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1. Driving of willy

1. Deploy the brakes

Normally a wheelchair has brakes. The brakes of Willy are removed.

2. Deploy the emergency stop

3. Turn the power on

Do it in the following order:

- Start the OpenWRT PI (Which is removed, because this was a private PI)
- Start the Notebook
- Start the Sensor and SI PI.

4. Undeploy the emergency stop



By default the **brain** will takeover the control. Make sure first move Willy with a Joystick to a safe place.

1.1. Stop Willy

1. Deploy the emergency stop
2. Shutdown all raspberry PI's from the notebook
 - a. Open the terminal on the notebook

```
sh /opt/willy/components/ansible/shutdown-pi.sh
```

Fill in the password of the PI's

1. Shutdown the notebook
2. Turn of the power