

COLX-531: Neural Machine Translation

Muhammad Abdul-Mageed

`muhammad.mageed@ubc.ca`

Natural Language Processing Lab

The University of British Columbia

Attention Is All You Need

Ashish Vaswani*

Google Brain

avaswani@google.com

Noam Shazeer*

Google Brain

noam@google.com

Niki Parmar*

Google Research

nikip@google.com

Jakob Uszkoreit*

Google Research

usz@google.com

Llion Jones*

Google Research

llion@google.com

Aidan N. Gomez* †

University of Toronto

aidan@cs.toronto.edu

Łukasz Kaiser*

Google Brain

lukaszkaiser@google.com

Illia Polosukhin* ‡

illia.polosukhin@gmail.com

Background

- **Goal:** to reduce sequential computation
- **Extended Neural GPU, ByteNet, and ConvS2Sb:** use convnets for computing hidden representations in parallel for all input and output positions.
- Still **difficult to learn dependencies between distant positions**
- **Transformer:** **Constant number of operations** to relate signals from two arbitrary input or output positions
- This is at the **cost of reduced effective resolution** due to **averaging attention-weighted positions**
- Counteracted with **Multi-Head Attention**

Self-Attention (aka intra-attention)

What is self-attention?

- An attention mechanism that **relates different positions of a single sequence** in order to compute a representation of the sequence
- Has been successfully applied to **reading comprehension, abstractive summarization, textual entailment, and learning task-independent sentence representations**

Self-Attention

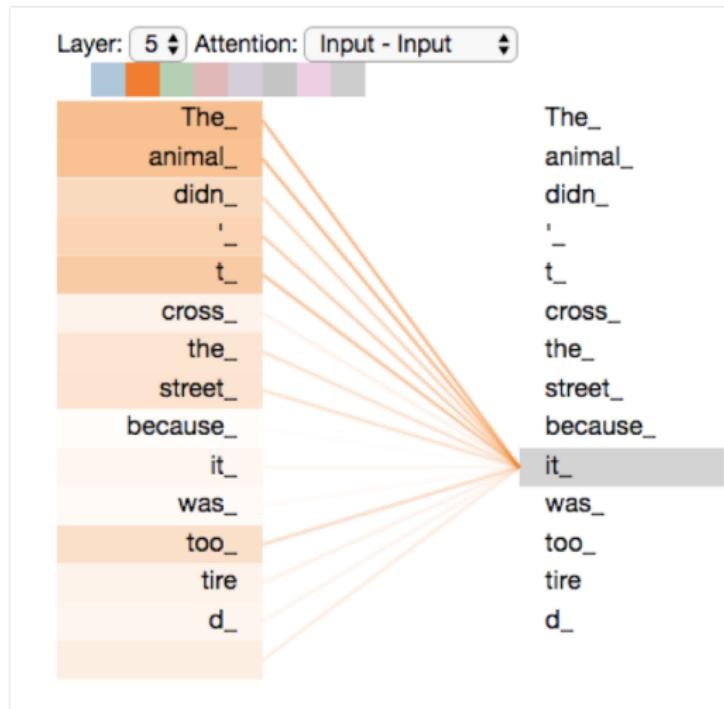


Figure: Self-attention. (Source: <http://jalammar.github.io>).

Transformer Architecture

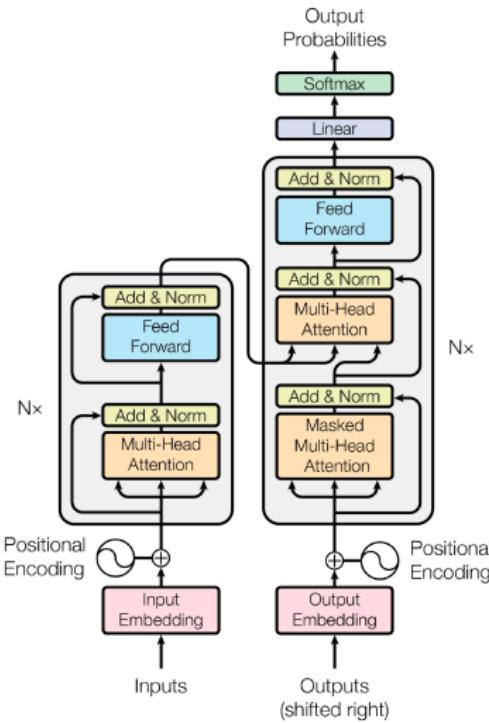
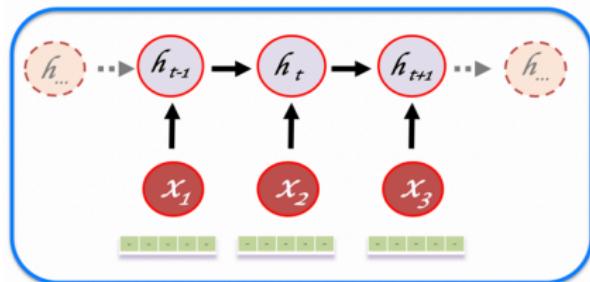
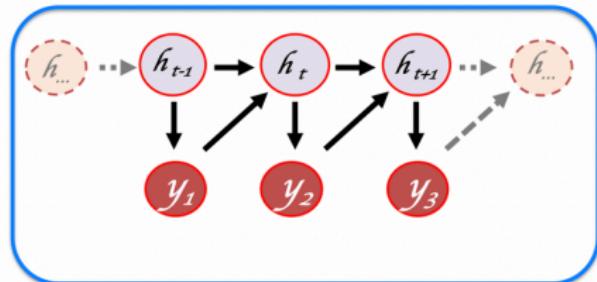


Figure: Transformer: Model Architecture.

Recall: Basic Encoder Decoder Idea



encoder



decoder

Figure: Transformer has an encoder and a decoder.

