# Mutual Exclusion Algorithms for Distributed Systems

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#### Centralized Algorithm

Coordinator Based Algorithm

## Permission Based Algorithms

Lamport's Algorithm Ricart and Agrawala's Algorithm Roucairol and Carvalho's Algorithm

## Quorum Based Algorithms Maekawa's Algorithm

Token Based Algorithms Raymond's Algorithm

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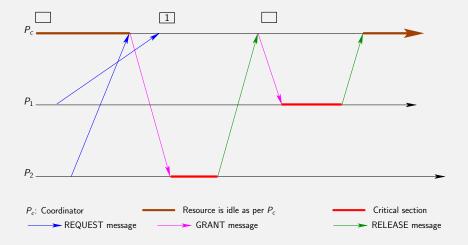
#### The Main Idea

- One of the processes in the system is selected as the coordinator.
  - ▶ The coordinator is responsible for deciding the order in which critical section requests are fulfilled.

- Every process sends its request for critical section to the coordinator and waits to receive permission from it.
  - Requests are fulfilled in the order in which they arrive at the coordinator.

- ► The coordinator grants permission to requests one at a time.
  - ► All other requests are queued in a FIFO queue.

## An Illustration



## Complexity Analysis

Parameters:

*N*: Number of processes in the system

T: Message transmission time

E: Critical section execution time

Message complexity: 3

- ▶ 1 REQUEST message + 1 GRANT message + 1 RELEASE message
- Message-size complexity: O(1)
- Response time (under light load): 2T + E
- Synchronization delay (under heavy load): 2T

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#### The Main Idea

Assumes that all channels are FIFO.

- Processes implement Lamport's logical clock.
- Requests are timestamped using logical clock.
- Requests are fulfilled in the order of their timestamps.
- ► Each process maintains a priority queue of all requests that are still outstanding as per its knowledge.

# Steps for Process $P_i$

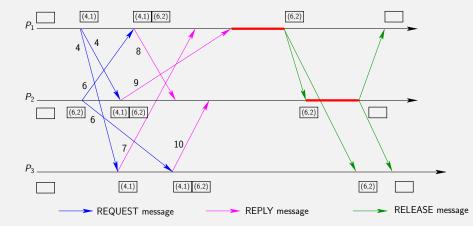
- On generating a critical section request:
  - Insert the request into the priority queue.
  - Broadcast the request to all processes.
- On receiving a critical section request from another process:
  - Insert the request into the priority queue.
  - Send a REPLY message to the requesting process.
- Conditions for critical section entry (unoptimized version):
  - ▶ L1': P<sub>i</sub> has received a REPLY message from all processes.
    - ▶ Any request received by  $P_i$  in the future will have timestamp larger than that of  $P_i$ 's own request.
  - **L2:**  $P_i$ 's own request is at the top of its queue.
    - P<sub>i</sub>'s request has the smallest timestamp among all requests received by P<sub>i</sub> so far.

# Steps for Process $P_i$ (Contd.)

- On leaving the critcal section:
  - Remove the request from the queue.
  - Broadcast a RELEASE message to all processes.

- ▶ On receiving a RELEASE message from another process:
  - Remove the request of that process from the queue.

## An Illustration

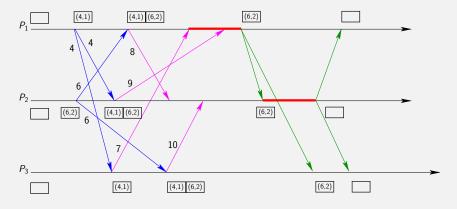


## Optimizing the Performance

- Replace L1' with the following condition:
  - ▶ L1: *P<sub>i</sub>* has received a message with timestamp larger than that of its own request from all processes.
    - Message can be any message: REQUEST, REPLY, RELEASE or even application

- Once L1 becomes true, we can still conclude that:
  - ▶ Any request received by  $P_i$  in the future will have timestamp larger than that of  $P_i$ 's own request.

# An Illustration with Optimization



Conditions for entry: L1' and L2 Conditions for entry: L1 and L2

## Complexity Analysis

Parameters:

N: Number of processes in the system

T: Message transmission time

E: Critical section execution time

▶ Message complexity: 3(N − 1)

ightharpoonup N-1 REQUEST messages + N-1 REPLY messages +

N-1 RELEASE messages

- ▶ Message-size complexity: O(1)
- Response time (under light load): 2T + E
- Synchronization delay (under heavy load): T

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## Inefficiencies in Lamport's Algorithm

- Scenario 1: Assume  $P_i$  and  $P_j$  concurrently generate requests for critical section and  $P_i$ 's request has smaller timestamp than  $P_j$ 's request.
  - ▶ Lamport's algorithm behavior:  $P_i$  first sends a REPLY message to  $P_j$  and later sends a RELEASE message to  $P_j$ .  $P_j$  enters its critical section only after it has received the RELEASE message from  $P_i$ .
  - ▶ Improvement:  $P_i$ 's REPLY message can be omitted.
- Scenario 2: P<sub>i</sub> generates a request for critical section but P<sub>j</sub> does not generate any request for some time.
  - ▶ Lamport's algorithm behavior: *P<sub>i</sub>* sends a RELEASE message to *P<sub>i</sub>* on leaving the critical section.
  - ▶ Improvement: If  $P_j$  generates a critical section request in the future, it will anyway contact  $P_i$  via a REQUEST message. So, there is no need for  $P_i$  to send a RELEASE message to  $P_j$ .

