



FireWire Hardware Installation Guide

V7.0.9

04 April 2011

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For customers in the U.S.A.

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a residential environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. However there is no guarantee that interferences will not occur in a particular installation. If the equipment does cause harmful interference to radio or television reception, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the distance between the equipment and the receiver.
- Use a different line outlet for the receiver.
- Consult a radio or TV technician for help.

You are cautioned that any changes or modifications not expressly approved in this manual could void your authority to operate this equipment. The shielded interface cable recommended in this manual must be used with this equipment in order to comply with the limits for a computing device pursuant to Subpart B of Part 15 of FCC Rules.

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Pour utilisateurs au Canada

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Contacting Allied Vision Technologies

Info



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Introduction

This **FireWire Hardware Installation Guide** describes the hardware installation procedures for the following 1394 AVT cameras: Oscar, Marlin, Guppy, Pike, Stingray and Guppy PRO.

The **FireWire Hardware Installation Guide** answers questions about putting AVT cameras into operation, about safety warnings, pin assignments on I/O connectors and 1394a/b connectors. Learn how to get more information at the AVT website (accessories), how to get information about software applicable with AVT cameras and how to get deep information from the Technical Manual of each camera family.

Note



Please read through this manual carefully before installing the hardware on your PC or laptop (FireWire card, cables) and operating the AVT cameras.

Document history

Version	Date	Remarks
V2.0.0	31.03.08	New Manual - RELEASE status
V2.1.0	21.05.08	Schematics standardized in Chapter <i>Cautions: Connecting a camera</i> on page 22ff. Marked Pin 1 with blue color in <i>Figure 10: Board level camera (Guppy): IEEE 1394 FireWire connector 1 (view on pins)</i> on page 41
to be continued on next page		

Table 1: Document history

Version	Date	Remarks
continued from last page		
V2.2.0	19.08.08	<p>Inserted Latching precautions for 1394a cables in Chapter Connecting camera to PC or laptop on page 36</p> <p>Corrected ordering number in Figure 3: Removing IR cut filter/ protection glass using special tool (E9020001) on page 29</p> <p>Restructuring Chapter Camera interfaces on page 37ff.</p> <p>New measurements of inputs and outputs and standardized descriptions of I/Os for all AVT camera families in Chapter Camera interfaces on page 37ff.</p> <p>New photo of Stingray camera with new screws on either side of the camera on title page</p> <p>New photo of Stingray backside in Figure 8: Example: Rear view of Stingray camera (2x 1394b copper) on page 37</p> <p>New photos of Dolphin, Oscar, Marlin, Guppy, Pike, Stingray (with HIROSE and 1394 copper) in Table 5: Rear view of AVT cameras (HIROSE and 1394 copper) on page 38</p> <p>New photos Pike fiber and Stingray fiber (with HIROSE and 1394b GOF and 1394b copper) in Table 6: Rear view of AVT cameras (HIROSE and 1394b GOF/copper) on page 39</p> <p>New photo of Pike fiber (with HIROSE and 1394b GOF and 1394b copper) in Figure 15: Rear view of Pike camera (1394b: 1 x GOF, 1 x copper) (Stingray similar) on page 45</p> <p>Deleted AVT Direct FirePackage in Chapter AVT software on page 15</p> <p>Revised Chapter AVT software on page 15f.</p> <p>New Stingray board level CAD drawings (1394b connectors are now (partially) visible):</p> <p>in Figure 12: Board level camera (Stingray): two IEEE 1394b FireWire connectors on page 43 and</p> <p>in Figure 21: Stingray board level camera: I/O pin assignment on page 54</p>
V2.3.0	12.09.08	<p>New Stingray board level CAD drawing with new Molex 1.25 mm Pitch PicoBlade Wire-to-Board Header (53047-1310) and new cable lengths in Figure 12: Board level camera (Stingray): two IEEE 1394b FireWire connectors on page 43 and in Figure 21: Stingray board level camera: I/O pin assignment on page 54</p>
to be continued on next page		

Table 1: Document history

Version	Date	Remarks
continued from last page		
V3.0.0	08.10.08	New Stingray F-125B/C: see Figure 20: Stingray output switching times on page 52
V4.0.0	21.10.08	New Stingray F-504B/C see Figure 20: Stingray output switching times on page 52
V5.0.0	24.10.08	New Guppy F-503B/C see Guppy delay on page 75
V5.1.0	28.01.09	New CAD drawings (hexagon socket head cap screw ISO 4762): <ul style="list-style-type: none"> • Figure 12: Board level camera (Stingray): two IEEE 1394b FireWire connectors on page 43 • Figure 21: Stingray board level camera: I/O pin assignment on page 54 Added 50 mA as max. input current on page 72. Dolphin camera family discontinued
V5.2.0	28.05.09	Changed <i>Camera In 1</i> signal $U_{in}(high)$ from 2 V to 2.4 V in Figure 33: Guppy (housing): Camera I/O connector pin assignment on page 70 Added minimum pulse width (inputs) for all camera families: <ul style="list-style-type: none"> • Stingray: see Chapter Stingray delay and minimum pulse width on page 50 • Pike: see Chapter Pike delay and minimum pulse width on page 57 • Guppy: see Chapter Guppy delay and minimum pulse width on page 73 • Marlin: see Chapter Marlin delay and minimum pulse width on page 79 • Oscar: see Chapter Oscar delay and minimum pulse width on page 85
to be continued on next page		

Table 1: Document history

Version	Date	Remarks
continued from last page		
V5.3.0	16.09.09	<p>New Stingray front flange:</p> <ul style="list-style-type: none"> Title page: new Stingray photo Table 4: How to remove the filter/protection glass on page 28 (new: Stingray Rev. 3) Figure 12: Board level camera (Stingray): two IEEE 1394b FireWire connectors on page 43 Figure 21: Stingray board level camera: I/O pin assignment on page 54 <p>New Pike front flange:</p> <ul style="list-style-type: none"> Title page: new Pike photo Table 4: How to remove the filter/protection glass on page 28 (Pike Description: both screws top (middle) and the right side)
V6.0.0	07.05.10	<p>Minor corrections:</p> <ul style="list-style-type: none"> Corrected Camera Input 1: $U_{in}(\text{high}) = 3.8 \text{ V} \dots 5 \text{ V}$ $U_{in}(\text{low}) = 0 \text{ V} \dots 1 \text{ V}$ in Figure 33: Guppy (housing): Camera I/O connector pin assignment on page 70 <p>Added Pike F-1100 and Pike F-1600:</p> <ul style="list-style-type: none"> Title page: photo of Pike F-1000/F-1600 Pike delay on page 61 <p>Discontinuation of Marlin F-131C</p> <p>New links to new AVT website</p> <ul style="list-style-type: none"> Chapter Contacting Allied Vision Technologies on page 6
to be continued on next page		

Table 1: Document history

Version	Date	Remarks
continued from last page		
V7.0.7	30.11.10	<p>Revised Manual (added Guppy PRO) — RELEASE status</p> <ul style="list-style-type: none"> Added Stingray in Chapter <i>Marlin/Stingray/Guppy PRO: changing filters safety instructions</i> on page 21 Changed URLs in this chapter to the new structured AVT website. <p>Added Guppy PRO cameras:</p> <ul style="list-style-type: none"> Added photo of Guppy PRO on title page Added Guppy PRO in Chapter <i>IEEE 1394b port pin assignment (Guppy PRO, Pike, Stingray)</i> on page 42 Added Guppy PRO in Chapter <i>Camera I/O connectors (12 pin) order numbers and cables: Guppy PRO, Stingray, Pike, Marlin, Oscar</i> on page 46 Added Chapter <i>Guppy PRO input block diagram</i> on page 64 Chapter <i>Guppy PRO delay and minimum pulse width</i> on page 65 Chapter <i>Guppy PRO block diagram</i> on page 66 Removed RS232: Chapter <i>Guppy PRO camera I/O connector pin assignment</i> on page 63 Chapter <i>Guppy PRO delay</i> on page 68
V7.0.8	07.01.11	<ul style="list-style-type: none"> Minor corrections Added caution (sensor damage) in Chapter <i>Sensor safety instructions</i> on page 18 Added Windows 7 support in Chapter <i>AVT cameras: installing hardware</i> on page 32 Recommended software package for SmartFeature control is now AVT Universal Package, see Chapter <i>AVT software</i> on page 15. Note: Only SmartView of AVT FirePackage provides extended GUI control options to evaluate AVT 1394 camera smart features, see Chapter <i>Overview hardware installation</i> on page 35.
to be continued on next page		

Table 1: Document history

Version	Date	Remarks
continued from last page		
V7.0.9	04 April 2011	<ul style="list-style-type: none"> Added Guppy PRO: Changing filter instructions same as Marlin/Stingray: see Chapter Marlin/Stingray/Guppy PRO: changing filters safety instructions on page 21 and Table 4: How to remove the filter/protection glass on page 28 Added Singapore: see Contacting Allied Vision Technologies on page 6 Revised camera delay descriptions: <ul style="list-style-type: none"> Chapter Stingray delay on page 52 Chapter Pike delay on page 61 Chapter Guppy PRO delay on page 68 Chapter Guppy delay on page 75 Chapter Marlin delay on page 81 Chapter Oscar delay on page 87

Table 1: Document history

Manual overview

The manual overview describes each chapter of this manual shortly.

- Chapter [Contacting Allied Vision Technologies](#) on page 6 lists AVT contact data for both: technical information / ordering and commercial information.
- Chapter [Introduction](#) on page 7 (this chapter) gives you the document history, a manual overview and conventions used in this manual (styles and symbols). Furthermore you learn how to get more information on **AVT accessories**, available **AVT software** and the **AVT Technical Manuals**.
- Chapter [Safety instructions](#) on page 17 describes safety instructions for AVT cameras in general and special safety instructions for camera families/models.
 - Read this chapter carefully before operating any AVT camera.**
 - Follow all safety instructions, especially the cautions when connecting cameras.**
 - Take special care when operating board level cameras (Caution-ESD, general warnings, loading and dirty environments). Read all notes and safety instructions before operating any AVT board level camera.**
- Chapter [AVT cameras: installing hardware](#) on page 32 describes the hardware installation procedures. In this chapter you get links to the AVT website (accessories) and you learn how to get more information on installing software.
 - Read this chapter before installing any hardware.**

- Read and follow the FireWire hot plug precautions.
 - Read and follow the caution when connecting a camera to PC or laptop.
- Chapter [Camera interfaces](#) on page 37 describes the interfaces of all AVT cameras (I/O connector and IEEE 1394a and 1394b connectors).
 - Read all notes and cautions carefully.
- Chapter [Firmware update](#) on page 89 describes how to get information on firmware updates.

Conventions used in this manual

To give this manual an easily understood layout and to emphasize important information, the following typographical styles and symbols are used:

Styles

Style	Function	Example
Bold	Programs, inputs or highlighting important things	bold
Courier	Code listings etc.	Input
Upper case	Register	REGISTER
Italics	Modes, fields	<i>Mode</i>
Parentheses and/or blue	Links	(Link)

Table 2: Styles

Symbols

Note This symbol highlights important information.



Caution This symbol highlights important instructions. You have to follow these instructions to avoid malfunctions.



Caution-ESD

This symbol highlights important ESD instructions. Only **qualified personnel** is allowed to install and operate components marked with this symbol.

www

This symbol highlights URLs for further information. The URL itself is shown in blue.

Example:

<http://www.alliedvisiontec.com>

More information

In this chapter you get more information on **AVT accessories**, available **AVT software** and the **AVT Technical Manuals**.

AVT accessories

Note

Allied Vision Technologies offers a wide range of **accessories** for the use of AVT Cameras and the easy integration in already existing applications.

