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Real-Time Systems

3a-Cyclic Scheduler

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Objective

To understand cyclic schedulers...

To design cyclic schedulers...

To analyze cyclic schedulers...

To evaluate the pros and cons of cyclic schedulers...

```
wait timer interrupt
frame=frame+1;
switch frame
  case 1:
    Task1(); Task2(); break;
  case 2:
    Task3(); Task4(); break;
  case 3:
    Task(5); break;
if (frame≥3) frame=0;
```

Cyclic scheduler

The scheduler chooses which task will be executed at each time instant.

Scheduling has two parts:

- -Algorithm: specifies how to assign a task to be executed in the processor(s) along time
- -Analysis: by analyzing the resulting policy, it is possible to guarantee timing constraints for RT-systems

The cyclic scheduler is the basis for most embedded systems
It is based on periodic tasks
Time constraints are ensured by design
Requires a time mechanism to generate periodic triggers of the scheduler

More details can be found in T. P. Baker and A. Shaw, "The cyclic executive model and Ada," *Proceedings. Real-Time Systems Symposium*, Huntsville, AL, USA, 1988, pp. 120-129.

Cyclic scheduler

Some maths

Icm less common múltiple (mínimo común mútiplo)

gcd greatest common divisor (máxiimo común divisor)

∧ and operator

[·] floor operator

[·] ceiling operator

∀ for each

∃ exists

∈ belongs to

 Z^+ positive integers

Requisites

The first approach for the cyclic scheduler is based on periodic tasks as follows:

1 microprocessor

Static tasks

Periodic tasks

No precedence among tasks

The WCET for each tasks is known, fitted and less than its deadline

Deadlines of each task equal to their periods

The schedulability analysis tries to know in advance if all the release times for each task occurs before its deadline

Methodology

Necessary but not sufficient conditions:

Check utilization factor

$$U_{\text{total}} = \sum_{i=1}^{n} U_i = \sum_{i=1}^{n} \frac{c_i}{T_i} = \frac{c_1}{T_1} + \frac{c_2}{T_2} + \dots + \frac{c_n}{T_n} \le 1$$
 (1)

Find the hiperperiod *H* as

$$H = \lim_{1 \le i \le n} T_i$$

Find the secondary frame T_s which has to satisfy

$$H = k T_S, k \in Z^+ \tag{4}$$

$$\forall i: 2T_S - \gcd(T_S, T_i) \le D_i \tag{5}$$

Once conditions are fulfilled, find suitable allocation of each task within the frames

(2)

Check utilization

$$U_{\text{total}} = \sum_{i=1}^{n} U_i = \sum_{i=1}^{n} \frac{c_i}{T_i} = \frac{5}{20} + \frac{5}{20} + \frac{10}{40} = 0.75 \le 1$$

Task τ _i	Computing time c _i (ms)	Period T _i = Deadline D _i (ms)
τ_1	5	20
τ ₂	5	20
τ_3	10	40

Hiperperiod H

$$H = \lim_{1 \le i \le n} T_i = \text{lcm}(20,20,40) = \text{lcm}(2^2 \cdot 5, 2^2 \cdot 5, 2^3 \cdot 5) = 40 \text{ ms}$$

Secondary period

$$\begin{split} T_S &\geq \max_{1 \leq i \leq n} c_i = \max(5,5,10) \geq 10 \text{ ms} \\ T_S &\leq \min_{1 \leq i \leq n} D_i = \min(20,20,40) \leq 20 \text{ ms} \\ H &= k \ T_S = 4 \cdot 10 \text{ms} = 40 \text{ms} \ , k = 4 \in Z^+ \\ H &= k \ T_S = 2 \cdot 20 \text{ms} = 40 \text{ms} \ , k = 2 \in Z^+ \end{split} \right\} T_S = \{10,20\} \text{ms}$$

