

7. Symmetric Matrices and Quadratic Forms

- 1) Diagonalization of Symmetric Matrices
- 2) Quadratic Forms
- 3) Singular Value Decomposition
- 4) Principal Component Analysis

1. Diagonalization of Symmetric Matrices

1) Symmetric matrix

(1) Definition : Symmetric matrix

A matrix A is symmetric if $A = A^T$

(2) Theorem

If A is symmetric, then any two eigenvectors from different eigenspaces are orthogonal

(3) Definition : Orthogonally diagonalizable

An $n \times n$ matrix A is said to be orthogonally diagonalizable if there are an orthogonal matrix P (with $P^{-1} = P^T$) and a diagonal matrix D such that

$$A = PDP^T = PDP^{-1}$$

(4) Theorem

An $n \times n$ matrix A is orthogonally diagonalizable if and only if A is symmetric matrix

2) Spectral Decomposition

(1) The Spectral Theorem for Symmetric Matrices

An $n \times n$ symmetric matrix A has the following properties

- ① A has n real eigenvalues, counting multiplicities.
- ② The dimension of the eigenspace for each eigenvalue λ equals the multiplicity of λ as a root of the characteristic equation.
- ③ The eigenspaces are mutually orthogonal, in the sense that eigenvectors corresponding to different eigenvalues are orthogonal.
- ④ A is orthogonally diagonalizable

(2) Spectral Decomposition

Suppose $A = PDP^{-1}$, where the columns of P are orthonormal eigenvectors $\mathbf{u}_1, \dots, \mathbf{u}_n$ of A and the corresponding eigenvalues $\lambda_1, \dots, \lambda_n$ are in the diagonal matrix D

$$A = PDP^T = \begin{bmatrix} \mathbf{u}_1 & \dots & \mathbf{u}_n \end{bmatrix} \begin{bmatrix} \lambda_1 & & 0 \\ & \dots & \\ 0 & & \lambda_n \end{bmatrix} \begin{bmatrix} \mathbf{u}_1^T \\ \dots \\ \mathbf{u}_n^T \end{bmatrix}$$

$$= \begin{bmatrix} \lambda_1 \mathbf{u}_1 & \dots & \lambda_n \mathbf{u}_n \end{bmatrix} \begin{bmatrix} \mathbf{u}_1^T \\ \dots \\ \mathbf{u}_n^T \end{bmatrix}$$

$$= \lambda_1 \mathbf{u}_1 \mathbf{u}_1^T + \dots + \lambda_n \mathbf{u}_n \mathbf{u}_n^T \quad \dots \quad \textcircled{1}$$

: Spectral decomposition of A

Each term in $\textcircled{1}$ is an $n \times n$ matrix of rank 1

Each matrix $\mathbf{u}_j \mathbf{u}_j^T$ is a projection matrix in the sense that for each \mathbf{x} in \mathbb{R}^n , the vector $(\mathbf{u}_j \mathbf{u}_j^T) \mathbf{x}$ is the orthogonal projection of \mathbf{x} onto the subspace spanned by \mathbf{u}_j

(Theorem : If $\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ is an orthonormal basis for a subspace W of \mathbb{R}^n , then

$$\text{proj}_W \mathbf{y} = UU^T \mathbf{y}, \text{ where } U = \begin{bmatrix} \mathbf{u}_1 & \mathbf{u}_2 & \dots & \mathbf{u}_p \end{bmatrix})$$

$$\text{ex) } A = \begin{bmatrix} 7 & 2 \\ 2 & 4 \end{bmatrix} = \begin{bmatrix} \frac{2}{\sqrt{5}} & \frac{-1}{\sqrt{5}} \\ \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \end{bmatrix} \begin{bmatrix} 8 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{2}} \\ \frac{-1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \end{bmatrix}$$

2. Quadratic Form

1) Quadratic Form

(1) Definition : Quadratic Form

A quadratic form on \mathbb{R}^n is a function Q defined on \mathbb{R}^n whose value at a vector \mathbf{x} in \mathbb{R}^n can be computed by an expression of the form $Q(\mathbf{x}) = \mathbf{x}^T A \mathbf{x}$, where A is an $n \times n$ symmetric matrix.

