



Lab Report (Grouped)
Microprocessor and Microcontroller lab
Group: 3 | Section: D

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Submission Date: 09.06.23

You are an adventurous person and have gone to find a rare species of spider in the Amazon. Whenever you see a spider from a distance, you push a button that activates an ultrasonic sensor, which then measures the distance between you and the spider. However, the spider is venomous and you don't want it getting too close to you. If it is closer than 500 cm to you, you need to signal your friend via RF transmission that you are in danger by saying "The spider is — cm close to me. Help". The ultrasonic sensor and push button are connected to the master Arduino. Connect a serial monitor to the slave Arduino to check whether the sent message is received properly.

The diagram illustrates a two-way communication system between two Arduino Uno boards (U1 and U2) using a serial-to-USB module (U4) and a TX module (U5) for U1, and an RX module (U6) for U2. Both boards are also equipped with an SRF04 ultrasonic sensor (U3).

Legend:

- U3 SRF04
- U4 MODULO RX
- U5 MODULO TX
- U2 ARDUINO UNO
- U1 ARDUINO UNO

Connections:

- U1 (Left Arduino Uno):**
 - TX Module (U5):** GND to GND, VCC to 5V, ANT to antenna.
 - SRF04 (U3):** GND to GND, VCC to 5V, TRIG to digital pin 2, ECHO to digital pin 3.
 - Serial-to-USB Module (U4):** GND to GND, VCC to 5V, TX to digital pin 2, RX to digital pin 3, ANT to antenna.
- U2 (Right Arduino Uno):**
 - RX Module (U6):** GND to GND, VCC to 5V, TX to digital pin 2, RX to digital pin 3, ANT to antenna.
 - SRF04 (U3):** GND to GND, VCC to 5V, TRIG to digital pin 2, ECHO to digital pin 3.
 - Serial-to-USB Module (U4):** GND to GND, VCC to 5V, TX to digital pin 2, RX to digital pin 3, ANT to antenna.

Code:

```
//Sender
#include <VirtualWire.h>
char msg[4];

void setup()
{
    Serial.begin(9600);
    vw_set_ptt_inverted(true);
    vw_setup(2000);
    vw_set_tx_pin(12);
    pinMode(9, OUTPUT); // Sets the trigPin as an Output
    pinMode(11, INPUT); // Sets the echoPin as an Input
    pinMode(2, INPUT_PULLUP);
    digitalWrite(9, LOW); // Clears the trigPin
    delayMicroseconds(2);
}

void loop()
{
    int x = digitalRead(2);
    if(x==LOW) {
        digitalWrite(9, HIGH);
        delayMicroseconds(10);
        digitalWrite(9, LOW);
        long duration = pulseIn(11, HIGH);
        long distance= (duration*0.034)/2;
        Serial.print("Distance from the Spider = ");
        Serial.print(distance);
        Serial.println(" cm");
        delay(1000);

        itoa(distance, msg, 10);
        if(distance<=500) {
            vw_send((uint8_t *)msg, sizeof(distance));
            delay(1000);
        }
    }
}
```

```
//Receiver:
#include <VirtualWire.h>
int i;

void setup()
{
    Serial.begin(9600);
    vw_set_ptt_inverted(true);
    vw_setup(2000);
    vw_set_rx_pin(11);
    vw_rx_start();
}

void loop()
{
    uint8_t sms[VW_MAX_MESSAGE_LEN];
    uint8_t len = VW_MAX_MESSAGE_LEN;
    if (vw_get_message(sms, &len))
    {
        Serial.print("The spider is ");
        for (i = 0; i < len; i++) {
            char c = sms[i];
            Serial.print(c);
        }
        Serial.println(" cm close to me. Help!!");
    }
}
```