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Zhejiang University

组合优化

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计算复杂性初步



3SAT

- **3SAT:** 在SAT问题的描述中, 限定任一子句包含文字数不超过3

任取SAT问题的一实例

$$\begin{aligned} & (l_{i_{11}} \vee l_{i_{12}} \vee \cdots \vee l_{i_{1l_1}}) \\ & \wedge (l_{i_{21}} \vee l_{i_{22}} \vee \cdots \vee l_{i_{2l_2}}) \\ & \wedge \cdots \wedge (l_{i_{k1}} \vee l_{i_{k2}} \vee \cdots \vee l_{i_{kl_k}}) \end{aligned}$$

任取3SAT问题的一实例

$$\begin{aligned} & (l_{i_{11}} \vee l_{i_{12}} \vee l_{i_{13}}) \\ & \wedge (l_{i_{21}} \vee l_{i_{22}} \vee l_{i_{23}}) \\ & \wedge \cdots \wedge (l_{i_{k1}} \vee l_{i_{k2}} \vee l_{i_{k3}}) \end{aligned}$$

- **2SAT** $\in \mathcal{P}$

Krom MR. The Decision Problem for a Class of First-Order Formulas in which all Disjunctions are Binary. *Mathematical Logic Quarterly*, 13, 15-20, 1967.

$$\text{SAT} \leq_m^p 3\text{SAT}$$

- 任取SAT问题一实例 $F_{\text{SAT}} = c_1 \wedge c_2 \wedge \cdots \wedge c_m$,
构造3SAT问题的实例 $F_{3\text{SAT}}$

- 若 c_i 中所含文字数不超过3, 则 F_3 也包含子句 c_i
- 若 $c_i = l_{i_1} \vee l_{i_2} \vee \cdots \vee l_{i_k}$, 则令

$$C_i = (l_{i_1} \vee l_{i_2} \vee y_{i1}) \wedge (\neg y_{i1} \vee l_{i_3} \vee y_{i2}) \wedge (\neg y_{i2} \vee l_{i_4} \vee y_{i3}) \\ \wedge \cdots \wedge (\neg y_{i,k-4} \vee l_{i_{k-2}} \vee y_{i,k-3}) \wedge (\neg y_{i,k-3} \vee l_{i_{k-1}} \vee l_{i_k})$$

其中 $y_{i1}, y_{i2} \cdots y_{i,k-3}$ 是新变量且不出现在别处。 F_3
中包含 C_i 中所有子句

$$\text{SAT} \leq_m^p 3\text{SAT}$$

- 若 F_{SAT} 答案为“是”，则存在一种赋值，使得任一子句 c_i 为真，因此 c_i 中文字至少有一个为真，不妨设为 l_{i_j}
- 存在一种赋值，使得 $F_{3\text{SAT}}$ 中每个子句均为真， $F_{3\text{SAT}}$ 答案也为“是”

$$c_i = l_{i_1} \vee l_{i_2} \vee \cdots \vee \overset{1}{l_{i_j}} \vee \cdots \vee l_{i_k} \quad F_{\text{SAT}} \text{ 中原有变量赋值保持不变}$$

$$\begin{aligned} C_i = & (l_{i_1} \vee l_{i_2} \vee \overset{1}{y_{i1}}) \wedge (\neg \overset{0}{y_{i1}} \vee l_{i_3} \vee \overset{1}{y_{i2}}) \wedge \cdots \wedge (\neg \overset{0}{y_{i,j-4}} \vee l_{i_{j-2}} \vee \overset{1}{y_{i,j-3}}) \\ & \wedge (\neg \overset{0}{y_{i,j-3}} \vee l_{i_{j-1}} \vee \overset{1}{y_{i,j-2}}) \wedge (\neg \overset{0}{y_{i,j-2}} \vee \overset{1}{l_{i_j}} \vee \overset{0}{y_{i,j-1}}) \wedge (\neg \overset{1}{y_{i,j-1}} \vee l_{i_{j+1}} \vee \overset{0}{y_{i,j}}) \\ & \wedge (\neg \overset{1}{y_{i,j}} \vee l_{i_{j+2}} \vee \overset{0}{y_{i,j+1}}) \wedge \cdots \wedge (\neg \overset{1}{y_{i,k-4}} \vee l_{i_{k-2}} \vee \overset{0}{y_{i,k-3}}) \wedge (\neg \overset{1}{y_{i,k-3}} \vee l_{i_{k-1}} \vee l_{i_k}) \end{aligned}$$

$$\text{SAT} \leq_m^p 3\text{SAT}$$

- 若 $F_{3\text{SAT}}$ 答案为“是”，则存在一种赋值，使得 $F_{3\text{SAT}}$ 中每个子句均为真
- 将该赋值限制到 F_{SAT} 中的变量，若存在一子句 c_i 为假，则 c_i 中所有文字均为假
- C_i 中有子句值为假，矛盾，故 c_i 中所有子句均为真， F_{SAT} 答案也为“是”

$$c_i = \overset{0}{l_{i_1}} \vee \overset{0}{l_{i_2}} \vee \cdots \vee \overset{0}{l_{i_j}} \vee \cdots \vee \overset{0}{l_{i_k}}$$

$$C_i = (\overset{0}{l_{i_1}} \vee \overset{0}{l_{i_2}} \vee \overset{1}{y_{i1}}) \wedge (\neg \overset{0}{y_{i1}} \vee \overset{0}{l_{i_3}} \vee \overset{1}{y_{i2}}) \wedge (\neg \overset{0}{y_{i2}} \vee \overset{0}{l_{i_4}} \vee \overset{1}{y_{i3}}) \wedge \cdots$$

$$\wedge \cdots \wedge (\neg \overset{0}{y_{i,k-5}} \vee \overset{0}{l_{i_{k-3}}} \vee \overset{1}{y_{i,k-4}}) \wedge (\neg \overset{0}{y_{i,k-4}} \vee \overset{0}{l_{i_{k-2}}} \vee \overset{1}{y_{i,k-3}}) \wedge (\neg \overset{0}{y_{i,k-3}} \vee \overset{0}{l_{i_{k-1}}} \vee \overset{0}{l_{i_k}})$$

One of the cherished customs of childhood is choosing up sides for a ball game. Where I grew up, we did it this way. The two chief bullies of the neighborhood would appoint themselves captains of the opposing teams, and then they would take turns picking other players. On each round, a captain would choose the most capable (or, toward the end, the least inept) player from the pool of remaining candidates, until everyone present had been assigned to one side or the other. The aim of this ritual was to produce two evenly matched teams and, along the way, to remind each of us of our precise ranking in the neighborhood pecking order. It usually worked.

