		model with d =	= 5 and			
Statistic	μ -d $\mid \epsilon_{95\% ext{CL}}$	$\epsilon_{ m 99\%CL}$	t (s)	$\mid \epsilon_{95\% ext{CL}} \mid$	$\epsilon_{99\%{ m CL}}$	t (s)
$t_{ m SW}$	$0.06637^{+0.032}_{-0.029}$	$0.09067^{+0.03}_{-0.029}$	508	$0.02563^{+0.0081}_{-0.0084}$	$0.03543^{+0.0079}_{-0.0079}$	547
$t_{\overline{\mathrm{KS}}}$	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	$0.0788^{+0.026}_{-0.027}$	536	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	$0.0626^{+0.013}_{-0.014}$	572
$t_{ m SKS}$	$\begin{array}{c} -0.028 \\ 0.06935^{+0.033}_{-0.032} \end{array}$	$0.09308^{+0.032}_{-0.022}$	982	$0.03556^{+0.011}_{-0.012}$	$0.0483^{+0.01}_{-0.01}$	1062
$t_{ m FGD}$	$0.06444^{+0.04}_{0.02}$	$0.09308^{+0.032}_{-0.032} \\ 0.08946^{+0.036}_{-0.028}$	533	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	$0.02862^{+0.0088}_{-0.0074}$	565
$t_{ m MMD}$	$\begin{array}{c c} -0.03 \\ 0.08197 \begin{array}{c} -0.03 \\ +0.055 \\ -0.036 \end{array}$	$0.11263^{+0.052}_{-0.036}$	1114	0.02366 0.010	$0.03246^{+0.015}_{-0.011}$	1212
$t_{ m LLR}$	$0.01986^{+0.013}_{-0.013}$	$0.02935^{+0.013}_{-0.013}$	1465	$0.0044_{-0.0026}^{+0.0026}$	$0.00639_{-0.0025}^{+0.0026}$	1357
$\Sigma_{i\neq j}$ -deformation			pow_+ -deformation			
Statistic	$\epsilon_{95\%\mathrm{CL}}$	$\epsilon_{99\%\mathrm{CL}}$	t (s)	$\epsilon_{95\%\mathrm{CL}}$	$\epsilon_{99\%\mathrm{CL}}$	t (s)
$t_{ m SW}$	$0.06084^{+0.013}_{-0.017}$	$0.08671^{+0.012}_{-0.013}$	652	$0.00648^{+0.003}_{-0.0027}$	$0.0091^{+0.0029}_{-0.0028}$	581
$t_{\overline{ ext{KS}}}$	$1.04761_{-0.015}^{-0.017}$	$1.06418^{+0.013}_{-0.014}$	615	$0.00947_{-0.0037}^{+0.0027}$	$0.01206^{+0.0023}_{-0.0033}$	607
$t_{ m SKS}$	$0.08062^{+0.021}_{-0.025}$	$0.11072^{+0.019}_{-0.023}$	809	$0.00731^{+0.003}_{-0.0031}$	$0.00962^{+0.0029}_{-0.0029}$	1091
$t_{ m FGD}$	$\begin{array}{c} 0.08062^{+0.021}_{-0.025} \\ \textbf{0.01582}^{+0.0038}_{-0.0046} \end{array}$	$0.11072_{-0.023}^{+0.019} \\ 0.02169_{-0.0038}^{+0.0032}$	962	$0.00554^{+0.0034}_{-0.0025}$	$0.00962^{+0.0029}_{-0.0029} \\ 0.00773^{+0.0031}_{-0.0024}$	614
$t_{ m MMD}$	$\begin{array}{c} -0.0048 \\ 0.09539^{+0.051}_{-0.041} \end{array}$	$0.12764^{+0.049}_{-0.038}$	1405	$0.00446^{+0.003}_{-0.002}$	$0.00612^{+0.0029}_{-0.002}$	1308
LLR	-	-	_	$0.00161^{+0.001}_{-0.001}$	$0.00228^{+0.001}_{-0.001}$	1490
	pow_	-deformation	$\mathcal{N} ext{-} ext{deformation}$			
Statistic	$\epsilon_{95\%\mathrm{CL}}$	$\epsilon_{99\%\mathrm{CL}}$	t (s)	$\epsilon_{95\%\mathrm{CL}}$	$\epsilon_{99\%\mathrm{CL}}$	t (s)
$t_{ m SW}$	$0.00714^{+10}_{-0.0025}$	$0.00976^{+10}_{-0.0025}$	526	$0.31414^{+0.046}_{-0.054}$	$0.37729^{+0.04}_{-0.039}$	488
$t_{\overline{ ext{KS}}}$	$0.00938^{+0.0036}_{-0.0035}$	$0.01208^{+0.0034}_{-0.0033}$	649	$0.2711^{+0.038}_{-0.059}$	$0.31549^{+0.032}_{-0.043}$	577
$t_{ m SKS}$	$0.00773^{+0.0029}_{-0.0028}$	$0.01011^{+0.0028}_{-0.0027}$	1089	$0.31014^{+0.045}_{-0.057}$	$0.3699^{+0.038}_{-0.047}$	965
$t_{ m FGD}$	$0.00626^{+0.0033}_{-0.0024}$	$0.00846^{+0.0031}_{-0.0023}$	608	$\mid 0.23539^{+0.025}_{-0.034} \mid$	$0.27474^{+0.019}$	468
$t_{ m MMD}$	$\mid 0.00517^{+0.0035}_{-0.0024} \mid$	$0.00699^{+0.0033}_{-0.0024}$	1321	$0.65882^{+0.16}_{-0.15}$	$0.77006^{+0.13}_{-0.11}$	964
LLR	$0.00174^{+0.001}_{-0.001}$	$0.00235^{+0.001}_{-0.001}$	1478	-	-	-
\mathcal{U} -deformation			Timing			
Statistic	$\epsilon_{95\%\mathrm{CL}}$	$\epsilon_{99\%\mathrm{CL}}$	t (s)	t^{null} (s)		
$t_{\rm SW}$	$ \begin{array}{c c} 0.54152^{+0.081}_{-0.091} \\ 0.45812^{+0.072}_{-0.096} \end{array} $	$0.65357^{+0.063}_{-0.071} \\ 0.53398^{+0.063}_{-0.071}$	470	279		
$t_{\overline{ ext{KS}}}$	$0.45812^{+0.072}_{-0.096}$	$0.53398^{+0.063}_{-0.071}$	557	32		
$t_{ m SKS}$	$ \begin{array}{c} -0.035 \\ 0.53293 ^{+0.035}_{-0.096} \\ 0.40466 ^{+0.047}_{-0.058} \end{array} $	$0.63342^{+0.064}_{-0.075}$ $0.47806^{+0.031}_{-0.035}$	601	375		
$t_{ m FGD}$	$\left \begin{array}{c} 0.40466^{+0.047}_{-0.058} \end{array} \right $	$0.47806^{+0.031}_{-0.035}$	455	465		
$t_{ m MMD}$	$\begin{array}{c c} -0.038 \\ 1.13409^{+0.27}_{-0.25} \end{array}$	$1.33277^{+0.23}_{-0.2}$	1057	1267		
$t_{ m LLR}$	-	-	-	-		