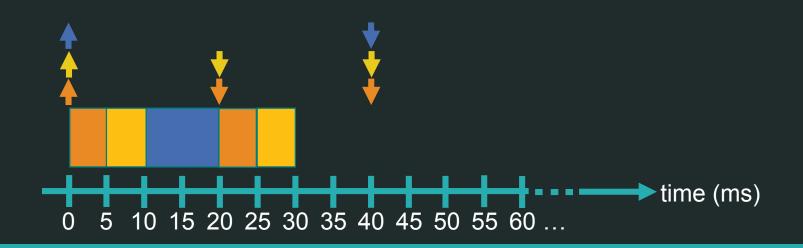
3a-Cyclic Scheduler

For $T_S = 20 \text{ms}$ check $\forall i: 2T_S - \gcd(T_S, T_i) \leq D_i$

$$i = \{1,2\}: 2 \cdot 20 - \gcd(20,20) = 40 - 20 = 20 \le 20$$

 $i = 3: 2 \cdot 20 - \gcd(20,40) = 40 - 20 = 20 \le 40$

Task τ _i	Computing time c _i (ms)	Period T _i = Deadline D _i (ms)
τ_1	5	20
τ ₂	5	20
τ ₃	10	40



```
wait timer interrupt(20ms)
frame=frame+1;
switch frame
  case 1:
    Task1();
    Task2();
    Task3();
    break;
  case 2:
    Task1();
    Task2();
    break;
if (frame > 2) frame = 0;
```

Check utilization

$$U_{\text{total}} = \sum_{i=1}^{n} U_i = \sum_{i=1}^{n} \frac{c_i}{T_i} = \frac{2}{6} + \frac{2}{8} + \frac{8}{24} = 0.92 \le 1$$

Task τ _i	Computing time c _i (ms)	Period T _i = Deadline D _i (ms)
τ_1	2	6
τ_2	2	8
τ_3	8	24

Hiperperiod H

$$H = \lim_{1 \le i \le n} T_i = \text{lcm}(6,8,24) = \text{lcm}(2 \cdot 3, 2^3, 2^3 \cdot 3) = 24 \text{ ms}$$

Secondary period

$$T_s \ge \max_{1 \le i \le n} c_i = \max(2,2,8) \ge 8 \text{ ms}$$

 $T_s \le \min_{1 \le i \le n} D_i = \min(6,8,24) \le 6 \text{ ms}$

$$T_S \le \min_{1 \le i \le n} D_i = \min(6, 8, 24) \le 6 \text{ ms}$$

Does not fulfill condition (3). Split task 3 into pieces

Such that:
$$T_{3A} = T_3$$

 $T_{3B} = T_3$
 $D_{3A} = D_3$
 $D_{3B} = D_3$
 $C_{3A} + C_{3B} = C_3$

 c_{3A} precedes to c_{3B} and no critical section in the edge

Check utilization

$$U_{\text{total}} = \sum_{i=1}^{n} U_i = \sum_{i=1}^{n} \frac{c_i}{T_i} = \frac{2}{6} + \frac{2}{8} + \frac{4}{24} + \frac{4}{24} = 0.92 \le 1$$

Task τ _i	Computing time c _i (ms)	Period T _i = Deadline D _i (ms)
τ_1	2	6
τ_2	2	8
τ_{3A}	4	24
τ_{3B}	4	24

Hiperperiod H

$$H = \lim_{1 \le i \le n} T_i = \text{lcm}(6,8,24,24) = \text{lcm}(2 \cdot 3, 2^3, 2^3 \cdot 3, 2^3 \cdot 3) = 24 \text{ ms}$$

Secondary period

$$T_S \ge \max_{1 \le i \le n} c_i = \max(2,2,4,4) \ge 4 \text{ ms}$$
 Now fulfills condition (3) $T_S \le \min_{1 \le i \le n} D_i = \min(6,8,24,24) \le 6 \text{ ms}$ Now fulfills condition (3) $H = k T_S = 6 \cdot 4 \text{ms} = 24 \text{ms}, k = 4 \in Z^+$ $T_S = \{4,6\} \text{ms}$ $T_S = \{4,6\} \text{ms}$

3a-Cyclic Scheduler

```
For T_s = 6ms check \forall i: 2T_s - \gcd(T_s, T_i) \le D_i

i = 1: 2 \cdot 6 - \gcd(6,6) = 12 - 6 = 6 \le 6

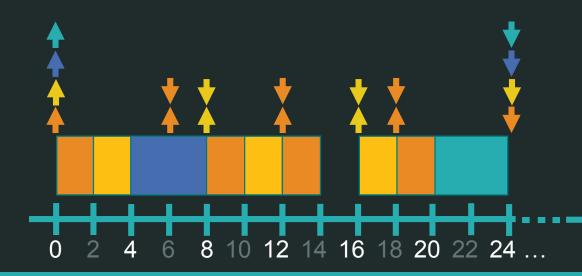
i = 2: 2 \cdot 6 - \gcd(6,8) = 12 - 2 = 10 \ge 8

For T_s = 4ms check \forall i: 2T_s - \gcd(T_s, T_i) \le D_i

i = 1: 2 \cdot 4 - \gcd(4,6) = 8 - 2 = 6 \le 6

i = 2: 2 \cdot 4 - \gcd(4,8) = 8 - 4 = 4 \le 8

i = \{3,4\}: 2 \cdot 4 - \gcd(4,24) = 8 - 4 = 4 \le 24
```



```
Computing
                                Period T_i =
Task τ<sub>i</sub>
                             Deadline D<sub>i</sub> (ms)
              time c<sub>i</sub> (ms)
                                     6
\tau_1
                                     8
T_2
                                    24
                                    24
\tau_{3B}
wait timer interrupt(4ms)
frame=frame+1;
switch frame
   case 1: Task1(); Task2(); break;
   case 2: Task3A(); break;
   case 3: Task1();Task2();break;
   case 4: Task1();break;
   case 5: Task1(); Task2();break;
   case 6: Task3B(); break;
if (frame≥6) frame=0;
```

time (ms)

Check utilization

$$U_{\text{total}} = \sum_{i=1}^{n} U_i = \sum_{i=1}^{n} \frac{c_i}{T_i} = \frac{5}{20} + \frac{10}{20} + \frac{10}{40} = 1 \le 1$$

Task τ _i	Computing time c _i (ms)	Period T _i = Deadline D _i (ms)
τ_1	5	20
τ ₂	10	20
τ_3	10	40

Hiperperiod H

$$H = \lim_{1 \le i \le n} T_i = \text{lcm}(20,20,40) = \text{lcm}(2^2 \cdot 5, 2^2 \cdot 5, 2^3 \cdot 5) = 40 \text{ ms}$$

Secondary period

$$T_{S} \ge \max_{1 \le i \le n} c_{i} = \max(5,10,10) \ge 10 \text{ ms}$$
 Now fulfills condition (3) $T_{S} \le \min_{1 \le i \le n} D_{i} = \min(20,20,40) \le 20 \text{ ms}$ Now fulfills condition (3) $H = k T_{S} = 4 \cdot 10 \text{ms} = 40 \text{ms}$, $k = 4 \in \mathbb{Z}$ $T_{S} = \{10,20\} \text{ms}$ $H = k T_{S} = 2 \cdot 20 \text{ms} = 40 \text{ms}$, $k = 2 \in \mathbb{Z}$

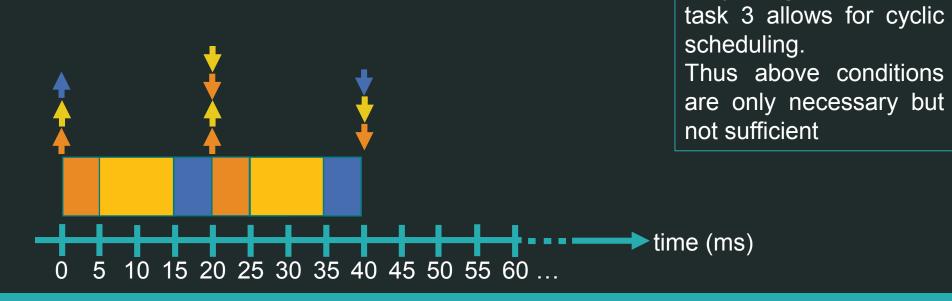
3a-Cyclic Scheduler

For $T_S = 20 \text{ms}$ check $\forall i: 2T_S - \gcd(T_S, T_i) \leq D_i$
$i = \{1,2\}: 2 \cdot 20 - \gcd(20,20) = 40 - 20 = 20 \le 20$
$i = 3$: $2 \cdot 20 - \gcd(20,40) = 40 - 20 = 20 \le 40$

For $T_s = 10 \text{ms check } \forall i : 2T_s - \gcd(T_s, T_i) \leq D_i$
$i = \{1,2\}: 2 \cdot 10 - \gcd(10,20) = 20 - 10 = 10 \le 20$
$i = 3$: $2 \cdot 10 - \gcd(10,40) = 20 - 10 = 30 \le 30$

Task τ _i	Computing time c _i (ms)	Period T _i = Deadline D _i (ms)
τ ₁	5	20
τ ₂	10	20
τ_3	10	40

Only segmentation of



Cyclic scheduler

Pros:

The cyclic scheduler is static, simple, easy to handle and robust

Deadlines are ensured by design

There is no real concurrency nor preemption

There is no need for mutual exclusion

Low-level scheduler

Cons:

Cyclic schedulers are not flexible

Segmentation of tasks increases complexity

Not suited for sporadic tasks (empty slots accommodation)

It can be hard to develop the allocation of the tasks within the frames.

Low-level scheduler