None of us in these days—not the hopefuls waiting for our name to be called, and certainly not the two thick-necked team leaders—recognized that our scheme for choosing sides implements a greedy heuristic for the balanced number partitioning problem. And we had no idea that this problem is NP-complete—that finding the optimum team rosters is certifiably hard. We just wanted to get on with the game.

And therein lies a paradox: If computer scientists find the partitioning problem so intractable, how come children the world over solve it every day? Are the kids that much smarter? Quite possibly they are. On the other hand, the success of playground algorithms for partitioning might be a clue that the task is not always as hard as that forbidding term “NP-complete” tends to suggest. As a matter of fact, finding a hard instance of this famously hard problem can be a hard problem—unless you know where to look. Some recent re-

searches into two sets with equal running time will balance the load on the processors. Another example is apportioning the miscellaneous assets of an estate between two heirs.

So What's the Problem?

Here is a slightly more formal statement of the partitioning problem. You are given a set of n positive integers, and you are asked to separate them into two subsets; you may put as many or as few numbers as you please in each of the subsets, but you must make the sums of the subsets as nearly equal as possible. Ideally, the two sums would be exactly the same, but this is feasible only if the sum of the entire set is even; in the event of an odd total, the best you can possibly do is to choose two subsets that differ by 1. Accordingly, a perfect partition is defined as any arrangement for which the “discrepancy”—the absolute value of the subset difference—is no greater than 1.

Try a small example. Here are 10 numbers—enough for two basketball teams—selected at random from the range between 1 and 10:

2 10 3 8 5 7 9 5 3 2

Can you find a perfect partition? In this instance it so happens there are 23 ways to divvy up the numbers into two groups with exactly equal sums (or 46 ways if you count mirror images as distinct partitions). Almost any reasonable method will converge on one of these perfect solutions. This is the answer I stumbled onto first:

(2 5 3 10 7) (2 5 3 9 8)

Both subsets sum to 27.

Hayes B. The easiest hard problem.
American Scientist,
90(2), 113-117, 2002.

划分问题

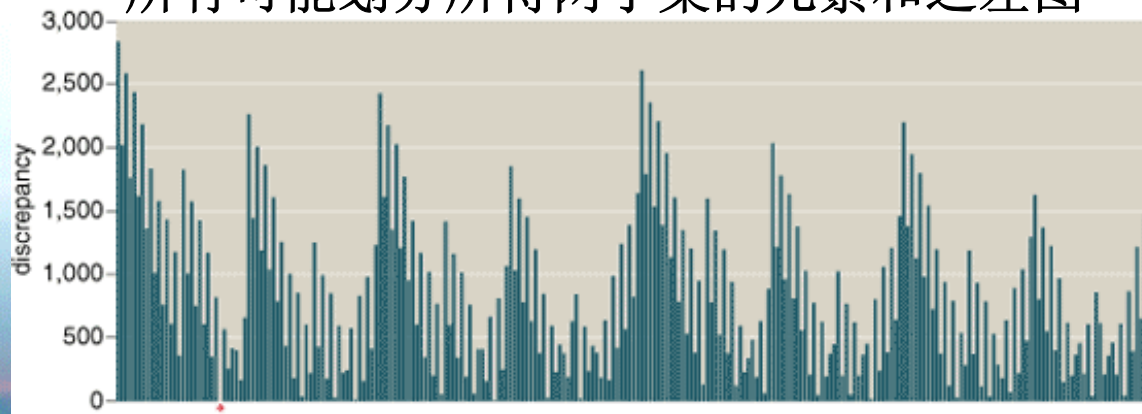
• 划分问题 (Partition)

- 给定一正整数集 $A = \{a_1, a_2, \dots, a_n\}$, 问是否存在子集 A_1, A_2 , 使得 $A = A_1 \cup A_2, A_1 \cap A_2 = \emptyset$, 且满足 $\sum_{a_i \in A_1} a_i = \sum_{a_i \in A_2} a_i = \frac{1}{2} \sum_{j=1}^n a_j$

$A = \{484, 114, 205, 288, 506, 503, 201, 127, 410\}$

$A_1 = \{410, 506, 503\}, A_2 = \{484, 114, 205, 288, 201, 127\}$

所有可能划分所得两子集的元素和之差图



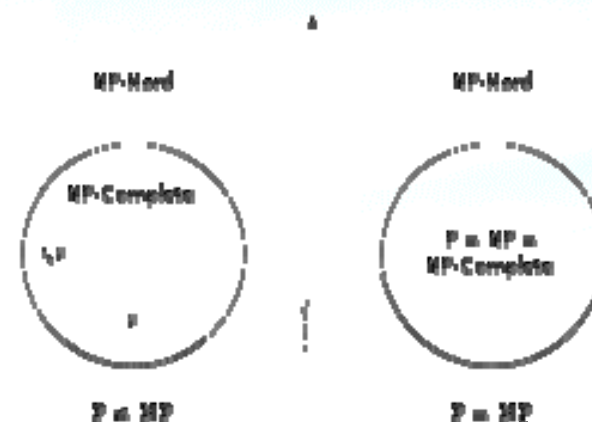
\mathcal{NP} -难



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- 至少和 \mathcal{NP} -完全问题一样难的问题称为 \mathcal{NP} -难 (\mathcal{NP} -hard) 问题
 - 在 $\mathcal{P} \neq \mathcal{NP}$ 的假设下, \mathcal{NP} -难问题也没有多项式时间算法
 - 若一优化问题的判定形式是 \mathcal{NP} -完全的, 则该优化问题是 \mathcal{NP} -难的





