Statistics Learning Theory: VC-Dimension and Linear Predictor

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Introduction

In today's slide, we aim to introduce the followings:

- VC-dimension and the fundamental theorem of PAC learning(The proof will be introduced in the nex week)
- 2. Linear predictor and their VC-dimension

Motivation:Infinite-Size Classes

In the last week, we prove that finite classes are learnable. However, the infinite size classes may be learnable. Consider the following example.

Motivation: Example

Let \mathcal{H} be the set of threshold functions over the real line, namely, $\{h_a: a \in R\}$, where $h_a(x) = I_{[x < a]}$. Then \mathcal{H} is infinite, however it can be proved is learnable in the PAC model using the ERM algorithm.

VC-Dimension

The natural question arises: what is the sufficient conditions for

learnability?

Answer: VC-dimension

VC-dimension

Definition (Restriction of \mathcal{H} to C)

Let \mathcal{H} be a class of functions from X to $\{0,1\}$ and let $C = \{c_1, \cdots, c_m\} \subset X$. The restriction of \mathcal{H} to C is the set of functions from C to $\{0,1\}$ that can be derived from \mathcal{H} . That is,

$$\mathcal{H}_{C} = \{h(c_1), \cdots, h(c_m)\} : h \in \mathcal{H}\}$$

Definition (Shattering)

A hypothesis class $\mathcal H$ shatters a finite set $C\subset X$ if the restriction of $\mathcal H$ to C is the set of all functions from C to $\{0,1\}$. That is, $|\mathcal H_C|=2^{|C|}$

VC-dimension

Definition (VC-dimension)

The VC-dimension of a hypothesis class \mathcal{H} , denoted VCdim(\mathcal{H}), is the maximalsize of a set $C \subset X$ that can be shattered by \mathcal{H} . If \mathcal{H} can shatter sets of arbitraily large size we say that \mathcal{H} has infinite VC-dimension.

VC-dimension: No Free Lunch Theorm

By No Free Lunch Theorem, given a training sample S with size m, if there exists a shattered set of size 2m, then we can find a distribution $\mathcal D$ such that $L_{\mathcal D}(A(S)) \geq 1/8$ with probability at least 1/7

Therefore, we have the following theorem

Theorem

Let ${\cal H}$ be a class of infinite VC-dimension. Then, ${\cal H}$ is not PAC learnable

VC-dimension: Examples

To show that $VCdim(\mathcal{H}) = d$ we need to show that

- 1. There exists a set $\it C$ of size $\it d$ that is shattered by $\it H$
- 2. Every set C of size d+1 is not shattered by $\mathcal H$

Examples: Threshold Functions

 $C=\{c_1\}$, $\mathcal H$ shatters C, therefore, $VCdim(\mathcal H)\geq 1$. If an arbitrary set $C=\{c_1,c_2\}$ where $c_1\leq c_2$, $\mathcal H$ does not shatter C. $VCdim(\mathcal H)=1$

Examples:Intervals

Let \mathcal{H} be the class of intervals over R, namely, $\mathcal{H}=\{h_{a,b}: a,b\in R, a< b\}$, where $h_{a,b}: R\to \{0,1\}$ is a function such that $h_{a,b}(x)=1_{x\in (a,b)}$. If $C=\{1,2\}$. Then \mathcal{H} shatters C and therefore $VCdim(\mathcal{H})\geq 2$. However $C=\{c_1,c_2,c_3\}$. The labeling (1,0,1) cannot be obtained. $VCdim(\mathcal{H})=2$.

Eamples: Finite case

Let \mathcal{H} be finite case, then for any set C, we have $|\mathcal{H}_C| \leq |\mathcal{H}|$ Thus, C cannot be shattered if $|\mathcal{H}| < 2^{|C|}$, hence, $VCdim(\mathcal{H}) \leq \log_2(|\mathcal{H}|)$

The Fundamental Theorem of PAC learning

Theorem (The Fundamental Theorem of Statistical Learning)

Let $\mathcal H$ be a hypothesis class of functions from a domain X to $\{0,1\}$ and let the loss function be the 0-1 loss. Then, the following are equivalent:

- 1. \mathcal{H} has the uniform convergence property
- 2. Any ERM rule is a successful agnostic PAC learner for ${\cal H}$
- 3. H is agnostic PAC learnable
- 4. H is PAC learnable
- 5. Any ERM rule is a successful PAC learner for H
- 6. H has a finite VC-dimension

Remark:Reminding the quantitative Version, the proof idea:the growth rate of \mathcal{H}_C is ploynomial, by Hoeffding's inequality, the converge rate is exponentially with |C|

Linear predictor

The basic idea of linear predictor is to use the linear function to predict the target.

- 1. Classification: Logistic Regression
- 2. Regression: Linear regression

Linear predictor:hypothesis classes

$$L_d\{h_{w,b}: w \in R^d, b \in R\}$$

where

$$h_{w,b}(x) = \langle w, x \rangle + b = (\sum_{i=1}^d w_i x_i) + b$$

$$HS_d = sign \circ L_d = \{ sign(h_{w,b}(x)) : h_{w,b} \in L_d \}$$

Linear predictor:implementation of ERM rule

- 1. In the realizable case (PAC case), ERM rule can be solved efficient
- In the agnostic case, implementing the ERM rule is computationally hard(Ben-David & Simon 2001)
- 3. Due to the computation difficulty, the Logistic regression uses the surrogate loss function to learn a halfspace that does not necessarily minimize the empirical risk with the 0-1 loss.
- 4. In the following, we will introduce the two way to implement the ERM rule(relizable case), and prove the learnability of the algorithm.