The matrix A is called the matrix of the quadratic form

ex) $Q(\mathbf{x}) = \mathbf{x}^T I \mathbf{x} = \|\mathbf{x}\|^2$

ex) $\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$, $A = \begin{bmatrix} 4 & 0 \\ 0 & 3 \end{bmatrix}$, $B = \begin{bmatrix} 3 & -2 \\ -2 & 7 \end{bmatrix}$

ex) $Q(x) = 5x_1^2 + 3x_2^2 + 2x_3^2 - x_1x_2 + 8x_2x_3$

(2) Change of Variable in a Quadratic Form

If \mathbf{x} represents a variable vector in \mathbb{R}^n , then a change of variable is an equation of the form

$$\mathbf{x} = P\mathbf{y}, \text{ or } \mathbf{y} = P^{-1}\mathbf{x} \dots \textcircled{1}$$

where P is an invertible matrix and \mathbf{y} is a new variable vector in \mathbb{R}^n

\mathbf{y} : the coordinate vector of \mathbf{x} relative to the basis of \mathbb{R}^n determined by the columns of P

If the change of variable $\textcircled{1}$ is made in a quadratic form $\mathbf{x}^T A \mathbf{x}$, then,

$$\mathbf{x}^T A \mathbf{x} = (P\mathbf{y})^T A (P\mathbf{y}) = \mathbf{y}^T P^T A P \mathbf{y} = \mathbf{y}^T (P^T A P) \mathbf{y} \dots \textcircled{2}$$

and the new matrix of the quadratic form is $P^T A P$

Since A is symmetric, there is an orthogonal matrix P such that $P^T A P$ is a diagonal matrix D , and the quadratic form in $\textcircled{2}$ becomes $\mathbf{y}^T D \mathbf{y}$

(3) Theorem : Principal Axes Theorem

Let A be an $n \times n$ symmetric matrix. Then there is an orthogonal change of variable, $\mathbf{x} = P\mathbf{y}$, that transforms the quadratic form $\mathbf{x}^T A \mathbf{x}$ into the quadratic form $\mathbf{y}^T D \mathbf{y}$ with no cross-product term.

The columns of P are called the principal axes of the quadratic form $\mathbf{x}^T A \mathbf{x}$

The vector \mathbf{y} is the coordinate vector of \mathbf{x} relative to the orthonormal basis of \mathbb{R}^n given by these principal axes.

ex) $Q(\mathbf{x}) = x_1^2 - 8x_1x_2 - 5x_2^2$

2) Classifying Quadratic Forms

(1) Classifying Quadratic Forms

When A is an $n \times n$ matrix, the quadratic form $Q(\mathbf{x}) = \mathbf{x}^T A \mathbf{x}$ is a real-valued function with domain \mathbb{R}^n

A quadratic form Q is

- ① positive definite if $Q(\mathbf{x}) > 0$ for all $\mathbf{x} \neq 0$
- ② positive semidefinite if $Q(\mathbf{x}) \geq 0$ for all $\mathbf{x} \neq 0$
- ③ negative definite if $Q(\mathbf{x}) < 0$ for all $\mathbf{x} \neq 0$
- ④ negative semidefinite if $Q(\mathbf{x}) \leq 0$ for all $\mathbf{x} \neq 0$
- ⑤ indefinite if $Q(\mathbf{x})$ assumes both positive and negative values

(2) Theorem : Quadratic Forms and Eigenvalues

Let A be an $n \times n$ symmetric matrix. Then a quadratic form $\mathbf{x}^T A \mathbf{x}$ is

- ① positive definite if and only if the eigenvalues of A are all positive
- ② negative definite if and only if the eigenvalues of A are all negative
- ③ indefinite if and only if A has both positive and negative eigenvalues

ex) $Q(\mathbf{x}) = 3x_1^2 + 2x_2^2 + x_3^2 + 4x_1x_2 + 4x_2x_3$

3. Singular value decomposition

1) Singular Value

(1) Purpose of singular value

(2) Singular value

Let A be $m \times n$ matrix. the singular values of A are the square root of the eigenvalues of $A^T A$, denoted by $\sigma_1, \dots, \sigma_n$, and they are arranged in decreasing order.