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子问题

- 在某问题 Π 的实例构成上增加一些限制就得到的一个子问题 (subproblem) Π'
 - Π' 的实例集包含在 Π 的实例集中, Π' 的答案为“是” (“否”) 的实例集恰为 Π 的答案为“是” (“否”) 的实例集与 Π' 的实例集之交
- 子问题的计算复杂性
 - 若 $\Pi \in \mathcal{P}$, 则 $\Pi' \in \mathcal{P}$, 但反之不然
 - 若 Π' 是 \mathcal{NP} -完全的, 则 Π 也是 \mathcal{NP} -完全的, 但反之不然
 - 希望寻找“最特殊”的 \mathcal{NP} -完全子问题和“最一般”的 \mathcal{P} 子问题

子集和问题

- 子集和问题 (Subset Sum)
 - 给定正整数集 $A = \{a_1, a_2, \dots, a_n\}$ 和数 B , 问是否存在子集 $A_1 \subseteq A$, 使得 $\sum_{a_i \in A_1} a_i = B$
 - 取 $B = \frac{1}{2} \sum_{j=1}^n a_j$, 划分问题成为子集和问题的子问题
 - 子集和问题的优化形式 子集和是 \mathcal{NP} 一完全问题
 - 求子集 $A_1 \subseteq A$, 使得 $\sum_{a_i \in A_1} a_i \leq B$ 且 $\sum_{a_i \in A_1} a_i$ 尽可能大
 - 若背包问题物品 j 的价值与大小均为 a_j , 容量为 B , 则子集和问题优化形式成为背包问题优化形式的子问题
- 背包问题判定形式是 \mathcal{NP} 一完全问题

子集和问题

- 子集和问题的优化形式（极小化） 极小化背包的定义与应用
 - 求子集 $A_1 \subseteq A$ ，使得 $\sum_{a_i \in A_1} a_i \geq B$ 且 $\sum_{a_i \in A_1} a_i$ 尽可能小
- 第 K 个最大子集和问题
 - 给定正整数集 $A = \{a_1, a_2, \dots, a_n\}$ 和数 B ，问是否存在 A 的 K 个子集 A_1, A_2, \dots, A_K ，使得 $\sum_{a_i \in A_i} a_i \leq B, i = 1, \dots, K$
 - 第 K 个最大子集和问题可能不属于 \mathcal{NP}
 - 实例规模: $n + \max_{i=1, \dots, n} \log a_i + \log B + \log K$
 - 可行解的规模: Kn

强 \mathcal{NP} - 完全

- 设 Π 为一 \mathcal{NP} - 完全问题，且存在多项式函数 p ，使得 Π 的某个所有实例满足 $\text{Max}(I) \leq p(\text{size}(I))$ 的子问题 Π' 是 \mathcal{NP} - 完全的，则称 Π 为强 \mathcal{NP} - 完全 (strongly \mathcal{NP} - complete) 的
- 在 $\mathcal{P} \neq \mathcal{NP}$ 的假设下，任何强 \mathcal{NP} - 完全问题不存在伪多项式时间算法
 - 若 Π 存在伪多项式时间算法 A ，其时间复杂性为
$$f(I) = O(\text{poly}(\text{size}(I), \text{Max}(I)))$$
 - 用 A 求解 Π 的子问题 Π' ，其时间复杂性为
$$f(I) = O(\text{poly}(\text{size}(I), \text{Max}(I))) = O(\text{poly}(\text{size}(I), p(\text{size}(I)))) = O(\text{poly}(\text{size}(I)))$$
 - A 为 Π' 的多项式时间算法，与 Π' 的 \mathcal{NP} - 完全性矛盾

强 \mathcal{NP} -完全性的证明



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组合优化

- 问题是 \mathcal{NP} -完全的，且其所有实例均满足 $\text{Max}(I) \leq p(\text{size}(I))$
 - Hamilton图问题、SAT问题
- 归约证明某问题的 \mathcal{NP} -完全性时所构造的该问题的实例均满足 $\text{Max}(I) \leq p(\text{size}(I))$
 - TSP问题的判定形式
- 按强 \mathcal{NP} -完全问题的定义证明
 - 寻找多项式函数 p 和所有实例满足 $\text{Max}(I) \leq p(\text{size}(I))$ 的子问题，通过归约证明该子问题是 \mathcal{NP} -完全的
- 用伪多项式时间归约从一个已知强 \mathcal{NP} -完全问题出发证明某问题的强 \mathcal{NP} -完全性



伪多项式时间归约

- 设有判定问题 Π_1, Π_2 ，若对 Π_1 的任一实例 I_1 ，可在 $O(\text{poly}(\text{size}(I_1), \text{Max}(I_1)))$ 时间内构造出 Π_2 的一个实例 $I_2 = f(I_1)$ ，使得
 - I_1 的答案为“是”当且仅当 I_2 的答案也为“是”
 - ↑ 实例构造的时间不太长
 - 可以反馈
 - $\text{Max}(I_2) \leq p_1(\text{size}(I_1), \text{Max}(I_1))$ ，这里 p_1 为某个二元多项式
 - ↑ 最大数没有显著增大
 - 实例规模没有显著缩小
 - $\text{size}(I_1) \leq p_2(\text{size}(I_2))$ ，这里 p_2 为某个多项式
 - ←
- 则称 Π_1 可伪多项式时间归约到 Π_2 ，记为 $\Pi_1 \leq_m^{pp} \Pi_2$

