

Shigley's Mechanical Engineering Design | (10th Edition)

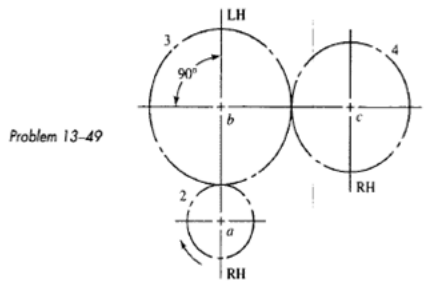
Chapter 13, Problem 49P

1 Bookmark

Show all steps: ON

Problem

Gear 2, in the figure, has 16 teeth, a 20° transverse angle, a 15° helix angle, and a module of 4 mm. Gear 2 drives the idler on shaft b , which has 36 teeth. The driven gear on shaft c has 28 teeth. If the driver rotates at 1600 rev/min and transmits 6 kW, find the radial and thrust load on each shaft.



Step-by-step solution

Step 1 of 8

Calculate the diameter of the gear by using the following relation:

$$d = N \times m$$

Here, N is the number of teeth on the gear and m is the module of the gear.

Calculate the diameter of the gear 2 (d_2).

$$d_2 = N_2 \times m$$

Substitute 16 for N_2 and 4 mm for m .

$$\begin{aligned} d_2 &= 16 \times 4 \\ &= 64 \text{ mm} \end{aligned}$$

Calculate the diameter of the gear 3 (d_3).

$$d_3 = N_3 \times m$$

Substitute 36 for N_3 and 4 mm for m .

$$\begin{aligned} d_3 &= 36 \times 4 \\ &= 144 \text{ mm} \end{aligned}$$

Calculate the diameter of the gear 4 (d_4).

$$d_4 = N_4 \times m$$

Substitute 28 for N_4 and 4 mm for m .

$$\begin{aligned} d_4 &= 28 \times 4 \\ &= 112 \text{ mm} \end{aligned}$$

[Comment](#)

Step 2 of 8

Post a question

Answers from our experts for your tough homework questions

[Continue to post](#)

20 questions remaining

My Textbook Solutions



Shigley's
Mechanical...
10th Edition



Discrete-
Time Signal...
3rd Edition



Signals,
Systems, &...
5th Edition

[View all solutions](#)

Chegg tutors who can help right now



Rakesh
Aryabhata Knowle... 400



Josh
Ph.D. in Mathematics 108



Ryan
University of South... 51

[Find me a tutor](#)



$$W_t = \frac{H}{\pi d n}$$

Here, H is the power, n is the speed of the driver gear, and d is the diameter of the driver gear.

Substitute 6 kW for H , 64 mm for d , and 1600 rpm for n .

$$\begin{aligned} W_t &= 60000 \frac{6}{\pi \times 64 \times 1600} \\ &= 1.119 \text{ kN} \end{aligned}$$

Calculate the input torque by using the following relation:

$$T_2 = W_t \times \frac{d_p}{2}$$

Here, d_p is the diameter of the pinion.

$$\begin{aligned} T_2 &= W_t \times \frac{d_p}{2} \\ &= 1.119 \times \frac{64}{2} \\ &= 35.52 \text{ kN} \cdot \text{mm} \end{aligned}$$

[Comment](#)

Step 3 of 8

Calculate the radial component of load (W_r).

$$W_r = W_t \tan \phi_i$$

Substitute 1.119 kN for W_t and 20° for ϕ_i .

$$\begin{aligned} W_r &= W_t \tan \phi_i \\ &= 1.119 \times \tan 20^\circ \\ &= 0.40728 \text{ kN} \end{aligned}$$

Calculate the axial component of load (W_a).

