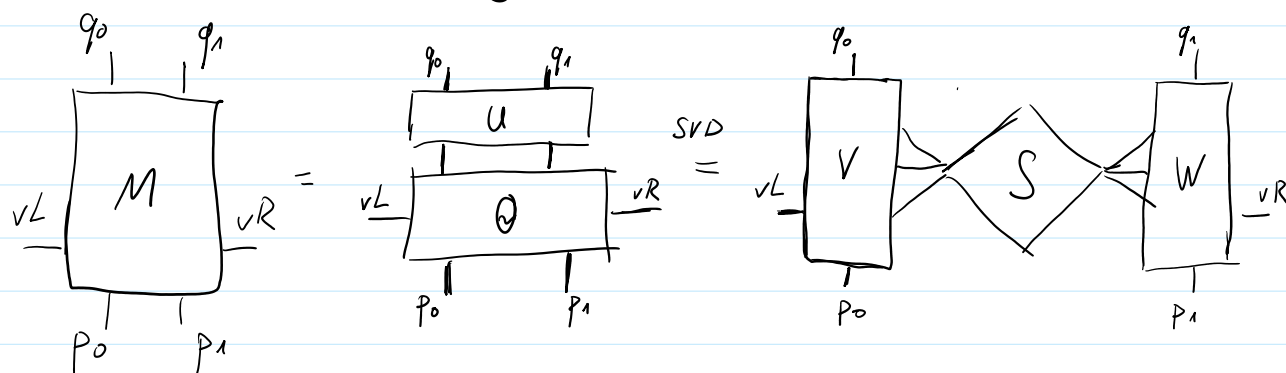


Calculating Euclidian Gradient

01 November 2021 21:09

We want to calculate Euclidian Gradient of Renyi entropy defined on the following tensor :



Cost function (Renyi Entropy):

$$\mathcal{J}(U) = \frac{1}{1-\alpha} \log [\text{tr}(S^\alpha)],$$

where Q is assumed to be constant.

$$\begin{aligned} \frac{\partial \mathcal{J}(U)}{\partial u_{a_0 a_1}^{a_0^* a_1^*}} &= \frac{1}{1-\alpha} \frac{\partial}{\partial u_{a_0 a_1}^{a_0^* a_1^*}} (\log [\text{tr}(S^\alpha)]) \\ &= \frac{1}{1-\alpha} \frac{1}{\text{tr}(S^\alpha)} \frac{\partial \text{tr}(S^\alpha)}{\partial u_{a_0 a_1}^{a_0^* a_1^*}} \end{aligned}$$

To calculate

gradients $\partial \mathcal{J}(U) / \partial u$, let's write tensors explicitly (using Einstein notation throughout, up / down indices do not indicate standard / dual spaces, they are just used to shorten the notation):

$$M_{v_L v_R p_0 p_1}^{q_0 q_1} = U_{q_0^* q_1^*}^{q_0 q_1} Q_{v_L v_R p_0 p_1}^{q_0^* q_1^*} = V_{v_L v_L' p_0 p_0'}^{q_0 q_0'} S_{q_0' q_1'}^{v_L' v_R' p_0' p_1'} W_{v_R v_R' p_1 p_1'}^{q_1 q_1'},$$

because V/W are left / right orthogonal we can write:

$$\left(V_{v_L v_L'' p_0 p_0''}^{q_0 q_0''} \right)^* M_{v_L v_R p_0 p_1}^{q_0 q_1} \left(W_{v_R v_R'' p_1 p_1''}^{q_1 q_1''} \right) =$$

$$\begin{aligned}
&= \underbrace{\left(V_{vL vL''}^{q_0 q_0''} \right)^* V_{vL vL'}^{q_0 q_0'} }_{\delta_{q_0' q_0''} \delta_{vL' vL''} \delta_{p_0' p_0''}} \sum_{q_0' q_1'}^{vL' vR' p_0' p_1'} \underbrace{W_{vR vR'}^{q_1 q_1'} (W_{vR vR''}^{q_1 q_1''})}_{\delta_{q_1' q_1''} \delta_{vR' vR''} \delta_{p_1' p_1''}} \\
&= \sum_{q_0'' q_1''}^{vL'' vR'' p_0'' p_1''}
\end{aligned}$$

From that we get :

$$\begin{aligned}
\frac{\partial \text{tr}(S^\alpha)}{\partial u_{a_0^* a_1^*}^{a_0 a_1}} &= \left[\begin{array}{c} \text{because } S \\ \text{is diagonal} \end{array} \right] = \frac{\partial}{\partial u_{a_0^* a_1^*}^{a_0 a_1}} \left(S_{qq}^{vv pp} \right)^\alpha \\
&\quad \left[\begin{array}{l} \text{Here we don't} \\ \text{sum over } v, p, q \\ \text{but for each} \\ \text{indices } v, p, q \\ \text{we set } v, p, q \\ \text{to same indices} \end{array} \right] \\
&= \alpha \left(S_{qq}^{vv pp} \right)^{\alpha-1} \frac{\partial}{\partial u_{a_0^* a_1^*}^{a_0 a_1}} S_{qq}^{vv pp} = \\
&= \alpha \left(S_{qq}^{vv pp} \right)^{\alpha-1} \frac{\partial}{\partial u_{a_0^* a_1^*}^{a_0 a_1}} \left[\left(V_{vL v p_0 p}^{q_0 q} \right)^* M_{vL vR p_0 p_1}^{q_0 q_1} W_{vR v p_1 p}^{q_1 q} \right] \\
&= \alpha \left(S_{qq}^{vv pp} \right)^{\alpha-1} \frac{\partial}{\partial u_{a_0^* a_1^*}^{a_0 a_1}} \left[\left(V_{vL v p_0 p}^{q_0 q} \right)^* u_{q_0^* q_1^*}^{q_0 q_1} \Theta_{vL vR p_0 p_1}^{q_0^* q_1^*} W_{vR v p_1 p}^{q_1 q} \right] \\
&= \alpha \left(S_{qq}^{vv pp} \right)^{\alpha-1} \delta_{a_0 q_0} \delta_{a_1 q_1} \delta_{a_0^* q_0^*} \delta_{a_1^* q_1^*} \left(V_{vL v p_0 p}^{q_0 q} \right)^* \Theta_{vL vR p_0 p_1}^{q_0^* q_1^*} W_{vR v p_1 p}^{q_1 q} \\
&= \alpha \left(S_{qq}^{vv pp} \right)^{\alpha-1} \left(V_{vL v p_0 p}^{a_0 q} \right)^* \Theta_{vL vR p_0 p_1}^{a_0^* a_1^*} W_{vR v p_1 p}^{a_1 q}
\end{aligned}$$

So the partial derivatives of the cost function are :

$$\frac{\partial \mathcal{J}(u)}{\partial u_{a_0^* a_1^*}^{a_0 a_1}} = \frac{\alpha}{1-\alpha} \frac{1}{\text{tr}(S^\alpha)} \left(S_{qq}^{vv pp} \right)^{\alpha-1} \left(V_{vL v p_0 p}^{a_0 q} \right)^* \Theta_{vL vR p_0 p_1}^{a_0^* a_1^*} W_{vR v p_1 p}^{a_1 q}$$