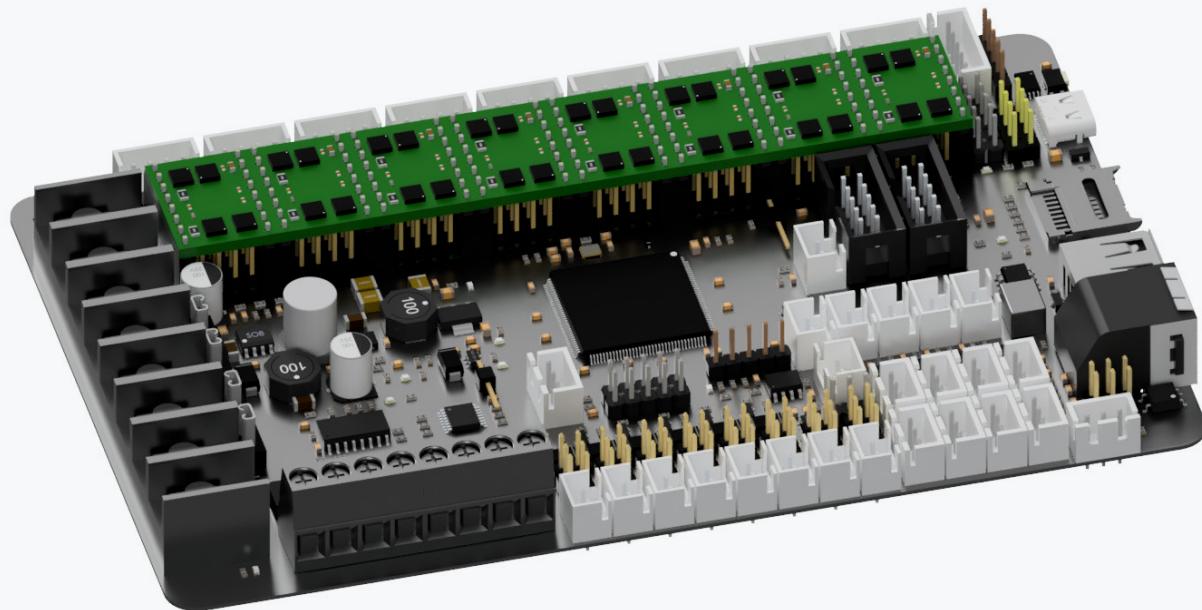


CONTROLLER BOARD

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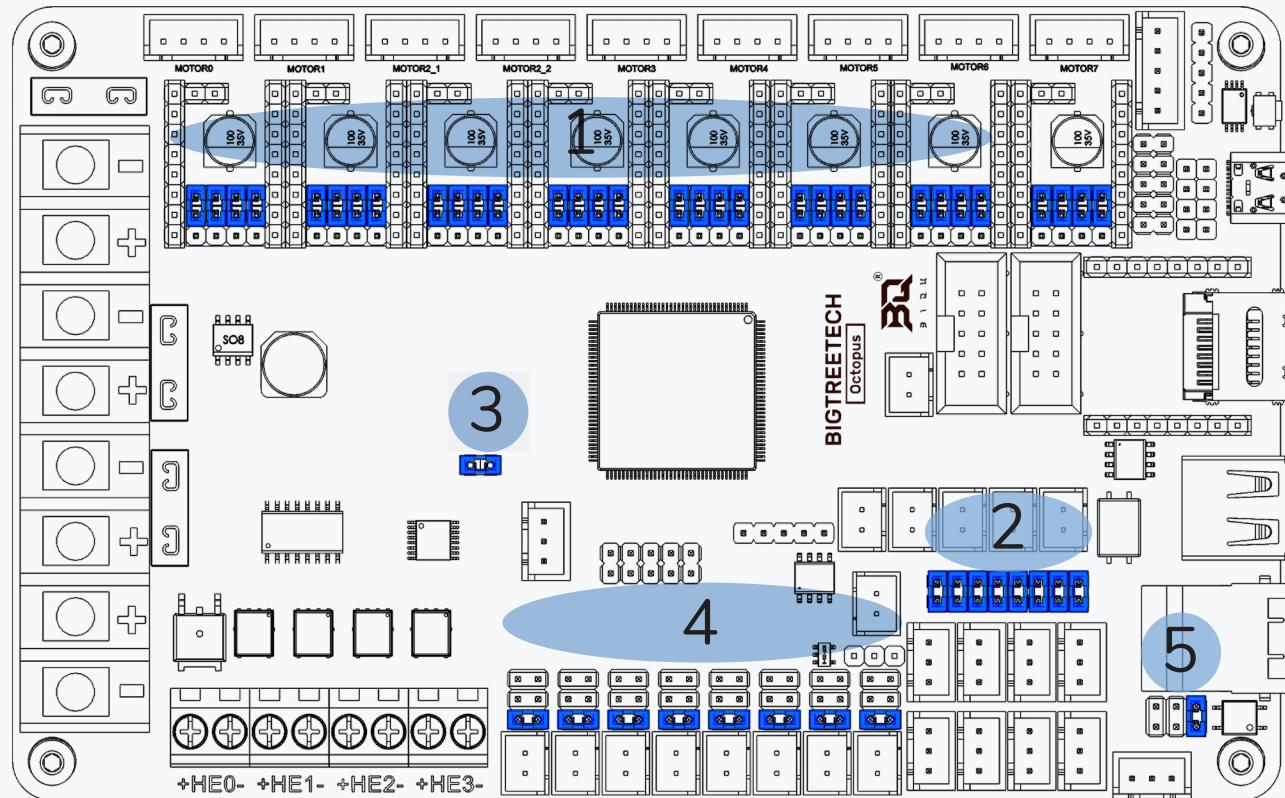
CONTROLLER BOARD

