

Introduction to Artificial Intelligence Exercise Sheet 7

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Due: April 27, 2022

## Exercise 7.1

- (a) Predicates: Properties of objects that we are interested in; can be true or false:
- Let  $B = \{Krämerbrücke, Schmiedbrücke, Honigbrücke, Holzbrücke, Grüne Brücke, Köttelbrücke, Hohe Brücke\}$  be the set of bridges.
- $V = \{crossedAtLeastOnce(b) | \forall b \in B\} \cup \{crossedAtMostOnce(b) | \forall b \in B\}$
- (b) Initial state (only predicates which are true are listed, because of closed-world assumption):
- $I = \bigwedge_{b \in B} \operatorname{crossedAtMostOnce}(b), \forall b \in B$
- (c) Goal state (both predicates have to be true in order to ensure that each Bridge is crossed exactly once):
- $G = \bigwedge_{b \in B} (crossedAtLeastOnce(b) \land crossedAtMostOnce(b)), \forall b \in B$
- (d) A is a finite set of actions  $a = \langle pre, eff \rangle$  with pre(a) and eff(a)  $A = \{crossFirstTime(b), crossAgain(b)\}, \forall b \in B$

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action a crossFirstTime(b):
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pre(crossFirstTime(b)) = \neg crossedAtLeastOnce(b) \land crossedAtMostOnce(b)
eff(crossFirstTime(b)) = crossedAtLeastOnce(b) \land crossedAtMostOnce(b)
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When the action crossFirstTime(b) is executed exactly once for every bridge the Goal state is reached.

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action crossAgain(b):

pre(crossAgain(b)) = crossedAtLeastOnce(b)

eff(crossAgain(b)) = crossedAtLeastOnce(b)
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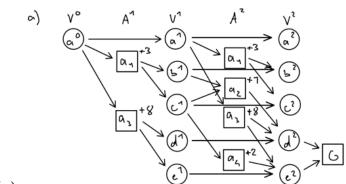
We can ignore crossedAtMostOnce in the action crossAgain(b) as its state is irrelevant for this action, i.e.  $crossedAtMostOnce \rightarrow false$  when crossing the same bridge numerous times.

The Goal state won't be reached when action crossAgain(b) is used.

## Exercise 7.2

- (a) Insert graph
- (b) Insert graph
- (c) PDB:
- $\{ \text{ loc} \to B, \text{ treasure } \to \bot \} = \infty$
- $\{ \text{ loc} \to A, \text{ treasure } \to \bot \} = \infty$
- $\{ \text{ loc} \to C, \text{ treasure} \to \bot \} = \infty$
- $\{ \text{ loc} \to A, \text{ treasure } \to \top \} = 2$
- $\{ \text{ loc} \to B, \text{ treasure } \to \top \} = 1$
- $\{ \text{ loc} \to C, \text{ treasure} \to \top \} = 0$

## Exercise 7.3



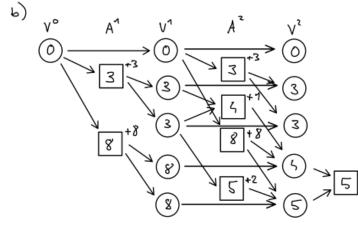
V1=V2, A1 ≠ A2 L> RPG did Not stabilize yet

question: Would we need to "add"

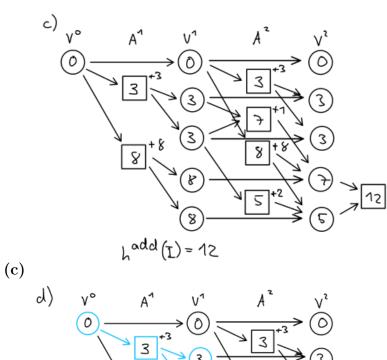
the goal mode 6 on

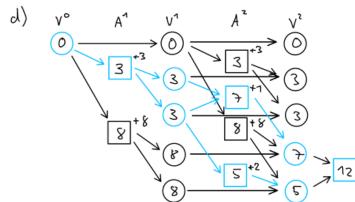
action layer A 100 ?

(a)



(b) \( \lambda\_{\max}(I) = 5 \ \ I = \{a\}





(d) 
$$h^{FF}(\Gamma) = 3+1+2 = 6$$