$\sigma_i = \sqrt{\lambda_i}$ for $i = 1, \dots, n$, where λ_i is the i th eigenvalue of $A^T A$

(3) Theorem

Suppose $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ is an orthonormal basis of \mathbb{R}^n consisting of eigenvectors of $A^T A$, arranged so that the corresponding eigenvalues of $A^T A$ satisfy $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n$, and suppose A has r nonzero singular values. Then $\{A\mathbf{v}_1, \dots, A\mathbf{v}_n\}$ is an orthogonal basis for $Col A$, and $rank A = r$

2) Singular Value Decomposition

(1) Singular Value Decomposition

Theorem : Singular Value Decomposition

Let A be $m \times n$ matrix with rank r . Then there exists an $m \times n$ matrix Σ such that

$$\Sigma = \begin{bmatrix} D & 0 \\ 0 & 0 \end{bmatrix}, \text{ where } D = \begin{bmatrix} \lambda_1 & 0 \\ & \dots \\ 0 & \lambda_r \end{bmatrix}. \text{ (Diagonal entries of } D \text{ are the first } r \text{ singular values of } A,$$

$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r > 0$, and there exists $m \times m$ orthogonal matrix U and $n \times n$ orthogonal matrix V such that

$$A = U\Sigma V^T$$

U and V are not uniquely determined by A , but diagonal entries of Σ are necessarily the singular values of A

The columns of U are called left singular vectors of A , the columns of V are called right singular vectors of A

example

$$A = \begin{bmatrix} 4 & 11 & 14 \\ 8 & 7 & -2 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & -1 \\ -2 & 2 \\ 2 & -2 \end{bmatrix}$$

4. Principal Component Analysis

1) Basic concepts of statistics

(1) 용어정리

data : $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$

① mean of data

$$\bar{X} = \frac{1}{n} \sum_{i=1}^n x_i, \quad \bar{Y} = \frac{1}{n} \sum_{i=1}^n y_i$$

② Sample Variance of data

$$Var(X) = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{X})^2, \quad Var(Y) = \frac{1}{n-1} \sum_{i=1}^n (y_i - \bar{Y})^2$$

③ Covariance of data

$$Cov(X, Y) = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{X})(y_i - \bar{Y})$$

(2) Covariance matrix

variable : X_1, X_2, \dots, X_p

$$\text{Covariance matrix of } X_1, X_2, \dots, X_p : \begin{bmatrix} Var(X_1) & Cov(X_1, X_2) & \dots & Cov(X_1, X_p) \\ Cov(X_2, X_1) & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots \\ Cov(X_p, X_1) & \dots & \dots & Var(X_p) \end{bmatrix}$$

2) Principal Component Analysis

(1) Principal Component Analysis

data : $(x_{11}, x_{12}, \dots, x_{1p}), (x_{21}, x_{22}, \dots, x_{2p}), \dots, (x_{n1}, x_{n2}, \dots, x_{np})$

$$X = \begin{bmatrix} x_{11} & x_{12} & \dots & x_{1p} \\ x_{21} & x_{22} & \dots & x_{2p} \\ \dots & \dots & \dots & \dots \\ x_{n1} & x_{n2} & \dots & x_{np} \end{bmatrix}$$

① scaling

② Covariance matrix

③ Spectral decomposition

④ New axis

⑤ meaning of eigenvalue and eigenvector

⑥ Dimensionality reduction