The assembly manual will outline the wiring for a Bigtreetech Octopus V1.1 board. You can find additional documentation and alternative configurations on docs.vorondesign.com.

JUMPERS

Several jumpers need to be configured on the controller board. We will begin by **removing all the JUMPERS** from the controller board (MCU).

- 1) Remove the jumpers in the “driver sockets”.
- 2) Remove all the jumpers in the “DIAG” header when using microswitch or Hall Effect endstops.
- 3) Remove the “USB 5V power supply” jumper to avoid the interaction between the USB 5V of Raspberry Pi and the 5V of the MCU.
- 4) Remove all the jumpers on the “Fan Voltage Selection” headers so that you can set the correct supply voltage.



- 5) Remove the jumper in “Probe Voltage Selection” header so that you can set it to the correct supply voltage.

Diagram courtesy of @GadgetAngel

JUMPERS

Several jumpers need to be set on the MCU.

Add the following JUMPERS to the controller board (MCU).

- 1) Set the jumpers in the "driver sockets" as shown to set TMC2209 UART mode.
- 2) Ensure all the jumpers in the "DIAG" header are removed.
- 3) Ensure the Power Selection header is empty.
- 4) Set the Jumpers for the "Fan Voltage Selection" header so they match your fan's voltage. Shown here are the settings for 24VDC.

- 5) Set the jumper in "Probe Voltage Selection" header to 24VDC.