Transformer is based on encoder-decoder design

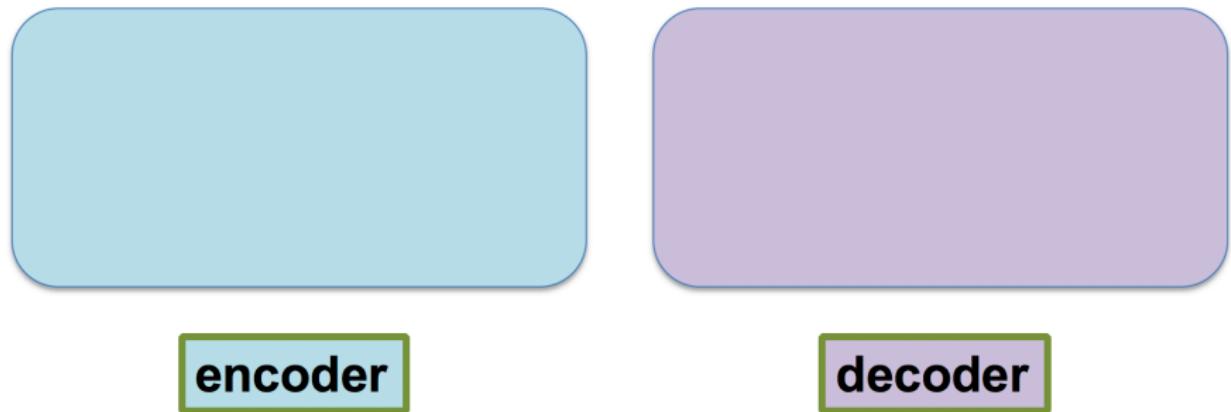


Figure: Transformer has an encoder and a decoder, **each with specialized building blocks.**

Basic Encoder-Decoder Operations

- **Encoder** maps an input sequence of symbol representations (x_1, \dots, x_n) to a sequence of continuous representations $\mathbf{z} = (z_1, \dots, z_n)$.
- Given \mathbf{z} , the **decoder** then generates an output sequence (y_1, \dots, y_m) of symbols one element at a time.
- **Auto-regressive:** At each step the model is auto-regressive, consuming the previously generated symbols as additional input when generating the next.

Input and Output Embeddings

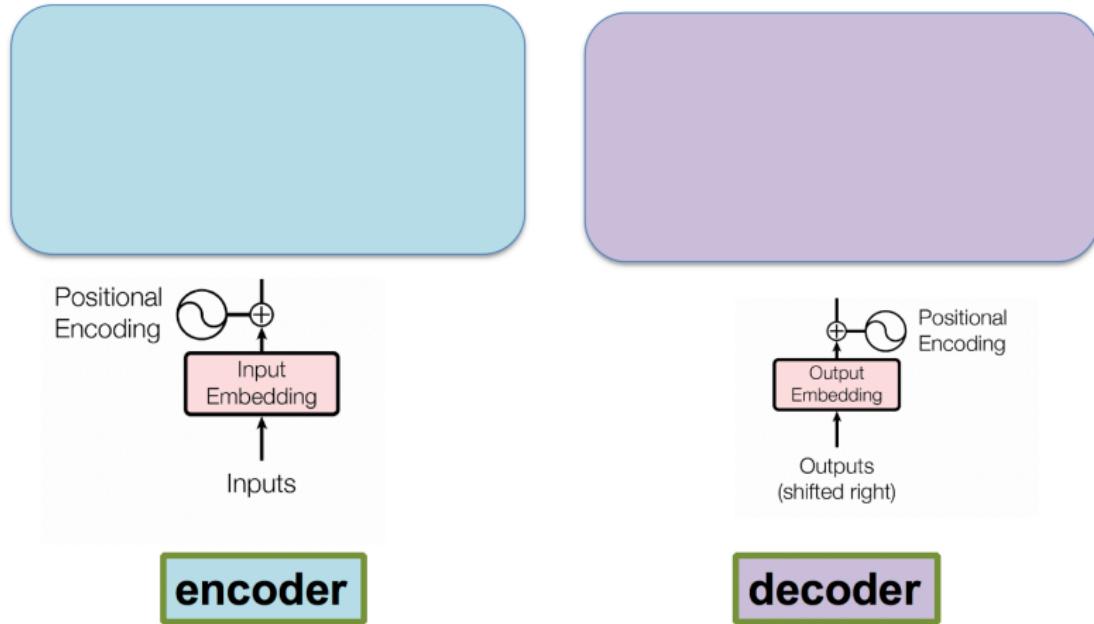
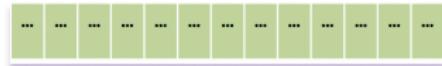


Figure: Embeddings for Encoder and Decoder.

Encoding Word Position



word embedding vector

+



sinusoidal vector



Figure: Simple Addition for encoding word positions

Positional Encoding

Recipe for PE

- Positional encodings added to the input embeddings at the bottoms of encoder and decoder stacks
- PEs *have the same dimension* d_{model} as the embeddings, so the two can be summed:
 $PE(pos, 2i) = \sin(pos/10000^{2i/d_{model}})$ &
 $PE(pos, 2i + 1) = \cos(pos/10000^{2i/d_{model}})$
where pos is the position and i is the dimension.

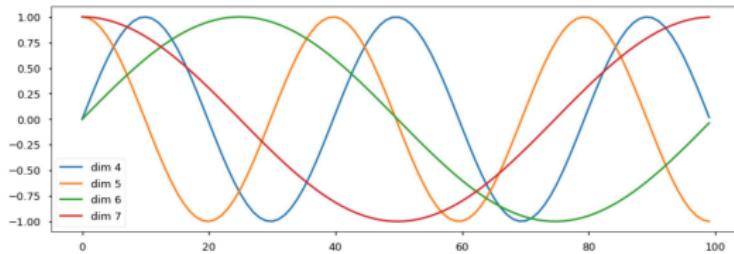


Figure: <https://nlp.seas.harvard.edu/2018/04/03/attention.html>.

Positional Encoding Example

PE Example

- For w at position $pos \in [0, L - 1]$, in sequence $s = (w_1, \dots, w_4)$, with 4-dimensional embedding e_w and $d_{model} = 4$:

$$\begin{aligned} e'_w &= e_w + \left[\sin\left(\frac{pos}{10000^0}\right), \cos\left(\frac{pos}{10000^0}\right), \sin\left(\frac{pos}{10000^{2/4}}\right), \cos\left(\frac{pos}{10000^{2/4}}\right) \right] \\ &= e_w + \left[\sin(pos), \cos(pos), \sin\left(\frac{pos}{100}\right), \cos\left(\frac{pos}{100}\right) \right] \end{aligned}$$

