



## ZMOD4510 API Documentation

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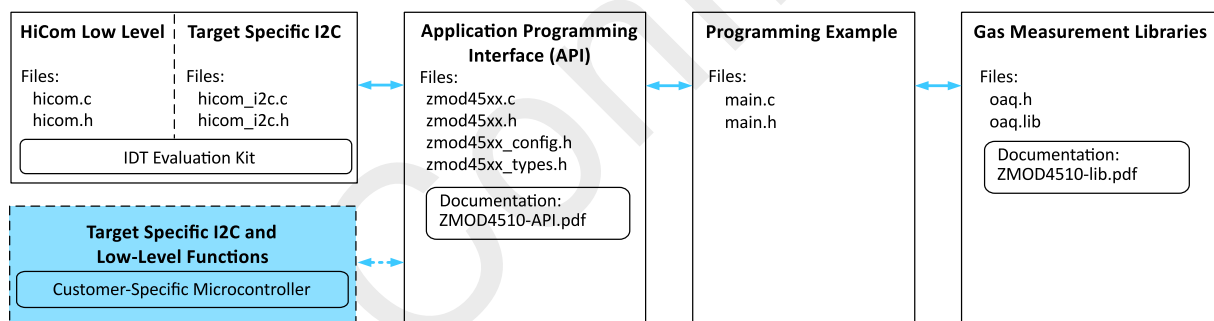
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## Chapter 1

# ZMOD4510 Application Programming Interface Overview

This document refers to the IDT document *ZMOD4510 Programming Manual - Read Me*. The figure below shows an overview of the ZMOD4510 API, programming example and libraries. Custom microcontrollers can be used to establish I2C communication. Using the user's own microcontroller requires implementing the user's own target-specific I2C and low-level functions (highlighted in light blue). The following describes in detail the Application Programming Interface (API) of the ZMOD4510.



## Chapter 2

# Module Index

### 2.1 Modules

Here is a list of all modules:

Gas sensor IDs . . . . .	5
Error codes . . . . .	6

## Chapter 3

# Data Structure Index

### 3.1 Data Structures

Here are the data structures with brief descriptions:

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## Chapter 4

# File Index

### 4.1 File List

Here is a list of all documented files with brief descriptions:

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## Chapter 5

# Module Documentation

### 5.1 Gas sensor IDs

#### Macros

- `#define ZMOD4510_PID (0x6320)`

#### 5.1.1 Detailed Description

The gas sensor product IDs.

## 5.2 Error codes

### Macros

- `#define ERROR_INIT_OUT_OF_RANGE` (1)
- `#define ERROR_GAS_TIMEOUT` (2)
- `#define ERROR_I2C` (3)
- `#define ERROR_SENSOR_UNSUPPORTED` (4)
- `#define ERROR_CONFIG_MISSING` (5)
- `#define ERROR_SENSOR` (6)
- `#define ERROR_ACCESS_CONFLICT` (7)
- `#define ERROR_POR_EVENT` (8)

### 5.2.1 Detailed Description

The gas sensor and API error codes.

### 5.2.2 Macro Definition Documentation

#### 5.2.2.1 `#define ERROR_ACCESS_CONFLICT` (7)

AccessConflict.

#### 5.2.2.2 `#define ERROR_CONFIG_MISSING` (5)

There is no pointer to a valid configuration.

#### 5.2.2.3 `#define ERROR_GAS_TIMEOUT` (2)

The operation took too long.

#### 5.2.2.4 `#define ERROR_I2C` (3)

Failure in i2c communication.

#### 5.2.2.5 `#define ERROR_INIT_OUT_OF_RANGE` (1)

The initialize value is out of range.

#### 5.2.2.6 `#define ERROR_POR_EVENT` (8)

POR\_event.

#### 5.2.2.7 `#define ERROR_SENSOR` (6)

Sensor malfunction.

#### 5.2.2.8 `#define ERROR_SENSOR_UNSUPPORTED` (4)

Sensor is not supported with this firmware.

## Chapter 6

# Data Structure Documentation

### 6.1 zmod45xx\_conf Struct Reference

Structure to hold the gas sensor module configuration.

```
#include <zmod45xx_types.h>
```

#### Data Fields

- `uint8_t start`
- [zmod45xx\\_conf\\_str h](#)
- [zmod45xx\\_conf\\_str d](#)
- [zmod45xx\\_conf\\_str m](#)
- [zmod45xx\\_conf\\_str s](#)
- [zmod45xx\\_conf\\_str r](#)

#### 6.1.1 Detailed Description

Structure to hold the gas sensor module configuration.

