

Bachelor's Thesis

Racing Line Detection - Recording and Comparison of Racing Lines

Ideallinienerkennung - Aufnahme und Vergleich von Ideallinien

by

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Potsdam, June 2016
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I certify that the material contained in this dissertation is my own work and does not contain significant portions of unreferenced or unacknowledged material. I also warrant that the above statement applies to the implementation of the project and all associated documentation.

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Potsdam, June 2, 2016	
(Tim Oesterreich)	



Kurzfassung

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Abstract

//TODO

Motor racing is all about getting around a track as fast as possible. One of the most important and most driver-influenced steps in achieving best times is the racing line, escpecially hitting the ideal racing line through corners.

Being able to track and compare difficult corners helps professional racing drivers to gain the necesseary tenth of a second to have an advantage over the competitors and racing beginners to learn track driving more quickly and efficiently.

This paper investigates ways of automatically recording the racing line from within the car using different methods like Visual Odometry and lane detection and use the extracted data to compare and analyse the driving behaviour of different drivers.

Contents



Contents

1.	Intro	oduction	1
	1.1.	Motivation	1
	1.2.	Project Scope	1
	1.3.	Problem Introduction/Description/Context	1
2.	Rela	ated Work	2
3.	Alg	orithm/Concept	5
	3.1.	Recording	5
		3.1.1. Visual Odometry	5
		3.1.2. Lane Detection	5
		3.1.3. GPS/Other Real Time Location Services	5
	3.2.	Comparing	5
		3.2.1. Visual Comparison of Racing Line	5
		3.2.2. Mathematical Comparison using Sensordata	5
4.	Imp	lementation	6
	4.1.	Hardware Setup	6
	4.2.	CUDA-accelerated Algorithms	6
5.	Eva	luation	6
	5.1.	Visual Odometry for recording Racing Lines	6
	5.2.	Usefulness of Racing Line Comparison	6
6.	Futi	ure Work	7
	6.1.	Open Research Questions	7
	6.2.	Extensions	7
7.	Con	nclusion	9
Bil	bliog	raphy	11
Α.	App	pendix	12



1. Introduction

- 1.1. Motivation
- 1.2. Project Scope
- 1.3. Problem Introduction/Description/Context

Brief Thesis Structure



2. Related Work

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3. Algorithm/Concept

- 3.1. Recording
- 3.1.1. Visual Odometry
- 3.1.2. Lane Detection
- 3.1.3. GPS/Other Real Time Location Services
- 3.2. Comparing
- 3.2.1. Visual Comparison of Racing Line
- 3.2.2. Mathematical Comparison using Sensordata



4. Implementation

4.1. Hardware Setup

4.2. CUDA-accelerated Algorithms

5. Evaluation

5.1. Visual Odometry to record Racing Lines

Pro: Many Datapoints (in theory up to Framerate positions per second) Capable of detecting fairly slight movements No need for external sensors (apart from camera which already exists) works in every environment (especially where there is no or poor GPS signal)

Con: uses fairly expensive operations in praxis mobile-range computers will only reach up to 10 fps no constant speed (slows down in areas with many feature points (like forests)) fairly error prone rounding errors and inaccurate calculations add up and distort the racing line

5.2. Usefulness of Racing Line Comparison



6. Future Work

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6.1. Open Research Questions

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6.2. Extensions

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7. Conclusion



References



A. Appendix

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