where the formula for positional encoding is as follows

$$PE(pos, 2i) = \sin\left(\frac{pos}{10000^{2i/d_{model}}}\right),$$

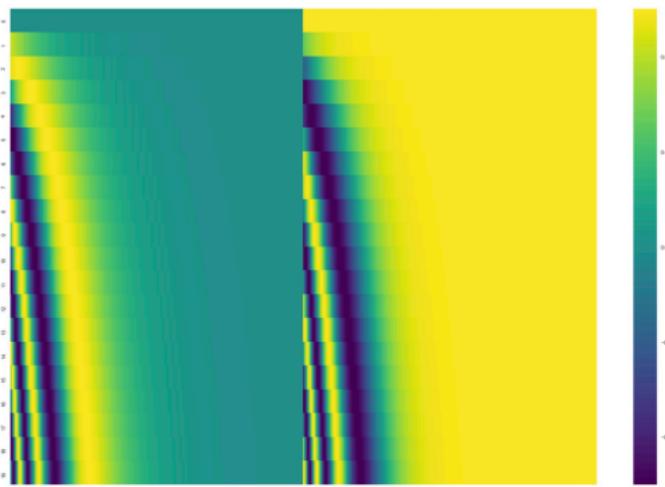
$$PE(pos, 2i + 1) = \cos\left(\frac{pos}{10000^{2i/d_{model}}}\right).$$

with $d_{model} = 512$ (thus $i \in [0, 255]$) in the original paper.

Figure: Source: <https://datascience.stackexchange.com/questions/51065/what-is-the-positional-encoding-in-the-transformer-model>.

Positional Encoding Illustrated

In the following figure, each row corresponds to the positional encoding of a vector. So the first row would be the vector we'd add to the embedding of the first word in an input sequence. Each row contains 512 values – each with a value between 1 and -1. We've color-coded them so the pattern is visible.



A real example of positional encoding for 20 words (rows) with an embedding size of 512 (columns). You can see that it appears split in half down the center. That's because the values of the left half are generated by one function (which uses sine), and the right half is generated by another function (which uses cosine). They're then concatenated to form each of the positional encoding vectors.

Figure: Source: <http://jalammar.github.io>. This illustration is unfortunately **incorrect** as it uses sin for the first half of the embedding and cos for the second half, instead of sin for even indices and cos for odd indices.

Torch Tensor for Word Embeddings

```
import math
import numpy as np
import torch
import matplotlib.pyplot as plot
#-----
max_seq_len= 4
d_model= 4
d_embed= 4
"""

Let's create a tensor of word embeddings with 4 dimensions for each word (d_embed),
for 4 words (max_seq_len)
"""

word_embeddings= torch.rand( (max_seq_len, d_embed))
print(word_embeddings)

tensor([[0.6981, 0.3755, 0.7078, 0.0328],
       [0.9458, 0.2585, 0.0134, 0.2634],
       [0.9467, 0.7712, 0.4704, 0.6277],
       [0.2791, 0.9099, 0.8795, 0.9542]])
```

Tensor for Positions

```
"""
Let's create a tensor of positional encodings, populate by zeros for now.
Each word vector will have a corresponding positional vector within this pe tensor
"""

pe = torch.zeros(max_seq_len, d_embed) # positional encoding
print(pe)

tensor([[0., 0., 0., 0.],
       [0., 0., 0., 0.],
       [0., 0., 0., 0.],
       [0., 0., 0., 0.]])
```



```
"""
Let's change the positional encodings tensor such that each dimension
is changed by sin or cos, as appropriate
"""

for pos in range(max_seq_len):
    for i in range(0, d_model, 2):
        pe[pos, i] = math.sin(pos / (10000 ** ((2 * i)/d_model)) )
        pe[pos, i + 1] = math.cos(pos / (10000 ** ((2 * i)/d_model)) )
print(pe)

tensor([[ 0.0000,  1.0000,  0.0000,  1.0000],
       [ 0.8415,  0.5403,  0.0001,  1.0000],
       [ 0.9093, -0.4161,  0.0002,  1.0000],
       [ 0.1411, -0.9900,  0.0003,  1.0000]])
```

Figure: A tensor for sinusoidal vectors at each position i (sin) and $i+1$ (cos).

Adding Embeddings and Positions for PE

```
"""
Let's retrieve positional encoding at index 3
and also embedding vector for index 3.
"""

pe3 = pe[2] # Positional encoding at index 3.
w3_embed = word_embeddings[2] # Embedding for word 3
#-----
print("\n-- Positional encoding for w in position 3:\n\n", pe3)
print("\n-- Embedding vector for w in position 3:\n\n", w3_embed)

-- Positional encoding for w in position 3:
tensor([ 0.9093, -0.4161,  0.0002,  1.0000])

-- Embedding vector for w in position 3:
tensor([0.9467, 0.7712, 0.4704, 0.6277])

# We simply add the two vectors
print("\n-- Embedding vector and positional encoding added:\n\n", word_embedding + pe3)

-- Embedding vector and positional encoding added:
tensor([1.7087, 0.0290, 0.2876, 1.9235], dtype=torch.float64)
```

Figure: Encoding for w3 is by adding its embed and sinusoidal pos vectors.

Encoder Blocks (6 Identical Blocks)

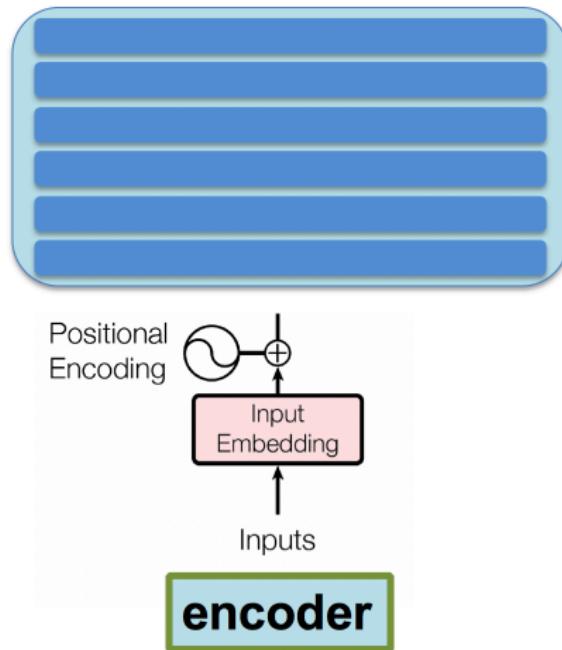


Figure: Encoder's 6 identical blocks.

An Encoder Block

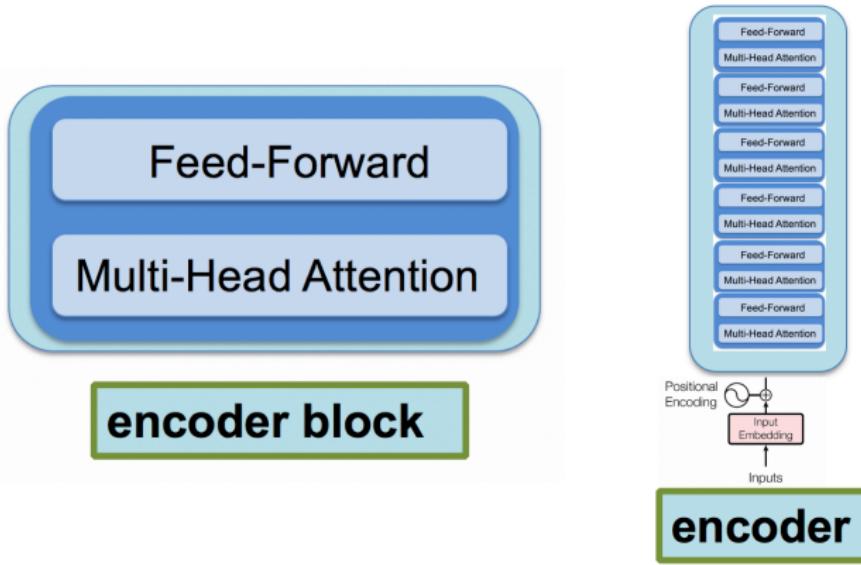


Figure: Each encoder block has two sub-layers, a multi-head attention and a feed-forward.

Self-Attention

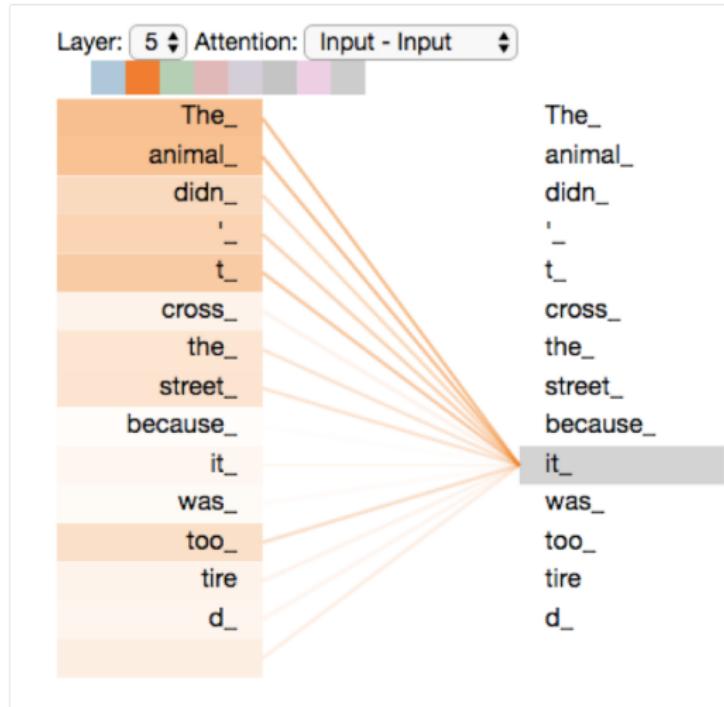
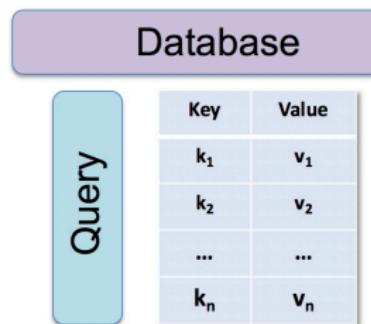


Figure: Self-attention. (Source: <http://jalammar.github.io>).

Query, Key, and Value

Intuition

- Retrieving from a database, we issue a **query (q)** to identify a **key (k)** that has a similarity, based on a **value (v)**, to q.
- To do **backpropagation** on the output, we will not just want one similarity value, but a **similarity distribution** over all keys.



$$\text{Attention}(q, \mathbf{k}, \mathbf{v}) = \sum_i \text{sim}(q, k_i) v_i$$

MT Example of Query, Key, and Value

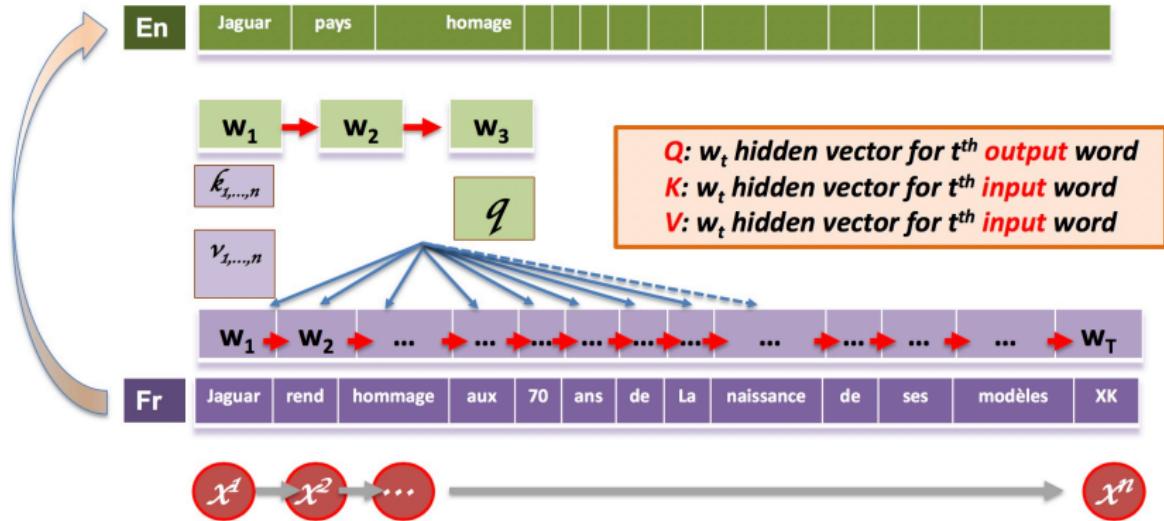


Figure: q , k , and v in MT.