$$W_a = W_t \tan \psi$$

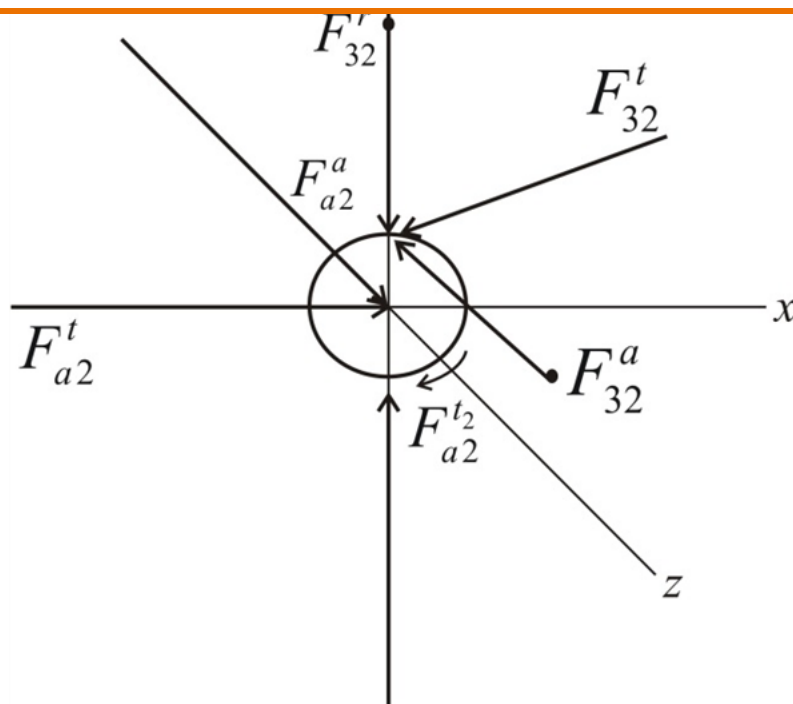
Substitute 1.119 kN for W_t and 15° for ψ .

$$\begin{aligned} W_a &= W_t \tan \psi \\ &= 1.119 \times \tan 15^\circ \\ &= 0.299 \text{ kN} \end{aligned}$$

[Comment](#)

Step 4 of 8

Draw the free body diagram of the forces acting on the gear 2.



Here, F'_{32} is the tangential force exerted by gear 3 against gear 2, F^a_{32} is the axial force exerted by the gear 3 against gear 2, F^r_{32} is the radial force exerted by the gear 3 against the gear 2, F^t_{a2} is the tangential force of gear 2 against shaft a, F^a_{a2} is the axial force of gear 2 against shaft a, and F^r_{a2} is the radial force of gear 2 against shaft a.

Calculate the load on shaft a in the vector form as follows:

$$F_{2a} = (-W_t \mathbf{i} - W_r \mathbf{j} - W_a \mathbf{k}) \text{ kN}$$

Substitute 1.11 kN for W_t , 0.4 kN for W_r , and 0.29 kN for W_a .

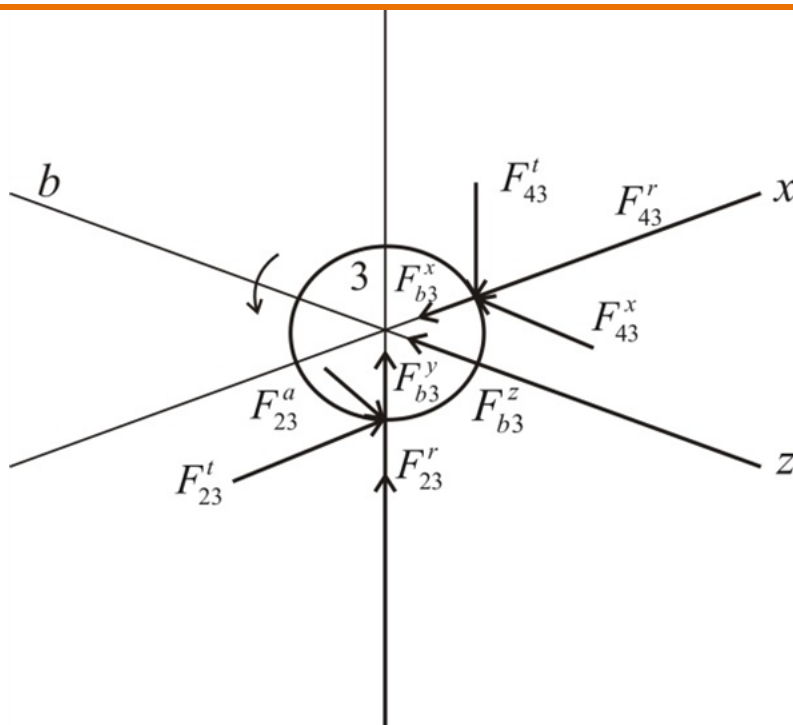
$$F_{2a} = (-1.1 \mathbf{i} - 0.4 \mathbf{j} - 0.29 \mathbf{k}) \text{ kN}$$

