team11 final project report

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Implement

1. IVF_SQ8_DIRECT

系統架構:參考PASE的IVF_FLAT以及VanillaDB既有的Index寫法(例如 HashIndex、IndexSelectPlan、ConstantRange、SearchKey、executeTrainIndex等等),不一樣的地方例如我們不用meta page(而是只從 vanilladb.properties取得)、我們的centroid page使用spanned record、我們的 data page包含原table所有的field(原來只包含key跟record id;這樣在搜尋資料的時候比較連續,可以降低I/O的次數)。我們另外實作了InsertionSortPlan,在知道KNN的K很小的情形下,不需要在disk上跑merge sort才能知道前K名是誰。 SQ8_DIRECT: 我們發現sift.txt裡面都是介於0~218的整數,所以應該可以做適當的quantization。我們一度以為直接用8個bit來存是作弊,但我們後來發現Faiss根本也有類似的東西:

換句話說,我們可以在完全不犧牲recall的情形下,進一步降低I/O的次數。所以, 我們新增了ByteVector相關的type跟method,來符合我們的要求。我們只有 quantize存在data page的vector, centroid vector一樣是用float來存。

2. Kmeans: 首先使用來RandomNonRepeatGenerator來從0~899999選不重複的數字

```
RandomNonRepeatGenerator RNRG = new RandomNonRepeatGenerator(SiftBenchConstants.NUM_ITEMS);

Map<Integer, Integer> M = new HashMap<>();

for (int i = 0; i < IVFFlatIndex.NUM_CENTROIDS; ++i){

int random_number = RNRG.next();

M.put(random_number,i);

}
```

接著掃過table, 如果遇到剛剛選到的點, 就把他設為一個cluster的中心

```
Plan test_tp = new TablePlan(tableName, tx);

Scan test_ts = test_tp.open();

test_ts.beforeFirst();

while(test_ts.next()){

int index = (Integer)test_ts.getVal(fldName:"i_id").asJavaVal();

if(M.containsKey(index)){

VectorConstant v = new VectorConstant((float[])test_ts.getVal(fldName:"i_emb").asJavaVal());

idx.setCentroidVector(M.get(index), v);

}

test_ts.close();
```

接著refine剛剛選到的中心iteration次,每次refine都會掃過整個table一次

```
// TODO: refine the centroids by K-means. It is recommended to log each iteration
int iteration = 2;

for (int i = 0; i < iteration; i++){
    System.err.print("Iteration " + i + "\n");
    Plan tp = new TablePlan(tableName, tx);
    Scan ts = tp.open();</pre>
```

3. SIMD

我們使用了sub、fma來計算Euclidean distance, 其中針對除以 SPECIES.length()的餘數部分再計算一次差平方做加總, 最後開根號並回傳

```
@Override
protected double calculateDistance(VectorConstant vec) {
    int i = 0;
    FloatVector sum = FloatVector.zero(SPECIES);
    for (; i < SPECIES.loopBound(vec.dimension()); i += SPECIES.length()) {
        FloatVector v = FloatVector.fromArray(SPECIES, vec.asJavaVal(), i);
        FloatVector q = FloatVector.fromArray(SPECIES, query.asJavaVal(), i);
        FloatVector diff = v.sub(q);
        sum = diff.fma(diff, sum);
    }
    double sum_d = sum.reduceLanes(VectorOperators.ADD);

for (i=0 ; i < vec.dimension(); i++) {
        double diff = query.get(i) - vec.get(i);
        sum_d += diff * diff;
    }
    return Math.sqrt(sum_d);
}</pre>
```

Other improvement

1. 我們發現public VectorConstant(byte[] bytes)是CPU效能瓶頸, 如下圖。我們一度想把這個constructor也SIMD化, 但後來發現用java.nio優化比較好。

```
Top methods over 60013 ms (0 ms paused), with 26653 counts:
     Rank
             Self
                    Stack
                            Method
         21% 21% org.vanilladb.core.sql.VectorConstant.<init>
29
         11% 11% org.vanilladb.core.storage.file.io.javanio.JavaNioFileChannel.write
         9% 9% org.vanilladb.core.storage.file.io.javanio.JavaNioFileChannel.append
        6% 6% org.vanilladb.core.storage.file.io.javanio.JavaNioFileChannel.<init>
        5% 19% org.vanilladb.core.storage.buffer.BufferMgr.pin
         3% 3% org.vanilladb.core.sql.VectorConstant.asBytes
         3% 4% org.vanilladb.core.storage.tx.concurrency.LockTable.sLock
         2% 27% org.vanilladb.core.storage.file.Page.getVal
     8
         2% 4% org.vanilladb.core.storage.tx.concurrency.LockTable.isLock
     10 2% 24% org.vanilladb.core.sql.Constant.newInstance
     11 2% 2% org.vanilladb.core.storage.tx.concurrency.LockTable.releaseLock
     12 2% 2% org.vanilladb.core.storage.file.io.javanio.JavaNioFileChannel.read
    13 1% 1% org.vanilladb.core.storage.tx.concurrency.LockTable.getAnchor
    14 1% 1% org.vanilladb.core.storage.file.io.javanio.JavaNioFileChannel.close
    15 1% 3% org.vanilladb.core.storage.file.FileMgr.delete
        1% 1% org.vanilladb.core.storage.record.RecordPage.close
     16
    16 1% 19% org.vanilladb.core.storage.record.RecordPage.<init>
    17 1% 1% org.vanilladb.core.storage.tx.concurrency.LockTable.prepareLockers
```