Self-Attention in Transformer with q, k, v

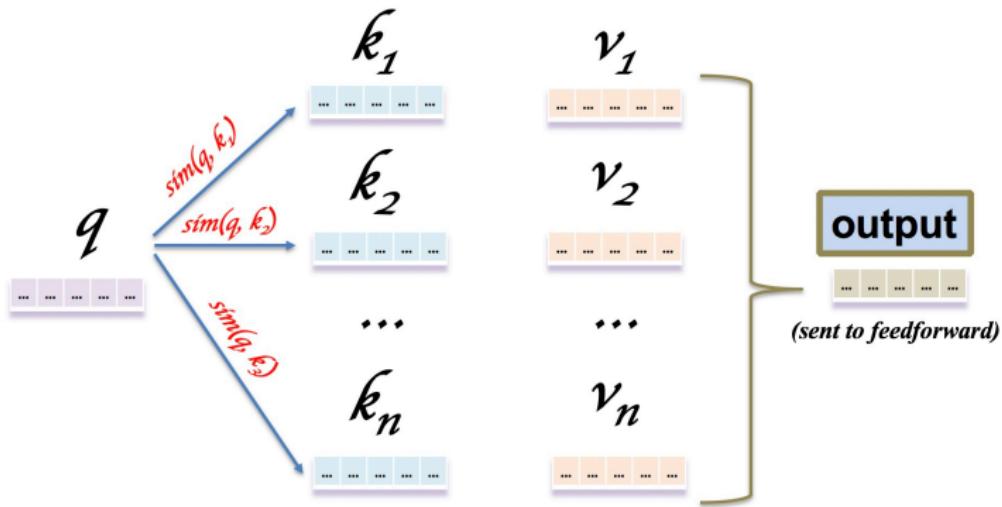


Figure: Mapping a **query** and a set of **key-value** pairs to an output. **Similarity** **s** will be based on **dot product**. Well, **scaled** dot product...

Z weighted sum of $\sum_i \text{softmax}(\text{sim}(q, k_i)) v_i$

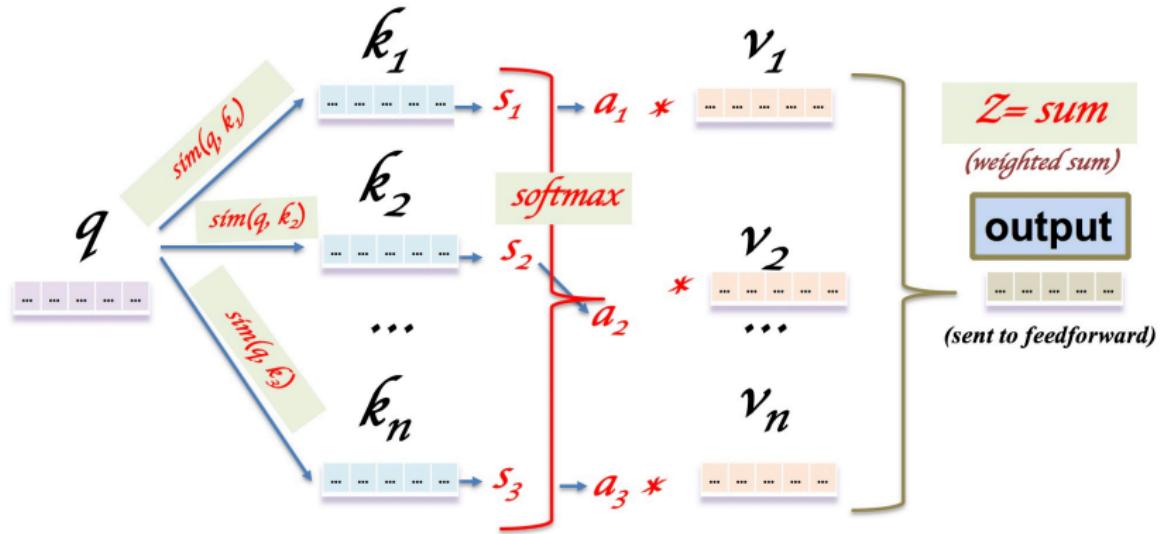


Figure: $s = \text{sim}(q, k_i)$. $\alpha = \text{softmax}(s)$. $Z = \sum_i \alpha_i v_i$

Self-Attention Illustrated: Query “the”

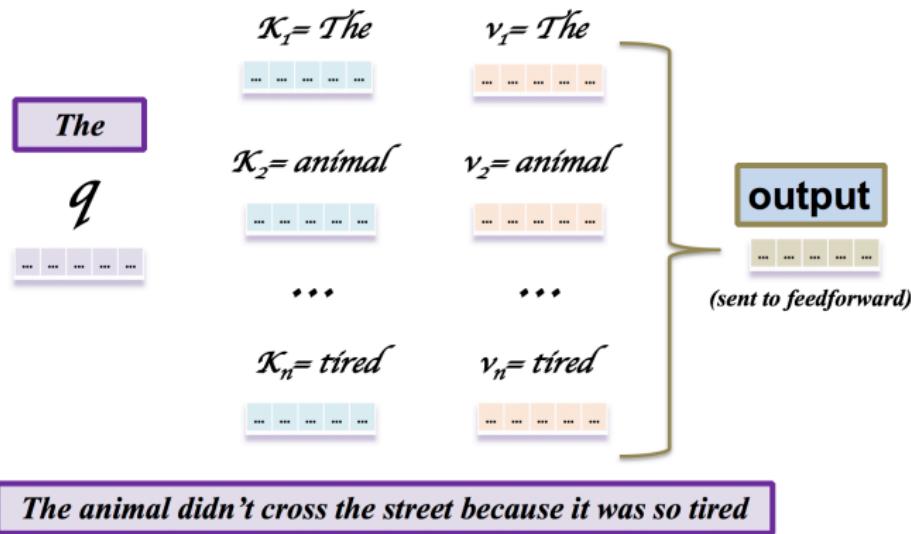
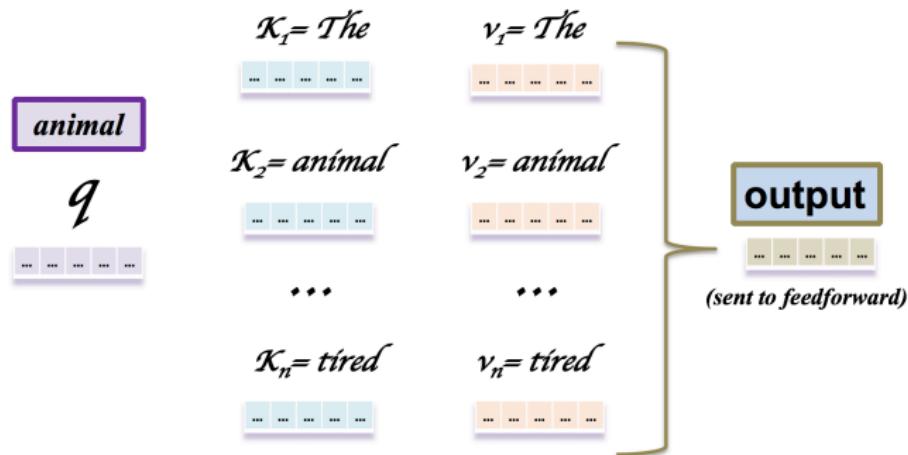


Figure: Mapping the **query** “the” and a set of **key-value** pairs to an output.