Linear programs(LP) are problems that can be expressed as maximizing a linear function subject to linear inequalities. That is,

$$\max_{w \in R^d} \langle u, w \rangle$$

subject to

Linear programs can be solved efficiently, we will show that the ERM problem for halfspace in the relizable case can be expressed as a linear program.

Let $S = \{(x_i, y_i)\}_{i=1}^m$ be a training set of size m.

Since we assume the realizable case, an ERM predictor should have zero errors on the training set. That is we are looking some vector $w \in \mathbb{R}^d$ for which

$$sign(\langle w, x \rangle) = y_i$$

Equivalently

$$y_i\langle w, x\rangle > 0$$

Let w^* be a vector that satisfies this condition(existence is ensured by realizability assumption). Define $\gamma = \min_i (y_i \langle w^*, x_i \rangle)$ and $\bar{w} = \frac{w^*}{\gamma}$, then we have

$$y_i\langle \bar{w}, x_i \rangle = \frac{1}{\gamma} y_i \langle w^*, x_i \rangle \geq 1$$

Therefore, there exists a vector that satisfies

$$y_i\langle w, x_i\rangle \geq 1$$
 (1)

and clearly, such a vector is an ERM predictor.

To find a vector that satisfies equation 1 we can rely on an LP solver as follows. Set A to be the $m \times d$ matrix whose rows are the instances multiplied by y_i . That is, $A_{i,j} = y_i x_{i,j}$. Let v be the vector $(1, \dots, 1)inR^m$. Then the equation 1 can be rewritten as

$$Aw = \begin{bmatrix} y_1x_{1,1} & y_1x_{1,2} & \cdots & y_1x_{1,d} \\ \vdots & \vdots & \vdots & \vdots \\ y_mx_{m,1} & y_mx_{m,2} & \cdots & y_mx_{m,d} \end{bmatrix} \begin{bmatrix} w_1 \\ \vdots \\ w_d \end{bmatrix} \ge \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} = v$$

The LP form requires a maximization objective yet all the w that satisfy the constraints are equal candidates as output hypothesis. Thus, we set a dummy objective, $u = (0, \dots, 0) \in \mathbb{R}^d$

Implementation of ERM rule: Batch Preception

Algorithm 1: Batch Perceptron

```
Input : \leftarrow A training set(x_1, y_1), \cdots (x_m, y_m);

Initialize : \leftarrow w^{(1)} = (0, 0, \cdots, 0);

while \exists i \ s.t. \ y_i \langle w^{(t)}, x_i \rangle \leq 0 do
| \ w^{(t+1)} = w^{(t)} + y_i x_i;

end while
Output : w^{(t)}
```

Implementation of ERM rule: Batch Preception

Theorem

Assume that $(x_1, y_1), \dots, (x_m, y_m)$ is separable, let $B = \min\{|w| : \forall i \in [m], \ y_i \langle w, x_i \rangle \geq 1\}$ and let $R = \max_i |x_i|$. Then, the Preceptron algorithm stops after at most $(RB)^2$ iterations, and when it stops it holds that $\forall i \in [m], y_i \langle w^{(t)}, x_i \rangle > 0$

By the definition of the stopping condition, if the Perceptron stops it must have separated all the examples. We will show that if the Perceptron runs for T iterations, then we must have $T \leq (RB)^2$. Let w^* be a vector that achieves the minimum in the definition of B. That is, $y_i \langle w^*, x_i \rangle \geq 1$ for all i, and among all vectors that satisfy these constraints, w^* is of minimal norm.

We claim that

$$\frac{\langle w^*, w^{(T+1)} \rangle}{|w^*||w^{(T+1)}|} \ge \frac{\sqrt{T}}{RB}$$

by Cauchy-Schwartz inequality, it will imply that

$$1 \ge \frac{\sqrt{T}}{RB}$$

hence

$$T \leq (RB)^2$$

Therefore, we focus on proving the above inequality.

We first show that $\langle w^*, w^{(T+1)} \rangle \geq T$. For t=1, $w^{(1)}=(0,\cdots,0)$ holds, suppose that on iteration t, we have that

$$\langle w^*, w^{(t+1)} \rangle - \langle w^*, w^{(t)} \rangle = \langle w^*, w^{(t+1)} - w^{(t)} \rangle$$
$$= \langle w^*, y_i x_i \rangle = y_i \langle w^*, x_i \rangle$$
$$\geq 1$$

Therefore, after T iterations, we get

$$\langle w^*, w^{(T+1)} \rangle = \sum_{t=1}^{T} (\langle w^*, w^{(t+1)} \rangle - \langle w^*, w^{(t)} \rangle) \geq T$$
 (2)

Next, we upper bound $|w^{(T+1)}|$

$$|w^{(T+1)}|^2 = |w^{(t)} + y_i x_i|^2$$
$$|w^{(t)}|^2 + 2y_i \langle w^{(t)}, x_i \rangle + y_i^2 |x_i|^2$$
$$|w^{(t)}|^2 + R^2$$

Using above recursively for T iterations, we obtain that

$$|w^{(T+1)}|^2 \le TR^2 \to |w^{(T+1)}| \le \sqrt{T}R$$
 (3)

Combining equation 2 with equation 3, we have that

$$\frac{\langle w^*, w^{(T+1)} \rangle}{|w^*||w^{(T+1)}|} \ge \frac{T}{B\sqrt{T}R} = \frac{\sqrt{T}}{BR}$$

Halfspace: VC-dimension

Theorem

The VC-dimension of the class of homogenous halfspace in \mathbb{R}^d is d

Theorem

The VC-dimension of the class of nonhomogenous halfspace in \mathbb{R}^d is d+1