

BFS

$O(V+E)$

Procedure $bfs(G, s)$

Input: Graph $G = (V, E)$, directed or undirected; vertex $s \in V$

Output: For all vertices u reachable from s , $dist(u)$ is set to the distance from s to u .

for all $u \in V$:

} initialization

$dist(u) = \infty$

$dist(s) = 0$

$Q = [s]$ # Q is a queue containing s

while Q is not empty:

$u = \text{eject}(Q)$

for all edges $(u, v) \in E$:

if $dist(v) = \infty$:

} $dist(v) = dist(u) + 1$

Master theorem

$$T(n) = aT(\lceil n/b \rceil) + O(n^d)$$

$$T(n) = \begin{cases} O(n^d) & \text{if } d > \log_b a \\ O(n^d \log n) & \text{if } d = \log_b a \\ O(n^{\log_b a}) & \text{if } d < \log_b a \end{cases}$$

Asymptotic linear function

$$\frac{T(n)}{n} \rightarrow \begin{cases} \infty & T \in \omega(n), T \gg n \\ \text{constant} & T \in \Theta(n), T = n \\ 0 & T \in o(n), T \ll n \end{cases}$$

$$\begin{array}{lll} T \in O(f) & T \in \Theta(f) & T \in \Omega(f) \\ T \leq f & T = f & T \geq f \end{array}$$

$a = \# \text{ of branching}$

$b = \text{is reduced size of input at each step}$

$d = \text{exponent of complexity of the merge/combine step}$

DFS $O(V+E)$

Procedure $dfs(G)$

for all $v \in V$:

$\text{visited}(v) = \text{false}$

for all $v \in V$:

if not visited: $\text{explore}(v)$

Procedure $\text{explore}(G, v)$:

Input: $G = (V, E)$ is a graph; $V \in V$

Output: $\text{visited}(u)$ is a set to true for all nodes u reachable from v

$\text{visited}(v) = \text{true}$

$\text{previsit}(v)$

for each edge $(v, u) \in E$:

if not $\text{visited}(u)$: $\text{explore}(u)$

$\text{postvisit}(v)$

Dijkstra shortest path $O(V^2)$ use vector, $O((V+E)\log V)$ use a queue

Input: Graph $G = (V, E)$, directed or undirected; positive edge lengths $\{l_e : e \in E\}$
vertex $s \in V$

Output: For all vertices u reachable from s , $dist(u)$ is set to the distance from s to u

for all $u \in V$:

$dist(u) = \infty$

$\text{prev}(u) = \text{nil}$

$dist(s) = 0$

H=make queue(V) # Vector or queue
while H is not empty:
 $u = \text{deletmin}(H)$
for all edges $(u, v) \in E$:
if $dist(v) > dist(u) + l(u, v)$:
 $dist(v) = dist(u) + l(u, v)$
 $\text{prev}(v) = u$
 $\text{decreasekey}(H, v)$

Bellman Ford $O(V \cdot E)$ Resulting path is not negative

procedure $\text{shortest-paths}(G, l, s)$

Input: Directed graph $G = (V, E)$;

edge lengths $\{l_e : e \in E\}$ with no negative cycles;

vertex $s \in V$

Output: For all vertices u reachable from s , $dist(u)$ is set to the distance from s to u .

for all $u \in V$:

$dist(u) = \infty$

$\text{prev}(u) = \text{nil}$

$dist(s) = 0$

repeat $|V| - 1$ times:

for all $e \in E$:

$\text{update}(e)$

procedure $\text{dag-shortest-paths}(G, l, s)$

Input: Dag $G = (V, E)$;

edge lengths $\{l_e : e \in E\}$; vertex $s \in V$

Output: For all vertices u reachable from s , $dist(u)$ is set to the distance from s to u .

for all $u \in V$:

$dist(u) = \infty$

$\text{prev}(u) = \text{nil}$

$dist(s) = 0$

Linearize G

for each $u \in V$, in linearized order:

for all edges $(u, v) \in E$:

