



Numerical Methods Lab 3

08 March 2018

Instructions

- Read all the instructions carefully.
- MATLAB has a help file for every function if you get stuck.
- There are also numerous sources available on the internet, Google is your friend!

SECTION 1

Some Useful MATLAB Built-in Commands

Command	Result
<code>zeros(m,n)</code>	Creates an $m \times n$ matrix consisting of all zeros.
<code>ones(m,n)</code>	Creates an $m \times n$ matrix consisting of all ones.
<code>eye(m,n)</code>	Creates an $m \times n$ Identity matrix.
<code>X = diag(v,k)</code>	Creates a diagonal matrix with elements of v on the k th diagonal. $k = 0$ is the main diagonal.
<code>v = diag(X)</code>	Returns a vector of the main diagonal of matrix X .
<code>transpose(X)</code>	Returns the transpose of matrix X .
<code>trace(X)</code>	Returns the sum of the elements on the main diagonal of X .
<code>inv(X)</code>	Returns the inverse of the square matrix X .
<code>det(X)</code>	Returns the determinant of the square matrix X .
<code>[V, D] = eig(X)</code>	Returns the eigenvalues and eigenvectors of matrix X .
<code>fliplr(X)</code>	Returns X with rows preserved and columns flipped in the left/right direction.
<code>flipud(X)</code>	Returns X with columns preserved and rows flipped in the up/down direction.
<code>tril(X,k)</code>	Extracts the lower triangular part of the matrix X , consisting of the elements on and below the k th diagonal.
<code>triu(X,k)</code>	Extracts the upper triangular part of the matrix X , consisting of the elements on and above the k th diagonal.
<code>linspace(a,b,n)</code>	Returns a vector of n equally spaced points between (and including) a and b .

SECTION 2

Main Exercises

The due date for the lab submission is the 12th of March 2018 at 12pm.

2.1

Exercise 1

Program the Bisection method to find the roots of equations. Your function should take as inputs, some function `f` (you will need to look up how function handles work), a tolerance value `tol`, as well as some initial bracket $I_0 = (a_{\text{initial}}, b_{\text{initial}})$ respectively. Your function should return as output the root c . Use the stopping criteria $\frac{|c_n - c_{n-1}|}{|c_n|} < \text{tol}$ for the convergence of the sequence c_n 's. The first line of your function must look like the following:

```
function root = bisectionSearch(f, tol, I_0)
```

2.2

Exercise 2

Program the False position method to find the roots of equations. Your function should take as inputs, some function `f` (you will need to look up how function handles work), a tolerance value `tol`, as well as some initial bracket $I_0 = (a_{\text{initial}}, b_{\text{initial}})$ respectively. Use a similar stopping criteria as in Exercise 1. Your function should return as output the root c . The first line of your function must look like the following:

```
function root = RegularfalsiSearch(f, tol, I_0)
```

2.3

Exercise 3

Program the Newton root finding method for a scalar equation. Your function should take as inputs, two function handles `f` and `fprime` (you will need to look up how function handles work). It must also take in an initial guess x_0 and a tolerance value `tol`. Your function should return as output the root x . Use the stopping criteria $\frac{|x_n - x_{n-1}|}{|x_n|} < \text{tol}$. The first line of your function must look like the following:

```
function x = Newtonmethodscaler(f, fprime, x0, tol)
```

2.4

Exercise 4

Do plot the error given by $\frac{|c_n - c_{n-1}|}{|c_n|}$ against the number of iterations for the bisection and the regular falsi Method. On the same graph, plot the error $\frac{|x_n - x_{n-1}|}{|x_n|}$ against the number of iterations for the Newton's method.

What do you see?

2.5

Exercise 5

Program the Newton root finding method for systems. Your function should take in as inputs, two function handles (anonymous functions) - F (system of equations as a column vector) and its Jacobian J (a matrix). It must also take in an initial guess x_0 and an tolerance value `tol`. The output of your function must be the roots of the system as a column vector x . The first line of your function should look like:

```
function x = Newtonmethodsystem(F, J, x0, tol)
```