伪多项式时间归约

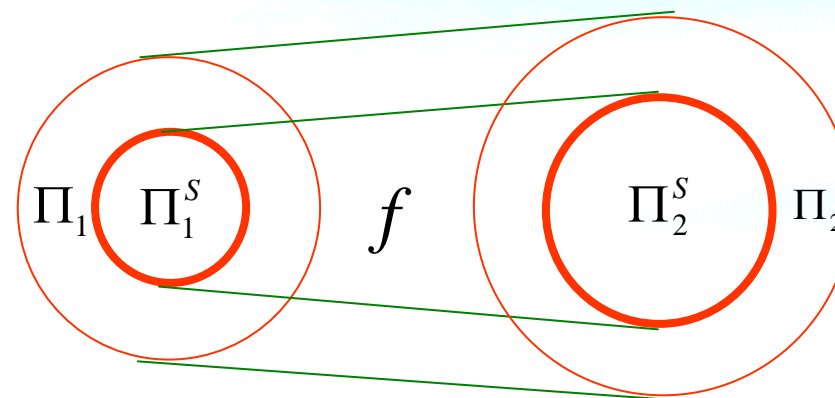
- 若 Π_1 为强 \mathcal{NP} -完全问题, $\Pi_2 \in \mathcal{NP}$ 且 $\Pi_1 \leq_m^{pp} \Pi_2$, 则 Π_2 也是强 \mathcal{NP} -完全问题
 - 由于 Π_1 为强 \mathcal{NP} -完全问题, 存在 Π_1 的子问题 Π_1^S , 其实例集 \mathcal{I}_1 中所有实例 I_1 满足 $\text{Max}(I_1) \leq p(\text{size}(I_1))$, 且 Π_1^S 是 \mathcal{NP} -完全的
 - 将以 $\mathcal{I}_2 = f(\mathcal{I}_1)$ 为实例集的 Π_2 的子问题记为 Π_2^S
 - 由于构造 $f(\mathcal{I}_1)$ 可在 $O(\text{poly}(\text{size}(I_1), \text{Max}(I_1))) = O(\text{poly}(\text{size}(I_1)))$ 时间内完成, f 也是 Π_1^S 到 Π_2^S 的多项式时间归约, 即 $\Pi_1^S \leq_m^p \Pi_2^S$, 因此 Π_2^S 是 \mathcal{NP} -完全的
 - 若能证明 \mathcal{I}_2 中所有实例 I_2 满足 $\text{Max}(I_2) \leq p'(\text{size}(I_2))$, 则由强 \mathcal{NP} -完全问题的定义可知 Π_2 是强 \mathcal{NP} -完全的

伪多项式时间归约

$$\begin{aligned}
 \text{Max}(I_2) &\leq p_1(\text{size}(I_1), \text{Max}(I_1)) \\
 &\leq p_1(\text{size}(I_1), p(\text{size}(I_1))) \\
 &\leq p'_1(\text{size}(I_1)) \\
 &\leq p'_1(p_2(\text{size}(I_2))) \\
 &\leq p'(\text{size}(I_2))
 \end{aligned}$$

若 $\text{size}(I_1) = \Omega(2^{\text{size}(I_2)})$,
 即 $\text{size}(I_2) = O(\log(\text{size}(I_1)))$,
 构造的实例规模显著缩小,
 从而 $\text{Max}(I_2) \leq p'(\text{size}(I_2))$ 未必成立, 未能找到满足要求的 \mathcal{NP} -完全的子问题

第一个强 \mathcal{NP} -完全问题



$$\text{Max}(I_1) \leq p(\text{size}(I_1)) \quad \text{Max}(I_2) \leq p'(\text{size}(I_2))?$$

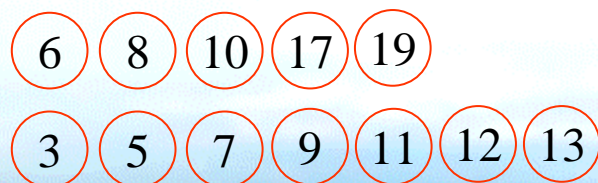
$$\begin{aligned}
 \text{Max}(I_2) &\leq p_1(\text{size}(I_1), \text{Max}(I_1)) \\
 \text{size}(I_1) &\leq p_2(\text{size}(I_2))
 \end{aligned}$$

上述两个条件容易验证, 实践中多数构造都能满足

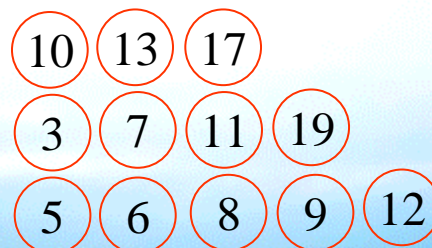
3-划分问题

• 3-划分 (3-partitioning)

- 给定由 $3m$ 个正整数组成的集合 $A = \{a_1, a_2, \dots, a_{3m}\}$ 和正整数 B ，其中 $\frac{B}{4} < a_j < \frac{B}{2}, j = 1, 2, \dots, 3m, \sum_{j=1}^{3m} a_j = mB$ ，问 A 是否可划分成 m 个互不相交的集合 A_1, A_2, \dots, A_m ，使得对任意的 $i, 1 \leq i \leq m, \sum_{a_j \in A_i} a_j = B$



划分



划分



3-划分

普通 \mathcal{NP} -完全

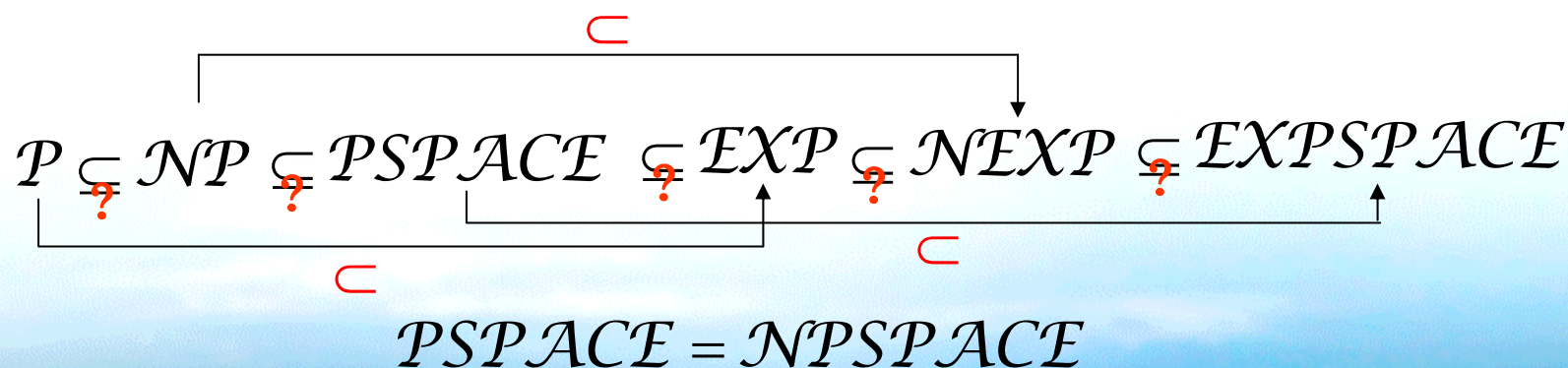


组合优化

- 若 Π 为 \mathcal{NP} -完全问题，且存在伪多项式时间算法，则 Π 不可能是强 \mathcal{NP} -完全的，此时称 Π 为普通意义下的 \mathcal{NP} -完全问题（ \mathcal{NP} -complete in the ordinary sense）
 - 背包、划分均为普通意义下的 \mathcal{NP} -完全问题
- 至少和强 \mathcal{NP} -完全问题一样难的问题称为强 \mathcal{NP} -难（strongly \mathcal{NP} -hard）问题
 - TSP 为强 \mathcal{NP} -难问题

