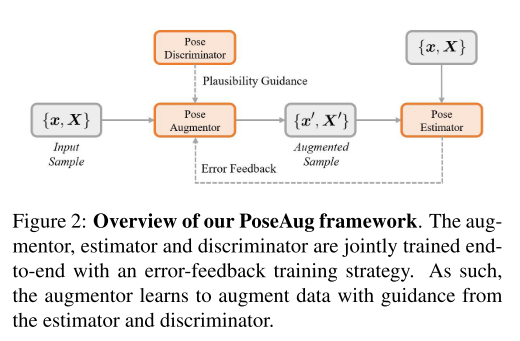
# PoseAug

PoseAug introduces a novel pose augmen- tor that learns to adjust various geometry factors (e.g., posture, body size, view point and position) of a pose through differentiable operations.



使用网络做数据增强，使用判别器对数据增强结果判别

预测目标：



数据增强优化目标：



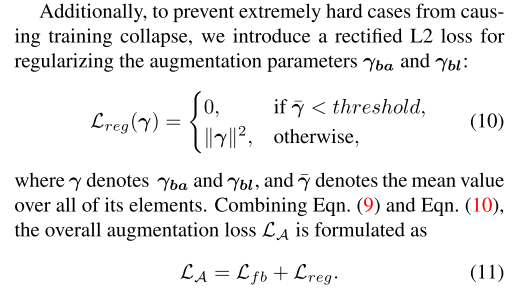
## 损失

预测模块：

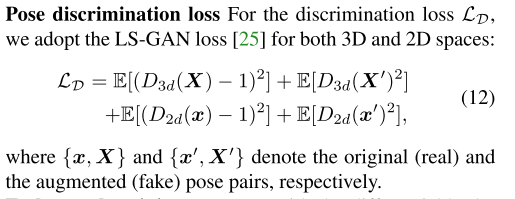


数据增模块：

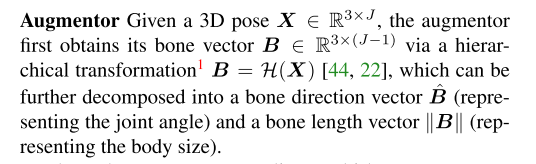


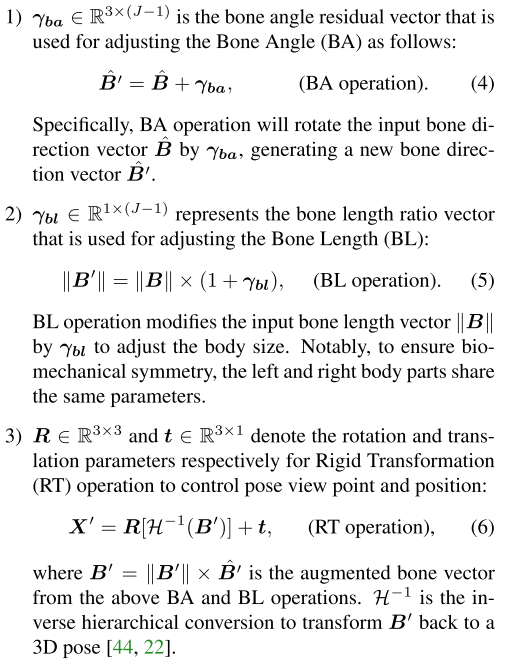


判别器模块：



数据增强是在向量维度上的：



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## 分块判别器

