| $egin{aligned} 	ext{CG model with d} = 	ext{5 and n} = 	ext{m} = 	ext{2} \cdot 	ext{10}^4 \ & \mu	ext{-deformation} \end{aligned}$ |   |  |            |  |   |       |
|--|---|--|------------|--|---|-------|
| Statistic  | $ \epsilon_{ m 95\%CL} $  | $\epsilon_{99\%\mathrm{CL}}$   | t (s)      | $\mid \epsilon_{95\%{ m CL}} \mid$   | $\epsilon_{99\%\mathrm{CL}}$                              | t (s) |
| $t_{\rm SW}$   | $0.06637^{+0.032}_{-0.029}$   | $0.09067^{+0.03}_{-0.029}$   | 508        | $\begin{array}{ c c c c c c c c c c c c c c c c c c c$                                   | $0.03543^{+0.0079}_{-0.0076}$                             | 547   |
| $t_{\overline{	ext{KS}}}$  |   | $0.0788^{+0.026}_{-0.027}$   | 536        | $0.04739^{+0.004}_{-0.016}$  | $0.0626^{+0.013}$   | 572   |
| $t_{ m SKS}$   | $\begin{array}{c} \textbf{0.0604}^{+0.028}_{-0.028} \\ 0.06935^{+0.033}_{-0.032} \\ 0.06444^{+0.04}_{-0.03} \\ \end{array}$ | $0.09308^{+0.032}_{-0.032}$  | 982        | $ \begin{vmatrix} 0.04739^{+0.014}_{-0.016} \\ 0.03556^{+0.011}_{-0.012} \end{vmatrix} $ | $0.0483_{-0.01}^{+0.01}$<br>$0.02862_{-0.0074}^{+0.0088}$ | 1062  |
| $t_{ m FGD}$   | $0.06444^{+0.04}_{-0.03}$   | $0.00040\pm0.036$  | 533        | L 0 00000+U.UU95   | $0.02862^{+0.0088}_{-0.0074}$                             | 565   |
| $t_{ m MMD}$   | $0.08197_{-0.036}^{+0.036}$   | $0.08946_{-0.028}^{+0.038} \ 0.11263_{-0.036}^{+0.052}$                                | 1114       | $0.02366^{+0.016}_{-0.011}$  | $0.03246^{+0.013}_{-0.011}$                               | 1212  |
| $t_{ m LLR}$   | $0.01986^{+0.013}_{-0.013}$   | $0.02935^{+0.013}_{-0.013}$  | 1465       | $0.0044^{+0.0026}_{-0.0026}$   | $0.00639_{-0.0025}^{+0.0026}$                             | 1357  |
| $\Sigma_{i\neq j}$ -deformation  |   |  |            | $pow_+$ -deformation   |   |       |
| Statistic  | $\epsilon_{95\%\mathrm{CL}}$  | $\epsilon_{99\%\mathrm{CL}}$   | t (s)      | $\epsilon_{95\%\mathrm{CL}}$   | $\epsilon_{99\%\mathrm{CL}}$                              | t (s) |
| $t_{ m SW}$  | $0.03062^{+0.0071}_{-0.0085}$   | $\begin{array}{c} 0.04408^{+0.0063}_{-0.007} \\ 1.06418^{+0.013}_{-0.014} \end{array}$ | 969        | $0.00648^{+0.003}_{-0.0027}$   | $0.0091^{+0.0029}_{-0.0028}$                              | 581   |
| $t_{\overline{	ext{KS}}}$  | $1.04761^{+0.013}_{-0.015}$   | $1.06418_{-0.014}^{+0.013}$  | 837        | $0.00947^{+0.0033}_{-0.0037}$  | $0.01206_{-0.0033}^{+0.0032}$                             | 607   |
| $t_{ m SKS}$   | $0.04058^{+0.01}_{-0.013}$  | $0.05559^{+0.01}_{-0.011}$   | 1124       | $0.00731^{+0.003}_{-0.0031}$   | $0.00962^{+0.0029}_{-0.0020}$                             | 1091  |
| $t_{ m FGD}$   | $0.00778^{+0.0023}_{-0.0021}$   | $0.01094^{+0.0018}_{-0.0017}$  | 1324       | $0.00554^{+0.0034}_{-0.0025}$  | $0.00773^{+0.0031}_{-0.0024}$                             | 614   |
