# SMART TRASH-BIN Engineering Clinics Project

## meet our team

DHYAN 20BCE7648 SCOPE VENKATA KARTHIK DRAKSHARAM 20BCN7028 SCOPE

KHUSHI SHARMA 20BCN7001 SCOPE ADUSUMILLI SERISHMA 20BES7039 SENSE

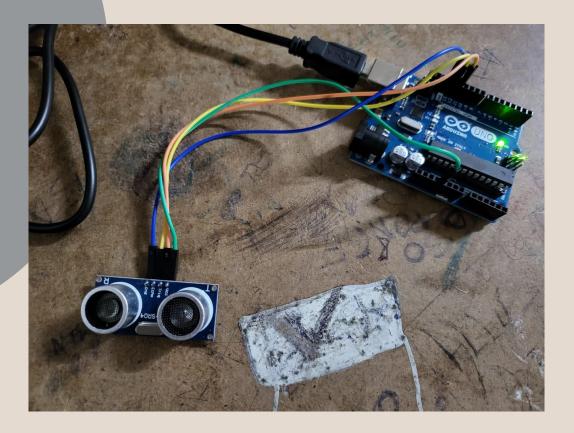
TWINKLE KUMARI 20BCN7023 SCOPE L SHANMUKHA SAI SRIVALLI 20BES7054 SENSE

## Working with Arduino

### Ultrasonic Sensor

### Output

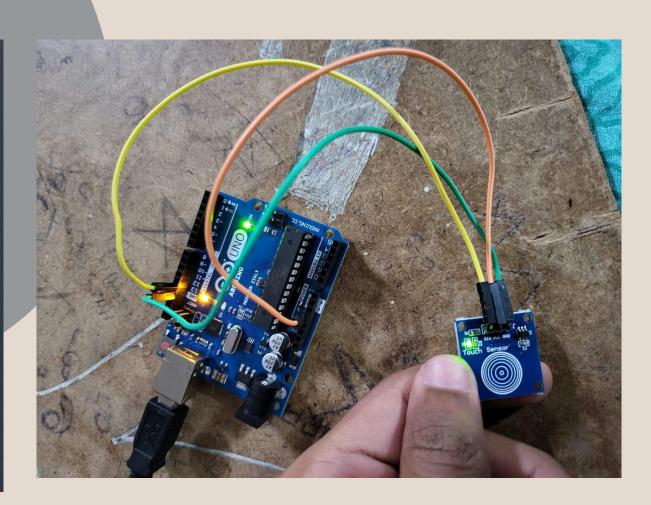
go	,~ <u> </u>	 					
2cm							
Sensor1	2cm						
Sensor1	2cm						
Sensor1	5cm						
Sensor1	251cm						
Sensor1	251cm						
Sensor1	251cm						
Sensor1							
Sensor1	251cm						
Sensor1	251cm						
Sensor1	251cm						A.
Sensor1	251cm						
Sensor1	251cm			•			
Sensor1	252cm						
Sensor1	250cm						
Sensor1	19cm						
Sensor1	15cm						
Sensor1	251cm						
Sensor1	251cm						
Sensor1	252cm						
Sensor1	254cm						
Sengar1	Acm						



### Touch Sensor(DRY WASTE)

### Output

Touch sensor activated Touch sensor activated



Moisture Sensor (WET WASTE)

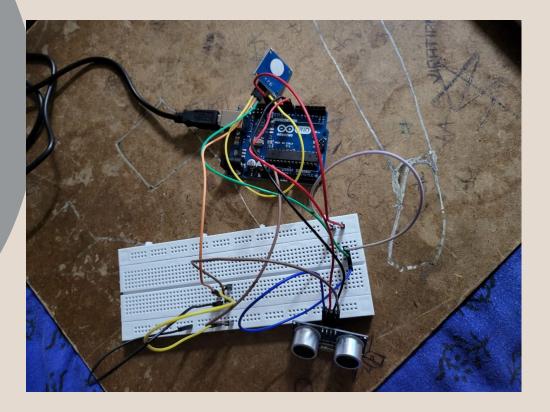
Output

```
Moisture Percentage = 43.01%
 Moisture Percentage = 43.50%
 Moisture Percentage = 42.13%
Moisture Percentage = 44.28%
Moisture Percentage = 43.40%
Partly cloudy
```

Activation of Touch Sensor when the user is within range

### Output

```
Sensor1 2cm
Sensorl 3cm
Touch sensor activated and inrange
Sensor1 2cm
Touch sensor activated and inrange
Sensorl 3cm
Touch sensor activated and inrange
Sensor1 3cm
Sensor1 3cm
Out of range
Sensor1 4cm
Sensor1 3cm
Out of range
Sensor1 4cm
Out of range
 Out of range
 26°C
```



Working of conveyor belt (Waste Segregation)

