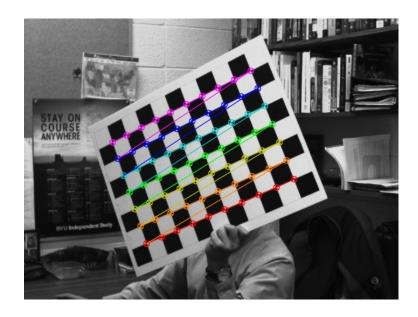
## Task 1 – Corner Detection



**Task 2 – Intrinsic Parameters** 

Calculated focal length: 8.48mm

Intrinsic parameters: [[1145.05898, 0.00000000, 328.612905]

[0.00000000, 1.14344385, 222.325254] [0.00000000, 0.00000000, 1.00000000]]

Distortion parameters: [[-0.254256031

-0.053261965

-0.001409690

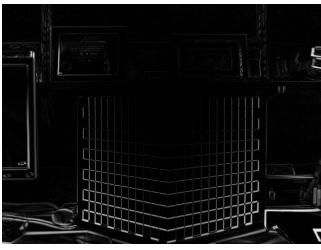
-0.001437376

2.28132168]]

## **Task 3 – Distortion Correction**







# Task 4 – Object Pose Estimation

R: [[ 0.73551327 -0.67738374 0.0130958 ] [-0.00323282 -0.02283801 -0.99973395] [ 0.67750261 0.73527525 -0.01898752]]

Euler Angles: [[ 1.51392294]

[-0.57974373] [ 0.58824618]]

Translation: [[-1.95992139e-02]

[ 1.04877854e+01] [ 4.67009922e+01]]

# Task 5 – My Camera's Intrinsic Parameters

Focal length is 10.88 mm (based on the 135 pix/mm, couldn't find a datasheet for mine)

Camera Matrix: [[1.46831591e+03 0.00000000e+00 6.13104006e+02]

Distortion: [[0.04017643

0.87701138 -0.00515214 -0.00955139 -3.39992284]]

# Task 6 – Distortion Correction on My Camera

My camera has a plastic lens and is pretty cheap. Here's what I got!

