Programming, Problem Solving, and Algorithms

CPSC 203, 2024 W2 (January – April 2025) Ian M. Mitchell Lecture 12B

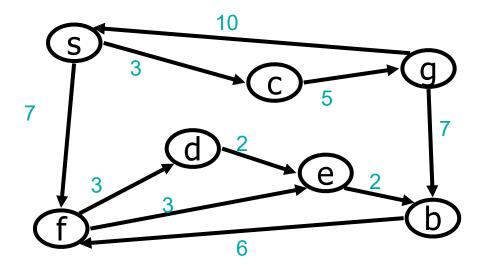
Slides from the Assigned Videos



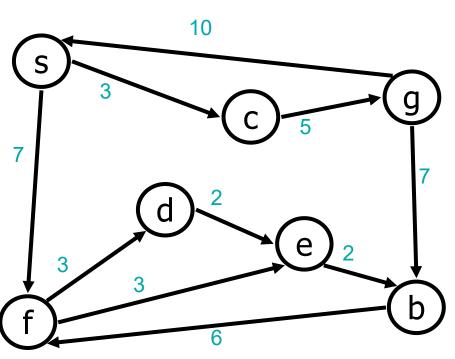
Given a start vertex (source) s, find the path of least total cost from s to every vertex in the graph.

Input: directed graph G with non-negative edge weights, and a start vertex s.

Output: A subgraph G' consisting of the shortest (minimum total cost) paths from s to every other vertex in the graph.



Dijkstra's Algorithm (1959)



Given a source vertex s, we wish to find the shortest path from s to every other vertex in the graph.

Initialize structure:

Repeat these steps:

- Label a new (unlabelled) vertex v, whose shortest distance has been found
- Update v's neighbors with an improved distance

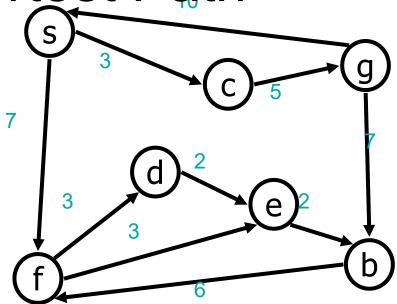
Initialize structure:

- 1. For all v, d[v] = "infinity", <math>p[v] = null
- 2. Initialize source: d[s] = 0
- 3. Initialize priority (min) queue

Repeat these steps n times:

- Find minimum d[] unlabelled vertex: v
- Label vertex v
- For all unlabelled neighbors w of v,

If
$$(_{}$$
 $d[w] = _{}$ $p[w] = v$



Your Turn...

Execute the algorithm on this graph:

Dijkstra's Algorithm

How is this algorithm similar to BFS/DFS?
How is this algorithm different from BFS/DFS?

Initialize structure:

- I. For all v, d[v] ="infinity", p[v] = null
- 2. Initialize source: d[s] = 0
- 3. Initialize priority (min) queue
- 4. Initialize set of labeled vertices to Ø.

Repeat these steps n times:

- Find & remove minimum d[] unlabelled vertex: v
- Label vertex v
- For all unlabelled neighbors w of v,
 If cost(v,w) < d[w]
 d[w] = cost(v,w)

$$v = [w]q$$

Priority Queues

- Basic operations: push, pop, is-empty
 - Python (FIFO) queue using deque q: q.appendleft, q.pop, q
 - Python stack using deque (or list) s: s.append, s.pop, s
- What about priority queue?
 - Try a list:
 - Try a deque: