

| CG model with d = 100 and n = m = 10 ⁵ | | | | | | |
|---|--|---|--------------|---|--|------------|
| μ-deformation | | | | Σ _{ii} -deformation | | |
| Statistic | ϵ _{95%CL} | ϵ _{99%CL} | t (s) | ϵ _{95%CL} | ϵ _{99%CL} | t (s) |
| t _{SW} | 0.02667 ^{+0.0083} _{-0.0098} | 0.03433 ^{+0.0074} _{-0.008} | 725 | 0.01065 ^{+0.0031} _{-0.0038} | 0.01351 ^{+0.0028} _{-0.003} | 753 |
| t _{KS} | 0.02531 ^{+0.0078} _{-0.0089} | 0.03236 ^{+0.0073} _{-0.0079} | 1179 | 0.0127 ^{+0.0042} _{-0.0049} | 0.01612 ^{+0.004} _{-0.0042} | 1267 |
| t _{SKS} | 0.02742 ^{+0.0084} _{-0.01} | 0.03493 ^{+0.0077} _{-0.0086} | 1219 | 0.01323 ^{+0.0042} _{-0.0052} | 0.01674 ^{+0.0038} _{-0.0043} | 1311 |
| t _{FGD} | 0.0292 ^{+0.01} _{-0.011} | 0.03631 ^{+0.0089} _{-0.0088} | 18261 | 0.0095^{+0.0028} -0.0031 | 0.01169^{+0.0026} -0.0026 | 18550 |
| t _{MMD} | 0.0207^{+0.0092} -0.0077 | 0.02578^{+0.0087} -0.0071 | 13097 | 0.01289 ^{+0.005} _{-0.0045} | 0.01617 ^{+0.0047} _{-0.004} | 11384 |
| t _{LLR} | 0.00164 ^{+0.0012} _{-0.0012} | 0.00237 ^{+0.0012} _{-0.0012} | 15370 | 0.00031 ^{+0.00021} _{-0.00022} | 0.00045 ^{+0.00022} _{-0.00022} | 16289 |
| Σ _{i≠j} -deformation | | | | pow ₊ -deformation | | |
| Statistic | ϵ _{95%CL} | ϵ _{99%CL} | t (s) | ϵ _{95%CL} | ϵ _{99%CL} | t (s) |
| t _{SW} | 0.01168 ^{+0.0033} _{-0.0044} | 0.01534 ^{+0.003} _{-0.0034} | 13649 | 0.00229 ^{+0.00068} _{-0.00082} | 0.00293 ^{+0.00062} _{-0.00067} | 797 |
| t _{KS} | 1.01551 ^{+0.0021} _{-0.0099} | 1.01751 ^{+0.002} _{-0.003} | 13723 | 0.0027 ^{+0.0008} _{-0.00094} | 0.0034 ^{+0.00073} _{-0.0008} | 1351 |
| t _{SKS} | 0.01469 ^{+0.0053} _{-0.0065} | 0.01907 ^{+0.0051} _{-0.0056} | 14289 | 0.00254 ^{+0.00073} _{-0.00093} | 0.00319 ^{+0.00067} _{-0.00074} | 1405 |
| t _{FGD} | 0.0012^{+0.0003} -0.0003 | 0.0015^{+0.0002} -0.0003 | 51195 | 0.00232 ^{+0.00071} _{-0.0008} | 0.00286 ^{+0.00064} _{-0.00066} | 19919 |
| t _{MMD} | 0.00691 ^{+0.0029} _{-0.0028} | 0.00882 ^{+0.0027} _{-0.0024} | 25984 | 0.00163^{+0.00076} -0.0006 | 0.00205^{+0.00071} -0.00058 | 12499 |
| t _{LLR} | 0.00674 ^{+0.0023} _{-0.0035} | 0.00802 ^{+0.0024} _{-0.0024} | 33251 | 0.0001 ^{+7e-05} _{-7e-05} | 0.00015 ^{+7e-05} _{-7e-05} | 21800 |
| pow ₋ -deformation | | | | ℳ-deformation | | |
| Statistic | ϵ _{95%CL} | ϵ _{99%CL} | t (s) | ϵ _{95%CL} | ϵ _{99%CL} | t (s) |
| t _{SW} | 0.00229 ⁺⁵ _{-0.00096} | 0.00293 ⁺⁵ _{-0.00079} | 717 | 0.28179 ^{+0.039} _{-0.054} | 0.32012 ^{+0.032} _{-0.037} | 619 |
| t _{KS} | 0.0027 ^{+0.00084} _{-0.001} | 0.0034 ^{+0.00073} _{-0.00085} | 1373 | 0.3116 ^{+0.049} _{-0.067} | 0.35101 ^{+0.042} _{-0.049} | 1063 |
| t _{SKS} | 0.00253 ^{+0.00087} _{-0.0011} | 0.00316 ^{+0.0008} _{-0.00092} | 1404 | 0.30315 ^{+0.045} _{-0.07} | 0.34204 ^{+0.037} _{-0.05} | 1102 |
| t _{FGD} | 0.00225 ^{+0.00076} _{-0.00086} | 0.00278 ^{+0.00071} _{-0.0007} | 20138 | 0.13244^{+0.016} -0.023 | 0.1479^{+0.011} -0.016 | 15260 |
| t _{MMD} | 0.00143^{+0.00077} -0.00064 | 0.00185^{+0.00073} -0.0006 | 12506 | 0.68952 ^{+0.078} _{-0.098} | 0.77914 ^{+0.057} _{-0.067} | 8037 |
| t _{LLR} | 0.00012 ^{+7e-05} _{-7e-05} | 0.00017 ^{+7e-05} _{-7e-05} | 17336 | - | - | - |
| ℳ-deformation | | | | Timing | | |
| Statistic | ϵ _{95%CL} | ϵ _{99%CL} | t (s) | t ^{null} (s) | | |
| t _{SW} | 0.4924 ^{+0.067} _{-0.098} | 0.55614 ^{+0.053} _{-0.064} | 588 | 394 | | |
| t _{KS} | 0.54132 ^{+0.081} _{-0.12} | 0.60655 ^{+0.069} _{-0.083} | 1034 | 1499 | | |
| t _{SKS} | 0.52074 ^{+0.082} _{-0.12} | 0.59085 ^{+0.066} _{-0.087} | 1039 | 1603 | | |
| t _{FGD} | 0.22963^{+0.025} -0.04 | 0.25498^{+0.021} -0.028 | 14613 | 51866 | | |
| t _{MMD} | 1.19904 ^{+0.13} _{-0.18} | 1.34688 ^{+0.11} _{-0.12} | 8790 | 18801 | | |
| t _{LLR} | - | - | - | - | | |