

Predicting Level of Acceptability of Cars using Machine Learning

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Summary

In this project, we attempt to predict the level of acceptability of cars by building a machine learning model in Python (Van Rossum and Drake 2009). The acceptability levels include four class labels: **unacc** (unacceptable), **acc** (acceptable), **good**, and **vgood** (very good). We use a data created by the efforts of M. Bohanec in the late 1980s. It is sourced from the UCI Machine Learning Repository and is publicly available for research. Every features and target in this dataset are all encoded by one-hot encoder for data analysis. To choose the best model for this task, we utilised several common machine learning models, and found out that the SVM RBF classifier achieved the best train and cross-validation scores, with a test accuracy of 0.952. The SVM RBF model also showed exceptional ability in determining the acceptability of cars as seen in accuracy. Because we see that there is a class imbalance on the dateset,

we calculate the F1 score to test if our model have good performance. With an f1 score of 0.99 on test data, we justify that the model performs well on unseen data, even with a class imbalance. This makes the SVM RBF model a solid choice for this project. By looking deep into the performance of model on difference classes, we see the model performs exceptionally well overall, with near-perfect scores across all metrics. However, class good has a slight recall issue, indicating some instances of this class are being missed. A confusion matrix with cross validation is brought to further visualize what is happening.

Introduction

The Car Evaluation Dataset was created as part of efforts to understand the factors that affect the acceptability of cars among consumers. These factors include buying price of a car, maintenance costs, passenger and luggage capacity, and safety. The goal of this project is to develop a machine learning model that can evaluate the quality of a car based on its attributes to help buyers make a more informed decision for their next car purchase.

Methods

Data

The dataset that was used in this project is of Car Evaluation Database (Bohanec 1988) created by the efforts of M. Bohanec in the late 1980s. It is sourced from the UCI Machine Learning Repository and is publicly available for research.

Each row in the dataset details a car's attributes (each feature is of categorical data type with several levels), which includes:

- Buying price: low, med, high, vhigh
- Maintenance cost: low, med, high, vhigh
- Number of doors: 2, 3, 4, 5more
- Seating capacity: 2, 4, more
- Boot size: small, med, big
- Safety rating: low, med, high

Each row in the dataset details a car's attributes (features) and its **acceptability** (target variable). The target variable is categorized into four class labels: - **unacc**: Unacceptable. Cars that fail to meet basic criteria. - **acc**: Acceptable. Cars that meet minimum requirements. - **good**: Good. Cars that exceed average standards in some aspects. - **vgood**: Very good. Cars that meet the highest standards.

Exploratory Data Analysis

Exploratory data analysis was carried out on the train dataset.

To assess the balance of target classes in the dataset, the distribution of the target variable was visualized (see Figure 1). We can see the dataset has a significant class imbalance which is the **unacceptable** class. This imbalance can affect model performance: - Models may overpredict the **unacceptable** class and fail to identify minority classes (**good**, **vgood**). - It could be high simply by predicting the majority class, so accuracy may be misleading. We can consider metrics like Precision, Recall, and F1-score. This imbalance may require further handling. For example, oversampling, undersampling, or class-weighted loss functions during training.

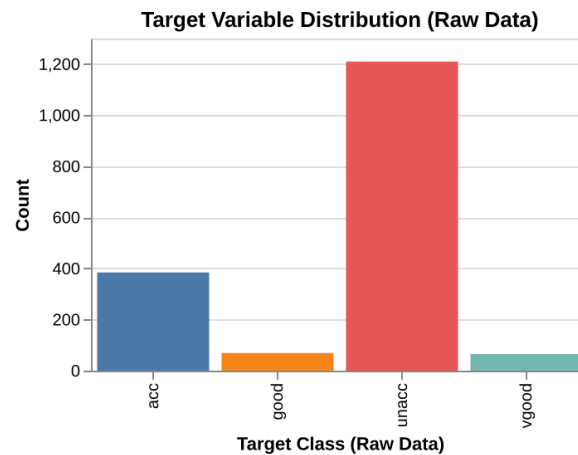


Figure 1: Distribution of Target Variable

From Figure 2, we can see the counts of records by target and category was visualised to gain a better idea of the dataset.

Through this analysis, we can see that examples with target class **unacceptable** represent a large proportion of the dataset.