- 2. 我們一度想要讓尋找最接近的centroid這個操作在多個thread上跑,因為它是" CPU"效能瓶頸之一。結果因為實作寫得不好,不小心pin了太多buffer,只好作 罷。
- 3. 在原版Kmean做refine的時候,我們一開始是掃過整個table才更新一次centroid ,但這樣更新一次要快將近20分鐘,centriod更新效率不高。因此,我們做了簡單 的優化,做法是每掃10000個record就更新一次centroid,這樣只需掃一次table 就能更新90次centroid。

Experiments

Environment:

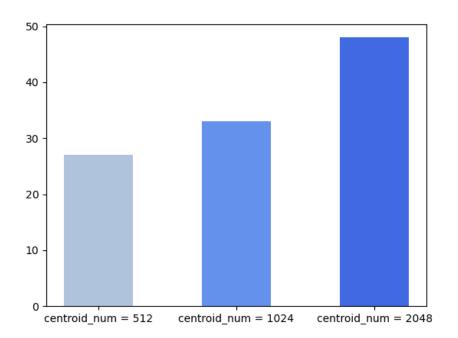
Intel Core i5-6400 CPU @ 2.7GHz, 16 GB RAM, 224 GB SSD, Windows 11

Different centroid num (probe bucket = 8)

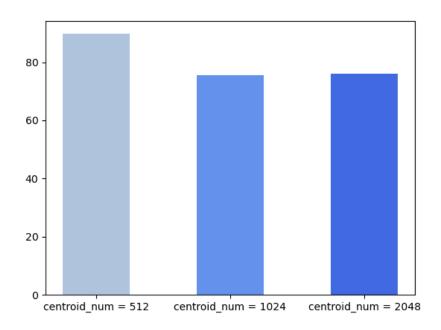
Results:

cen_num	512	1024	2048
commit	27	33	48
recall	89.77%	75.46%	75.95%

Graph(Committed):



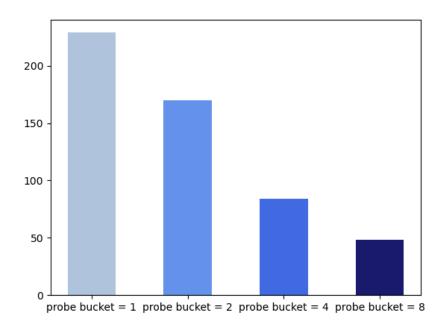
Graph(Recall):



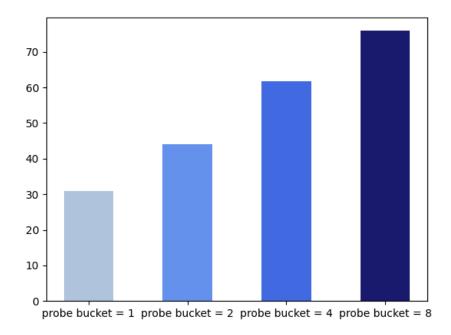
Different probe bucket (centroid_num = 2048) Result:

pro_bucket	1	2	4	8
commit	229	170	84	48
recall	30.94%	44.10%	61.72%	75.95%

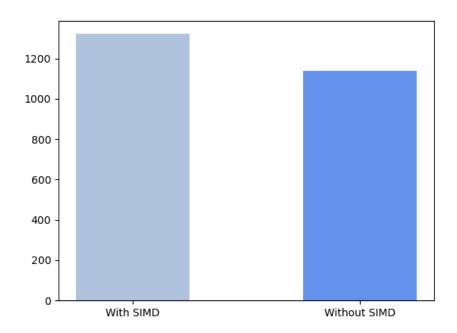
Graph(Committed):



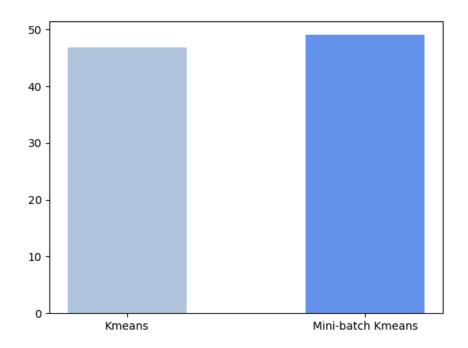
Graph(Recall):



With/Without SIMD (centroid_num = 512, probe bucket = 8)
Graph(Committed):



Kmeans/Mini-Batch Kmeans (centroid_num = 512, probe bucket = 8)
Graph(Recall):



Conclusion

1. For centroid_num

- a. centroid_num越低, recall就越高。因為當cluster切的越大塊, KNN搜索的 範圍就會越大, 找到實際最近的機率就會越高
- b. centroid_num越低, commited就越低。因為搜索範圍越大塊, 要接觸到的 vector就會越多
- 2. For probe bucket
 - a. probe bucket越高, recall就越高。因為找的cluster越多, 表示搜索範圍越大
 - b. probe bucket越高, commited就越低。因為搜索範圍越大塊, 要接觸到的 vector就會越多
- 3. 由實驗結果可以看出有做SIMD能有效增加commit的txn
- 4. Mini-Batch Kmeans之recall比Kmeans高3%左右, 這是因為Mini-Batch較頻繁更新centroid, 故其收斂較快