$\text{update}(u, v)$

$O(?)$

Adjacency list look up time $O(|V|)$
worst case for dense graph

Divide and Conquer

```
function merge(x[1...k], y[1...l])
    if k = 0: return y[1...l]
    if l = 0: return x[1...k]
    if x[1] ≤ y[1]:
        return x[1] ∘ merge(x[2...k], y[1...l])
    else:
        return y[1] ∘ merge(x[1...k], y[2...l])
```

```
function iterative-mergesort(a[1...n])
    Input: elements  $a_1, a_2, \dots, a_n$  to be sorted
```

```
Q = [] (empty queue)
for i = 1 to n:
    inject(Q,  $a_i$ )
while |Q| > 1:
    inject(Q, merge(eject(Q), eject(Q)))
return eject(Q)
```

Finds numbers using divide and conquer

```
def random_number(arr, k):
    if len(arr) == 1:
        return arr[0]
    if len(arr) == 2:
        if k == 0:
            return min(arr)
        else:
            return max(arr)
    if len(arr) == 0:
        print("Error: empty array")
        return 0
    rand = arr[random.randint(0, len(arr)-1)]
    s1 = []
    s2 = []
    s3 = []
    for i in range(len(arr)):
        if arr[i] < rand:
            s1.append(arr[i])
        elif arr[i] == rand:
            s2.append(arr[i])
        else:
            s3.append(arr[i])
    if k < len(s1):
        return random_number(s1, k)
    elif k < len(s1) + len(s2):
        return rand
    else:
        return random_number(s3, k - len(s1) - len(s2))
```

Asymptotic linear function

$$\frac{T(n)}{n} \rightarrow \begin{cases} \infty & T \in \omega(n), T \gg n \\ \text{constant} & T \in \Theta(n), T = n \\ 0 & T \in o(n), T \ll n \end{cases}$$

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Sparse Graph:

$|E|$ is very close to $|V|$

Dense Graph:

$|E|$ is very close to $O(|V|^2)$

Complete graph:

$$|E| = \frac{n(n-1)}{2}$$

Chord: An edge that connects a pair of vertices in a cycle, but is not actually in a cycle.

Induced cycles contains no chords

Induced subgraphs needs to contain all the edges, except the ones connected to a removed node

Simple cycles!

A cycle that is broken down to its most simple form

A cycle in a graph that has no repeat vertices

Edge Disjoint Path

Disjoint sub graphs

Do not share common vertices or edges

It can be Edge or vertices disjoint path

Spanning tree:

A subgraph that contains all the vertices and only remove edges, such that the graph is a tree.

procedure $\text{previsit}(v)$

$\text{pre}[v] = \text{clock}$

$\text{clock} = \text{clock} + 1$

procedure $\text{postvisit}(v)$

$\text{post}[v] = \text{clock}$

$\text{clock} = \text{clock} + 1$

Dijkstra's algorithm

Binary heap implementation preferable use when

$$|E| < \frac{|V|^2}{\log(|V|)}$$

Binary Heap $\mathcal{O}(|V| + |E|) \log(|V|)$

```

function makeheap(S)
    h = empty array of size |S|
    for x ∈ S:
        h[|h| + 1] = x
    for i = |S| down to 1:
        siftdown(h, h[i], i)
    return h

procedure bubbleup(h, x, i)
    (place element x in position i of h, and let it bubble up)
    p = [i/2]
    while i ≠ 1 and key(h(p)) > key(x):
        h(i) = h(p); i = p; p = [i/2]
    h(i) = x

procedure siftdown(h, x, i)
    (place element x in position i of h, and let it sift down)
    c = minchild(h, i)
    while c ≠ 0 and key(h(c)) < key(x):
        h(i) = h(c); i = c; c = minchild(h, i)
    h(i) = x

```

Topological sort

```

function linearization(G)
Input: directed acyclic graph (DAG) G = (V, E)
Output: linearization of G

for all v in V: // O(|V|)
    in-degree(v) = 0

run DFS and for each edge (u, v): // O(|V| + |E|)
    increment in-degree(v) by 1

S = [] (empty queue of source vertices)

for all v in V: // O(|V|)
    if in-degree(v) is 0:
        add v to S

while S is not empty: // O(|V| + |E|)
    u = de-queue(S)
    print u
    for each edge (u, v):
        if in-degree(v) is 0:
            add v to S

```

DAG Properties:

