

view\_frames Result  
Recorded at time: 1688078951.7568445

map

Broadcaster: /ekf\_localization  
Average rate: 50.202  
Buffer length: 4.98  
Most recent transform: 1688078951.706  
Oldest transform: 1688078946.726

t265\_odom\_frame

Broadcaster: /t265/realsense2\_camera\_manager  
Average rate: 200.291  
Buffer length: 4.993  
Most recent transform: 1688078951.712  
Oldest transform: 1688078946.719

t265\_pose\_frame

Broadcaster: /t265/realsense2\_camera\_manager  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

t265\_link

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

Broadcaster: /t265/realsense2\_camera\_manager  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

Broadcaster: /t265/realsense2\_camera\_manager  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

base\_link

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

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Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

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Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

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Average rate: 10000.0  
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Most recent transform: 0.0  
Oldest transform: 0.0

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Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

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Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

Broadcaster: /robot\_state\_publisher  
Average rate: 10.19  
Buffer length: 4.907  
Most recent transform: 1688078951.701  
Oldest transform: 1688078946.794

Broadcaster: /robot\_state\_publisher  
Average rate: 10.19  
Buffer length: 4.907  
Most recent transform: 1688078951.701  
Oldest transform: 1688078946.794

Broadcaster: /robot\_state\_publisher  
Average rate: 10.19  
Buffer length: 4.907  
Most recent transform: 1688078951.701  
Oldest transform: 1688078946.794

Broadcaster: /robot\_state\_publisher  
Average rate: 10.19  
Buffer length: 4.907  
Most recent transform: 1688078951.701  
Oldest transform: 1688078946.794

Broadcaster: /robot\_state\_publisher  
Average rate: 10.19  
Buffer length: 4.907  
Most recent transform: 1688078951.701  
Oldest transform: 1688078946.794

Broadcaster: /t265/realsense2\_camera\_manager  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

Broadcaster: /t265/realsense2\_camera\_manager  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

t265\_gyro\_optical\_frame

t265\_accel\_optical\_frame

sensor\_arch\_link

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

os\_sensor

Broadcaster: /ouster/os\_nodelet\_mgr  
Average rate: 10.205  
Buffer length: 4.9  
Most recent transform: 2090.632  
Oldest transform: 2085.732

os\_lidar

Broadcaster: /ouster/os\_nodelet\_mgr  
Average rate: 10.205  
Buffer length: 4.9  
Most recent transform: 2090.632  
Oldest transform: 2085.732

os\_imu

top\_chassis\_link

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

top\_plate\_link

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

top\_plate\_front\_link

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

top\_plate\_rear\_link

user\_rail\_link

front\_left\_wheel\_link

front\_right\_wheel\_link

rear\_left\_wheel\_link

rear\_right\_wheel\_link