- **IEEE 1394a** and **IEEE 1394b** accessories (interface cards, hubs and repeaters, cables)
- **Lenses** (for cameras with sensors of type 1/3, 1/2, 1, 2/3 and 1.2)

www

For **more information on accessories** and on **ordering accessories online** (by clicking the article and sending an inquiry) go to:

<http://www.alliedvisiontec.com/emea/products/accessories.html>

AVT software

Note



AVT cameras are **compliant to IIDC V1.30/V1.31**. Moreover AVT cameras offer many more functions than specified in the IIDC V1.30/V1.31: so-called AVT SmartFeatures. These features are accessible via direct register access, or by using special functions provided in the following **AVT Software Packages**:

- AVT Universal Package
- AVT Fire4Linux

To evaluate all AVT SmartFeatures with a GUI tool use SmartView (which is part of the AVT FirePackage).

All software packages provided by AVT are **free of charge** and contain the following components:

- Drivers
- Software Development Kit (SDK) for camera control and image acquisition
- Examples based on the provided APIs of the SDK
- Documentation and release notes
- Viewer application to operate/configure the cameras and access/test the **AVT SmartFeatures**.

www



All software packages (including documentation and release notes) provided by AVT can be downloaded at:

<http://www.alliedvisiontec.com/emea/products/software.html>

There is no product CD.

www

In addition to the AVT Software Packages Allied Vision Technologies offers special **Integration Packages** to integrate AVT cameras into any third-party vision software that supports the IIDC standard.

For more information refer to the **Software Package Selector Guide**.

Go to:

<http://www.alliedvisiontec.com/emea/products/software.html>

Here you also find the **AVT Software Packages for download** and **additional software documentation**:

- FirePackage User Guide
- FirePackage64 User Guide
- Active FirePackage User Guide
- [tbd: Fire4Linux User Guide]
- [tbd: Fire4Linux Command Reference Guide]
- Release Information
- Operating AVT cameras with SmartView (this manual is part of the FirePackage)

AVT Technical Manuals

Note

Besides hardware installation procedures (this guide) and the software documentation there is an in-depth description of all AVT cameras in the so-called **Technical Manuals** (one for each AVT camera family):

- Oscar Technical Manual
- Marlin Technical Manual
- Guppy Technical Manual
- Guppy PRO Technical Manual
- Pike Technical Manual
- Stingray Technical Manual

Here you find: technical data, functional descriptions, features of the camera and how to use, register descriptions (IIDC V1.30/V1.31 and AVT advanced registers)

www

For **downloading the Technical Manuals** go to:

<http://www.alliedvisiontec.com/emea/support/downloads/product-literature.html>

Safety instructions

This chapter describes safety instructions/cautions valid for all AVT camera families and special safety instructions/cautions depending on the camera family/model used.

General safety instructions

Note



- There are no switches or parts inside the camera that require adjustment. The guarantee becomes void upon opening the camera casing.
- If the product is disassembled, reworked or repaired by other than a recommended service person, AVT or its suppliers will take no responsibility for the subsequent performance or quality of the camera.
- The camera does **not** generate dangerous voltages internally. However, because the IEEE 1394a and 1394b standard permit cable power distribution at voltages higher than 36 V, **please note that various country-specific regulations apply.**

Note



- All **color models** are equipped with an **optical filter** to eliminate the influence of infrared light hitting the sensor. Please be advised that, as a side effect, this filter reduces sensitivity in the visible spectrum. The optical filter is part of the back focus ring, which is threaded into the C-Mount.
- **B/w models** are delivered with a **sensor protection glass** mounted in the back focus ring to ensure maximum sensitivity. In certain applications and depending on the lighting source and optics, the use of either IR blocking or IR passing filter may be required to improve the image quality.

Sensor safety instructions

Caution



Sensor may be damaged

Light intensity or exposure time exceeding the saturation of the sensor may damage the sensor irreparably.

This may occur in following situations:

- Laser light hitting the sensor directly
- Bright light sources (e.g. sunlight) hitting the sensor directly
- Camera is exposed to X-rays

Damages may be caused by:

- Overheating of color filters, microlenses or pixel structures
- Accelerated aging of color filters or pixel structures

To avoid sensor damage

- Use light source with lower intensity
- Use external shutter
- Use optical filters
- Use lens cap (when camera not in use)
- Vary local light spot / laser spot on sensor
- X-rays:
 - Keep camera out of X-ray path. Guide the light source via mirrors to the sensor. Or
 - Use lead glass to protect lens and sensor. Use lead jacket for the body of the camera.

The warranty does not cover damaged cameras caused by X-ray applications or too much light/laser light.

FireWire safety instructions

FireWire hot-plug and screw-lock precautions

Caution



Hot-plug precautions

- Although FireWire devices can **theoretically** be hot-plugged without powering down equipment, **we strongly recommend turning the computer power off, before connecting a digital camera** to it via a FireWire cable.
- **Static electricity or slight plug misalignment during insertion may short-circuit and damage components.**
- The physical ports **may be damaged** by **excessive ESD** (electrostatic discharge), when connected under powered conditions. It is good practice to ensure proper grounding of computer case and camera case to the same ground potential, before plugging the camera cable into the port of the computer. This ensures that no excessive difference of electrical potential exists between computer and camera.
- It is **very** important **not** to exceed an inrush current of 18 mJoule in 3 ms. (This means that a device, when powered via 12 V bus power must **never** draw more than 1.5 A, even not in the first 3 ms.)
- **Higher inrush current may damage the physical interface chip of the camera and/or the phy chip in your PC.**
- Whereas inrush current is not a problem for one Pike/Stingray camera, daisy chaining multiple cameras or supplying bus power via (optional) HIROSE power out to circuitry with unknown inrush currents needs careful design considerations to be on the safe side.

Latching / screw-lock precautions

- **1394a cameras:** We strongly recommend using **only 1394a cables with latch connectors**, to insure a tight electrical connection that is resistant to vibration and gravity.
- **1394b cameras:** All AVT 1394b camera and cables have **industrial screw-lock fasteners**, to insure a tight electrical connection that is resistant to vibration and gravity.
- **We strongly recommend using only 1394b adapter cards with screw-locks.**

Changing filters safety instructions

Caution



- Mount/dismount lenses and filters in a **dust-free environment**, and **do not** use compressed air (which can push dust into cameras and lenses).
- Use only **optical quality tissue**/cloth if you must clean a lens or filter.

Ask your dealer if you are not familiar with these procedures.

Guppy: changing filters safety instructions

Old CS-/C-Mounting	New CS-/C-Mounting starting with serial no. 06/05-84312215
<p>CS-Mount models have the filter or protection glass mounted directly in front of the sensor. Taking out the filter or protection glass is not possible at customer site.</p> <p>Ask your dealer for a camera with the respective filter already installed.</p>	<p>All models have the filter or protection glass mounted directly in the CS-Mount adapter. (Standard delivery is a CS-Mount camera). Taking out the filter or protection glass is not possible at customer site.</p> <p>Ask your dealer for a camera with the respective filter already installed.</p>
<p>C-Mount models have the filter or protection glass mounted in the CS- to C-Mount extension adapter.</p> <p>Ask your dealer for an extension adapter with the intended filter already mounted.</p>	<p>In order to get a C-Mount camera, screw the 5 mm C-Mount adapter onto the CS-Mount camera.</p> <p>Unscrew the 5 mm C-Mount adapter to get again a CS-Mount camera.</p>
<p>Removing the C-Mount adapter opens the front section of the camera. This greatly enhances the risk for dust or particles to migrate on the sensor's protection glass.</p> <p>In order to remove the adapter:</p> <p>Hold the camera so that the adapter points downwards while changing the adapter. Use optical cleaning tissues for cleaning the sensor's protection glass if needed. Never use compressed air for cleaning purposes.</p> <p>Ask your dealer if you are not familiar with these procedures.</p>	<p>Removing the CS-Mount adapter opens the front section of the camera. This greatly enhances the risk for dust or particles to migrate on the sensor's protection glass.</p> <p>In order to remove the adapter:</p> <p>Hold the camera so that the adapter points downwards while changing the adapter. Use optical cleaning tissues for cleaning the sensor's protection glass if needed. Never use compressed air for cleaning purposes.</p> <p>Ask your dealer if you are not familiar with these procedures.</p>

Table 3: Old and new CS-/C-Mounting of Guppy cameras

Pike/Oscar: changing filters safety instructions

Note



- **Pike/Oscar** models only: **Changing filters** is achieved by changing back focus rings with the appropriate filter already mounted. Please be advised that back focus adjustment will be necessary in order to match C-Mount distance of 17.526 mm. Ask your dealer for further information or assistance.

Marlin/Stingray/Guppy PRO: changing filters safety instructions

Note



- **Marlin/Stingray/Guppy PRO** models only: For certain applications it may be recommended to take out the filter by means of a special tool which can be ordered from AVT under the following number: E9020001.
- Taking out the filter requires special care. Ask your dealer to help you if you are not confident with the procedure.

Cautions: Connecting a camera

Caution



ALL CAMERAS

- **Do not touch the shield of the camera cable** connected to a computer and the ground terminal of the lines at the same time.
- If you are charged: before touching the shield of the camera cable, make sure to discharge first (by touching the ground terminal of the lines).
- **Use only DC power supplies with insulated cases.** These are identified by having only **two** power connectors.
- Although IEEE 1394a and 1394b are functionally plug and play, the physical ports **may be damaged** by **excessive ESD** (electrostatic discharge), when connected under powered conditions. It is good practice to ensure proper grounding of computer case and camera case to the same ground potential, before plugging the camera cable into the port of the computer. This ensures that no excessive difference of electrical potential exists between computer and camera.
- If you feel uncomfortable with the previous advice or if you have no knowledge about the connectivity of an installation, **we strongly recommend powering down all systems before connecting or disconnecting a camera.**

Pike/Stingray GOF connectors

Caution



Special warning for all Pike/Stingray models with GOF connectors:

GOF connectors are very sensitive. **Any dust or dirt may cause damage.**

- Always keep the GOF connector and optical fiber plug clean.
- If GOF connection is not in use, keep GOF dust cover on the GOF connector.
- Reduce mating cycles to a minimum to prevent abrasion.
- Please note that optical fiber cables have a very limited deflection curve radius.

Safety instructions for board level cameras

Note



Read the Guppy Technical Manual or Stingray Technical Manual and this safety instructions before use.

Abuse or misapplication of the camera may result in limited warranty or cancelation of warranty.

Caution-ESD



Board level cameras: ESD warnings

- Only **qualified personnel** is allowed to install and operate the Board level cameras.
- Board level cameras are delivered without housing. Handle the sensor board and main board with care. Do not bend the boards. Do not touch the components or contacts on a board. Hold a board by its edges.
- Sensor board and main board are sensitive to electrostatic discharge. To avoid possible damage, handle all static-sensitive boards and components in a static-safe work area. Follow the procedures below.
- ESD (electrostatic discharge): Static electricity can damage the sensor board or the main board of your Board level cameras. To prevent static damage, discharge static electricity from your body before you touch any of your board level cameras's electronic components, such as sensor board or main board. To do so, use a static-safe work area with static-dissipative mat and wear a static-dissipative wrist strap. Do not hold any components of your Board level cameras against your clothing. Even if you are wearing a wrist strap, your body is grounded but your clothes are not.
- Do not remove the sensor board and main board from its anti-static packaging unless your body is grounded.
- **ESD shielding:** To protect the boards from radiation of other modules or devices use a special ESD protective housing.

Caution**Board level cameras: General Warnings**

- Be sure that all power to your board level cameras is switched off, before mounting the sensor board or making connections to the camera.
- Do not connect or disconnect any cables during an electrical storm.
- Do not use your board level cameras during an electrical storm.
- To help avoid possible damage to the sensor board or main board, wait 5 seconds after power is switched off, before connecting or disconnecting any cable to the board level cameras.
- Ensure that nothing rests on the cables of your board level cameras.
- Keep your board level cameras away from radiators and heat sources.
- Do not spill food or liquids on your board level cameras.

Caution**Board level cameras: Loading**

- Avoid any mechanical forces to the board level cameras, the boards and its components, especially torsional, tensile and compressive forces. Any of these forces may result in damage of the board level cameras, the boards and its components.
- To avoid damages of the boards, provide cables with an external pull relief so that no force is applied to the connectors itself.

Caution**Board level cameras: Dirty environments**

- Always use clean boards.
- To protect the boards from dirt like dust, liquids or swarf always use the board level cameras only in clean room environment or use a protective housing.

AVT camera cleaning instructions

This section describes safety instructions/cautions valid for all AVT camera families in case of cleaning lenses, optical filters/protection glass or sensors.

Note



- Please read these instructions before you contact your AVT camera dealer for assistance.
- Ask your AVT camera dealer if you are not familiar with the procedures described below.

Warranty

Caution



Warranty precautions

- To ensure your warranty remains in force:
 - Do not open the camera housing.
 - Follow instructions described below.
 - Use only optical quality tissue/cloth if you must clean a lens or filter.
 - Use only optics cleaner (60% ethyl alcohol, 40% ether). Never use aggressive cleaners like benzine or spirit. Such cleaners may destroy the surface.
 - **Do not use compressed air which can push dust into camera and lens.**
- AVT does not warranty against any physical damage to the sensor/filter/protection glass or lenses caused by the user during the cleaning process.

Caution



General warnings

- Do not touch any optical component with bare fingers. Oil or other impurities may damage the surface.
- Only follow the processes described below if you are familiar with these procedures and if you have the necessary equipment.
- If you are uncomfortable with the outlined precautions, please return your camera to AVT for cleaning.

Caution-ESD ESD warnings

Image sensors are easily damaged by static discharge (ESD).

- Please use anti-static gloves, clothes and materials. Also use conductive shoes.
- Install a conductive mat on the floor and/or working table to prevent the generation of static electricity.

Avoiding the necessity of camera cleaning

When changing camera lenses please follow these procedures:

- Simply hold the camera with the C-mount opening towards the floor, when removing the dust-cap or changing the lens:



Figure 1: Hold camera like this while changing the lens/removing the dust cap of a camera

- Thread the lens onto the camera while holding the camera in this position. This will minimize the possibility of any contaminants falling on the glass surface.
- Always store cameras and lenses with dust-caps installed.

Is it an impurity? – Identifying impurities

If you observe any image artefacts in your video preview of your AVT camera you may have impurities either on the lens, filter/protection glass or, theoretically on the sensor protection glass, although every AVT camera gets cleaned prior to sealing and shipment.

Impurities (dust, particles or fluids) on the sensor or optical components (*Figure 2: Image with tiny dust on the filter (left) and dust on the sensor (right)* on page 27) will appear as a dark area, patch or spot on the image and will remain fixed in the preview window while you rotate the camera over the target.

Do not confuse this with a pixel defect which will appear as a distinct point. It is crucial to differentiate between dust (e.g. flakes of skin, particles) and other dirt (e.g. liquids, fingerprints, grease). Particles can either rest loosely or can be more or less stuck to the optical surface.

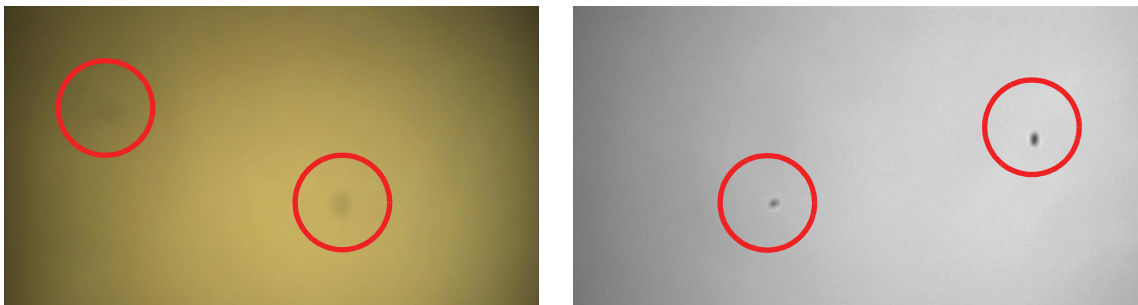


Figure 2: Image with tiny dust on the filter (left) and dust on the sensor (right)

Where is the impurity? – Locating impurities

Before you dismount the lens you should find out if the impurity is on the filter, lens or sensor. Therefore you should view a uniform image (e.g. a white sheet of paper) with the camera. The affected optical surface is identified when a suspected optical component is moved and the dirt follows this movement.

1. If you move only the lens (not the camera) and the impurity moves as well, the impurity is on the lens.
2. If you move the IR cut filter/protection glass window and the impurity moves as well:

Please carefully remove the filter/protection glass (for certain camera models, indicated below, requiring a special tool which can be ordered under the following number: E9020001) and clean it on both sides using the techniques explained below.

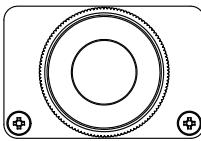
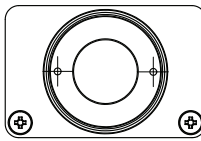
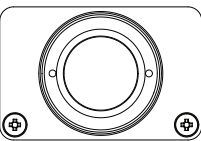
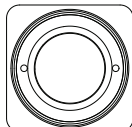
Camera type	Tool to be used	Description
Oscar	1.3 mm hex key (Allen key) AVT order number K 9020411	Loosen both countersunk screws. Remove chromatic flange: Take care, C-Mount adjustment spacers may fall out. Put them back carefully on chromatic flange and screw chromatic flange with adjustment spacers in camera.
Marlin	AVT order number E9020001	Figure 3: Removing IR cut filter/protection glass using special tool (E9020001) on page 29
Guppy	Pliers and leather	Carefully unscrew the knurled ring.
Pike	1.3 mm hex key (Allen key) AVT order number K 9020411	Loosen both countersunk screws (looking in front of the lens the screws are on the top (middle) and on the right side of the housing). Remove chromatic flange: Take care, C-Mount adjustment spacers may fall out. Put them back carefully on chromatic flange and screw chromatic flange with adjustment spacers in camera.
Stingray	<ul style="list-style-type: none"> Stingray cameras Rev. 1: see Guppy Stingray cameras Rev. 2 and 3: AVT order number E9020001 	<ul style="list-style-type: none"> Stingray cameras Rev. 1: see Guppy Stingray cameras Rev. 2/3: Figure 3: Removing IR cut filter/protection glass using special tool (E9020001) on page 29 <div style="display: flex; justify-content: space-around; align-items: center;">    </div> <div style="display: flex; justify-content: space-around; align-items: center;"> Stingray Rev. 1 Stingray Rev. 2 Stingray Rev. 3 </div>
Guppy PRO	AVT order number E9020001	<ul style="list-style-type: none"> Guppy PRO cameras: Figure 3: Removing IR cut filter/protection glass using special tool (E9020001) on page 29 <div style="text-align: center;">  </div> <p>Guppy PRO</p>

Table 4: How to remove the filter/protection glass

Not all camera types have the design to remove the filter/protection glass. See Chapter [Changing filters safety instructions](#) on page 20.

Note

- Taking out the filter requires special care. The customer is **fully responsible** for all actions of changing/removing filter by himself.
- Ask your dealer to help you if you are not confident with the procedure.



Figure 3: Removing IR cut filter/protection glass using special tool (E9020001)

3. If the impurity is neither on the lens nor the IR cut filter/protection glass, it is probably on the sensor.

Cleaning Instructions

Perform all cleaning operations (lenses, filter/protection glass, sensor in a **dust-free clean-room**. The optical components are very fragile so it is important to avoid touching them with your fingers or any hard material.

1. Unplug the camera from any power supply before cleaning.
2. Apply a small amount of optics cleaner (60% ethyl alcohol, 40% ether) to clean, new lens cleaning tissue.

Acceptable material includes medical-grade sterile optical cotton, or lens tissue that is chemically pure and free from silicones and other additives.

- **Do not** use cosmetic cotton.
- **Do not** use consumer eyeglass cleaning cloths pre-treated with silicon.



Figure 4: Medical-grade sterile optical cotton

The cotton or lens tissue should be moist, but not dripping. Please hold the camera away from your body to avoid falling particles like flakes from skin on the sensor. Hold the camera sensor diagonally upwards.

3. Wipe the glass surface with a spiral motion from the centre to the rim. Normally several spiral wipes are recommended. Wipe only on glass avoiding contact to metal surfaces, because microscopic dirt could be released and could cause scratches on the glass.



Figure 5: Sensor cleaning

4. When you've finished cleaning, examine the surface in a strong light. Take an out-of-focus picture of a flat, illuminated surface to see if any dirt or dust remains.
5. If dust spots remain, repeat this procedure using new clean lens tissue (as described above).

Caution



- Never wipe lenses with dry swabs or tissue - this causes scratches.
- Do not use any disposable cotton cosmetic swabs; they are not free from contamination.

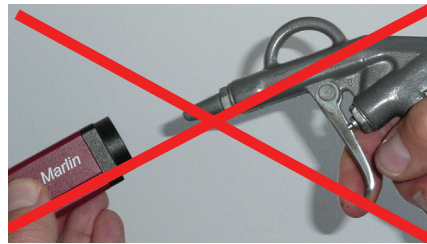


Figure 6: Don't use compressed air

6. If despite warnings you want to clean your camera with compressed air:

Caution



- Use an air blower/compressed air only if you are familiar with cleaning a camera with this instrument.
- **Compressed air may push dust into cameras and lenses.** Therefore keep the pressure at a moderate strength only:
 - The pressure at the tube should be less than 1 bar
 - operating distance: 5-30 cm

7. Please gently blow the impurities off with dust-filtered, oil-free air (< 1 bar). Using ionized air will help to remove any dirt stuck to the optical component because of static electricity.

Note

If dust spots remain after cleaning twice, please contact your AVT dealer.



AVT cameras: installing hardware

This chapter describes the **hardware installation** of 1394a/b AVT cameras, 1394 adapters (PC or laptop) and the necessary cabling.

Note For **software/driver installation** read the documentation of the corresponding AVT software package.



If you connect an AVT camera to your PC/laptop (before software/driver installation), the following window will appear (example Windows XP):



Figure 7: Window: Found New Hardware Wizard

You have two choices:

- If you want to use an **AVT SoftwarePackage**, click **Cancel** to close the window. The necessary AVT driver can be installed during the installation process of the selected AVT software package.
- If you want to use your **own image processing software**, ask your image processing vendor what to do now.

Hardware conditions

- AVT IEEE 1394a or 1394b camera (1394a: Oscar, Marlin, Guppy; 1394b: Guppy PRO, Pike, Stingray) with corresponding lens
- 1394 cable
- PC or laptop with built-in IEEE 1394 interface
- IEEE 1394 adapter (OHCI) card for PCI bus or PCI Express bus or PC card or ExpressCard with IEEE 1394 port(s)

Note

AVT offers a wide range of IEEE 1394 adapters, both 1394a or 1394b for different requirements.