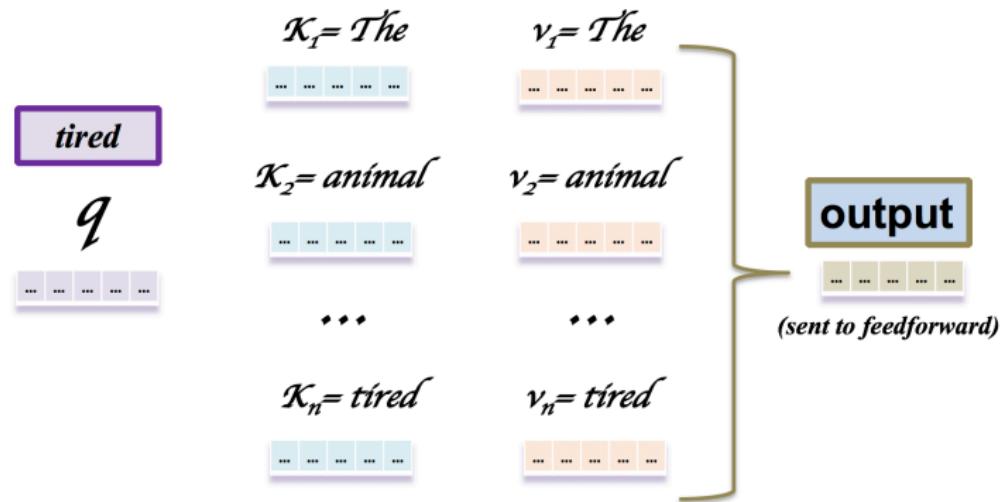
Self-Attention Illustrated: Query “animal”



The animal didn't cross the street because it was so tired

Figure: Mapping the **query** “animal” and a set of **key-value** pairs to an output.

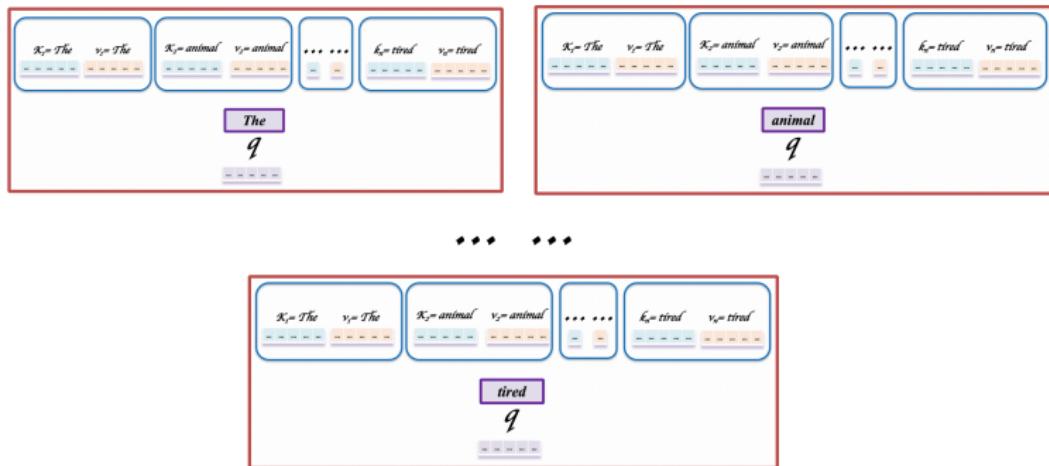
Self-Attention Illustrated: Query “tired”



The animal didn't cross the street because it was so tired

Figure: Mapping the **query** “tired” and a set of **key-value** pairs to an output.

Self-Attention Illustrated: All-Queries Overview'



The animal didn't cross the street because it was so tired

Figure: Mapping all **queries** and a set of **key-value** pairs to an output.

Scaled Dot-Product Attention

$$\text{Attention}(\mathbf{Q}, \mathbf{K}, \mathbf{V}) = \text{softmax} \left(\frac{\mathbf{X}}{\sqrt{d_k}} \right) \mathbf{V} = \mathbf{Z}$$

The diagram illustrates the components of scaled dot-product attention. At the top, four boxes labeled Q , K^T , V , and Z are shown above their respective matrix representations. Below these, the formula for scaled dot-product attention is given as $\text{Attention}(\mathbf{Q}, \mathbf{K}, \mathbf{V}) = \text{softmax} \left(\frac{\mathbf{X}}{\sqrt{d_k}} \right) \mathbf{V} = \mathbf{Z}$. The matrix \mathbf{X} is positioned between the input matrices and the output matrix \mathbf{Z} .

Figure: **Scaled dot-product attention** in the Transformer.