The documentation for this struct was generated from the following file:

- [zmod45xx\\_types.h](#)

### 6.2 zmod45xx\_conf\_str Struct Reference

A single data set for the configuration.

```
#include <zmod45xx_types.h>
```

## Data Fields

- `uint8_t addr`
- `uint8_t len`
- `const uint8_t * data`

### 6.2.1 Detailed Description

A single data set for the configuration.

The documentation for this struct was generated from the following file:

- [zmod45xx\\_types.h](#)

## 6.3 zmod45xx\_dev\_t Struct Reference

Device structure ZMOD45xx.

```
#include <zmod45xx_types.h>
```

## Data Fields

- `uint8_t i2c_addr`
- `uint8_t config [6]`
- `uint8_t general_purpose [9]`
- `uint16_t mox_er`
- `uint16_t mox_lr`
- `uint16_t pid`
- `zmod45xx_i2c_ptr_t read`
- `zmod45xx_i2c_ptr_t write`
- `zmod45xx_delay_ptr_p delay_ms`
- `const zmod45xx_conf * init_conf`
- `const zmod45xx_conf * meas_conf`

### 6.3.1 Detailed Description

Device structure ZMOD45xx.

### 6.3.2 Field Documentation

#### 6.3.2.1 `uint8_t config[6]`

configuration parameter set

#### 6.3.2.2 `zmod45xx_delay_ptr_p` delay\_ms

function pointer to delay function

#### 6.3.2.3 `uint8_t` general\_purpose[9]

general purpose data

#### 6.3.2.4 `uint8_t` i2c\_addr

i2c address of the sensor

#### 6.3.2.5 `const zmod45xx_conf*` init\_conf

pointer to the initialize configuration

#### 6.3.2.6 `const zmod45xx_conf*` meas\_conf

pointer to the measurement configuration

#### 6.3.2.7 `uint16_t` mox\_er

sensor specific parameter

#### 6.3.2.8 `uint16_t` mox\_lr

sensor specific parameter

#### 6.3.2.9 `uint16_t` pid

product id of the sensor

#### 6.3.2.10 `zmod45xx_i2c_ptr_t` read

function pointer to i2c read

#### 6.3.2.11 `zmod45xx_i2c_ptr_t` write

function pointer to i2c write

The documentation for this struct was generated from the following file:

- [zmod45xx\\_types.h](#)

## Chapter 7

# File Documentation

### 7.1 zmod45xx.c File Reference

ZMOD45xx functions.

```
#include "zmod45xx.h"  
#include "zmod45xx_config.h"
```

#### Functions

- `int8_t zmod45xx_read_sensor_info (zmod45xx_dev_t *dev)`  
*Read sensor parameter.*
- `int8_t zmod45xx_calc_factor (zmod45xx_dev_t *dev, float factor, uint8_t *data)`
- `int8_t zmod45xx_init_sensor (zmod45xx_dev_t *dev)`  
*Initialize the sensor after power on.*
- `int8_t zmod45xx_init_measurement (zmod45xx_dev_t *dev)`  
*Initialize the sensor for zmod4510 measurement.*
- `int8_t zmod45xx_start_measurement (zmod45xx_dev_t *dev)`  
*Start the measurement.*
- `int8_t zmod45xx_read_status (zmod45xx_dev_t *dev, uint8_t *status)`  
*Read the status of the device.*
- `int8_t zmod45xx_read_adc_results (zmod45xx_dev_t *dev, uint8_t *adc_result)`  
*Read adc values from the sensor.*
- `int8_t zmod45xx_calc_rmox (zmod45xx_dev_t *dev, uint8_t *adc_result, float *rmox)`  
*Calculate mox resistance.*

### 7.1.1 Detailed Description

ZMOD45xx functions.

#### Version

2.0.0

#### Date

2019-10-02

#### Author

IDT

### 7.1.2 Function Documentation

#### 7.1.2.1 `int8_t zmod45xx_calc_rmx ( zmod45xx_dev_t * dev, uint8_t * adc_result, float * rmx )`

Calculate mx resistance.