空间复杂性

- 算法的**空间复杂度** (**space complexity**) 是关于实例规模 n 的一个函数 $f(n)$ ，它表示用该算法求解所有规模为 n 的实例中算法使用空间量最多的那个实例算法使用的空间量
- 空间复杂度类
 - $PSPACE$, $NPSPACE$, $EXPSPACE$, $PSPACE$ -完全

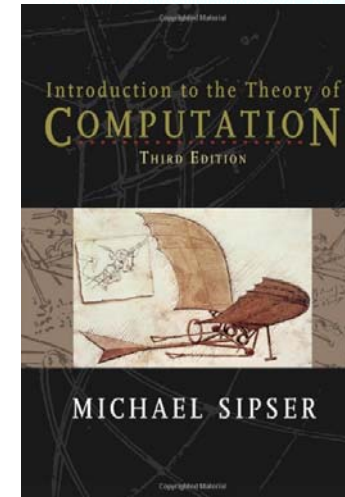
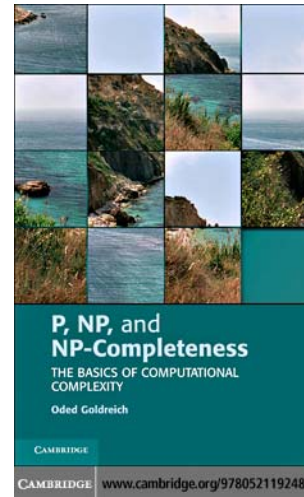
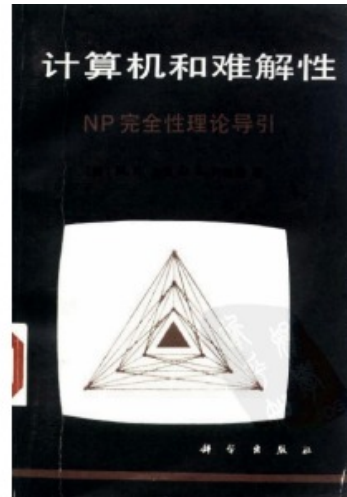
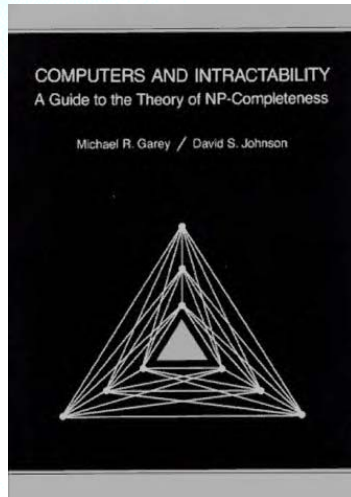


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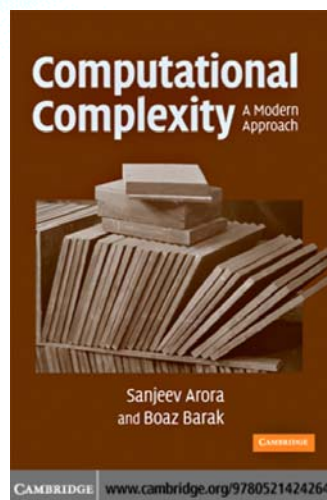
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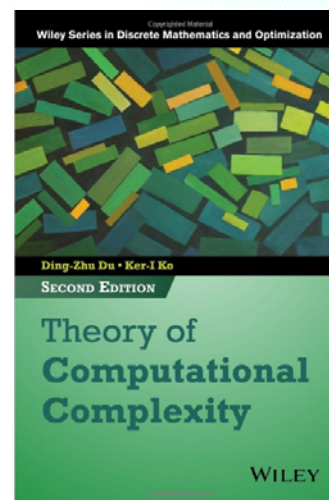
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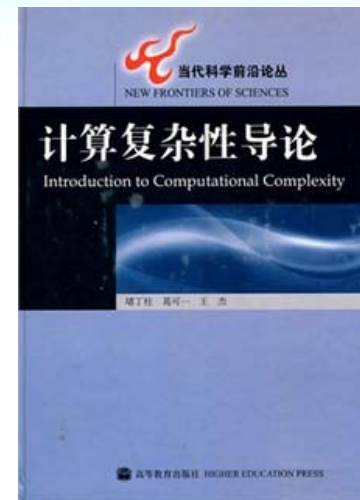
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NP 优化问题汇编



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A compendium of NP optimization problems

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[Gerhard Woeginger](#)

Sequencing and Scheduling.

This is a continuously updated catalog of approximability results for NP optimization problems. The compendium is also a part of the book [Complexity and Approximation](#). The compendium has not been updated for a while, so there might exist recent results that are not mentioned in the compendium. If you happen to notice such a missing result, please report it to us using the web forms.

You can use web forms to report [new problems](#), [new results on existing problems](#), [updates of references](#) or [errors](#).