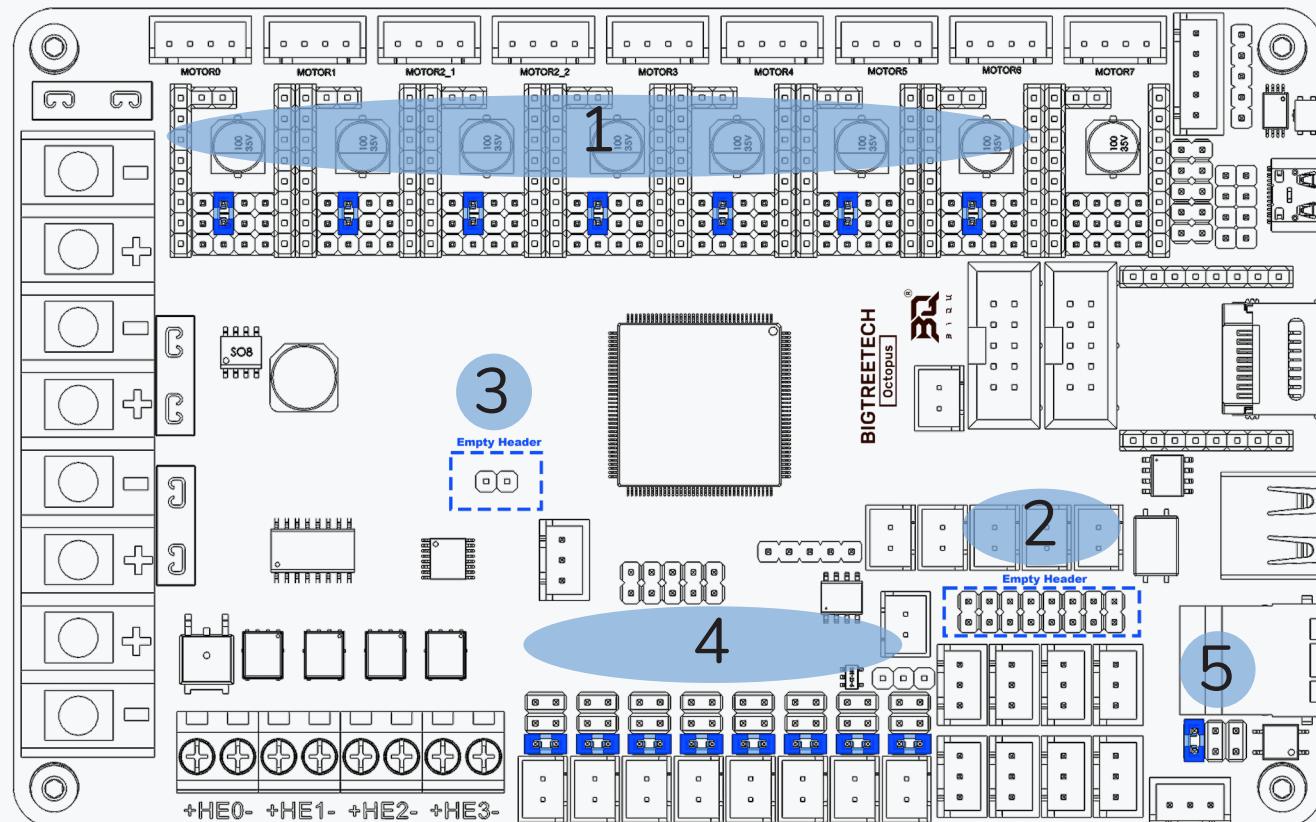


Diagram courtesy of @GadgetAngel

STEPPER DRIVERS

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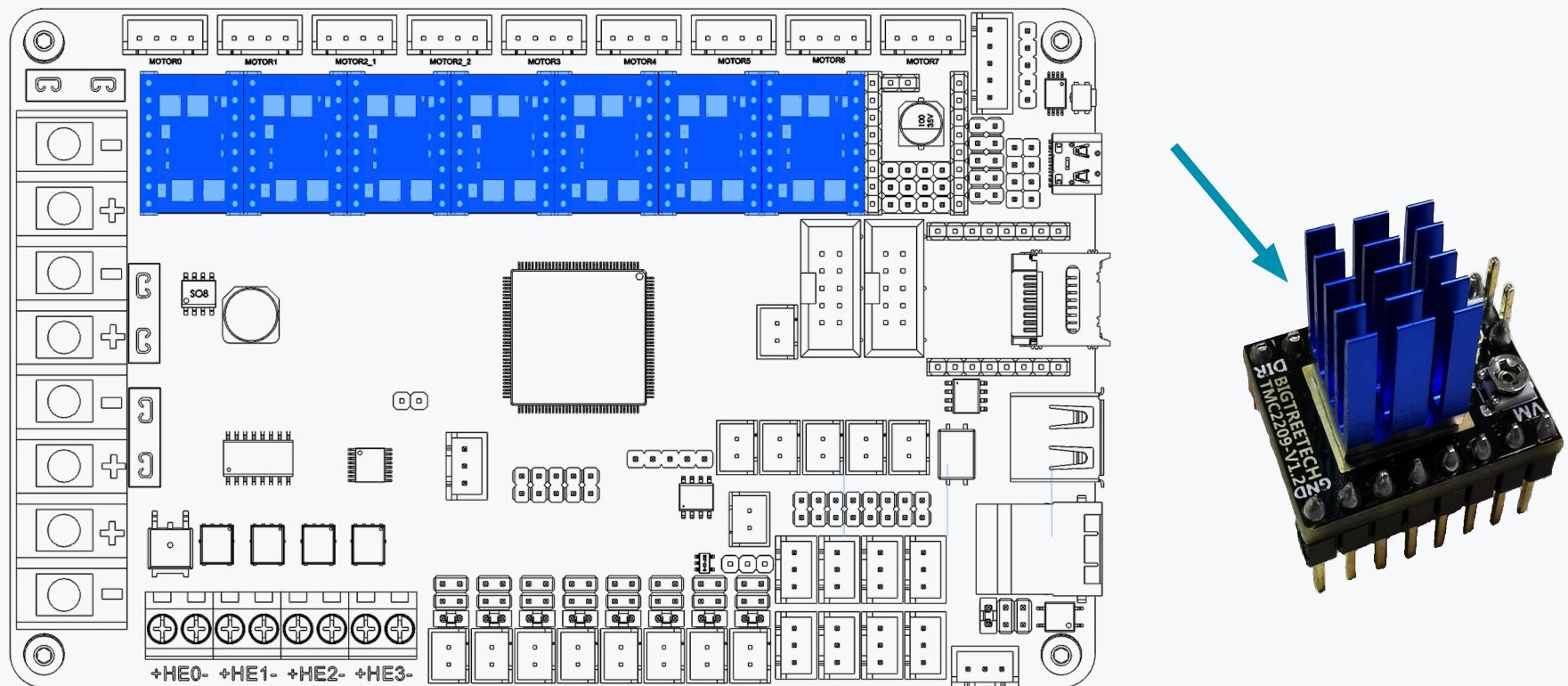