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For **more information on accessories** and on **ordering accessories online** (by clicking the article and sending an inquiry) go to:

<http://www.alliedvisiontec.com/emea/products/accessories.html>

FireWire hot-plug and screw-lock precautions

Caution



Hot-plug precautions

- Although FireWire devices can **theoretically** be hot-plugged without powering down equipment, **we strongly recommend turning the computer power off, before connecting a digital camera** to it via a FireWire cable.
- **Static electricity or slight plug misalignment during insertion may short-circuit and damage components.**
- The physical ports **may be damaged** by **excessive ESD** (electrostatic discharge), when connected under powered conditions. It is good practice to ensure proper grounding of computer case and camera case to the same ground potential, before plugging the camera cable into the port of the computer. This ensures that no excessive difference of electrical potential exists between computer and camera.

Screw-lock precautions

- Also, all AVT 1394b camera and cables have **industrial screw-lock fasteners**, to insure a tight electrical connection that is resistant to vibration and gravity.
- **We strongly recommend using only 1394b adapter cards with screw-locks.**

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<http://www.alliedvisiontec.com/emea/products/accessories/firewire-accessories.html>

Overview hardware installation

- Install IEEE 1394 adapter (if PC or laptop does not have an IEEE 1394 port)
- Install AVT software package and start the corresponding viewer provided with the AVT SDK you have selected (see the corresponding SDK manual)
- Connect camera to PC or laptop and ensure that the camera is powered

Note



Read the software manuals to get information on licensing, acquiring your first image with viewer and troubleshooting.

Only the viewer of AVT FirePackage (SmartView) provides extended GUI control options to evaluate AVT 1394 camera smart features.

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For more information see **AVT Software Selector Guide:**

<http://www.alliedvisiontec.com/emea/support/downloads/software.html>

Installing IEEE 1394 adapter

1. **PC:** Install the IEEE 1394 adapter according to the instructions you got from your adapter manufacturer.
Laptop: Insert the IEEE 1394 PC Card into your laptop. Connect external power supply to the adapter to power the camera or power the camera via Hirose connector.
2. Windows XP/ Windows Vista / Windows 7 will detect the hardware automatically and installs a Windows 1394 driver.

Connecting camera to PC or laptop

1. Shut down your PC or laptop and **turn computer power off**.

Caution



- **Do not touch the shield of the camera cable** connected to a computer and the ground terminal of the lines at the same time.
- If you are charged: before touching the shield of the camera cable, make sure to discharge first (by touching the ground terminal of the lines).
- **Use only DC power supplies with insulated cases.** These are identified by having only **two** power connectors.
- If you feel uncomfortable with the previous advice or if you have no knowledge about the connectivity of an installation, **we strongly recommend powering down all systems before connecting or disconnecting a camera.**

Caution



Hot-plug precautions

- Although FireWire devices can **theoretically** be hot-plugged without powering down equipment, **we strongly recommend turning the computer power off, before connecting a digital camera** to it via a FireWire cable.
- **Static electricity or slight plug misalignment during insertion may short-circuit and damage components.**
- The physical ports **may be damaged** by **excessive ESD** (electrostatic discharge), when connected under powered conditions. It is good practice to ensure proper grounding of computer case and camera case to the same ground potential, before plugging the camera cable into the port of the computer. This ensures that no excessive difference of electrical potential exists between computer and camera.

Screw-lock / Latching precautions

- We strongly recommend using only 1394a cables with **latch connectors** / 1394b cables with **industrial screw-lock fasteners**, to insure a tight electrical connection that is resistant to vibration and gravity.
- **We strongly recommend using only 1394b adapter cards with screw-locks.**

2. Insert one end of the FireWire cable into your 1394 adapter or 1394 PC card.
3. Insert the other end of the FireWire cable into your camera.
4. Check that the camera is powered (green LED ON).

Camera interfaces

Each AVT camera has the following interfaces:

- The 12-pin camera I/O connector (Guppy: 8-pin) provides different control inputs and output lines.
- One or two IEEE 1394a or 1394b connectors with screw lock mechanism provide access to the IEEE 1394 bus and thus makes it possible to control the camera and output frames.
 - Oscar, Marlin and Guppy provide one 1394a connector.
 - Pike and Stingray provide 2x 1394b connectors.
 - Guppy PRO provides one 1394b connector.

Note For information on **status LEDs** see the **Technical Manuals**.

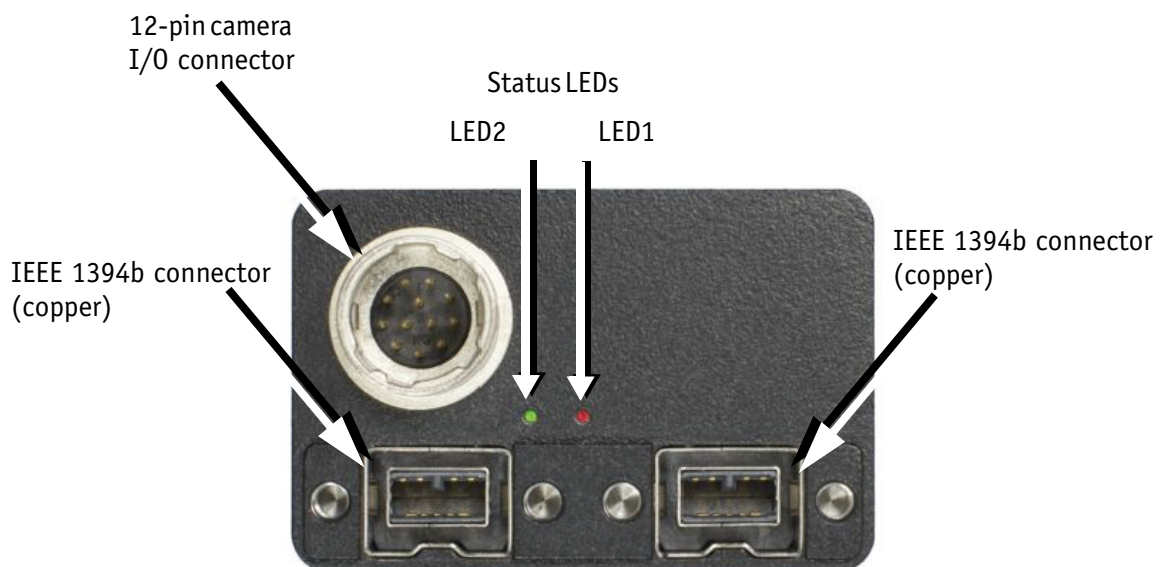


Figure 8: Example: Rear view of Stingray camera (2x 1394b copper)

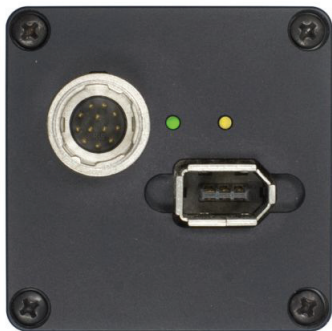
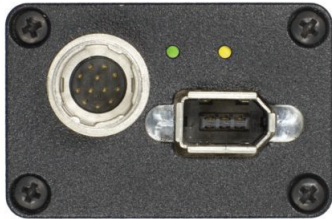




Oscar	Marlin	Guppy
 <p>HIROSE and 1x 1394a</p>	 <p>HIROSE and 1x 1394a</p>	 <p>HIROSE and 1x 1394a</p>
Pike	Stingray	Guppy PRO
 <p>HIROSE and 2x 1394b</p>	 <p>HIROSE and 2x 1394b</p>	 <p>HIROSE and 1x 1394b</p>

Table 5: Rear view of AVT cameras (HIROSE and 1394 copper)



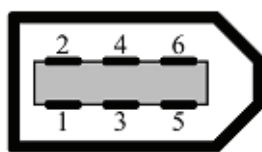
Pike fiber	Stingray fiber	
 <p>HIROSE and 1x 1394b GOF, 1x 1394b copper</p> <p>GOF (marked with red line): 2x optical fiber on LCLC, dust cover off</p>	 <p>HIROSE and 1x 1394b GOF, 1x 1394b copper</p> <p>GOF (marked with red line): 2x optical fiber on LCLC, dust cover off</p>	

Table 6: Rear view of AVT cameras (HIROSE and 1394b GOF/copper)

IEEE 1394a port pin assignment (Oscar, Marlin, Guppy)

The IEEE 1394a connector is designed for industrial use and has the following pin assignment as per specification:



Pin	Signal
1	Cable power
2	Cable GND
3	TPB-
4	TPB+
5	TPA-
6	TPA+

Figure 9: IEEE 1394a connector

Note



Cables with latching connectors on one or both sides can be used and are available with various lengths from 0.5 m to 17.5 m. Ask your local dealer for more details.

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<http://www.alliedvisiontec.com/emea/products/accessories/firewire-accessories.html>

Board level camera (Guppy): IEEE 1394a port pin assignment

Board level Guppies have two 1394a ports to allow daisy chaining of cameras.

The IEEE 1394a pin header (2.54 mm connector: FireWire connector 1) is designed for adding a 1394a adapter cable of:

e.g. IEEE 1394 6 PIN - PANEL F TO 2X5 F (AVT#: K1200155)

It has the following pin assignment:

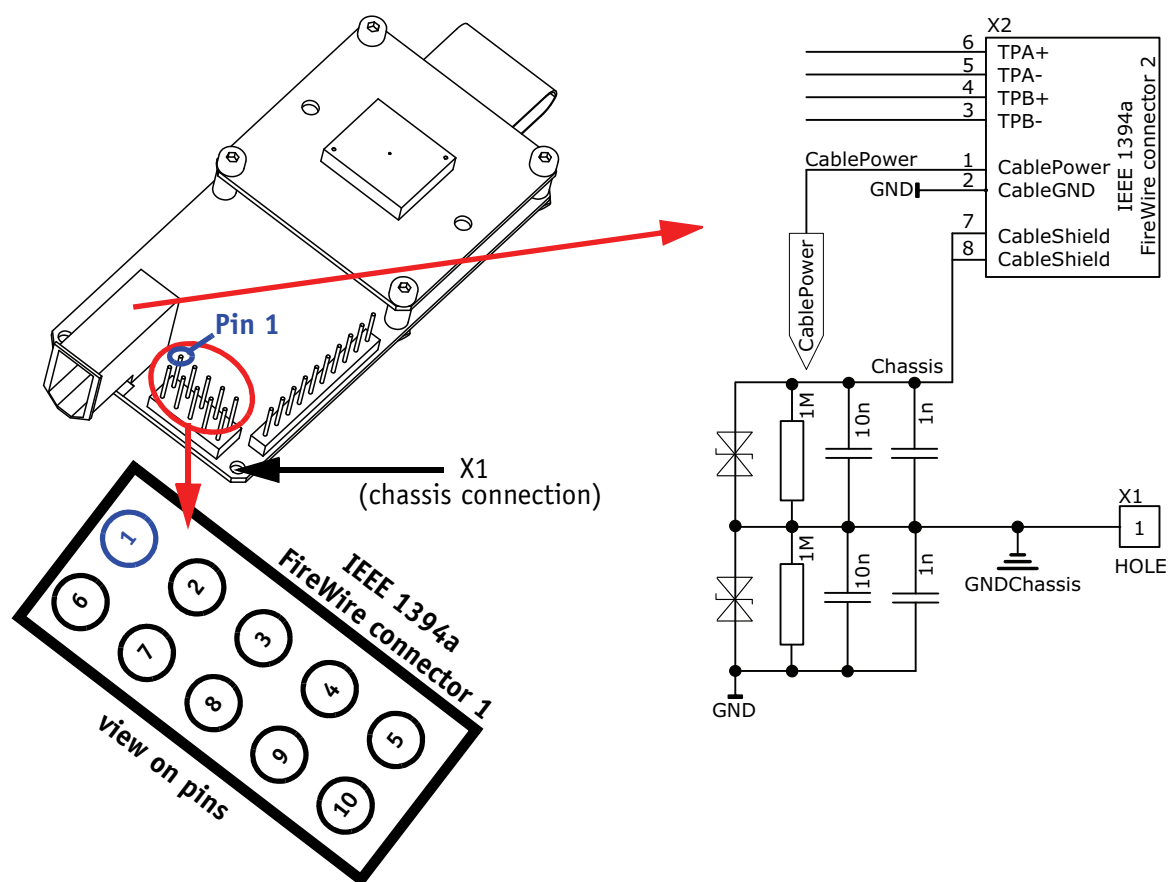


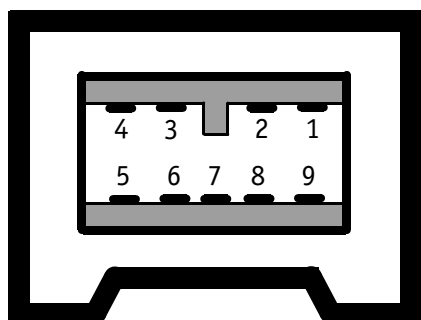
Figure 10: Board level camera (Guppy): IEEE 1394 FireWire connector 1 (view on pins)

