

| CG model with $d = 100$ and $n = m = 10^4$ | | | | | | |
|--|--|---|------------|---|---|------------|
| Statistic | μ -deformation | | | Σ_{ii} -deformation | | |
| | $\epsilon_{95\%CL}$ | $\epsilon_{99\%CL}$ | t (s) | $\epsilon_{95\%CL}$ | $\epsilon_{99\%CL}$ | t (s) |
| t_{SW} | $0.08359^{+0.028}_{-0.034}$ | $0.10651^{+0.025}_{-0.028}$ | 846 | $0.03133^{+0.012}_{-0.014}$ | $0.03977^{+0.011}_{-0.012}$ | 889 |
| t_{KS} | $0.08229^{+0.027}_{-0.033}$ | $0.10339^{+0.025}_{-0.028}$ | 653 | $0.03958^{+0.015}_{-0.018}$ | $0.05039^{+0.014}_{-0.016}$ | 689 |
| t_{SKS} | $0.08589^{+0.029}_{-0.037}$ | $0.10945^{+0.026}_{-0.03}$ | 942 | $0.04009^{+0.015}_{-0.019}$ | $0.05107^{+0.014}_{-0.016}$ | 1027 |
| t_{FGD} | $0.09233^{+0.032}_{-0.033}$ | $0.11682^{+0.029}_{-0.027}$ | 3410 | $0.02875^{+0.01}_{-0.011}$ | $0.03664^{+0.0092}_{-0.0087}$ | 3739 |
| t_{MMD} | $0.05661^{+0.03}_{-0.026}$ | $0.07172^{+0.028}_{-0.024}$ | 1163 | $0.0369^{+0.016}_{-0.016}$ | $0.04633^{+0.015}_{-0.014}$ | 1257 |
| t_{LLR} | $0.00541^{+0.0033}_{-0.0032}$ | $0.00768^{+0.0033}_{-0.0032}$ | 2277 | $0.00101^{+0.00073}_{-0.00071}$ | $0.0015^{+0.00073}_{-0.00071}$ | 2566 |
| Statistic | $\Sigma_{i \neq j}$ -deformation | | | pow ₊ -deformation | | |
| | $\epsilon_{95\%CL}$ | $\epsilon_{99\%CL}$ | t (s) | $\epsilon_{95\%CL}$ | $\epsilon_{99\%CL}^{pow+}$ | t (s) |
| t_{SW} | $0.03515^{+0.011}_{-0.015}$ | $0.0461^{+0.01}_{-0.012}$ | 887 | $0.00693^{+0.0024}_{-0.003}$ | $0.0088^{+0.0022}_{-0.0024}$ | 944 |
| t_{KS} | $1.02012^{+0.01}_{-0.003}$ | $1.02919^{+0.003}_{-0.003}$ | 510 | $0.00853^{+0.0028}_{-0.0035}$ | $0.01068^{+0.0025}_{-0.0029}$ | 878 |
| t_{SKS} | $0.0402^{+0.016}_{-0.019}$ | $0.05406^{+0.014}_{-0.017}$ | 1010 | $0.00784^{+0.0026}_{-0.0034}$ | $0.00985^{+0.0024}_{-0.0026}$ | 1109 |
| t_{FGD} | $0.00341^{+0.00091}_{-0.0011}$ | $0.00438^{+0.00077}_{-0.00088}$ | 4053 | $0.00707^{+0.0025}_{-0.0025}$ | $0.00898^{+0.0022}_{-0.0021}$ | 4281 |
| t_{MMD} | $0.02391^{+0.0084}_{-0.0083}$ | $0.02992^{+0.008}_{-0.0075}$ | 1141 | $0.00447^{+0.0024}_{-0.0021}$ | $0.00569^{+0.0022}_{-0.0019}$ | 1027 |
| t_{LLR} | $4e - 05^{+3e-05}_{-2e-05}$ | $6e - 05^{+3e-05}_{-3e-05}$ | 3373 | $0.00038^{+0.00019}_{-0.0002}$ | $0.00052^{+0.00019}_{-0.00019}$ | 2640 |
| Statistic | pow ₋ -deformation | | | \mathcal{N} -deformation | | |
| | $\epsilon_{95\%CL}$ | $\epsilon_{99\%CL}^{pow-}$ | t (s) | $\epsilon_{95\%CL}$ | $\epsilon_{99\%CL}^{\mathcal{N}}$ | t (s) |
| t_{SW} | $0.00702^{+5}_{-0.0032}$ | $0.00889^{+5}_{-0.0026}$ | 863 | $0.4895^{+0.084}_{-0.13}$ | $0.55438^{+0.069}_{-0.087}$ | 761 |
| t_{KS} | $0.00823^{+0.0028}_{-0.0035}$ | $0.01034^{+0.0025}_{-0.0029}$ | 879 | $0.55303^{+0.094}_{-0.14}$ | $0.6216^{+0.083}_{-0.098}$ | 705 |
| t_{SKS} | $0.00765^{+0.0027}_{-0.0036}$ | $0.00961^{+0.0024}_{-0.0028}$ | 1120 | $0.53076^{+0.092}_{-0.16}$ | $0.60111^{+0.075}_{-0.1}$ | 898 |
| t_{FGD} | $0.00686^{+0.0026}_{-0.0026}$ | $0.00886^{+0.0023}_{-0.0023}$ | 4380 | $0.23754^{+0.029}_{-0.045}$ | $0.26842^{+0.023}_{-0.03}$ | 3350 |
| t_{MMD} | $0.00537^{+0.0023}_{-0.002}$ | $0.00664^{+0.0022}_{-0.0018}$ | 1039 | $1.21562^{+0.16}_{-0.25}$ | $1.35657^{+0.13}_{-0.16}$ | 803 |
| t_{LLR} | $0.00033^{+0.00019}_{-0.0002}$ | $0.00047^{+0.00019}_{-0.0002}$ | 2712 | - | - | - |
| Statistic | \mathcal{U} -deformation | | | Timing | | |
| | $\epsilon_{95\%CL}$ | $\epsilon_{99\%CL}^{\mathcal{U}}$ | t (s) | t^{null} (s) | | |
| t_{SW} | $0.84895^{+0.14}_{-0.22}$ | $0.96147^{+0.12}_{-0.15}$ | 715 | 275 | | |
| t_{KS} | $0.95234^{+0.17}_{-0.24}$ | $1.07042^{+0.14}_{-0.17}$ | 680 | 491 | | |
| t_{SKS} | $0.91554^{+0.16}_{-0.25}$ | $1.04113^{+0.13}_{-0.19}$ | 879 | 468 | | |
| t_{FGD} | $0.41168^{+0.048}_{-0.076}$ | $0.4652^{+0.039}_{-0.051}$ | 3227 | 5381 | | |
| t_{MMD} | $2.08745^{+0.3}_{-0.41}$ | $2.34223^{+0.24}_{-0.27}$ | 747 | 633 | | |
| t_{LLR} | - | - | - | - | | |