##### Parameters

in	<i>dev</i>	pointer to the device
in, out	<i>adc_result</i>	pointer to the adc results
in, out	<i>rmx</i>	pointer to the rmx values

##### Returns

error code

##### Return values

0	success
!= 0	error

#### 7.1.2.2 `int8_t zmod45xx_init_measurement ( zmod45xx_dev_t * dev )`

Initialize the sensor for zmod4510 measurement.

##### Parameters

in	<i>dev</i>	pointer to the device
----	------------	-----------------------

**Returns**

error code

**Return values**

0	success
!= 0	error

**7.1.2.3 int8\_t zmod45xx\_init\_sensor ( zmod45xx\_dev\_t \* dev )**

Initialize the sensor after power on.

**Parameters**

in	dev	pointer to the device
----	-----	-----------------------

**Returns**

error code

**Return values**

0	success
!= 0	error

**7.1.2.4 int8\_t zmod45xx\_read\_adc\_results ( zmod45xx\_dev\_t \* dev, uint8\_t \* adc\_result )**

Read adc values from the sensor.

**Parameters**

in	dev	pointer to the device
in, out	adc_result	pointer to the adc results

**Returns**

error code

**Return values**

0	success
!= 0	error



#### 7.1.2.5 `int8_t zmod45xx_read_sensor_info ( zmod45xx_dev_t * dev )`

Read sensor parameter.

##### Parameters

<code>in</code>	<code>dev</code>	pointer to the device
-----------------	------------------	-----------------------

##### Returns

error code

##### Return values

<code>0</code>	success
<code>!= 0</code>	error

##### Note

This function must be called once before running other sensor functions.

#### 7.1.2.6 `int8_t zmod45xx_read_status ( zmod45xx_dev_t * dev, uint8_t * status )`

Read the status of the device.

##### Parameters

<code>in</code>	<code>dev</code>	pointer to the device
<code>in, out</code>	<code>status</code>	pointer to the status variable

##### Returns

error code

##### Return values

<code>0</code>	success
<code>!= 0</code>	error

#### 7.1.2.7 `int8_t zmod45xx_start_measurement ( zmod45xx_dev_t * dev )`

Start the measurement.

## Parameters

in	dev	pointer to the device
----	-----	-----------------------

## Returns

error code

## Return values

0	success
!= 0	error

## 7.2 zmod45xx.h File Reference

ZMOD45xx functions.

```
#include "zmod45xx_types.h"
```

### Macros

- #define **ZMOD4510\_I2C\_ADDRESS** (0x33)
- #define **ZMOD45XX\_ADDR\_PID** (0x00)
- #define **ZMOD45XX\_ADDR\_CONF** (0x20)
- #define **ZMOD45XX\_ADDR\_GENERAL\_PURPOSE** (0x26)
- #define **ZMOD45XX\_ADDR\_CMD** (0x93)
- #define **ZMOD45XX\_ADDR\_STATUS** (0x94)
- #define **ZMOD45XX\_ADDR\_TRACKING** (0x3A)
- #define **ZMOD45XX\_LEN\_PID** (2)
- #define **ZMOD45XX\_LEN\_CONF** (6)
- #define **ZMOD45XX\_LEN\_TRACKING** (6)
- #define **ZMOD45XX\_LEN\_GENERAL\_PURPOSE** (9)
- #define **STATUS\_SEQUENCER\_RUNNING\_MASK** (0x80)
- #define **STATUS\_SLEEP\_TIMER\_ENABLED\_MASK** (0x40)
- #define **STATUS\_ALARM\_MASK** (0x20)
- #define **STATUS\_LAST\_SEQ\_STEP\_MASK** (0x1F)
- #define **STATUS\_POR\_EVENT\_MASK** (0x80)
- #define **STATUS\_ACCESS\_CONFLICT\_MASK** (0x40)

## Functions

- `int8_t zmod45xx_read_sensor_info (zmod45xx_dev_t *dev)`  
*Read sensor parameter.*
- `int8_t zmod45xx_init_sensor (zmod45xx_dev_t *dev)`  
*Initialize the sensor after power on.*
- `int8_t zmod45xx_init_measurement (zmod45xx_dev_t *dev)`  
*Initialize the sensor for zmod4510 measurement.*
- `int8_t zmod45xx_start_measurement (zmod45xx_dev_t *dev)`  
*Start the measurement.*
- `int8_t zmod45xx_read_status (zmod45xx_dev_t *dev, uint8_t *status)`  
*Read the status of the device.*
- `int8_t zmod45xx_read_adc_results (zmod45xx_dev_t *dev, uint8_t *adc_result)`  
*Read adc values from the sensor.*
- `int8_t zmod45xx_calc_rmx (zmod45xx_dev_t *dev, uint8_t *adc_result, float *rmx)`  
*Calculate rmx resistance.*

### 7.2.1 Detailed Description

ZMOD45xx functions.