Preprocessing of Dataset for Machine Learning

We preprocess the dataset to prepare it for machine learning:

- Transform categorical features using **OrdinalEncoder** from scikit-learn
- Split the dataset into training and testing sets

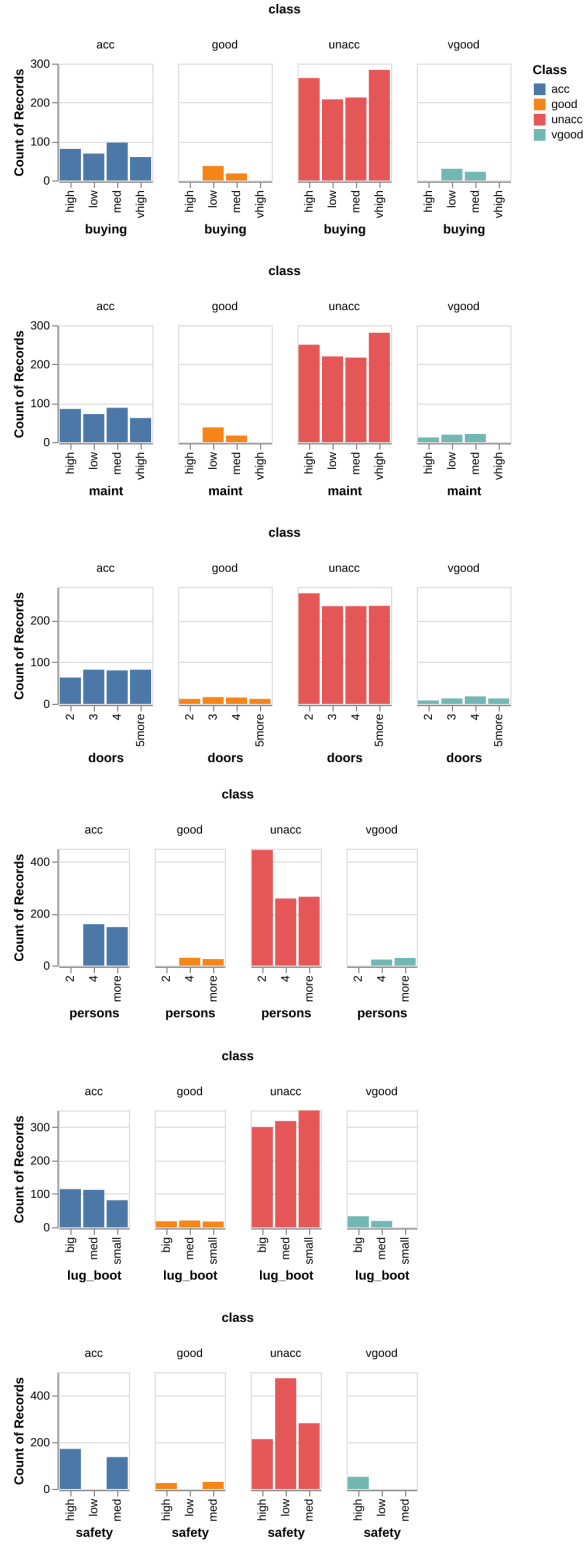


Figure 2: Distribution of Features by Class

Model Selection

The core of this project is choosing the appropriate machine learning model. Thus, several machine learning models from scikit-learn (Pedregosa et al. 2011) will be evaluated using cross-validation. The models evaluated are:

- `DummyClassifier` (Dummy), which serves as a baseline to compare the performance of other models,
- `DecisionTreeClassifier` (Decision Tree),
- `KNeighboursClassifier` (KNN),
- `SVC` with RBF kernel (SVM RBF),
- Naive Bayes using `MultinomialNB` (Naive Bayes), and
- `LogisticRegression` (Logistic Regression).

Table 1: Results of model selection conducted using cross-validation

Model	Mean train score	SD train score	Mean CV score	SD CV score
Dummy	0.7	0	0.7	0.001
Decision Tree	1	0	0.97	0.009
KNN	0.97	0.003	0.943	0.01
SVM RBF	0.971	0.004	0.952	0.018
Naive Bayes	0.711	0.002	0.708	0.004
Logistic Regression	0.838	0.007	0.834	0.019

The results of the model selection is shown in Table 1. According to the results, SVM RBF achieved high train and cross-validation scores of 0.971 and 0.952 respectively, suggesting it is the best model for generalising unseen data.

While the Decision Tree model yielded the best train and cross-validation scores, the perfect train score suggests that the model has overfitted to the data. Therefore, we will be using SVM RBF for this project.

Model Optimisation

With the best model identified, the next step was to improve its performance through hyperparameter optimization. Using `RandomizedSearchCV`, a range of values for the SVM's hyperparameters `C` and `gamma` were explored. This approach allowed for an efficient and thorough search across the parameter space, and results in an optimal estimator to use. We use `f1` weighted score to tune because of a multiclass dataset.

