	CG	$\mathbf{model\ with\ d} = 1$	100 an	$\mathbf{d} \ \mathbf{n} = \mathbf{m} = 2 \cdot 10^4$	L	
		eformation	Σ_{ii} -deformation			
Statistic	$\epsilon_{95\% ext{CL}}$	$\epsilon_{99\% ext{CL}}$	t (s)	$\epsilon_{95\%{ m CL}}$	$\epsilon_{99\%\mathrm{CL}}$	t (s)
$t_{ m SW}$	$\begin{array}{c} 0.05955^{+0.021}_{-0.023} \\ 0.05834^{+0.019}_{-0.022} \\ 0.06195^{+0.021}_{-0.023} \\ 0.06396^{+0.025}_{-0.024} \end{array}$	$0.07615^{+0.019}_{-0.02}$	890	$0.0225^{+0.0073}_{-0.0082}$	$0.02867^{+0.0068}_{-0.0069}$	954
$t_{\overline{ ext{KS}}}$	$0.05834_{-0.022}^{+0.019}$	$0.07252^{+0.019}_{-0.019}$	802	$0.02825^{+0.0094}_{-0.01}$	$0.03574^{+0.0088}_{-0.0095}$	861
$t_{ m SKS}$	$0.06195^{+0.021}_{-0.023}$	$0.07913^{+0.019}_{-0.021}$	1200	$0.02901^{+0.0093}_{-0.011}$	$0.03683^{+0.0086}_{-0.0092}$	1080
$t_{ m FGD}$	$0.06396^{+0.025}_{-0.024}$	$0.07971^{+0.022}_{-0.021}$	5360	$0.02023^{+0.0075}_{-0.0082}$	$0.02523^{+0.0066}_{-0.0069}$	5467
$t_{ m MMD}$	$\mid 0.04176^{+0.022}_{-0.018} \mid$	$0.05326^{+0.021}_{-0.017}$	1934	$0.02689^{+0.012}_{-0.01}$	$0.03445^{+0.011}_{-0.0094}$	1959
$t_{ m LLR}$	$0.00379^{+0.0026}_{-0.0026}$	$0.0055^{+0.0026}_{-0.0026}$	3816	$0.00074^{+0.00053}_{-0.00053}$	$0.00108^{+0.00052}_{-0.00053}$	4378
$\Sigma_{i \neq j}$ -deformation				pow_+ -deformation		
Statistic	$\epsilon_{95\% ext{CL}}$	$\epsilon_{99\%\mathrm{CL}}$	t (s)	$\mid \epsilon_{95\% ext{CL}}$	$\epsilon_{99\%\mathrm{CL}}^{\mathrm{pow}_{+}}$	t (s)
$t_{ m SW}$	$0.02522^{+0.0067}_{-0.0084}$	$0.03331^{+0.0057}_{-0.0068}$	911	$0.00495^{+0.0017}_{-0.0019}$	$0.00629^{+0.0017}_{-0.0016}$	978
$t_{\overline{ ext{KS}}}$	$1.0119^{+0.0062}_{-0.003}$	$1.0209^{+0.003}_{-0.003}$	$\bf 552$	$0.00613^{+0.0019}_{-0.0022}$	$0.00754^{+0.0018}_{-0.0010}$	896
$t_{ m SKS}$	$\mid 0.02906^{+0.0095}_{-0.011}$	$0.03857^{+0.0087}_{-0.0096}$	1090	$0.00572^{+0.0019}_{-0.0021}$	$0.00714^{+0.0018}_{-0.0018}$	1180
$t_{ m FGD}$	$0.00239^{+0.00064}_{-0.00081}$	$0.00299^{+0.00054}_{-0.0062}$	6363	$0.00494^{+0.0019}_{-0.002}$	$0.00613^{+0.0018}_{-0.0017}$	6351