Signal	Pin	Pin	Signal
TPA+	6	1	TPA-
-	7	2	GND
TPB+	8	3	TPB-
-	9	4	Cable power
-	10	5	Cable shield

Table 7: Board level camera (Guppy): IEEE 1394a pin assignment (FireWire connector 1)

IEEE 1394b port pin assignment (Guppy PRO, Pike, Stingray)

The IEEE 1394b connector is designed for industrial use and has the following pin assignment as per specification:



Pin	Signal
1	TPB-
2	TPB+
3	TPA-
4	TPA+
5	TPA (Reference ground)
6	VG (GND)
7	N.C.
8	VP (Power, VCC)
9	TPB (Reference ground)

Figure 11: IEEE 1394b connector

Note



- Both IEEE 1394b connectors with screw lock mechanism provide access to the IEEE 1394 bus and thus makes it possible to control the camera and output frames. Connect the camera by using either of the connectors. The other connector can be used to daisy chain a second camera.
- Cables with latching connectors on one or both sides can be used. Ask your local dealer for more details.

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<http://www.alliedvisiontec.com/emea/products/accessories/firewire-accessories.html>

Board level camera (Stingray): IEEE 1394b port pin assignment

Board level Stingray cameras have two 1394b ports to allow daisy chaining of cameras.

They have the same pin assignment as the Stingray housing cameras.

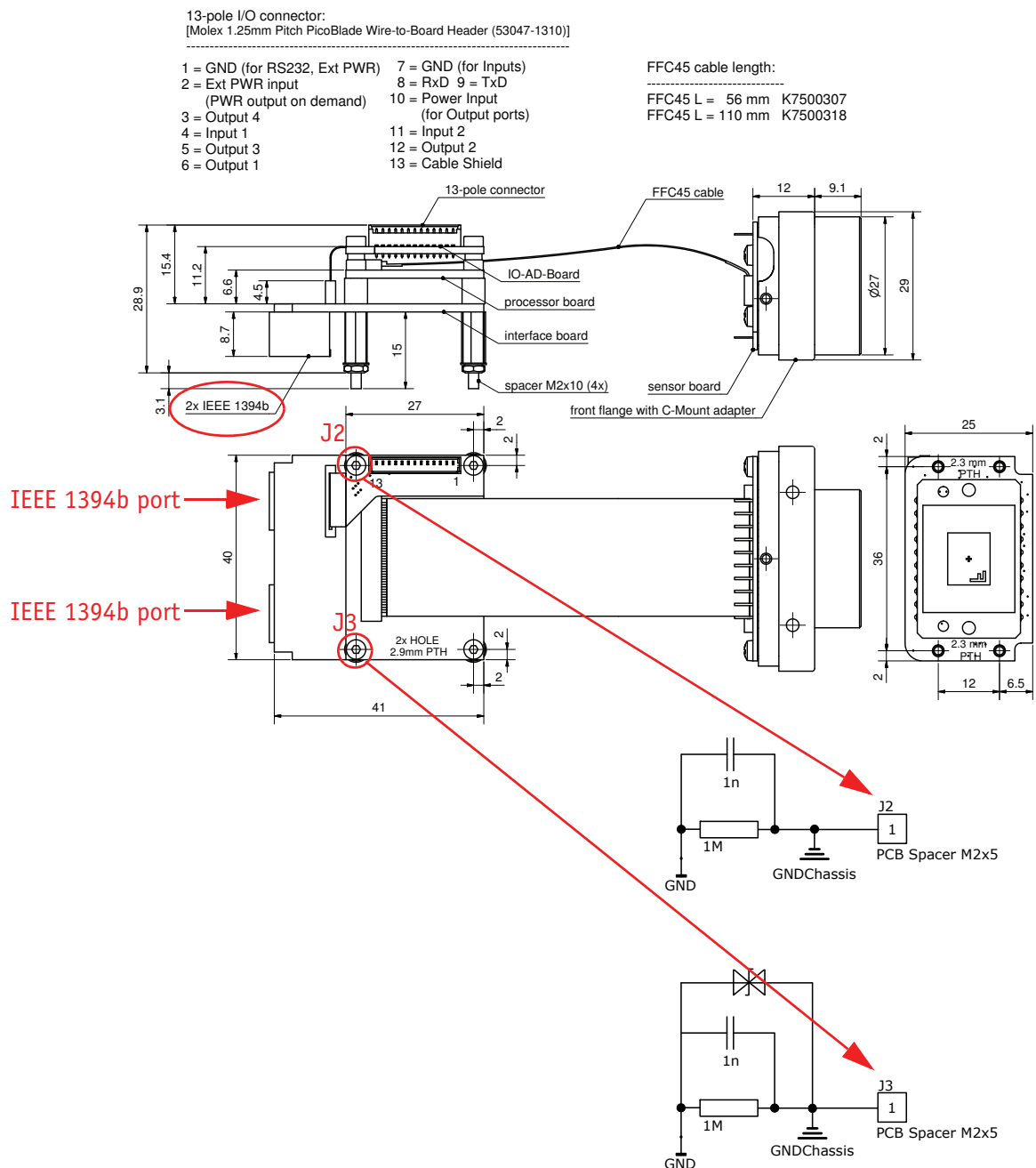


Figure 12: Board level camera (Stingray): two IEEE 1394b FireWire connectors

Pike/Stingray fiber infos and cautions

All Pike and Stingray cameras are also available as **fiber version** with **1 x GOF connector and 1x copper connector**.

The GOF connector is of the following type: **2 x optical fiber on LCLC**

The GOF transmission uses **MMF (multi-mode fiber at 850 nm)**.

Connect the camera by using either of the connectors. The other connector can be used to daisy chain a second camera. In case of long distances between PC and camera, use the GOF connector for the long distance and the IEEE 1394b connector for optional daisy-chaining. Please ensure that you use a GOF hub on the PC side for reconversion from GOF to copper (order number E3000074 (with mounting plate) or E3000084 (with top-hat rail)). Alternatively use PCI or PCIExpress cards with built in GOF port. Ask your dealer for availability and details of these cards.

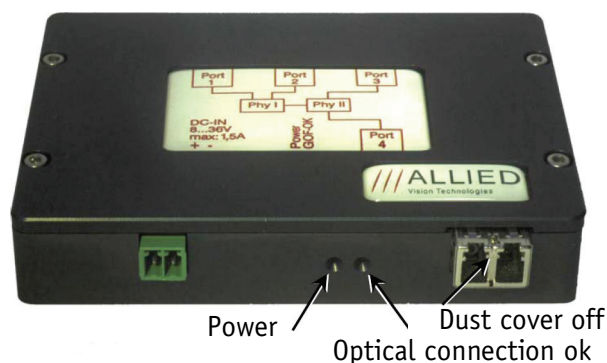


Figure 13: GOF hub

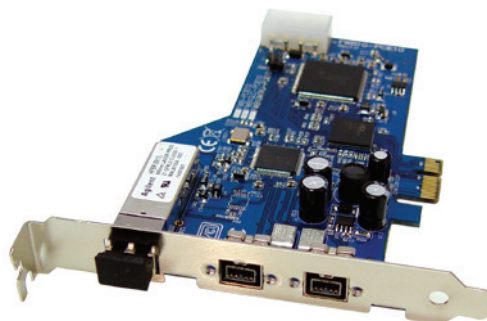


Figure 14: PCI Express card (1 x GOF, 2 x 1394 bilingual)

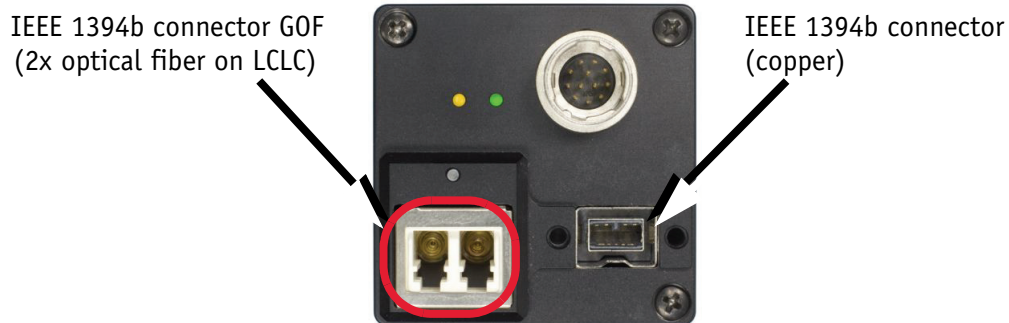


Figure 15: Rear view of Pike camera (1394b: 1 x GOF, 1 x copper) (Stingray similar)

Caution



Special warning for all Pike/Stingray models with GOF connectors:

GOF connectors are very sensitive. **Any dust or dirt may cause damage.**

- **Always keep the GOF connector and optical fiber plug clean.**
- If GOF connection is not in use, **keep GOF dust cover on the GOF connector.**
- **Reduce mating cycles to a minimum** to prevent abrasion.
- Please note that optical fiber cables have a **very limited deflection curve radius.**

Camera I/O connectors (12 pin) order numbers and cables: Guppy PRO, Stingray, Pike, Marlin, Oscar

The 12-pin camera I/O connector (Guppy PRO, Stingray, Pike, Marlin, Oscar) is also designed for industrial use and, in addition to providing access to the inputs and outputs on the camera, it also provides a serial interface for e.g. the firmware update.

The connector is available in straight and angled version.

Note AVT supplies suitable I/O cables of different lengths (up to 10 m) as shown below.



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For **more information on cables** and on **ordering cables online** (by clicking the article and sending an inquiry) go to:

<http://www.alliedvisiontec.com/emea/products/accessories/firewire-accessories.html>

Note



For pinning of the I/O connectors as viewed in pin direction see:

- Chapter [Stingray camera I/O connector pin assignment](#) on page 48
- Chapter [Pike camera I/O connector pin assignment](#) on page 55
- Chapter [Guppy PRO camera I/O connector pin assignment](#) on page 63
- Chapter [Marlin camera I/O connector pin assignment](#) on page 77
- Chapter [Oscar camera I/O connector pin assignment](#) on page 83

Camera I/O connectors (8 pin) order numbers and cables: Guppy

The 8-pin camera I/O connector (only Guppy cameras) is designed for industrial use.

It provides:

- access to the inputs and outputs on the camera
- a serial interface

AVT also supplies various I/O cables of different lengths.