<http://www.nada.kth.se/~viggo/problemlist/compendium.html>



\mathcal{NP} 优化问题汇编

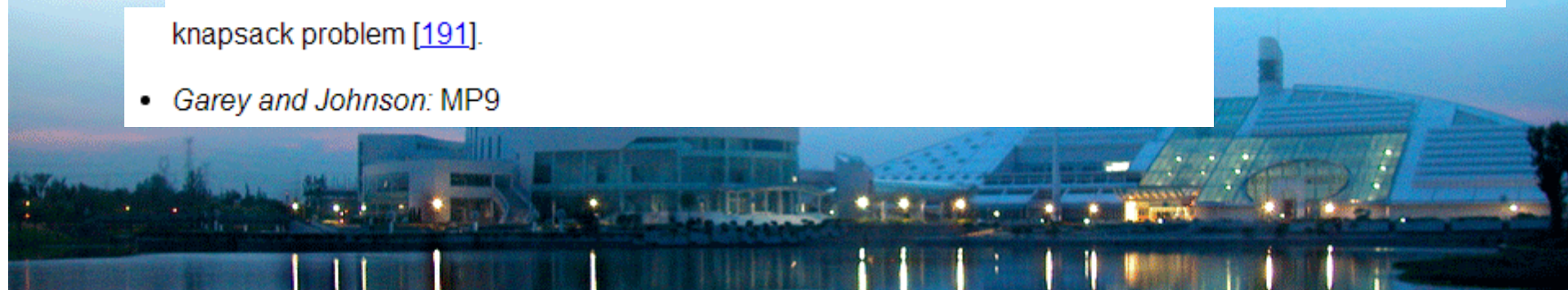


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MAXIMUM KNAPSACK

- **INSTANCE:** Finite set U , for each $u \in U$ a size $s(u) \in \mathbb{Z}^+$ and a value $v(u) \in \mathbb{Z}^+$, a positive integer $B \in \mathbb{Z}^+$.
- **SOLUTION:** A subset $U' \subseteq U$ such that $\sum_{u \in U'} s(u) \leq B$.
- **MEASURE:** Total weight of the chosen elements, i.e., $\sum_{u \in U'} v(u)$.
- *Good News:* Admits an FPTAS [\[266\]](#).
- *Comment:* The special case when $s(u)=v(u)$ for all $u \in U$ is called MAXIMUM SUBSET SUM. The corresponding minimization problem where $\sum_{u \in U'} s(u) \geq B$ also admits an FPTAS, as well as several other variations of the knapsack problem [\[191\]](#).
- *Garey and Johnson:* MP9



Complexity Zoo



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- There are now 535 classes and counting

All Classes

Complexity classes by letter: Symbols - A - B - C - D - E - F - G - H - I - J - K - L - M - N - O - P - Q - R - S - T - U - V - W - X - Y - Z

Lists of related classes: Communication Complexity - Hierarchies - Nonuniform

Symbols

0-1-NP_C - 1NAuxPDA^P - 2-EXP - 3SUM-hard - #AC⁰ - #L - #L/poly - #GA - #P - #V[t] - eEXP - eL - eL/poly - eP - eSAC⁰ - eSAC¹

A

AgPP - AC - AC⁰ - AC⁰[n] - AC¹ - ACC⁰ - AH - AL - ALL - ALOGTIME - AlgP/poly - Almost-NP - Almost-P - Almost-PSPACE - AM - AM_{Exp} - AM ∩ coAM - AM[polylog] - AmpMP - AmpP-BQP - AP - APP - APX - ATIME - AUC-SPACE(f(n)) - AuxPDA - AVBPP - AvgE - AvgP - AW[P] - AWPP - AW[SAT] - AW[*] - AW[t] - AxP - AxPP

B

βP - BH - BP_d(P) - BPE - BPEE - BP_qSPACE(f(n)) - BPL - BP-NP - BPP - BPP^{CC} - BPP_k^{CC} - BPP_k^{KT} - BPP/log - BPP/mlog - BPP/ilog - BPP/ilog - BPP/obdd - BPP_{path} - BPQP - BPPSPACE(f(n)) - BPTIME(f(n)) - BQNC - BQNP - BQP - BQP/ilog - BQP/poly - BQP/mlog - BQP/mpoly - BQP/qlog - BQP/qpoly - BQP-OBDD - BQPSPACE - BQPCTC - BQP_W/poly - BQTIME(f(n)) - k-BWBP

NL: Nondeterministic Logarithmic-Space

Has the same relation to L as NP does to P.

In a breakthrough result, was shown to equal coNL [Imm88] [Sze87]. (Though contrast to mNL.)

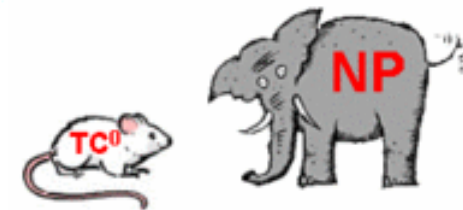
Is contained in LOGCFL [Sud78], as well as NC².

Is contained in UL/poly [RA00].

Deciding whether a bipartite graph has a perfect matching is hard for NL [KUW86].

NL can be defined in a logical formalism as SO(krom) and also as FO(tc), reachability in directed graph is NL-Complete under FO-reduction.

<https://complexityzoo.uwaterloo.ca/>





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线性规划和 整数规划简介

数学规划

- 若干个变量在满足一些等式或不等式限制条件下，使一个或多个目标函数取得最大值或最小值
 - 满足所有约束条件的点称为**可行点（解）**（feasible point），可行点的集合称为**可行域**（feasible region），记为 S
 - 可行解 \mathbf{x}^* 称为一（极小化）数学规划问题的**最优解**（optimal solution），若对任意 $\mathbf{x} \in S$ ， $f(\mathbf{x}^*) \leq f(\mathbf{x})$ ；相应地 $f(\mathbf{x}^*)$ 称为**最优值**
- 单目标数学规划

$$\begin{array}{ll} \min & f(\mathbf{x}) \quad \leftarrow \text{目标函数} \\ \text{s.t.} & g_j(\mathbf{x}) \geq 0 \quad j = 1, \dots, s \quad \leftarrow \text{不等式约束} \\ & h_l(\mathbf{x}) = 0 \quad l = 1, \dots, t \quad \leftarrow \text{等式约束} \\ & \mathbf{x} \in \mathbb{R}^n \quad \leftarrow \text{变量取值范围约束} \end{array}$$

min 极小
max 极大

subject to:
以下为约束条件

数学规划分类

- 线性规划与非线性规划
 - 线性规划: f, g_i, h_j 均为线性函数
 - 非线性规划: f, g_i, h_j 至少有一个是非线性函数
- 整数规划: 至少有一个决策变量限定取整数值
 - 混合整数规划 (Mixed Integer Programming, MIP): 部分决策变量取整数值
 - 0-1规划: 所有决策变量都取 0 或 1

$$\begin{aligned} \min \quad & f(\mathbf{x}) \\ \text{s.t.} \quad & g_j(\mathbf{x}) \geq 0 \quad j = 1, \dots, s \\ & h_l(\mathbf{x}) = 0 \quad l = 1, \dots, t \\ & x_i \in \mathbb{Z} \end{aligned}$$

$$x_i \in \{0, 1\}$$



线性规划

- 任何线性规划总可通过适当变形变为标准形标准型

$$\min \quad c_1x_1 + c_2x_2 + \cdots + c_nx_n$$

$$s.t. \quad a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2$$

...

