[Team #2 Project Name: Camera Based Tracking System]

[University of Alberta - ECE492 - Capstone Project]

Team Members Names: Puer Liu, Qiufeng Du, Wenchen Zhang, Jiahui Wang

Project Lead: Paul Liu

Project Start Date: 1/7/2020 (Tuesday)
Today's Date: 2/29/2020 (Saturday)

Display Week: 1

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	Week 1 1 / 6 / 20	Week 2 1 / 13 / 20	Week 3 1/20/20	Week 4 1 / 27 / 20	Week 5 2 / 3 / 20	Week 6 2 / 10 / 20	Week 7 2 / 17 / 20	Week 8 2 / 24 / 20	Week 9 3 / 2 / 20	Week 10 3 / 9 / 20	Week 11 3 / 16 / 20	Week 12 3 / 23 / 20	Week 13 3 / 30 / 20	Week 14 4 / 6 / 20
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Reading Week(Week 7)

Meeting Minutes Date Team members present

 2020/2/10
 Puer Liu, Qiufeng Du, Wenchen Zhang, Jiahui Wang

 2020/2/24
 Puer Liu, Qiufeng Du, Wenchen Zhang, Jiahui Wang

base on the performance and speed, we select KCF as our tracking method and set boundary box limitation to achieve sufficent FPS, we find the servo motor is not suitable for this project and we purchase another 2 motors, Ask Qiufeng doing 3D modeling and printing we discuss the package we should use for high speed webpage communication, check servo motor and fans and plan to print the gimbal and test

Discussions