- a directed graph has a cycle if and only if its DFS reveals a back edge.
- In a DAG, every edge leads to a vertex with a lower post number.
- Every DAG has at least one source and one sink.
- Every graph is a DAG of its SCC's

Kosaraju's SCC Algorithm

- 1.) Find the Transpose of graph G
- 2.) perform DFS on GT defining clock of each vertex
- 3.) perform DFS on G in order of decreasing post # from 1.)
 - each invocation finds one SCC

Algorithm 3: Checking if a Graph Is an Induced Subgraph of Another Graph

Data: $G_1 = (V_1, E_1)$ - the input graph with nodes V_1 and edges E_1 , $S \subseteq V$ - the inducing set of nodes
Result: $G_S = (S, E_S)$ - the subgraph of G induced by S
 $E_S \leftarrow \emptyset$
for $u \in S$ do
 for $v \in \text{ADJACENT-NODES}(u)$ do
 $E_S \leftarrow E_S \cup \{(u, v)\}$
 end
end
 $G_S \leftarrow (S, E_S)$
return G_S

Algorithm 3: Checking if a Graph Is an Induced Subgraph of Another Graph

Data: $G_1 = (V_1, E_1)$ - the input graph with nodes V_1 and edges E_1 , $G_2 = (V_2, E_2)$ - a graph of nodes in V_1 (so $V_2 \subseteq V_1$, but not necessarily $E_2 \subseteq E_1$)
Result: true, if G_2 is an induced subgraph of G_1 ; false, otherwise

// First check if G_2 is a subgraph of G_1
for $(u, v) \in E_2$ do
 if $(u, v) \notin E_1$ then
 return false
 end
end
// If yes, check if it's induced by V_2
for $u \in V_2$ do
 // check all the nodes adjacent to u in G_1
 for $v \in \text{ADJACENT-NODES}(u)$ do
 if $(u, v) \notin E_2$ then
 return false
 end
 end
end
return true

Rendered by Qu

Algorithm 1: Constructing an Induced Subgraph

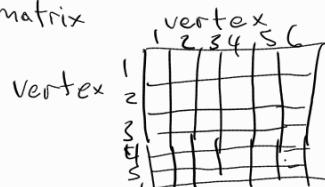
Data: $G = (V, E)$ - the input graph with nodes V and edges E , $S \subseteq V$ - the inducing set of nodes
Result: $G_S = (S, E_S)$ - the subgraph of G induced by S
 $E_S \leftarrow \emptyset$
for $u \in S$ do
 for $v \in \text{ADJACENT-NODES}(u)$ do
 $E_S \leftarrow E_S \cup \{(u, v)\}$
 end
end
 $G_S \leftarrow (S, E_S)$
return G_S

Algorithm 2: Checking if a Subgraph Is Induced

Data: $G_1 = (V_1, E_1)$ - the input graph with nodes V_1 and edges E_1 , $G_2 = (V_2, E_2)$ - a subgraph of G_1 ($V_2 \subseteq V_1$ and $E_2 \subseteq E_1$)
Result: true, if G_2 is an induced subgraph; false, otherwise

for $u \in V_2$ do
 // check all the nodes adjacent to u in G_1
 for $v \in \text{ADJACENT-NODES}(u)$ do
 if $(u, v) \notin E_2$ then
 return false
 end
 end
end
return true

Adjacency matrix



$$G(V, E) = (\{\text{set of vertices}\}, \{\text{set of edges}\})$$

SUMS – COMMON SUMS

Prove using induction...!

Common Sums. Prove these sums by induction on n . Please do it!		
1. $\sum_{i=k}^n 1 = n + 1 - k$	4. $\sum_{i=1}^n i = n(n+1)/2$	7. $\sum_{i=0}^n 2^i = 2^{n+1} - 1$
2. $\sum_{i=1}^n f(x) = nf(x)$	5. $\sum_{i=1}^n i^2 = n(n+1)(2n+1)/6$	8. $\sum_{i=0}^n \frac{1}{2^i} = 2 - \frac{1}{2^n}$
3. $\sum_{i=0}^n r^i = \frac{1-r^{n+1}}{1-r}$ ($r \neq 1$)	6. $\sum_{i=1}^n i^3 = n^2(n+1)^2/4$	9. $\sum_{i=1}^n \log i = \log n!$