Therefore, the forces acting on the shaft a is $\boxed{(-1.1 \mathbf{i} - 0.4 \mathbf{j} - 0.29 \mathbf{k}) \text{ kN}}$.

[Comment](#)

Step 5 of 8

Draw the free body diagram of the forces acting on the gear 3.



[Comment](#)

Step 6 of 8

From the free body diagram, calculate the load on the shaft b in the vector form as follows:

$$F_{3b} = (W_t - W_r)\mathbf{i} - (W_t - W_r)\mathbf{j} \text{ kN}$$

Substitute 1.11 kN for W_t and 0.4 kN for W_r .

$$F_{3b} = (1.11 - 0.4)\mathbf{i} - (1.11 - 0.4)\mathbf{j}$$

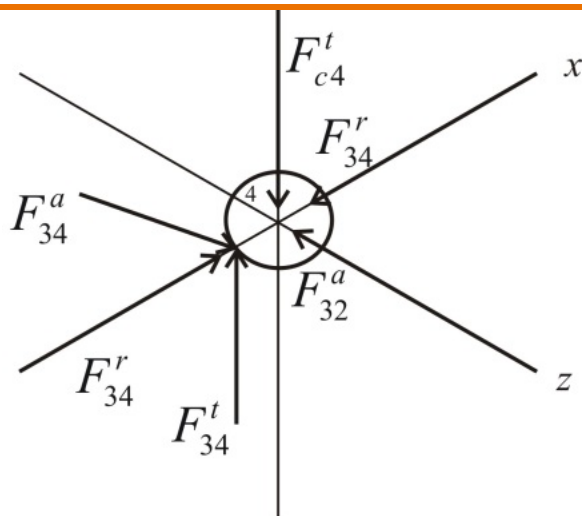
$$F_{3b} = (0.71\mathbf{i} - 0.71\mathbf{j}) \text{ kN}$$

Therefore, the forces acting on the shaft b is $(0.71\mathbf{i} - 0.71\mathbf{j}) \text{ kN}$.

[Comment](#)

Step 7 of 8

Draw the free body diagram of forces acting on the gear 4.



[Comment](#)

Step 8 of 8

Calculate the forces acting on the shaft c in the vector form as follows:

$$F_{4c} = (W_r \mathbf{i} + W_t \mathbf{j} + W_a \mathbf{k}) \text{ kN}$$

Substitute 1.11 kN for W_t , 0.4 kN for W_r , and 0.29 kN for W_a .

$$F_{4c} = (0.4\mathbf{i} + 1.11\mathbf{j} + 0.29\mathbf{k}) \text{ kN}$$

Therefore, the forces acting on the shaft c is $(0.4\mathbf{i} + 1.11\mathbf{j} + 0.29\mathbf{k}) \text{ kN}$.

[Comment](#)

Was this solution helpful?

7

1

Recommended solutions for you in Chapter 13

Chapter 13, Problem 38P

For the countershaft in Prob. 3?72, p. 138, assume the gear ratio from gear B to its mating gears 2 to 1.(a) Determine the minimum number of teeth that can be used on gear B without an interference problem in the teeth.(b) Using the number of...

[See solution](#)

Chapter 13, Problem 7P

A parallel helical gearset consists of a 19-tooth pinion driving a 57-tooth gear. The pinion has a left-hand helix angle of 30° , a normal pressure angle of 20° , and a normal module of 2.5 mm. Find:(a) The normal, transversal and axial circular...

[See solution](#)