$$a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_m$$

$$x_1, \cdots, x_n \geq 0$$

价格系数
向量

系数矩阵

右端向量

$$\begin{array}{ll} \min & \mathbf{c}\mathbf{x} \\ s.t. & \mathbf{A}\mathbf{x} = \mathbf{b} \\ & \mathbf{x} \geq \mathbf{0} \end{array}$$



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单纯形法

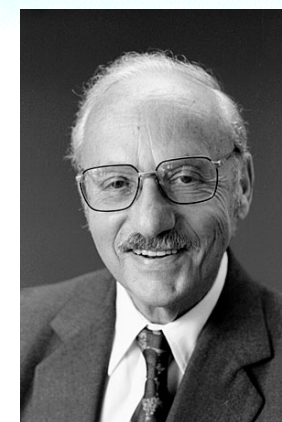
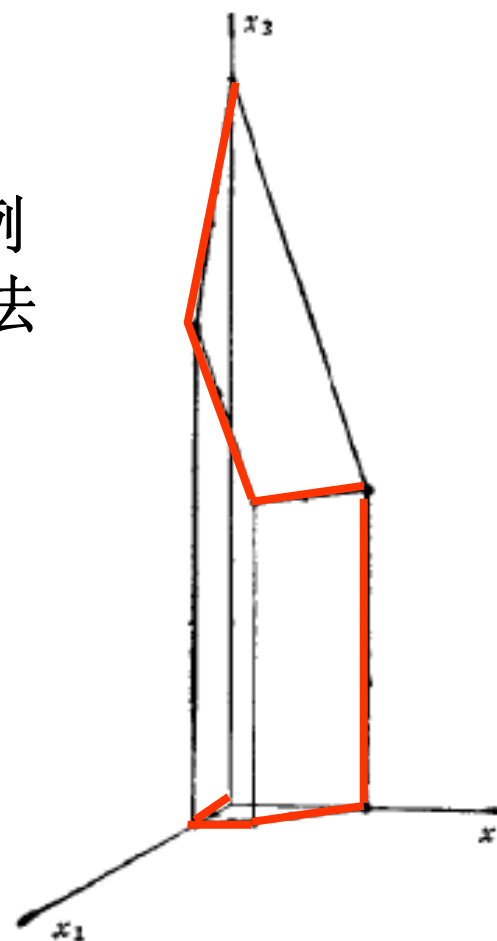
- 1947年Dantzig提出了求解线性规划的单纯形法
- 1967年得到的Klee-Minty实例说明单纯形法是指数时间算法

$$\max \sum_{i=1}^m 10^{m-i} x_i$$

$$s.t. \ 2 \sum_{i=1}^{j-1} 10^{j-i} x_i + x_j \leq 100^{j-1}, \ j = 1, \dots, m$$

$$x_i \geq 0, i = 1, \dots, m$$

Klee V, Minty GJ, How good is the simplex algorithm? In *Inequalities – III* (Shisha O, Eds.), Academic Press, 159–175, 1972



George Bernard
Dantzig
(1914-2005)
美国运筹学家

多项式时间算法

- 1979年，Khachiyan 给出了求解线性规划的第一个多项式时间算法——**椭球法**（Ellipsoid algorithm），说明线性规划是多项式时间可解的
- 1984年，Karmarkar 给出了实际效果更好的线性规划多项式时间算法——**内点法**（Interior Point Method），在数学规划领域产生了深远的影响



Narendra
Karmarkar
(1957-)
印度数学家



Leonid Genrikhovich
Khachiyan
(1952-2005)
苏联数学家

Khachiyan L, A polynomial algorithm in linear programming. *Doklady Akademii Nauk SSSR*, 244, 1093-1096, 1979

Karmarkar NK, A new polynomial-time algorithm for linear programming. *Combinatorica*, 4, 373-395, 1984

The Mathematical Sputnik



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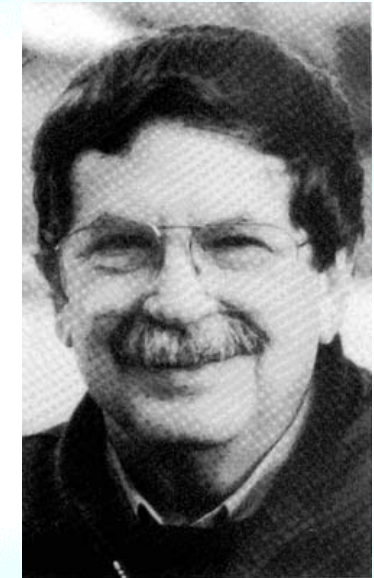
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- The New York Times of November 7, 1979 announced an event which its readers could easily believe had the importance of the launching of Sputnik. “A surprise discovery by an obscure Soviet mathematician has rocked the world of mathematics and computer analysis ... Apart from its profound theoretical interest... the theory of codes could eventually be affected by the Russian discovery, and this fact has obvious importance to intelligence agencies everywhere”.
- In England, the Guardian broke the story three days earlier, under the headline, “Soviet Answer to ‘Traveling Salesmen’.”

The New York Times

theguardian

Lawler EL. The great mathematical Sputnik of 1979. *The Mathematical Intelligencer*, 2, 191-198, 1980.