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<http://www.alliedvisiontec.com/emea/products/accessories/firewire-accessories.html>

Note

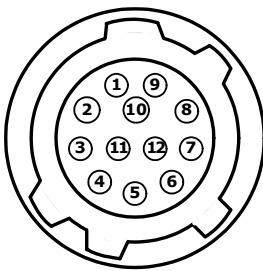


For pinning of the I/O connectors as viewed in pin direction see Chapter *[Guppy camera I/O connector pin assignment](#)* on page 70.

Stingray camera interfaces

Stingray camera I/O connector pin assignment

(For board level see Chapter [Stingray board level camera: I/O pin assignment](#) on page 54)



Pin	Signal	Direction	Level	Description
1	External GND		GND for RS232 and ext. power	External Ground for RS232 and external power
2	External Power		+8 ... +36 V DC	Power supply
3	Camera Out 4	Out	Open emitter	Camera Output 4 (GPOut4) default: -
4	Camera In 1	In	$U_{in}(high) = 3 V...24 V$ $U_{in}(low) = 0 V...1.5 V$	Camera Input 1 (GPIn1) default: Trigger
5	Camera Out 3	Out	Open emitter	Camera Output 3 (GPOut3) default: Busy
6	Camera Out 1	Out	Open emitter	Camera Output 1 (GPOut1) default: IntEna
7	Camera In GND	In	Common GND for inputs	Camera Common Input Ground (In GND)
8	RxD RS232	In	RS232	Terminal Receive Data
9	TxD RS232	Out	RS232	Terminal Transmit Data
10	Camera Out Power	In	Common VCC for outputs max. 36 V DC	External Power for digital outputs (OutVCC)
11	Camera In 2	In	$U_{in}(high) = 3 V...24 V$ $U_{in}(low) = 0 V...1.5 V$	Camera Input 2 (GPIn2) default: -
12	Camera Out 2	Out	Open emitter	Camera Output 2 (GPOut2) default: Follow CameraIn2

Figure 16: Stingray: Camera I/O connector pin assignment

Stingray input description

Stingray input block diagram

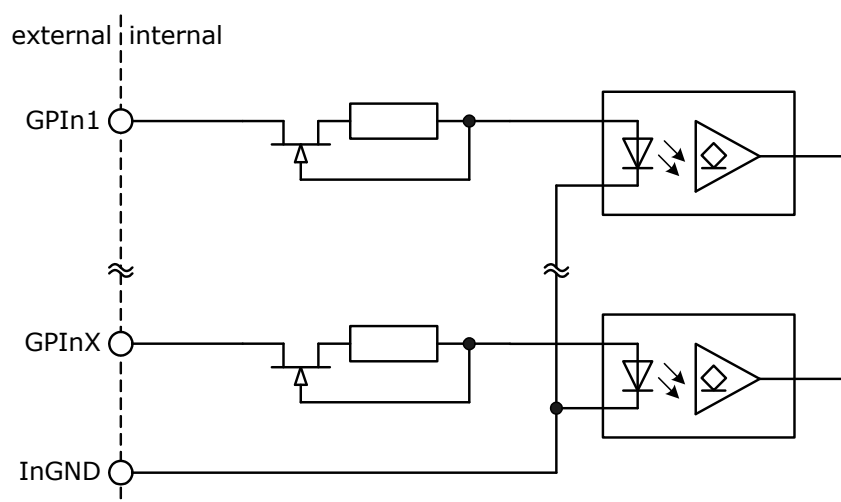


Figure 17: Stingray input block diagram

The inputs can be connected directly up to max. +24 V. If you want to use voltages from +24 V...+36 V you have to place an external resistor of 1.5 k Ω (1/10 watt) in series with your voltage source.

Caution



Stingray

- Voltages above +24 V (without external resistor) may damage the camera.
- Voltages above +36 V (with an external resistor of 1.5 k Ω) may damage the camera.

Parameter	Value
U_{in} (low)	0 V ... 1.5 V
U_{in} (high)	3 V ... 24 V
Current (constant current source within the camera)	8 mA
Flux voltage of the LED (@ 10 mA)	1.5 V

Table 8: Stingray input parameters

Stingray delay and minimum pulse width

The **cycle delay** for all Stingray cameras is:

$t_{pdLH} < 1.0 \mu s$ and $t_{pdHL} < 1.5 \mu s$

The **minimum pulse width** for all Stingray cameras is:

$t_p > 1.6 \mu s$

Test conditions

The input signal was driven with 12 V and a 2.2 k Ω pull down resistor to GND.

Stingray output description

Stingray block diagram

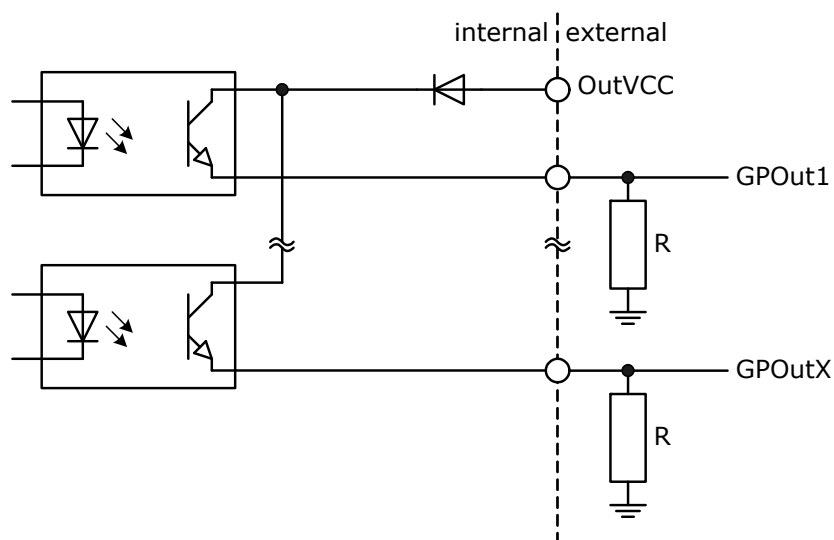


Figure 18: Stingray: output block diagram

Caution



Stingray

- Max. 15 mA per output
- OutVCC > 36 V may damage the camera.

OutVCC		Resistor value	
5 V	1 kΩ	~ 5 mA load recommended	
12 V	2.4 kΩ		
24 V	4.7 kΩ		
5 V	0.33 kΩ	~ 15 mA load absolute maximum	
12 V	0.82 kΩ		
24 V	1.6 kΩ		

Figure 19: Stingray: OutVCC and external resistor

Stingray delay

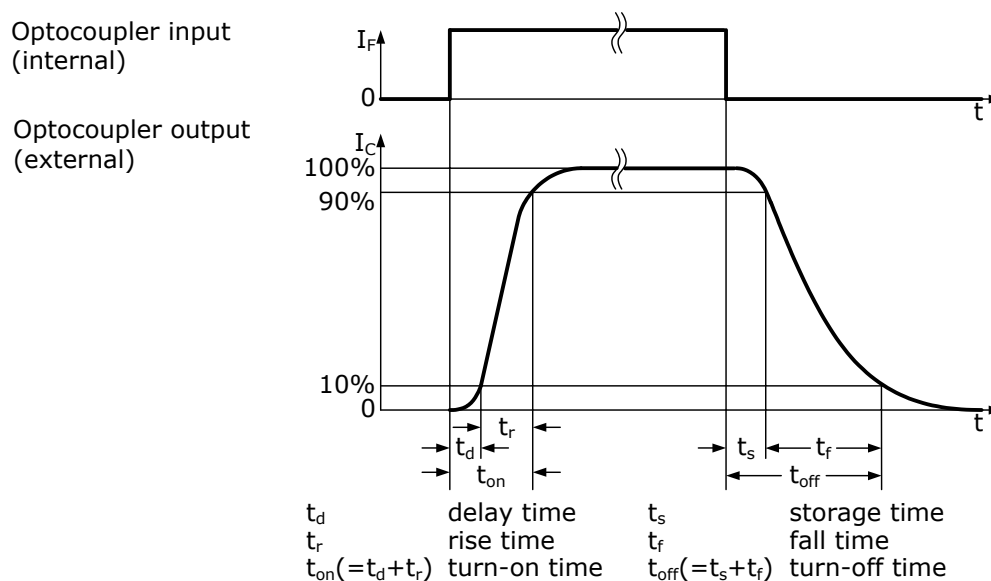


Figure 20: Stingray output switching times

For all Stingray models:

Parameter and value	
$t_d \approx 1 \mu s$	$t_s \approx 26 \mu s$
$t_r \approx 1 \mu s$	$t_f \approx 21 \mu s$
$t_{on} = t_d + t_r \approx 2 \mu s$	$t_{off} = t_s + t_f \approx 47 \mu s$ (t_{off} can deviate by $\pm 5 \mu s$)

Table 9: Parameters for Stingray

Test conditions

Camera: Format_7 Mode_0, Mono8, S800, extended shutter set to minimum

Output: external 2.4 k Ω resistor to GND, power input for output ports set to 12 V

Stingray data

The RS232 data interface has a typical output voltage from ± 4.2 V.

Stingray power

In accordance to IEEE 1394b specification the power supply (+8 V ... +36 V) should deliver a current of at least 1.5 A.

Note



If using daisy chain the camera has to supply further components with also 1.5 A.

In such cases your power supply should be able to deliver 3.0 A.

Stingray board level camera: I/O pin assignment

The following diagram shows the 13-pole I/O pin connector of a Stingray board level camera:

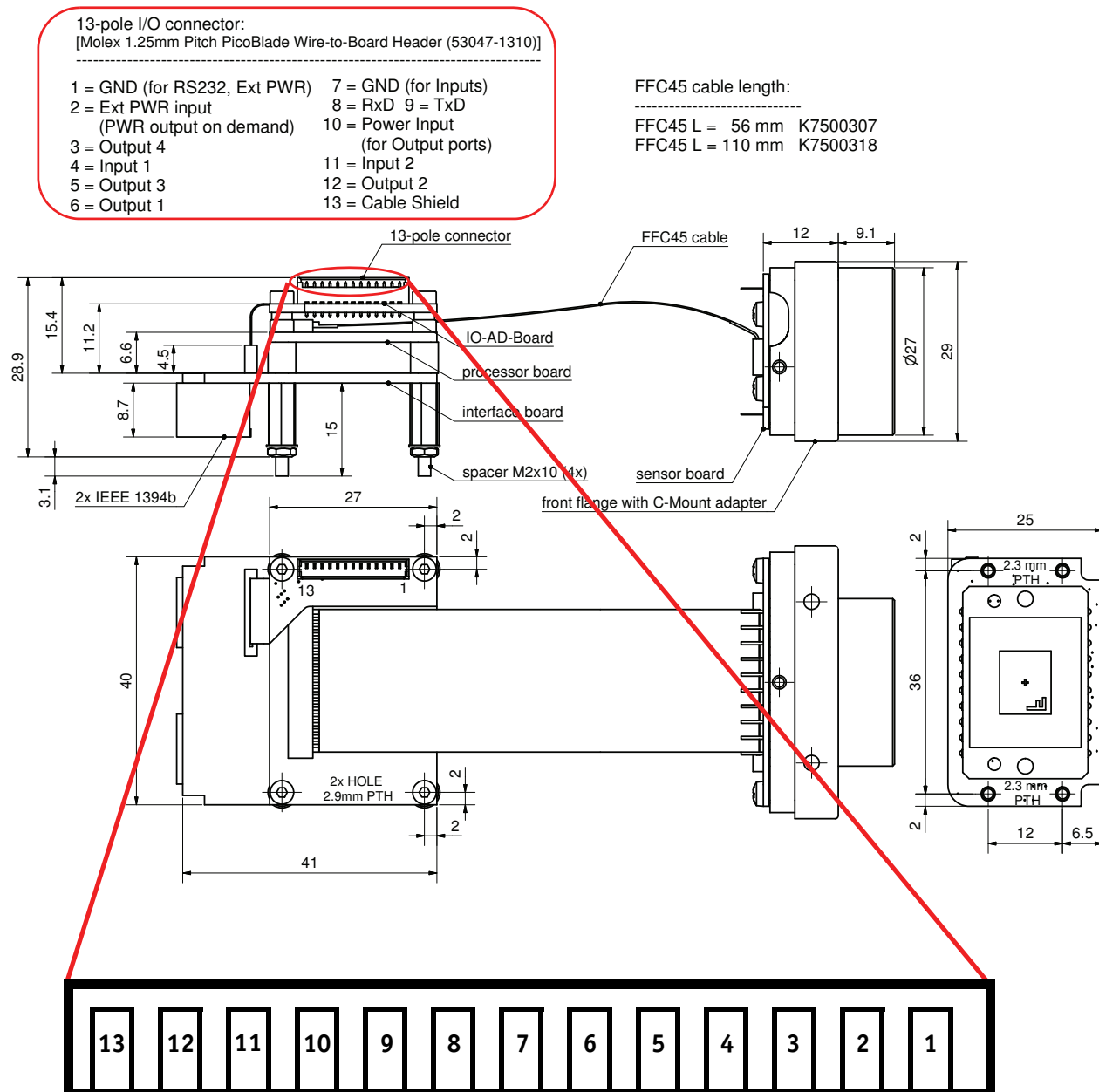
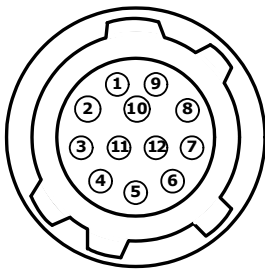