Scaled Dot-Product Attention: Paper Illustration

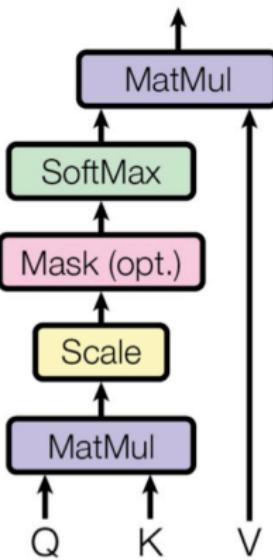


Figure: Scaled dot-product attention

Linear Projections of Query, Key, and Value (for Multi-Head Attention)

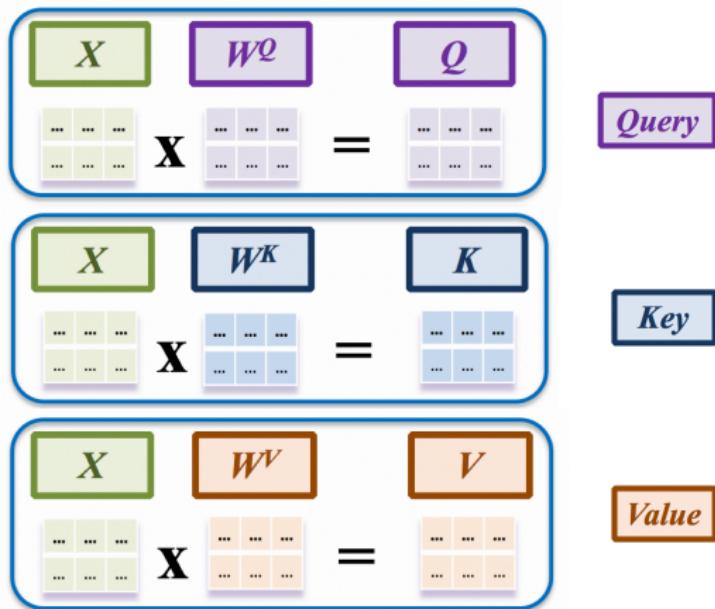


Figure: Linear projections of Q, K, and V. W matrixes are learned linear projections.

Multi-Head Attention

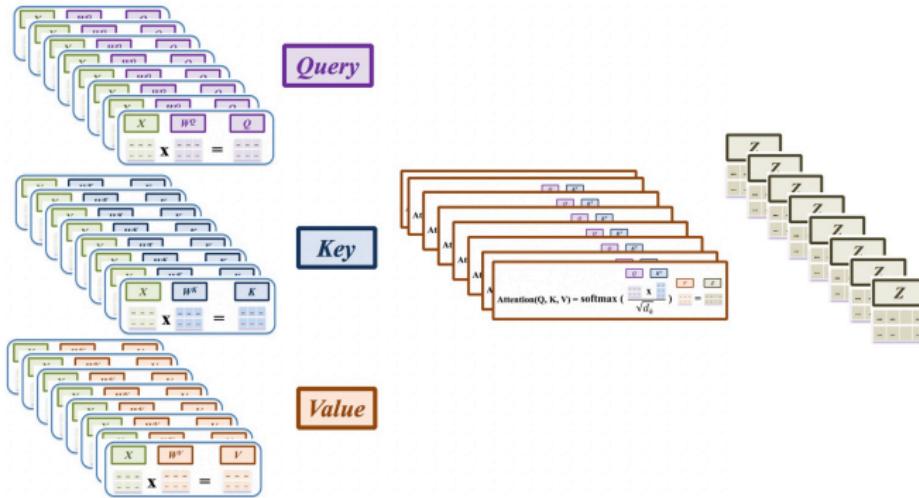


Figure: Multi-Head Attention with 8 attention heads.

Multi-Head Attention in Paper

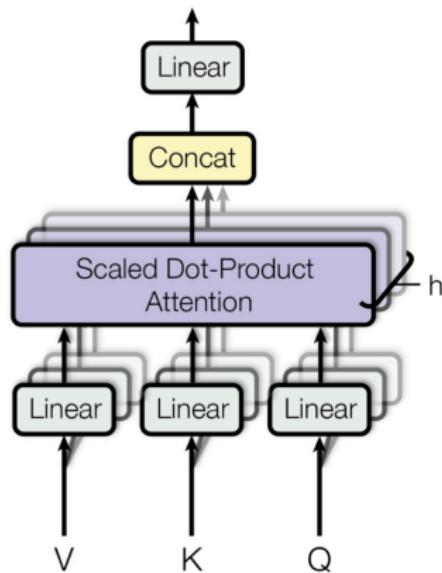
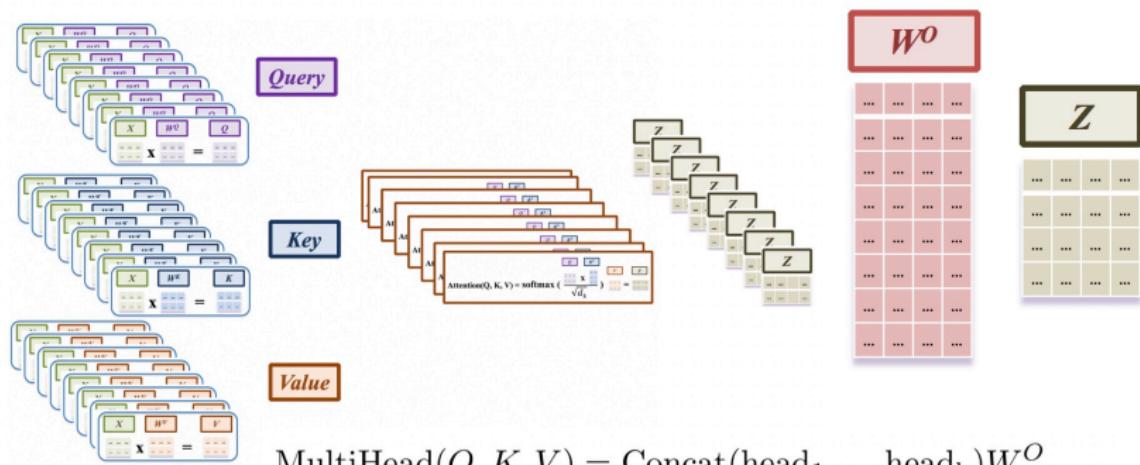


Figure: **Multi-Head Attention**

Multi-Head Attention: Output Concatenation

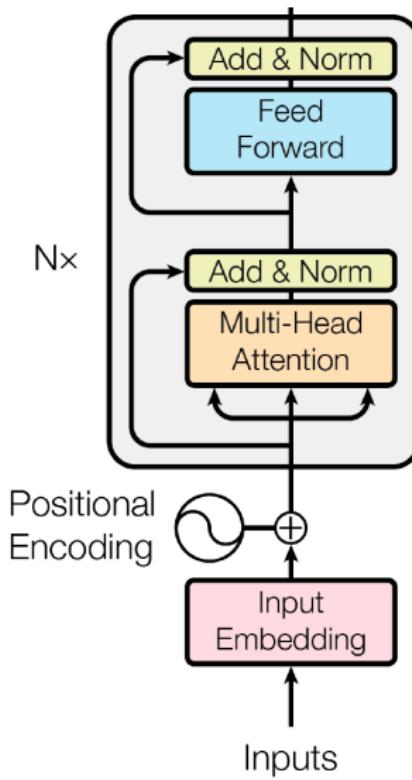


$$\text{MultiHead}(Q, K, V) = \text{Concat}(\text{head}_1, \dots, \text{head}_h)W^O$$