Eugene Leighton
(Gene) Lawler
(1933-1994)
美国运筹学家



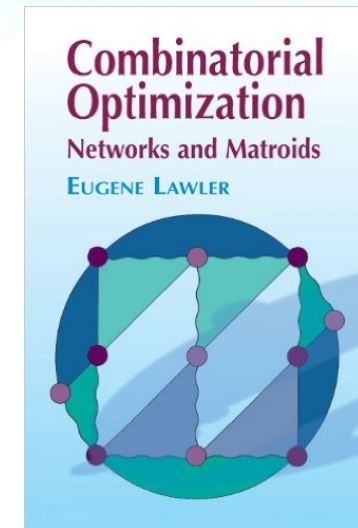
The Mathematical Sputnik



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- Khachiyan emphatically did not discover a polynomial bounded algorithm for the TSP...What Khachiyan did do was to answer a much smaller question in complexity theory. Linear programming had been known to be a problem in \mathcal{NP} . It had not been shown to be \mathcal{NP} -complete...Khachiyan squeezed linear programming into \mathcal{P} and thereby resolved the issue.
- Only much later, on March 21, did the Times print a retraction,...But the headline read “A Russian's Solution in Math Questioned” and the subhead read “Americans Who Studied Khachiyan Linear Programming Method Express Doubt on Scope.” That made it sound as though poor Khachiyan had exaggerated the importance of his work, and Western mathematicians had cut him down to size.



Lawler E.
*Combinatorial
Optimization:
Networks and
Matroids*, Dover
Publications, 1976



整数线性规划的 \mathcal{NP} -完全性



组合优化

- 划分问题 \leq_m^p 整数线性规划
 - 任取划分问题的实例 $A = \{a_1, a_2, \dots, a_n\}$, 考虑整数规划
$$\sum_{j=1}^n a_j x_j = \frac{1}{2} \sum_{j=1}^n a_j, x_j \in \{0, 1\}$$
 - 整数规划有可行解当且仅当划分问题实例答案为“是”
- 整数线性规划 $\in \mathcal{NP}$
 - 若线性不等式组 $\mathbf{Ax} \geq \mathbf{b}$ 有整数解, 必存在一整数解, 其规模不超过实例规模的多项式

Papadimitriou CH. On the complexity of integer programming. *Journal of the ACM*, 28, 765-768, 1981



整数线性规划算法



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- 1958年，Gomory给出了求解整数线性规划的割平面法（cutting plane method）
- 1960年，Land和Doig给出了求解整数规划的分支定界法（Branch and Bound）

Gomory RE, Outline of an Algorithm for Integer Solutions to Linear Programs, *Bulletin of the American Mathematical Society*, 64, 275–278, 1958

Land A, Doig A, An automatic method of solving discrete programming problems, *Econometrica* 28, 497–520, 1960



Ralph Edward
Gomory
(1929-)

美国运筹学家

左上:Ailsa Land
左下:Alison Doig



松弛

- 设有整数线性规划（**IP**），去除决策变量取整数约束后所得线性规划记为（**LP**），称（**LP**）为（**IP**）的**松弛**（relaxation）
 - （**IP**）的可行域包含于（**LP**）的可行域中
 - （**IP**）的可行解也是（**LP**）的可行解，但反之不然
 - （**IP**）的最优值不优于（**LP**）的最优值
 - 若（**LP**）的最优解为整数解，则它也是（**IP**）的最优解

$$\begin{aligned} & \min \mathbf{c}\mathbf{x} \\ (\text{IP}) \quad & s.t. \mathbf{A}\mathbf{x} = \mathbf{b} \\ & \mathbf{x} \in \mathbb{Z}_+^n \end{aligned}$$

$$\begin{aligned} & \min \mathbf{c}\mathbf{x} \\ (\text{LP}) \quad & s.t. \mathbf{A}\mathbf{x} = \mathbf{b} \\ & \mathbf{x} \in \mathbb{R}_+^n \end{aligned}$$



参考资料



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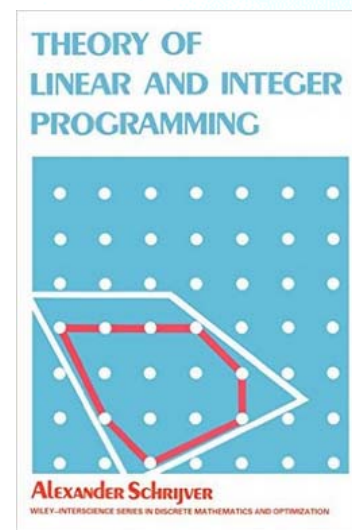
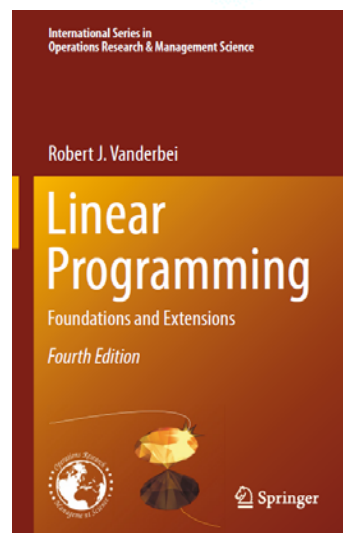
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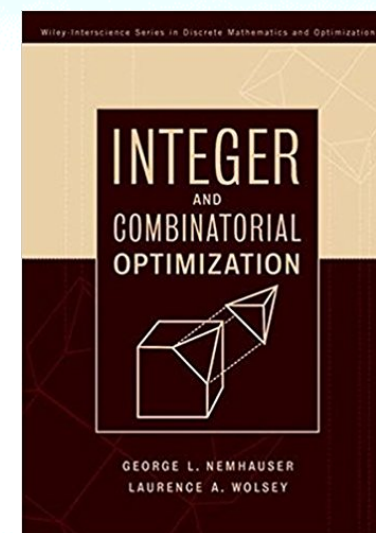
黄红选, 韩继业, 数学规划, 清华大学出版社, 2006

Vanderbei RJ, *Linear Programming: Foundations and Extensions*, Springer, 2014



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Wolsey LA, Nemhauser GL. *Integer and Combinatorial Optimization*, Wiley, 1999





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谢 谢