Figure 21: Stingray board level camera: I/O pin assignment

Pike camera interfaces

Pike camera I/O connector pin assignment



Pin	Signal	Direction	Level	Description
1	External GND		GND for RS232 and ext. power	External Ground for RS232 and external power
2	External Power		+8 ... +36 V DC	Power supply
3	Camera Out 4	Out	Open emitter	Camera Output 4 (GPOut4) default: -
4	Camera In 1	In	$U_{in}(high) = 2 V \dots U_{inVCC}$ $U_{in}(low) = 0 V \dots 0.8 V$	Camera Input 1 (GPIn1) default: Trigger
5	Camera Out 3	Out	Open emitter	Camera Output 3 (GPOut3) default: Busy
6	Camera Out 1	Out	Open emitter	Camera Output 1 (GPOut1) default: IntEna
7	Camera In GND	In	Common GND for inputs	Camera Common Input Ground (In GND)
8	RxD RS232	In	RS232	Terminal Receive Data
9	TxD RS232	Out	RS232	Terminal Transmit Data
10	Camera Out Power	In	Common VCC for outputs max. 36 V DC	External Power for digital outputs (OutVCC)
11	Camera In 2	In	$U_{in}(high) = 2 V \dots U_{inVCC}$ $U_{in}(low) = 0 V \dots 0.8 V$	Camera Input 2 (GPIn2) default: -
12	Camera Out 2	Out	Open emitter	Camera Output 2 (GPOut2) default: Follow CameraIn2

Figure 22: Pike: Camera I/O connector pin assignment

Pike input description (not Pike F-505)

(for Pike F-505 see Chapter *Input description of Pike F-505* on page 58)

Pike input block diagram

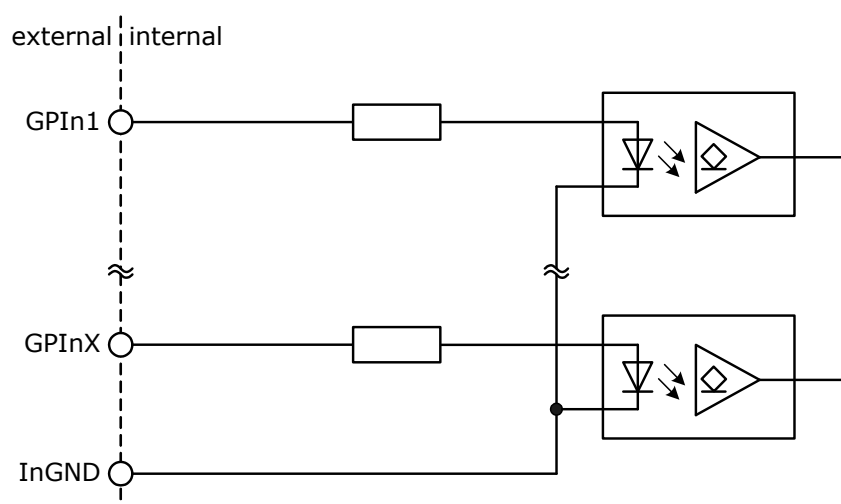


Figure 23: Pike input block diagram

The inputs can be connected directly to +5 V. If a higher voltage is used, an external resistor must be placed in series.

Caution



Pike

Voltages above +36 V may damage the camera.

Used input voltage (U_{inVCC})	External series resistor
5 V	none
12 V	0.82 k Ω
24 V	2.2 k Ω
36 V	3.3 k Ω

Table 10: Pike: external resistors for voltages higher than 5 V

Parameter	Value
Initial on-current	5 mA
Flux voltage of the LED (@ 10 mA)	1.5 V
Maximum off-current	0.25 mA
Maximum input current	15 mA

Table 11: Pike: input parameters

Pike delay and minimum pulse width

The **cycle delay** for all Pike cameras (except Pike F-505) is:
 $t_{pdLH} < 2.2 \mu s$ and $t_{pdHL} < 2.9 \mu s$

The **minimum pulse width** for all Pike cameras (inclusive Pike F-505) is:
 $t_p > 2.0 \mu s$

Test conditions

The input signal was driven with 12 V and a 2.2 k Ω pull down resistor to GND.

Input description of Pike F-505

Pike F-505 has a different input wiring compared to the other Pike models. The inputs of Pike F-505 are the same as the inputs of Stingray.

Pike F-505 input block diagram

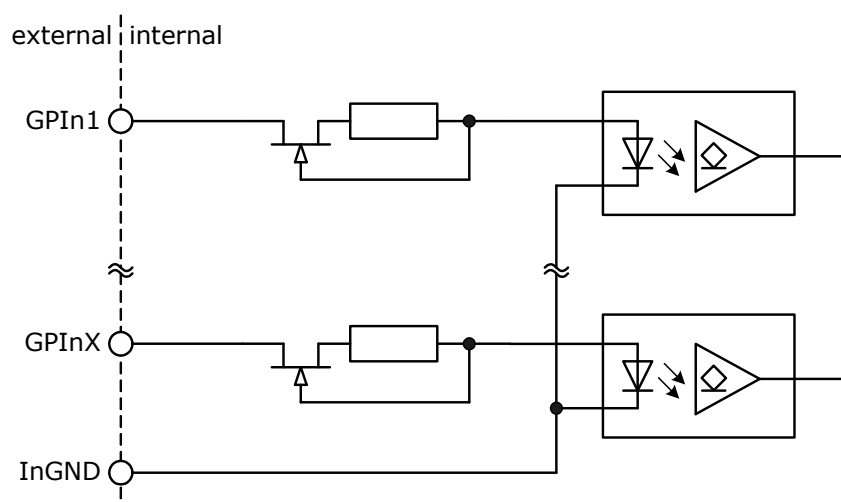


Figure 24: Pike F-505 input block diagram

The inputs can be connected directly up to max. +24 V. If you want to use voltages from +24 V...+36 V you have to place an external resistor of 1.5 k Ω (1/10 watt) in series with your voltage source.

Caution



Pike F-505

- Voltages above +24 V (without external resistor) may damage the camera.
- Voltages above +36 V (with an external resistor of 1.5 k Ω) may damage the camera.

Parameter	Value
U_{in} (low)	0 V ... 1.5 V
U_{in} (high)	3 V ... 24 V
Current (constant current source within the camera)	8 mA
Flux voltage of the LED (@ 10 mA)	1.5 V

Table 12: Stingray input parameters

Pike F-505 delay and minimum pulse width

The **cycle delay** for the Pike F-505 is:

$t_{pdLH} < 2.2 \mu s$ and $t_{pdHL} < 2.8 \mu s$

The **minimum pulse width** for the Pike F-505 is:

$t_p > 2.0 \mu s$

Pike F-505 test conditions

The input signal was driven with 12 V and a 2.2 k Ω pull down resistor to GND.

Pike output description

Pike output block diagram

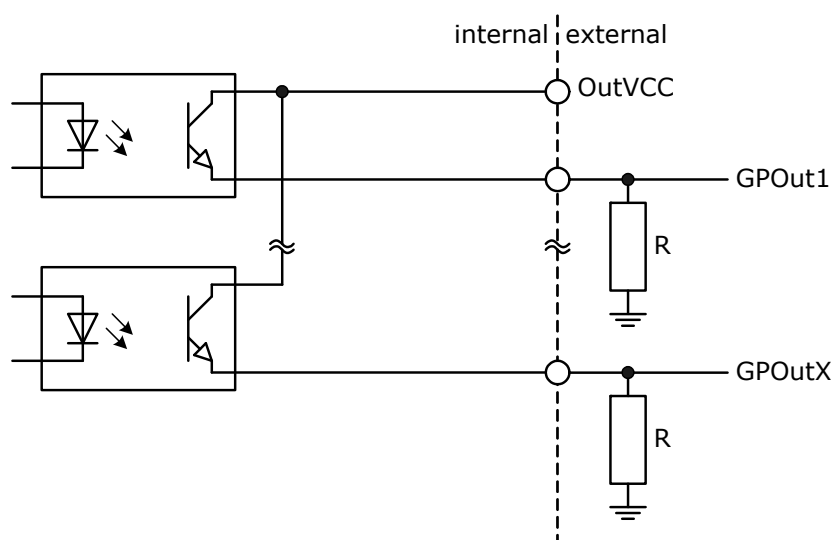


Figure 25: Pike: output block diagram

Caution



Pike

- Max. 20 mA per output
- OutVCC > 36 V may damage the camera.