| $t_{ m MMD}$   | $0.04776^{+0.028}_{-0.02}$  | $0.06485^{+0.025}_{-0.019}$  | 1723       | $0.00446^{+0.003}_{-0.002}$  | $0.00612^{+0.0029}_{-0.002}$                              | 1308  |
| $t_{ m LLR}$   | $0.0342^{+0.014}_{-0.017}$  | $0.04471^{+0.01}_{-0.015}$   | 2711       | $0.00161^{+0.001}_{-0.001}$  | $0.00228^{+0.001}_{-0.001}$                               | 1490  |
| powdeformation   |   |  |            | $\mathcal{N}	ext{-}	ext{deformation}$  |   |       |
| Statistic  | $\epsilon_{95\%\mathrm{CL}}$  | $\epsilon_{99\%\mathrm{CL}}$   | t (s)      | $\epsilon_{95\%{ m CL}}$   | $\epsilon_{99\%\mathrm{CL}}$                              | t (s) |
| $t_{ m SW}$  | $0.00714_{-0.0025}^{+10}$   | $0.00976^{+10}_{-0.0025}$  | $\bf 526$  | $0.31414^{+0.046}_{-0.054}$  | $0.37729^{+0.04}_{-0.039}$                                | 488   |
| $t_{\overline{	ext{KS}}}$  | $0.00938^{+0.0036}_{-0.0035}$   |  | 649        | $\begin{array}{ c c c c c c c c c c c c c c c c c c c$                                   | $0.31549^{+0.032}_{-0.043}$                               | 577   |
| $t_{ m SKS}$   | $0.00773^{+0.0029}_{-0.0028}$   | $0.01208^{+0.0034}_{-0.0033}$ $0.01011^{+0.0028}_{-0.0027}$                            | 1089       | $0.31014^{+0.045}_{-0.057}$  | $0.3699^{+0.038}_{-0.047}$                                | 965   |
| $t_{ m FGD}$   | $0.00626^{+0.0033}_{-0.0024}$   | $0.00846^{+0.0031}_{-0.0023}$  | 608        | $\mid 0.23539^{+0.025}_{-0.034} \mid$  | $0.27474^{+0.019}_{-0.02}$                                | 468   |
| $t_{ m MMD}$   | $0.00517^{+0.0035}_{-0.0024}$   | $0.00699^{+0.0033}_{-0.0024}$  | 1321       | $0.65882^{+0.16}_{-0.15}$  | $0.77006^{+0.13}_{-0.11}$                                 | 964   |
| $t_{ m LLR}$   | $0.00174^{+0.001}_{-0.001}$   | $0.00235^{+0.001}_{-0.001}$  | 1478       | -  | -   | -     |
| $\mathcal{U}$ -deformation   |   |  | Timing     |  |   |       |
| Statistic  | $\epsilon_{95\%\mathrm{CL}}$  | $\epsilon_{99\%\mathrm{CL}}$   | t (s)      | $t^{\text{null}}$ (s)  |   |       |
| $t_{ m SW}$  | $0.54152^{+0.081}_{-0.091}$   | $0.65357_{-0.071}^{+0.063} \\ 0.53398_{-0.071}^{+0.063}$                               | 470        | 279  |   |       |
| $t_{\overline{	ext{KS}}}$  |   | $0.53398^{+0.063}_{-0.071}$  | 557        | 32   |   |       |
| $t_{ m SKS}$   | $ \begin{array}{c} 0.45812^{+0.072}_{-0.096} \\ 0.53293^{+0.085}_{-0.096} \end{array} $                                     | $0.63342^{+0.064}_{-0.075}$  | 601        | 375  |   |       |
| $t_{ m FGD}$   | $\mid 0.40466^{+0.047}_{-0.058} \mid$   | $0.03542_{-0.075} \ 0.47806_{-0.035}^{+0.031}$   | <b>455</b> | 465  |   |       |
| $t_{ m MMD}$   | $1.13409^{+0.27}_{-0.25}$   | $1.33277_{-0.2}^{+0.23}$   | 1057       | 1267   |   |       |
| $t_{ m LLR}$   | _   | -  | -          | -  |   |       |