#### The Main Idea

Combine REPLY and RELEASE messages.

On leaving the critical section, only send a REPLY/RELEASE message to those processes that have unfulfilled requests for critical section.

Eliminate priority queue.

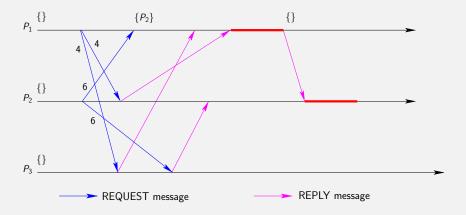
# Steps for Process $P_i$

- On generating a critical section request:
  - Broadcast the request to all processes.
- On receiving a critical section request from another process:
  - Send a REPLY message to the requesting process if:
    - P<sub>i</sub> has no unfulfilled request of its own, or
    - P<sub>i</sub>'s unfulfilled request has larger timestamp than that of the received request.

Otherwise, defer sending the REPLY message.

- Condition for critical section entry:
  - P<sub>i</sub> has received a REPLY message from all processes.
- On leaving the critical section:
  - Send all deferred REPLY messages.

## An Illustration



# Ricart and Agrawala's Algorithm: Complexity Analysis

Parameters:

N: Number of processes in the system

T: Message transmission time

E: Critical section execution time

▶ Message complexity: 2(N-1)

ightharpoonup N-1 REQUEST messages +N-1 REPLY messages

• Message-size complexity: O(1)

Response time (under light load): 2T + E

Synchronization delay (under heavy load): T

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## Inefficiency in Ricart and Agrawala's Algorithm

Every process handles every critical section request.

- Objective: Modify the algorithm such that only those processes that are "actively" generating critical section requests are involved in conflict resolution.
  - Processes that do not generate any requests for a long time eventually stop receiving and sending mutual exclusion messages until the time they generate requests.

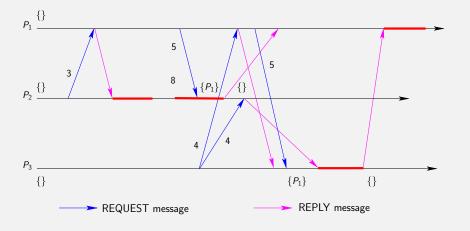
#### The Main Idea

- ▶ When  $P_j$  sends a REPLY message to  $P_i$ , it means that  $P_j$  is granting permission to  $P_i$  to execute its critical section.
- P<sub>i</sub> continues to have this permission from P<sub>j</sub> until the time P<sub>i</sub> sends a REPLY message to P<sub>j</sub>.
- Modification to Ricart and Agrawala's Algorithm:
  - To execute its critical section, P<sub>i</sub> needs to ask for permission from another process, say P<sub>j</sub>, if:
    - P<sub>i</sub> has sent a REPLY message to P<sub>j</sub> but
    - $ightharpoonup P_i$  has not received a REPLY message from  $P_j$  since then.

#### OR

▶ It is  $P_i$ 's first request and i > j.

## An Illustration



## Complexity Analysis

Parameters:

N: Number of processes in the system

T: Message transmission time

E: Critical section execution time

Message complexity:

▶ Best case: 0

▶ Worst case: 2(N-1)

ightharpoonup N-1 REQUEST messages + N-1 REPLY messages

- ▶ Message-size complexity: O(1)
- Response time (under light load):

▶ Best case: *E* 

• Worst case: 2T + E

Synchronization delay (under heavy load): T

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#### The Main Idea

- Each process is associated with a subset of processes referred to as its quorum.
- ▶ A process multicasts its request for critical section only to its quorum members.
- Each quorum member behaves like a coordinator in the centralized algorithm.
  - It grants permission to enter critical section to only one request at a time.
- ▶ A process enters its critical section once it has received permission to enter from all its quorum members.

## Achieving Mutual Exclusion

- ► How do we ensure that at most one process is executing its critical section at any time?
  - It is necessary and sufficient to ensure the following intersection property:
    - Quorums of any two processes have at least one process in common.

Algorithm described so far is prone to deadlocks.

