x - \cos 2x \log(\sec 2x + \tan 2x).$$

(iii) Proceed as in part (i) by taking  $a = 1$ . The general solution is

$$y = C_1 \cos x + C_2 \sin x - \cos x \log(\sec x + \tan x)$$

(iv) Given 
$$y_2 + a^2 y = \cot ax \quad \dots (1)$$

Comparing (1) with  $y_2 + Py_1 + Qy = R$ , we have 
$$R = \cot ax$$

Consider 
$$y_2 + a^2 y = 0 \quad \text{or} \quad (D^2 + a^2)y = 0, \quad D \equiv d/dx \quad \dots (2)$$

Auxiliary equation of (2) is 
$$D^2 + a^2 = 0 \quad \text{so that} \quad D = \pm ia.$$

$\therefore$  C.F. of (1) =  $c_1 \cos x + c_2 \sin ax$ ,  $c_1$  and  $c_2$  being arbitrary constants  $\dots (3)$

Let 
$$u = \cos ax, \quad v = \sin ax. \quad \text{Also, here} \quad R = \cot ax \quad \dots (4)$$

Here 
$$W = \begin{vmatrix} u & v \\ u_1 & v_1 \end{vmatrix} = \begin{vmatrix} \cos ax & \sin ax \\ -a \sin ax & a \cos ax \end{vmatrix} = a \neq 0 \quad \dots (5)$$

Then 
$$\text{P.I. of (1)} = uf(x) + vg(x), \quad \dots (6)$$

where 
$$f(x) = -\int \frac{vR}{W} dx = -\int \frac{\sin ax \cot ax}{a} dx = -\frac{1}{a} \int \cos ax dx = -\frac{\sin ax}{a^2}, \text{ using (4) and (5)}$$

and 
$$g(x) = \int \frac{uR}{W} dx = \int \frac{\cos ax \cot ax}{a} dx = \frac{1}{a} \int \frac{1 - \sin^2 ax}{\sin ax} dx, \text{ by (4) and (5)}$$



$$\begin{aligned}\text{Using (6), P.I. of (1)} &= \cos ax \times (-1/a^2) \times \sin ax + \sin ax \times (1/a^2) \times \{\log \tan (ax/2) + \cos ax\} \\ &= (1/a^2) \times \log \tan (ax/2)\end{aligned}$$

Hence, the general solution of (1) is  $y = \text{C.F.} + \text{P.I.}$

$$\text{i.e., } y = c_1 \cos ax + c_2 \sin ax + (1/a^2) \times \log \tan (ax/2)$$

(v) Proceed like part (iv) with  $a = 2$ . The solution is

$$y = c_1 \cos 2x + c_2 \sin 2x + (1/4) \times \log \tan x$$

**Ex. 4.** Apply the method of variation of parameters to solve

(i)  $y_2 - y = 2/(1 + e^x)$  [Delhi Maths (H) 2001; Delhi Maths (G) 1999; Rohilkhand 2002;  
Allahabad 2000, 05; Kanpur 2007; Nagpur 2001, 06; Bangalore 2004

(ii)  $y_2 - 3y_1 + 2y = e^x/(1 + e^x)$  Delhi B.Sc. (Prog) 2009]

(iii)  $y_2 - 4y_1 + 3y = e^x/(1 + e^x).$

H.W. 4,5,8