| | CG | model with d = | = 100 an | $d n = m = 2 \cdot 10^4$ | 1 | |
|---------------------------------|--|---|----------------------------|---|--|-------|
| | μ | | Σ_{ii} -deformation | | | |
| Statistic | $\epsilon_{95\%\mathrm{CL}}$ | $\epsilon_{99\%\mathrm{CL}}$ | t (s) | $\mid \epsilon_{95\%	ext{CL}} \mid$ | $\epsilon_{99\%\mathrm{CL}}$ | t (s) |
| $t_{ m SW}$ | $\begin{array}{c} 0.05955^{+0.021}_{-0.023} \\ 0.05834^{+0.019}_{-0.022} \\ 0.06195^{+0.021}_{-0.023} \\ 0.06396^{+0.025}_{-0.024} \\ \textbf{0.04176}^{+0.022}_{-0.018} \\ 0.00379^{+0.0026}_{-0.0026} \end{array}$ | $0.07615^{+0.019}_{-0.02}$ | 890 | $0.0225^{+0.0073}_{-0.0082}$ | $0.02867^{+0.0068}_{-0.0069}$ | 954 |
| $t_{\overline{	ext{KS}}}$ | $0.05834_{-0.022}^{+0.029}$ | | 802 | $\begin{array}{c} 0.0223 - 0.0082 \\ 0.02825 + 0.0094 \\ 0.02901 + 0.0093 \\ 0.02903 + 0.0075 \\ -0.0082 \\ 0.02689 + 0.012 \\ 0.02689 + 0.0053 \\ 0.02689 + 0.00053 \\ 0.02689 + 0.00053 \\ 0.02689 + 0.00053 \\ 0.0000000000000000000000000000000000$ | $0.03574^{+0.0088}_{-0.0095}$ | 861 |
| $t_{ m SKS}$ | $0.06195^{+0.021}_{-0.023}$ | 0.0=010±0.019 | 1200 | $0.02901^{+0.0093}_{-0.011}$ | $0.03683^{+0.0086}_{-0.0092}$ | 1080 |
| $t_{ m FGD}$ | $0.06396^{+0.025}_{-0.024}$ | $0.07913_{-0.021}^{+0.022} \ 0.07971_{-0.021}^{+0.022} \ 0.05326_{-0.017}^{+0.021}$ | 5360 | $0.02023^{+0.0075}_{-0.0082}$ | $0.02523_{-0.0069}^{+0.0066}$ | 5467 |
| $t_{ m MMD}$ | $0.04176^{+0.022}_{-0.018}$ | $0.05326^{+0.021}_{-0.017}$ | 1934 | $0.02689^{+0.012}_{-0.01}$ | $0.03445^{+0.011}_{-0.0094}$ | 1959 |
| $t_{ m LLR}$ | $0.00379^{+0.0026}_{-0.0026}$ | $0.0055^{+0.0026}_{-0.0026}$ | 3816 | $0.00074^{+0.00053}_{-0.00053}$ | $\begin{array}{c} 0.02507_{-0.0069} \\ 0.03574_{-0.0095}^{+0.0088} \\ 0.03683_{-0.0092}^{+0.0066} \\ \textbf{0.02523}_{-0.0069}^{+0.0066} \\ 0.03445_{-0.0094}^{+0.0011} \\ 0.00108_{-0.00053}^{+0.00052} \end{array}$ | 4378 |
| $\Sigma_{i\neq j}$ -deformation | | | | pow_+ -deformation | | |
| Statistic | $\epsilon_{95\%\mathrm{CL}}$ | $\epsilon_{99\%\mathrm{CL}}$ | t (s) | $\epsilon_{95\%\mathrm{CL}}$ | $\epsilon_{99\%\mathrm{CL}}$ | t (s) |
| $t_{ m SW}$ | $0.02576^{+0.0068}_{-0.0085}$ | $0.03407^{+0.0058}_{-0.007}$ | 18315 | $ \begin{array}{c} 0.00495^{+0.0017}_{-0.0019} \\ 0.00613^{+0.0019}_{-0.0022} \end{array} $ | $\begin{array}{c} 0.00629^{+0.0017}_{-0.0016} \\ 0.00754^{+0.0018}_{-0.0019} \end{array}$ | 978 |
| $t_{\overline{	ext{KS}}}$ | $1.02602_{-0.007}^{+0.0085}$ | $1.03113^{+0.015}_{-0.003}$ | 12342 | $0.00613^{+0.0019}_{-0.0022}$ | $0.00754_{-0.0019}^{+0.0018}$ | 896 |