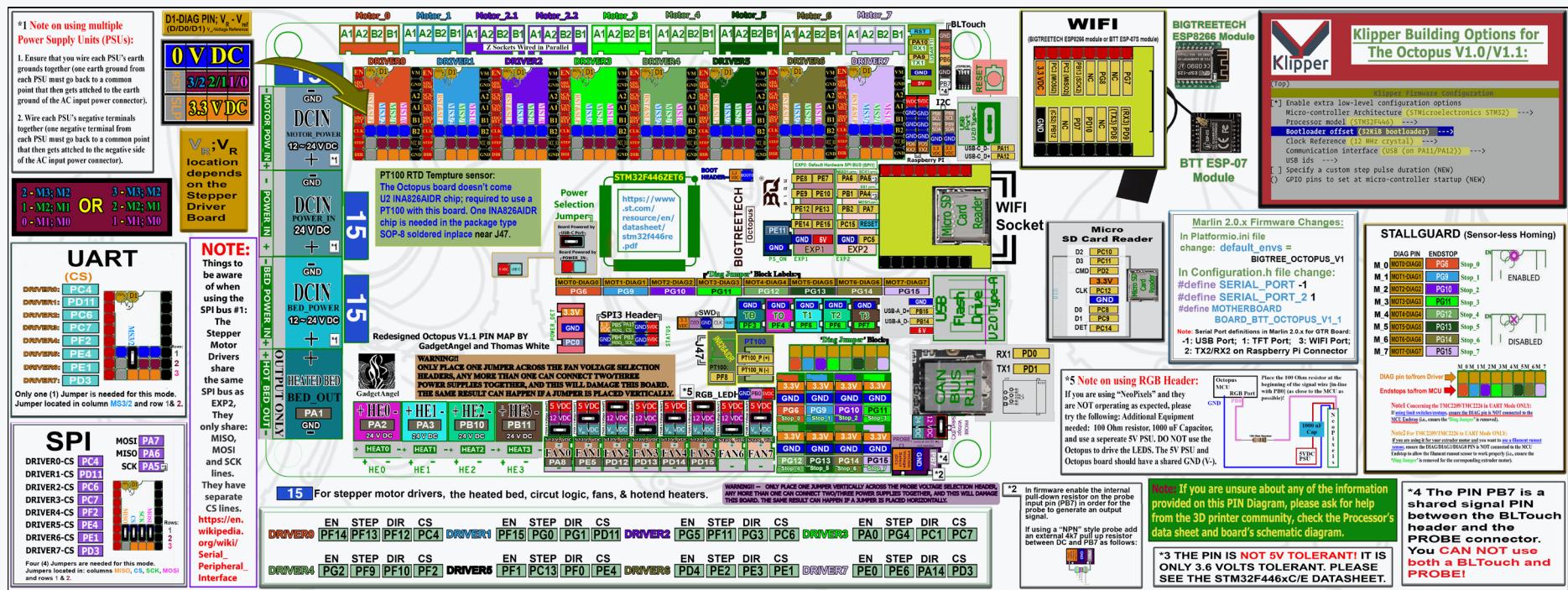
Diagram courtesy of @GadgetAngel

CONTROLLER BOARD

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OCTOPUS PINOUT REFERENCE

This [Coloured PIN diagram](#) can be found on GadgetAngel's GitHub repository for the Octopus V1.1



The original PIN diagram can be found on Bigtreetech's GitHub repository for Octopus V1.1

Diagram courtesy of @GadgetAngel

A year later this figure grew to 350 Voron2 printers.