

# Tushar Chugh

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## EDUCATION

### CARNEGIE MELLON UNIVERSITY M.S. IN ROBOTIC SYSTEMS

#### DEVELOPMENT

Aug'15 - Dec'16 | Pittsburgh GPA: 3.75

### YOUNG INDIA FELLOWSHIP (WITH UNIVERSITY OF PENNSYLVANIA)

#### MASTER'S PROGRAM IN LIBERAL ARTS

Jun'11-May'12 | New Delhi, India

Selected in top 57 across India

Developed a **haptic belt** device for visually impaired to help navigate by providing haptic feedback for avoiding obstacles. (won awards)

### MAHARSHI DAYANAND UNIVERSITY

#### B.TECH IN ELECTRONICS AND COMMUNICATION ENGINEERING

Jul'07 - May'11 | Faridabad MARKS:71/100

Awarded chairman scholarship at MRCE

## LINKS

Github:// [tusharchugh](#)

LinkedIn:// [tusharchugh](#)

## COURSEWORK

### GRADUATE

Machine Learning

Computer Vision

Robot Autonomy

Embedded Real Time Systems (Linux Kernel)

Software - Object, Design and Concurrency

Systems Engineering

### UNDERGRAD AND YIF

Embedded Systems

Statistics

Linear Algebra

Art Appreciation

## SKILLS

### PROGRAMMING

C++ • Java • MATLAB • Python

### PLATFORM | FRAMEWORK | IDE

Linux • ROS • OpenCV • TensorFlow

Android Dev • Visual Studio (WPF, WCF)

Git • CI(Travis, Jenkins)

### HARDWARE

Raspberry Pi • Arduino(also mbed, ATMEAL and PIC) • PCB Designing (Basics)

## EXPERIENCE AND PROJECTS

### GENERAL MOTORS | AUTONOMOUS PERCEPTION SOFTWARE

Feb'17 - Present | Warren, MI

- Developed ROS based drivers (including viz plugins) for short range radars
- Created algorithm to classify images for sensor cleaning system verification
- Programming CNN's for detecting traffic signs and traffic lights
- Worked on **vehicle detection** using HOG and SVM in OpenCV (Udacity)
- Worked on **behavioral cloning** with deep learning using Udacity's simulator
- Worked on **lane detection** and estimation of curvature (Udacity)

### QUALCOMM RESEARCH CENTER | SOFTWARE INTERN

May'16 - Aug'16 | San Diego, CA

- Worked on software development of **Neural Processing Engine (NPE)**
- Contributed in bringing up the new ASIC emulator platform, coded AlexNet conv layers in Assembly and created programmers guide for developers
- Designed a cap for the blind to narrate the scene using NPE and Alexa

### MICROSOFT INDIA (R&D) | SOFTWARE DEVELOPMENT ENGINEER 2

May'12 - Jul'15 | Hyderabad, India

- Envisioned, created and **released** to public **Kinect Ripple** - a dual projection infotainment platform built in C# with javascript based API's
- Co-founded Makerzby for Internet of Things(IoT) related development

### MICROSOFT RESEARCH, CAMBRIDGE | SENSORS AND DEVICES

Aug'13 - Jan'14 | Cambridge, UK

- Researched on a novel way for quick & low cost printing of electronic circuits using an inkjet printer with silver nanoparticles.
- Developed firmware for windows phone based gaming peripherals

### NATIONAL ROBOTICS ENGINEERING CENTER | CAPSTONE CMU

Aug'15 - May'16 | Pittsburgh, PA

- **Autonomous Water Taxi**: Implemented path-planning stack using SBPL and ROS. Created Occupancy Grip Map (OGM) using OpenStreet maps, designed framework to add and inflate obstacle data to OGM, used ARA\* algorithm as global planner and tuned motion primitives
- **Andy - Instructing robot arms via speech commands** Enabled Andy to understand speech commands for performing table-top manipulation tasks. Used HSV as color space, HOG features and SVM for detecting shapes and Amazon Alexa for speech. NLP and path planner were provided by NREC

## PUBLICATIONS

**Circuit Stickers**: ACM CHI, 2014 Canada, Steve Hodge, Et Al.

**Vector2703**: Autonomous Ground Vehicle, IEEE Explore Japan, T. Chugh, Et Al.

## AWARDS

2016 3rd

2016 1st

2013 Editor's choice

2013 Top 12 Asia

2013 2nd/10 countries

2012 1st(India)

2010 1st(India)

Amazon Alexa

Qualcomm

Maker Faire, NYC

Wall Street Journal

Health 2.0, SF

Accenture and Yahoo

Microsoft

**Internet of Voice Challenge  
Hackmobile**

Microsoft Research demo

**Best Asian Innovations**

Developer World Cup for Health

Innovation Jockeys

Imagine Cup, Poland