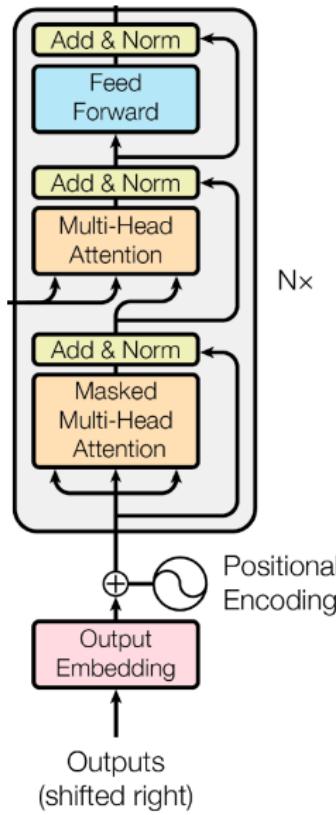
$$\text{where } \text{head}_i = \text{Attention}(QW_i^Q, KW_i^K, VW_i^V)$$

Figure: Output of attention heads are concatenated and projected to a linear layer.

Detailed Encoder Block



Detailed Decoder Block



Masked Attention

1: Attention

$$\text{Attention}(Q, K, V) = \text{softmax}\left(\frac{QK^T}{\sqrt{d_k}}\right)V$$

2: Masked Attention

$$\text{Masked Attention}(Q, K, V) = \text{softmax}\left(\frac{QK^T + M}{\sqrt{d_k}}\right)V$$

Masking Matrix M

M is a matrix of 0's (in lower triangular) and $-\infty$ (in upper triangular)

Masked Attention II

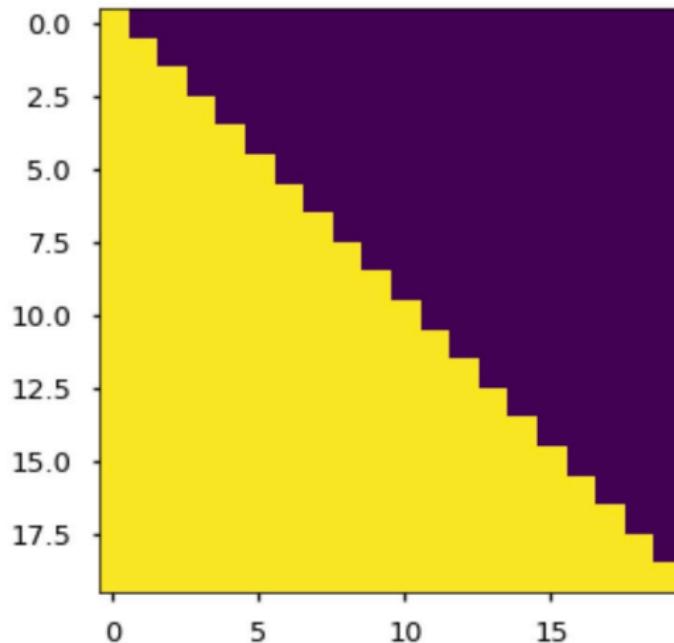


Figure: Masking in Transformer. (Source: <https://nlp.seas.harvard.edu/2018/04/03/attention.html>).

Residual Learning

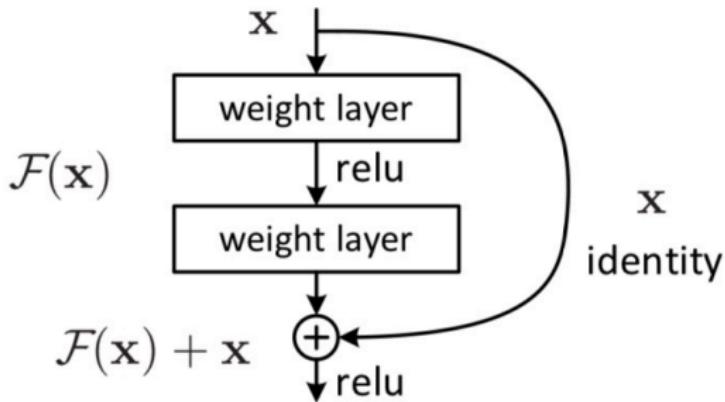


Figure 2. Residual learning: a building block.

Figure: Source: He et al. ("Deep Residual Learning for Image Recognition", 2016)
http://openaccess.thecvf.com/content_cvpr_2016/papers/He_Deep_Residual_Learning_CVPR_2016_paper.pdf

Whole Transformer Architecture

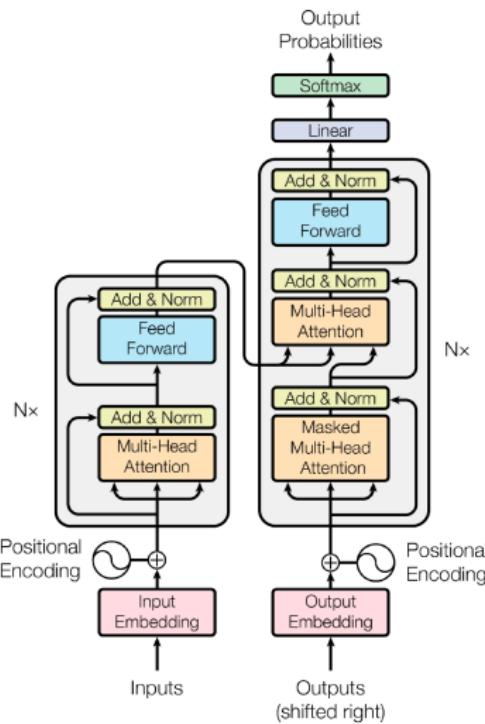


Figure: Transformer: Model Architecture.

Application of Attention in the Transformer

Attention in Transformer

- ① **Encoder self-attention layers:** In a self-attention layer all of the keys, values and queries come from the same place, in this case, the output of **the previous layer in the encoder**.
- ② In “**encoder-decoder attention**” layers: **queries come from the previous decoder layer**, and the **memory keys and values come from the output of the encoder**.
- ③ **Decoder self-attention layers:** Each position in the decoder attends to all positions in the decoder up to and including that position.