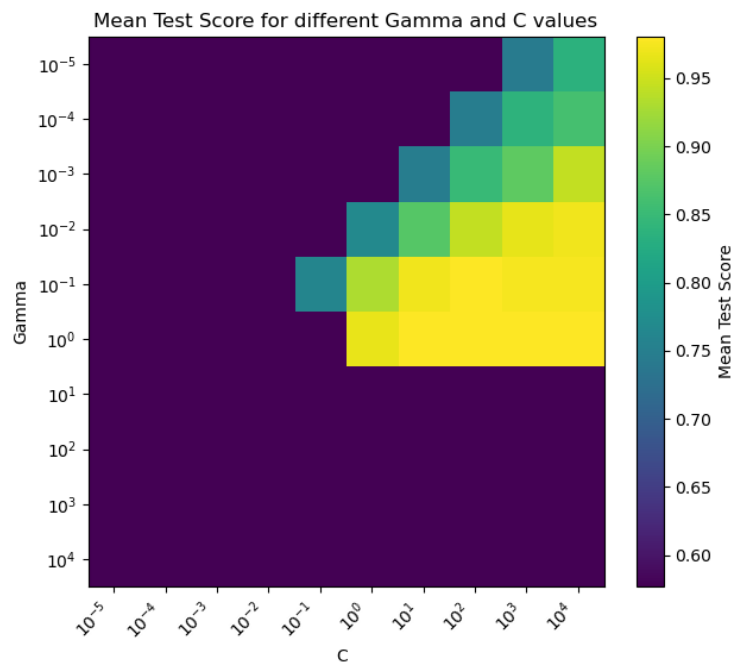


Figure 3: Heatmap of test scores obtained during hyperparameter optimisation

The visualizations below, including a heatmap (Figure 3) of test scores obtained during hyperparameter optimization. This interpretability aids in understanding which parameters are most critical and how sensitive the model is to these settings.

We observed that the best hyperparameter of `C` and `gamma` are 100.0 and 0.1 respectively. All categorical features were passed through `OrdinalEncoder` prior to model fitting. The Python programming language (Van Rossum and Drake 2009) and the following Python packages were used to perform the analysis: `numpy` (Harris et al. 2020), `Pandas` (McKinney 2010), `matplotlib` (Hunter 2007), `scikit-learn` (Pedregosa et al. 2011). The code used to perform the analysis and create this report can be found here: https://github.com/UBC-MDS/Car_Evaluation_Analysis/blob/main/scripts

Results & Discussion

After performing hyperparameter optimisation, the SVM RBF model manage to achieve the best f1 score of 0.99 on the test. This suggests the model has been generalised well, with high scores on both the train and test sets. Let's have a look at the classification report Table 2. It has a balanced performance across precision, recall, and F1-scores for each class. The weighted average metrics further confirm the robustness of the model. The weighted average F1-score 0.991 reflects balanced performance even with class imbalance. However, slightly lower recall for class good (0.857) suggests some misclassification, which could be improved with better feature engineering, or can be improved by increasing the data points.

Table 2: Classification report of the model

class	precision	recall	f1-score	support
acc	0.962	1	0.981	77
good	1	0.857	0.923	14
unacc	1	0.996	0.998	242
vgood	1	1	1	13
accuracy	0.991	0.991	0.991	0.991
macro avg	0.991	0.963	0.975	346
weighted avg	0.992	0.991	0.991	346

Below is a confusion matrix from cross validation(Figure 4), we can visualize how model performs specifically on each classes.

To further improve the model's utility, several changes can be made. One such change is feeding the model with features that are not just categorical. Instead, for features such as buying price, maintenance cost and safety features, numeric data should be collected. At the same time, more features can be included, such as the type of car and fuel efficiency ratings.

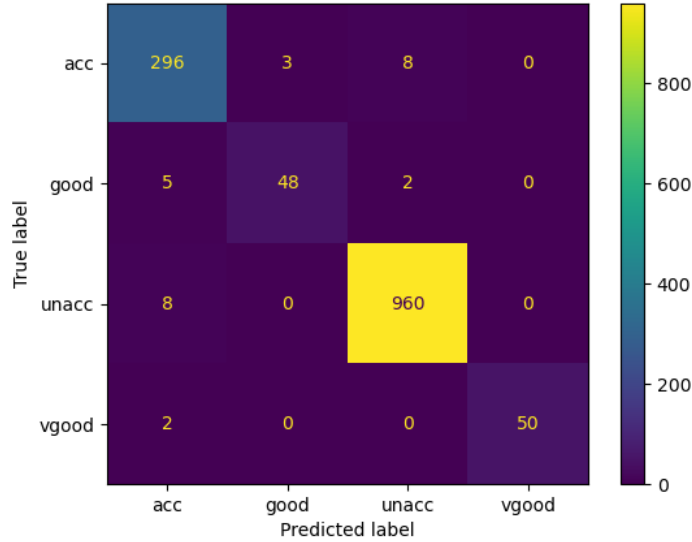


Figure 4: Confusion matrix from cross validation

By allowing the model to take in more complex data, this may allow the model to make more accurate predictions to let customers make a more informed choice when purchasing a new car.

References

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