#### Version

2.0.0

#### Date

2019-10-02

#### Author

IDT

### 7.2.2 Macro Definition Documentation

#### 7.2.2.1 #define STATUS\_ACCESS\_CONFLICT\_MASK (0x40)

AccessConflict

#### 7.2.2.2 #define STATUS\_ALARM\_MASK (0x20)

Alarm

### 7.2.2.3 #define STATUS\_LAST\_SEQ\_STEP\_MASK (0x1F)

Last executed sequencer step

### 7.2.2.4 #define STATUS\_POR\_EVENT\_MASK (0x80)

POR\_event

### 7.2.2.5 #define STATUS\_SEQUENCER\_RUNNING\_MASK (0x80)

Sequencer is running

### 7.2.2.6 #define STATUS\_SLEEP\_TIMER\_ENABLED\_MASK (0x40)

SleepTimer\_enabled

## 7.2.3 Function Documentation

### 7.2.3.1 int8\_t zmod45xx\_calc\_rmx ( zmod45xx\_dev\_t \* dev, uint8\_t \* adc\_result, float \* rmx )

Calculate mx resistance.

#### Parameters

in	<i>dev</i>	pointer to the device
in, out	<i>adc_result</i>	pointer to the adc results
in, out	<i>rmx</i>	pointer to the rmx values

#### Returns

error code

#### Return values

0	success
!= 0	error

### 7.2.3.2 int8\_t zmod45xx\_init\_measurement ( zmod45xx\_dev\_t \* dev )

Initialize the sensor for zmod4510 measurement.

**Parameters**

in	<i>dev</i>	pointer to the device
----	------------	-----------------------

**Returns**

error code

**Return values**

0	success
$\neq 0$	error

**7.2.3.3 int8\_t zmod45xx\_init\_sensor ( zmod45xx\_dev\_t \* *dev* )**

Initialize the sensor after power on.

**Parameters**

in	<i>dev</i>	pointer to the device
----	------------	-----------------------

**Returns**

error code

**Return values**

0	success
$\neq 0$	error

**7.2.3.4 int8\_t zmod45xx\_read\_adc\_results ( zmod45xx\_dev\_t \* *dev*, uint8\_t \* *adc\_result* )**

Read adc values from the sensor.

**Parameters**

in	<i>dev</i>	pointer to the device
in, out	<i>adc_result</i>	pointer to the adc results

**Returns**

error code

## Return values

0	success
!= 0	error

7.2.3.5 `int8_t zmod45xx_read_sensor_info ( zmod45xx_dev_t * dev )`

Read sensor parameter.

## Parameters

in	<i>dev</i>	pointer to the device
----	------------	-----------------------

## Returns

error code

## Return values

0	success
!= 0	error

## Note

This function must be called once before running other sensor functions.

7.2.3.6 `int8_t zmod45xx_read_status ( zmod45xx_dev_t * dev, uint8_t * status )`

Read the status of the device.

## Parameters

in	<i>dev</i>	pointer to the device
in, out	<i>status</i>	pointer to the status variable

## Returns

error code

## Return values

0	success
!= 0	error

### 7.2.3.7 `int8_t zmod45xx_start_measurement ( zmod45xx_dev_t * dev )`

Start the measurement.

#### Parameters

<code>in</code>	<code>dev</code>	pointer to the device
-----------------	------------------	-----------------------

#### Returns

error code

#### Return values

<code>0</code>	success
<code>!= 0</code>	error

## 7.3 `zmod45xx_config.h` File Reference

ZMOD45xx configuration.

```
#include <stdint.h>
#include "zmod45xx_types.h"
```

#### Variables

- `const uint8_t data_set_4510 []`
- `const uint8_t data_set_4510i []`
- `const zmod45xx_conf zmod4510`  
*ZMOD4510 configuration.*
- `const zmod45xx_conf zmod45xxi`  
*ZMOD45XX sensor initialization configuration.*

### 7.3.1 Detailed Description

ZMOD45xx configuration.

#### Version

2.0.0

#### Date

2019-07-18

#### Author

IDT

### 7.3.2 Variable Documentation

#### 7.3.2.1 `const uint8_t data_set_4510[]`

**Initial value:**

```
= { 0x20, 0x05, 0xA0, 0x18, 0xC0, 0x1C,
    0x03,
    0x00, 0x00, 0x00, 0x08, 0x00, 0x10, 0x00,
    0x01, 0x00, 0x09, 0x00, 0x11, 0x00, 0x02,
    0x00, 0x0A, 0x00, 0x12, 0x00, 0x03, 0x00,
    0x0B, 0x00, 0x13, 0x00, 0x04, 0x00, 0x0C,
    0x80, 0x14 }
```

#### 7.3.2.2 `const uint8_t data_set_4510i[]`

**Initial value:**

```
= { 0x00, 0xA4, 0xC3, 0xE3,
    0x00, 0x00, 0x80, 0x40 }
```

#### 7.3.2.3 `const zmod45xx_conf zmod4510`

**Initial value:**

```
= {
    .start = 0x80,
    .h = { .addr = 0x40, .len = 10 },
    .d = { .addr = 0x50, .len = 6, .data = &data_set_4510[0] },
    .m = { .addr = 0x60, .len = 1, .data = &data_set_4510[6] },
    .s = { .addr = 0x68, .len = 30, .data = &data_set_4510[7] },
    .r = { .addr = 0x97, .len = 30 }
}
```

ZMOD4510 configuration.

#### 7.3.2.4 `const zmod45xx_conf zmod45xxi`

**Initial value:**

```
= {
    .start = 0x80,
    .h = { .addr = 0x40, .len = 2 },
    .d = { .addr = 0x50, .len = 2, .data = &data_set_4510i[0] },
    .m = { .addr = 0x60, .len = 2, .data = &data_set_4510i[2] },
    .s = { .addr = 0x68, .len = 4, .data = &data_set_4510i[4] },
    .r = { .addr = 0x97, .len = 4 }
}
```

ZMOD45XX sensor initialization configuration.



## 7.4 zmod45xx\_types.h File Reference

ZMOD45xx types.

```
#include <stdint.h>
#include <stdio.h>
```

### Data Structures

- struct [zmod45xx\\_conf\\_str](#)  
*A single data set for the configuration.*
- struct [zmod45xx\\_conf](#)  
*Structure to hold the gas sensor module configuration.*
- struct [zmod45xx\\_dev\\_t](#)  
*Device structure ZMOD45xx.*

### Macros

- #define **ZMOD4510\_PID** (0x6320)
- #define **ZMOD45XX\_OK** (0)
- #define **ERROR\_INIT\_OUT\_OF\_RANGE** (1)
- #define **ERROR\_GAS\_TIMEOUT** (2)
- #define **ERROR\_I2C** (3)
- #define **ERROR\_SENSOR\_UNSUPPORTED** (4)
- #define **ERROR\_CONFIG\_MISSING** (5)
- #define **ERROR\_SENSOR** (6)
- #define **ERROR\_ACCESS\_CONFLICT** (7)
- #define **ERROR\_POR\_EVENT** (8)

### Typedefs

- typedef int8\_t(\* [zmod45xx\\_i2c\\_ptr\\_t](#)) (uint8\_t addr, uint8\_t reg\_addr, const uint8\_t \*data, uint8\_t len)  
*function pointer type for i2c access*
- typedef void(\* [zmod45xx\\_delay\\_ptr\\_p](#)) (uint32\_t ms)  
*function pointer to hardware dependent delay function*

#### 7.4.1 Detailed Description

ZMOD45xx types.

Version

2.0.0

Date

2019-07-18

Author

IDT

## 7.4.2 Macro Definition Documentation

### 7.4.2.1 #define ZMOD45XX\_OK (0)

Return value if no fault has been found.

## 7.4.3 Typedef Documentation

### 7.4.3.1 typedef int8\_t(\* zmod45xx\_i2c\_ptr\_t) (uint8\_t addr, uint8\_t reg\_addr, const uint8\_t \*data, uint8\_t len)

function pointer type for i2c access

#### Parameters

in	<i>addr</i>	7-bit I2C slave address of the ZMOD45xx
in	<i>reg_addr</i>	address of internal register to read/write
in, out	<i>data</i>	pointer to the read/write data value
in	<i>len</i>	number of bytes to read/write

#### Returns

error code

#### Return values

0	success
!= 0	error