

Linear Systems & Augmented Matrices

Solutions of Linear Equations

Given n real numbers s_1, s_2, \dots, s_n , we say that $x_1=s_1, x_2=s_2, \dots, x_n=s_n$ is a solution to a linear equation $a_1x_1=s_1, a_2x_2=s_2, \dots, a_nx_n=b$ if the equation is satisfied when we substitute the values into the equation accordingly.

In other words, if $a_1s_1+a_2s_2+\dots+a_ns_n=b$, s_1, s_2, \dots, s_n is a solution to $a_1x_1+a_2x_2+\dots+a_nx_n=b$.

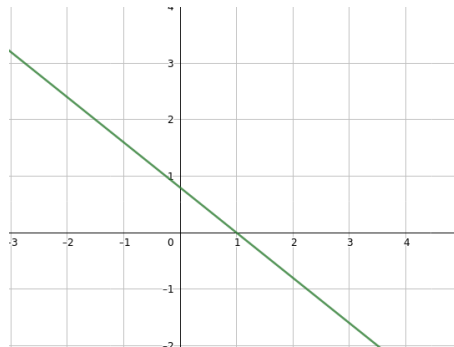
In even simpler words, for example given a linear equation, such as $4x+2y+5z=2$ what are the numbers x, y, z that I can plug into the equation such that it is true?

Or if given $y=-0.8x+0.8$, what are the numbers a, b that I can plug into the equation such that it is true?

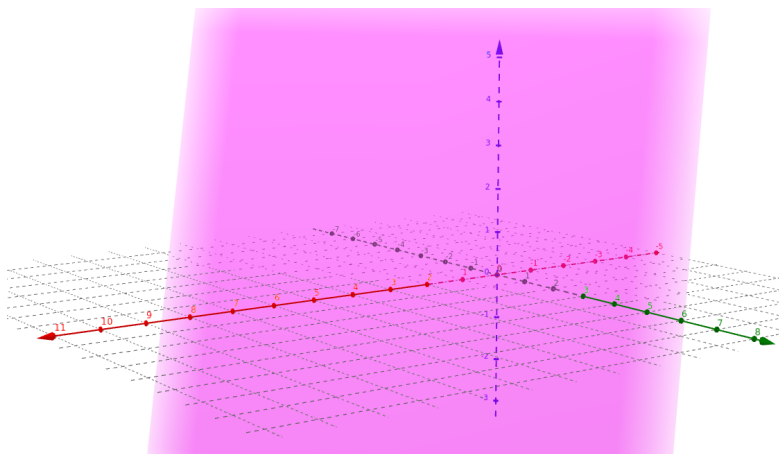
Given the equation $4x+2y+5z=2$, $x=-1.75, y=2, z=1$ is one of the infinitely many possible solutions to the equation, because $4(-1.75)+2(2)+5(1)=2$. Similarly, $x=-1.75, y=2, z=1$ is another possible solution since $4(0)+2(-4)+5(2)=2$.

Geometrical Representation of Solutions of Linear Equations

The solutions of an equation can be visualised geometrically. For example, given the formula $y = -0.8x + 0.8$, we can represent all the solutions as a line.



Similarly, for the general equation $3x + 2y + z = 6$, we can represent its solutions as a plane.



You might recognise $3x + 2y + z = 6$ as a plane equation and that is no coincidence. Any point in that plane will satisfy the equation. Let's call this plane P . This means that the normal of our plane is $(3, 2, 1)$ and $(3, 2, 1) \cdot (x, y, z) = 6 \mid (x, y, z) \in P$.

General Solutions of Linear Equations

Consider the linear equation $4x - 2y = 1$ which has infinitely many solutions. The general solution is, $x = t, y = 2t - 0.5$ where t is an arbitrary parameter. In other words, any point $(t, 2t - 0.5) \mid t \in \mathbb{R}$ lies on the line $4x - 2y = 1$.

Alternatively, we can also write the general solution as $x = 0.5s + 0.25, y = s$, where s is an arbitrary parameter. In other words, any point $(0.5s + 0.25, s) \mid s \in \mathbb{R}$ lies on the line $4x - 2y = 1$.

Linear Systems

A finite set of linear equations in the variables x_1, x_2, \dots, x_n is called a **linear system** (also known as a **system of linear equations**).

A linear system looks like:

$$\begin{aligned} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n &= b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n &= b_2 \\ &\vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n &= b_m \end{aligned} \quad \text{where } a_{11}, a_{12}, \dots, a_{mn} \text{ and } b_1, b_2, \dots, b_m \text{ are real constants.}$$

Some examples of linear systems are:

$$\begin{aligned} x + 2y + 3z &= 11 \\ 4x + 5y + 6z &= 16 \\ 7x + 8y + 9z &= 63 \end{aligned} \quad \text{where } x, y, z \text{ are the solutions to the linear system.}$$

$$\begin{aligned} x + 2y &= 4 \\ 3x + 2y &= 11 \\ 6x + 6y &= -43 \end{aligned} \quad \text{where } x, y \text{ are the solutions to the linear system.}$$

$$\begin{aligned} w &= 0.432 \\ x &= 5 \\ y &= -1.7 \\ z &= -9 \end{aligned} \quad \text{where } w, x, y, z \text{ are the solutions to the linear system.}$$

A linear system can only have either 0, 1 or infinitely many solutions. Therefore it is impossible for a linear system to only have 2, 3, 7, 46, 500 or 3213 unique solutions.

Homogeneous Linear Systems

A system of linear equations is homogeneous if all the constant terms are zero.

$$\begin{aligned} 1x + 2y + 3z &= 0 \\ 4x + 5y + 6z &= 0 \\ 7x + 8y + 9z &= 0 \end{aligned} \quad \text{or} \quad \left(\begin{array}{ccc|c} 1 & 2 & 3 & 0 \\ 4 & 5 & 6 & 0 \\ 7 & 8 & 9 & 0 \end{array} \right)$$

A homogeneous linear system always has the origin as the solution. The origin is called the trivial solution. Any other solution is called a non-trivial solution. Since any linear system may only have 0, 1 or infinite number of solutions, and a homogeneous linear system always has the origin as its solution, we can deduce that a homogeneous linear system will either have 1 or infinite number of solutions.

Augmented Matrices

A system of linear equations can be represented by an augmented matrix.

$$\begin{array}{l} 1x+2y+3z=11 \\ 4x+5y+6z=16 \\ 7x+8y+9z=63 \end{array} \text{ can be represented as } \left(\begin{array}{ccc|c} 1 & 2 & 3 & 11 \\ 4 & 5 & 6 & 16 \\ 7 & 8 & 9 & 63 \end{array} \right).$$

$$\begin{array}{l} 1x+2y+3z=0 \\ 4x+5y+6z=0 \\ 7x+8y+9z=0 \end{array} \text{ can be represented as } \left(\begin{array}{ccc|c} 1 & 2 & 3 & 0 \\ 4 & 5 & 6 & 0 \\ 7 & 8 & 9 & 0 \end{array} \right).$$

Augmented matrices allow us to solve for the solutions of a linear system using **Gaussian elimination** and **Gauss-Jordan elimination**. You are expected to know **Gaussian elimination** and **Gauss-Jordan elimination**. They will not be covered in this document but is crucial to its understanding.