| $t_{ m SKS}$ | $\pm 0.03286^{+0.01}$ | $0.04309^{+0.0093}$ | 13093 | $0.00572^{+0.0019}_{-0.0021}$ | 0.00714 ± 0.0018 | 1180 |
| $t_{ m FGD}$ | $0.0025^{+0.0007}_{-0.00071}$ | - $ +$ 0.0061 | 23984 | $0.00494^{+0.0019}_{-0.002}$ | $0.00613^{+0.0018}_{-0.0017}$ | 6351 |
| $t_{ m MMD}$ | -0.01614 ± 0.0066 | $0.02053^{+0.0062}_{-0.0054}$ | 16373 | $0.00332^{+0.0018}_{-0.0014}$ | $0.00423^{+0.0017}_{-0.0013}$ | 2150 |
| $t_{ m LLR}$ | $ \begin{array}{c} 0.01014_{-0.0062} \\ 0.01052_{-0.0043}^{+0.0042} \end{array} $ | $0.01376^{+0.0035}_{-0.0044}$ | 21223 | $0.00021^{+0.00015}_{-0.00015}$ | $0.00032^{+0.00015}_{-0.00015}$ | 4341 |
| $pow\deformation$ | | | | $\mathcal{N}	ext{-}	ext{deformation}$ | | |
| Statistic | $\epsilon_{95\%\mathrm{CL}}$ | $\epsilon_{99\%\mathrm{CL}}$ | t (s) | $\epsilon_{95\%	ext{CL}}$ | $\epsilon_{99\%\mathrm{CL}}$ | t (s) |
| $t_{ m SW}$ | $0.00508^{+5}_{-0.0017}$ | $0.00647^{+5}_{-0.0015}$ | 915 | $0.41334^{+0.062}_{-0.084}$ | $0.46898^{+0.052}_{-0.058}$ | 805 |
| $t_{\overline{	ext{KS}}}$ | $0.00597^{+0.0019}_{-0.0021}$ | $0.0074^{+0.0017}_{-0.0018}$ | 900 | $0.46482^{+0.07}_{-0.097}$ | 0.59444 + 0.056 | 731 |
| $t_{ m SKS}$ | $0.00563^{+0.0017}_{-0.002}$ | $0.00704^{+0.0016}_{-0.0017}$ | 1185 | $0.44843^{+0.067}_{-0.096}$ | $0.52444_{-0.075} \\ 0.50879_{-0.069}^{+0.057}$ | 928 |
| $t_{ m FGD}$ | $0.00508^{+0.0017}_{-0.0018}$ | $0.00625^{+0.0016}_{-0.0015}$ | 6610 | $0.1987^{+0.025}_{-0.037}$ | $0.22055^{+0.021}$ | 5119 |
| $t_{ m MMD}$ | $0.00353^{+0.0019}_{-0.0016}$ | $0.0045^{+0.0018}_{-0.0014}$ | 2116 | $1.01973^{+0.13}_{-0.17}$ | $1.1523^{+0.097}_{-0.11}$ | 1563 |
| $t_{ m LLR}$ | $0.00028^{+0.00015}_{-0.00015}$ | $0.00039^{+0.00015}_{-0.00015}$ | 4141 | - | - | - |
| $\mathcal{U}	ext{-deformation}$ | | | | | Timing | |
| Statistic | $\epsilon_{95\%\mathrm{CL}}$ | $\epsilon_{99\%\mathrm{CL}}$ | t (s) | t^{null} (s) | | |
| $t_{ m SW}$ | $ \begin{vmatrix} 0.71388^{+0.11}_{-0.14} \\ 0.80534^{+0.12}_{-0.17} \\ 0.77724^{+0.12}_{-0.16} \end{vmatrix} $ | $0.81581^{+0.084}_{-0.1}$ | 775 | 294 | | |
| $t_{\overline{	ext{KS}}}$ | $0.80534_{-0.17}^{+0.12}$ | $0.90238^{+0.1}$ | 710 | 527 | | |
| $t_{ m SKS}$ | $0.77724^{+0.12}_{-0.16}$ | $0.88187^{+0.098}_{-0.13}$ | 913 | 592 | | |
| $t_{ m FGD}$ | $0.34266^{+0.043}_{-0.065}$ | $0.88187^{+0.098}_{-0.13}$ $0.38262^{+0.033}_{-0.044}$ | 4326 | 7457 | | |
| $t_{ m MMD}$ | $1.76762^{+0.21}_{-0.3}$ | $1.99743^{+0.17}_{-0.19}$ | 1492 | 2390 | | |
| $t_{ m LLR}$ | - | - | - | - | | |