#### An Illustration of Deadlock

- ▶ Three processes:  $P_1$ ,  $P_2$  and  $P_3$ 
  - Quorum of  $P_1 = \{Q_1, Q_2\}$
  - Quorum of  $P_2 = \{Q_2, Q_3\}$
  - Quorum of  $P_3 = \{Q_3, Q_1\}$
- ▶ All three processes concurrently generate requests for critical section:
  - $Q_1$  queues  $P_2$ 's request and grants permission to  $P_1$ 's request.
  - ▶  $Q_2$  queues  $P_3$ 's request and grants permission to  $P_2$ 's request.
  - ▶  $Q_3$  queues  $P_1$ 's request and grants permission to  $P_3$ 's request.

No process is able to enter the critical section and, moreover, the condition persists forever.

## Achieving Starvation Freedom

- Uses pre-emption to avoid deadlocks.
  - Quorum members can be viewed as resources that can only be held in mutually exclusive manner.
  - ▶ When a quorum member Q grants a process P permission to enter critical section, it means that P has locked Q.
- Processes implement Lamport logical clock.
- Request are assigned timestamps using the logical clock.
- ► Each quorum member maintains a priority queue of still unfulfilled requests it knows so far.

# Achieving Starvation Freedom (Contd.)

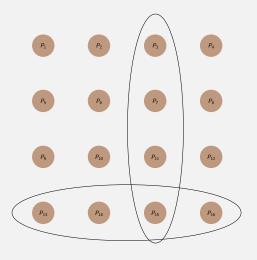
- Suppose a quorum member Q has granted P<sub>i</sub> permission to enter its critical section. It then receives a request from P<sub>j</sub>.
  - ▶ Case 1:  $P_i$ 's request has smaller timestamp than  $P_i$ 's request.
    - Q sends a FAILED message to P<sub>j</sub> informing P<sub>j</sub> that its request cannot be immediately satisfied.
  - ► Case 2:  $P_i$ 's request has larger timestamp than  $P_j$ 's request.
    - ightharpoonup Q sends an INQUIRE message to  $P_i$ .
    - On receiving the INQUIRE message, P<sub>i</sub> relinquishes its lock on Q if P<sub>i</sub> has received a FAILED message from another quorum member.

## Constructing Quorums

How to construct quorums of small size that distribute the load uniformly?

- Use grid quorum system:
  - Arrange processes in a square grid.
  - Quorum of a process = all processes in its row + all processes in its column.
  - ▶ Size of a quorum  $\approx 2\sqrt{N} 1$ .
    - N: Number of processes in the system

## An Illustration of Grid Quorum System



Sixteen processes;  $P_1$ ,  $P_2$ , ...,  $P_{16}$ 

# Complexity Analysis

Parameters:

*N*: Number of processes in the system

T: Message transmission time

E: Critical section execution time

S: Maximum quorum size

Message complexity: 7S

▶ At most 2*S* GRANT messages.

 $\blacktriangleright$  All other messages are bounded by S each.

▶ Message-size complexity: *O*(1)

Response time (under light load): 2T + E

 Synchronization delay (under heavy load): 2T (ignoring deadlock avoidance messages) Centralized Algorithm

Permission Based Algorithms

Quorum Based Algorithms

Token Based Algorithms

#### General Idea

▶ Token based algorithms use a special entity called token.

There is exactly one token in the system.

A process can execute its critical section only if it is holding the token.

► Token has to move around to prevent starvation.

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#### The Main Idea

Processes are arranged in a tree topology.

- Each process maintains a variable that points in the direction of the token.
  - Basically, the variable contains the identifier of the neighbor that has to be contacted in order to reach the token.

Each process also maintains a FIFO queue of still unfulfilled requests for token that it has seen so far.

# Steps for Process $P_i$

- On generating a critical section request:
  - If have the token, then enter the critical section. Otherwise:
    - Insert the request into the queue.
    - Send a request for token towards the token holder.
- On receiving a request for token from a neighbor:
  - ▶ If have the token and the token is idle, then send the token to the neighbor.
  - ▶ If have the token and the token is in use, then insert the request into the queue.
  - ▶ If do not have the token, then:
    - Insert the request into the queue.
    - If the queue was empty before, then send a request for token towards the token holder.

# Steps for Process $P_i$ (Contd.)

- On receiving the token:
  - Remove the first entry from the queue.
  - If the entry belongs to a neighbor, then send the token to the neighbor.

Otherwise, enter the critical section.

- On leaving the critical section:
  - ▶ If the queue is non-empty, then:
    - Remove the first entry from the queue (should belong to a neighbor).
    - ▶ Send the token to the requesting neighbor.
    - If the queue is still non-empty, send request for token to the neighbor to which the token was sent.

# Complexity Analysis

Parameters:

*N*: Number of processes in the system

T: Message transmission time

E: Critical section execution time

D: Diameter of the tree

Message complexity:

▶ Best case: 0

▶ Worst case: 2D

▶ D REQUEST messages + D TOKEN messages

▶ Message-size complexity: O(1)

Response time (under light load):

▶ Best case: *E* 

▶ Worst case:  $2D \times T + E$ 

▶ Synchronization delay (under heavy load): D × T