$t_{ m MMD}$	$0.01597^{+0.0065}_{-0.0061}$	$0.02031^{+0.0061}_{-0.0054}$	1993	$0.00332^{+0.0018}_{-0.0014}$	$0.00423^{+0.0017}_{-0.0013}$	2150
$t_{ m LLR}$	$3e - 05^{+2e - 05}_{-2e - 05}$	$0.02031_{-0.0054}^{+0.0061}$ $4e - 05_{-2e-05}^{+2e-05}$	5629	$0.00021^{+0.00015}_{-0.00015}$	$0.00032^{+0.00015}_{-0.00015}$	4341
	$pow\deformation$			$\mathcal{N} ext{-} ext{deformation}$		
Statistic	$\epsilon_{95\% ext{CL}}$	$\epsilon_{99\%\mathrm{CL}}^{\mathrm{pow}_{-}}$	t (s)	$\epsilon_{95\% ext{CL}}$	$\epsilon_{99\%\mathrm{CL}}^{\mathcal{N}}$	t (s)
$t_{ m SW}$	$0.00508^{+5}_{-0.0017}$	$0.00647^{+5}_{-0.0015}$	915	$0.41334^{+0.062}_{-0.084}$	$0.46898^{+0.052}_{-0.058}$	805
$t_{\overline{ ext{KS}}}$	$0.00597^{+0.0019}_{-0.0021}$	$0.0074^{+0.0017}_{-0.0018}$	900	$0.46482^{+0.07}_{-0.097}$	$0.52444^{+0.056}_{-0.075}$	731
$t_{ m SKS}$	$0.00563^{+0.0017}_{-0.002}$	$0.00704^{+0.0016}_{-0.0017}$	1185	$0.44843^{+0.067}_{-0.096}$	$0.50879_{-0.069}^{+0.057}$	928
$t_{ m FGD}$	$0.00508^{+0.0017}_{-0.0018}$	$0.00625^{+0.0016}_{-0.0015}$	6610	$\left \begin{array}{c} 0.1987^{+0.025}_{-0.037} \end{array} \right $	$0.22055^{+0.021}$	5119
$t_{ m MMD}$	$0.00353^{+0.0019}$	$0.0045^{+0.0018}_{-0.0014}$	2116	$1.01973^{+0.13}_{-0.17}$	$1.1523^{+0.097}_{-0.11}$	1563
$t_{ m LLR}$	$0.00028^{+0.00015}_{-0.00015}$	$0.00039^{+0.00015}_{-0.00015}$	4141	-	-	-
\mathcal{U} -deformation				Timing		
Statistic	$\epsilon_{95\% ext{CL}}$	$\epsilon_{99\%\mathrm{CL}}^{\mathcal{U}}$	t (s)	t^{null} (s)		
$t_{ m SW}$	$0.71388^{+0.11}_{-0.14}$	$0.81581^{+0.084}_{-0.1} \\ 0.90238^{+0.1}_{-0.130}$	775	294		
$t_{\overline{ ext{KS}}}$	$0.80534_{-0.17}^{+0.\bar{1}\bar{2}}$	$0.90238^{+0.\bar{1}}_{-0.13}$	710	527		
$t_{ m SKS}$	$0.77724_{-0.16}^{+0.12}$	$0.88187^{+0.098}_{-0.13}$	913	592		
$t_{ m FGD}$	$\begin{array}{c} 0.80534^{+0.12}_{-0.17} \\ 0.80534^{+0.12}_{-0.17} \\ 0.77724^{+0.12}_{-0.16} \\ \textbf{0.34266}^{+0.043}_{-0.065} \end{array}$	$0.88187^{+0.098}_{-0.13} \ 0.38262^{+0.033}_{-0.044}$	4326	7457		
$t_{ m MMD}$	$1.76762^{+0.21}_{-0.3}$	$1.99743^{+0.17}_{-0.19}$	1492	2390		
$t_{ m LLR}$	-	-	-	-		