OutVCC	Resistor value	
5 V	1 kΩ	~ 5 mA load recommended
12 V	2.4 kΩ	
24 V	4.7 kΩ	
5 V	0.27 kΩ	~ 20 mA load absolute maximum
12 V	0.62 kΩ	
24 V	1.2 kΩ	

Figure 26: Pike: OutVCC and external resistor

Pike delay

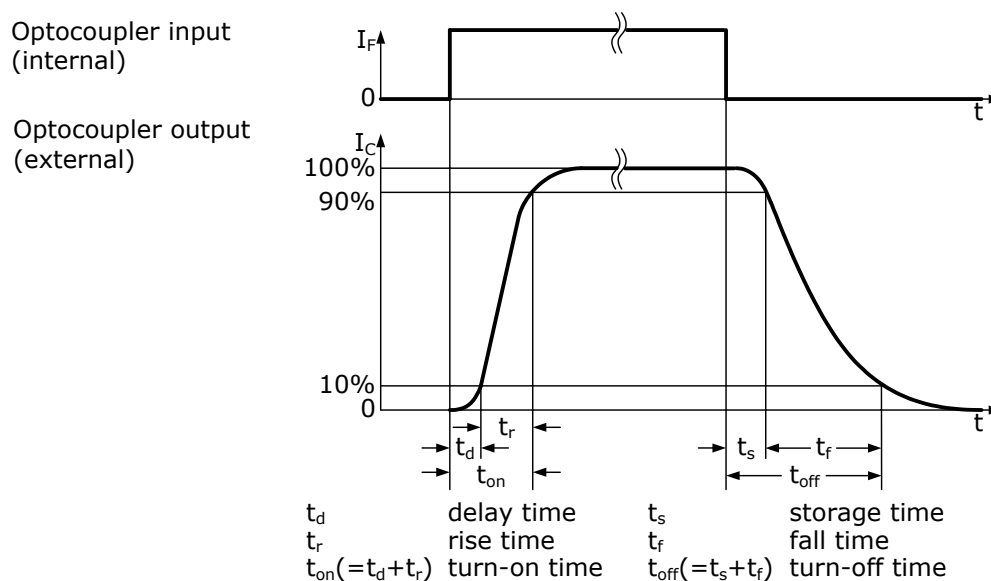


Figure 27: Pike output switching times

For all Pike models:

Parameter and value	
$t_d \approx 1 \mu s$	$t_s \approx 30 \mu s$
$t_r \approx 1 \mu s$	$t_f \approx 25 \mu s$
$t_{on} = t_d + t_r \approx 2 \mu s$	$t_{off} = t_s + t_f \approx 55 \mu s$ (t_{off} can deviate by $\pm 5 \mu s$)

Table 13: Parameters for Pike

Test conditions

Camera: Format_7 Mode_0, Mono8, S800, extended shutter set to minimum

Output: external 2.4 k Ω resistor to GND, power input for output ports set to 12 V

Pike data

The RS232 data interface has a typical output voltage from ± 4.2 V.

Pike power

In accordance to IEEE 1394b specification the power supply (+8 V...+36 V) should deliver a current of at least 1.5 A.

Note

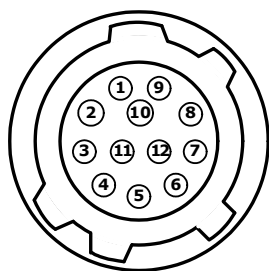


If using daisy chain the camera has to supply further components with also 1.5 A.

In such cases your power supply should be able to deliver 3.0 A.

Guppy PRO camera interfaces

Guppy PRO camera I/O connector pin assignment



Pin	Signal	Direction	Level	Description
1	External GND		GND for ext. power	External Ground for external power
2	External Power		+8 ... +36 V DC	Power supply
3	---	---	---	---
4	Camera In 1	In	$U_{in}(high) = 3 V...24 V$ $U_{in}(low) = 0 V...1.5 V$	Camera Input 1 (GPIn1) default: Trigger
5	Camera Out 3	Out	Open emitter	Camera Output 3 (GPOut3) default: Busy
6	Camera Out 1	Out	Open emitter	Camera Output 1 (GPOut1) default: IntEna
7	Camera In GND	In	Common GND for inputs	Camera Common Input Ground (In GND)
8	---	---	---	---
9	---	---	---	---
10	Camera Out Power	In	Common VCC for outputs max. 36 V DC	External Power for digital outputs (OutVCC)
11	---	---	---	---
12	Camera Out 2	Out	Open emitter	Camera Output 2 (GPOut2) default: Off

Figure 28: Guppy PRO: Camera I/O connector pin assignment

Guppy PRO input description

Guppy PRO input block diagram

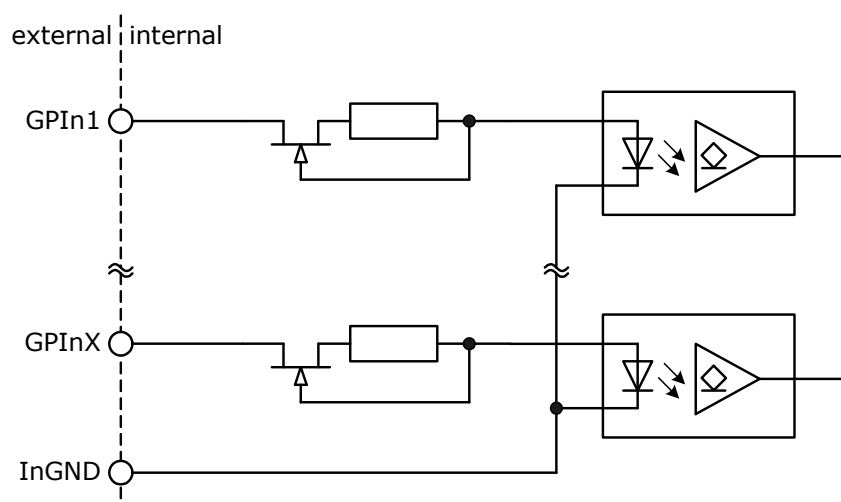


Figure 29: Guppy PRO input block diagram

The inputs can be connected directly up to max. +24 V. If you want to use voltages from +24 V... +36 V you have to place an external resistor of 1.5 k Ω (1/10 watt) in series with your voltage source.

Caution



Guppy PRO

- Voltages above +24 V (without external resistor) may damage the camera.
- Voltages above +36 V (with an external resistor of 1.5 k Ω) may damage the camera.

Parameter	Value
U_{in} (low)	0 V ... 1.5 V
U_{in} (high)	3 V ... 24 V
Current (constant current source within the camera)	8 mA
Flux voltage of the LED (@ 10 mA)	1.5 V

Table 14: Guppy PRO input parameters

Guppy PRO delay and minimum pulse width

The **cycle delay** for all Guppy PRO cameras is:

$t_{pdLH} < 1.0 \mu s$ and $t_{pdHL} < 1.5 \mu s$

The **minimum pulse width** for all Guppy PRO cameras is:

$t_p > 1.6 \mu s$

Test conditions

The input signal was driven with 12 V and a 2.2 k Ω pull down resistor to GND.

Guppy PRO output description

Guppy PRO block diagram

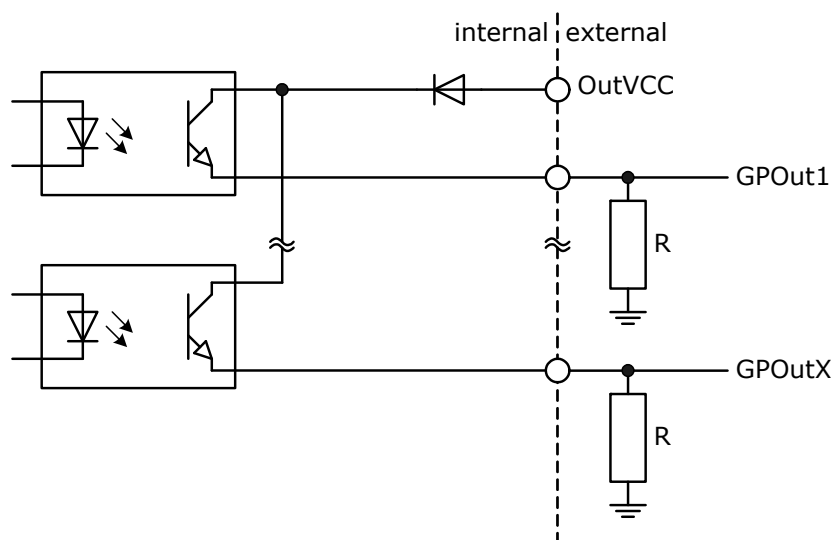


Figure 30: Guppy PRO: output block diagram

Caution



Guppy PRO

- Max. 15 mA per output
- OutVCC > 36 V may damage the camera.

OutVCC	Resistor value	
5 V	1 kΩ	~ 5 mA load recommended
12 V	2.4 kΩ	
24 V	4.7 kΩ	
5 V	0.33 kΩ	~ 15 mA load absolute maximum
12 V	0.82 kΩ	
24 V	1.6 kΩ	

Figure 31: Guppy PRO: OutVCC and external resistor

Note



Guppy PRO F-503:

IntEna is high, when all pixels are integrated simultaneously.

⇒ Using IntEna with electronic rolling shutter and global reset release shutter: see **Guppy PRO Technical Manual**, Chapter *Trigger modi*.

Guppy PRO delay

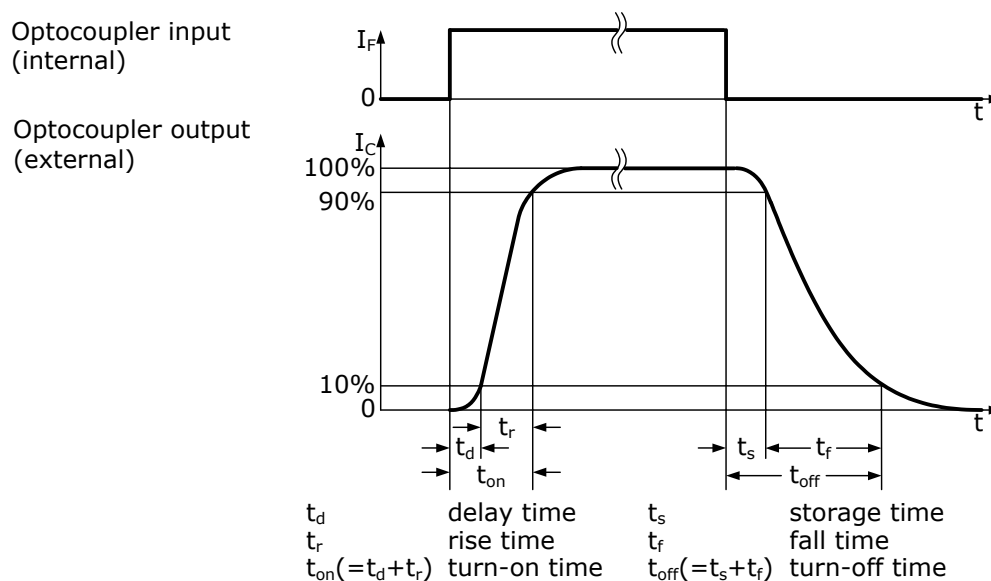


Figure 32: Guppy PRO output switching times

For all Guppy PRO models:

Parameter and value	
$t_d \approx 1 \mu s$	$t_s \approx 26 \mu s$
$t_r \approx 1 \mu s$	$t_f \approx 21 \mu s$
$t_{on} = t_d + t_r \approx 2 \mu s$	$t_{off} = t_s + t_f \approx 47 \mu s$ (t_{off} can deviate by $\pm 5 \mu s$)

Table 15: Parameters for Pike

Test conditions

Camera: Format_7 Mode_0, Mono8, S800, extended shutter set to minimum

Output: external 2.4 k Ω resistor to GND, power input for output ports set to 12 V

Guppy PRO data

Currently RS232 data interface is not implemented.

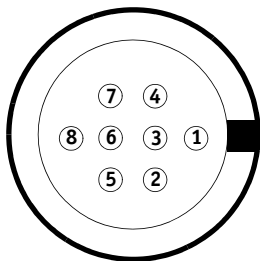
Guppy PRO power

In accordance to IEEE 1394b specification the power supply (+8 V ... +36 V) should deliver a current of at least 1.5 A.

Guppy camera interfaces

Guppy camera I/O connector pin assignment

Guppy (housing)

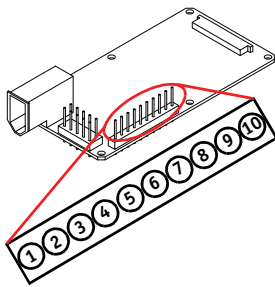


Pin	Signal	Direction	Level	Description
1	Camera Out 1	Out	$U_{out}(high) = 2.4\text{ V} \dots 5\text{ V}$ $U_{out}(low) = 0\text{ V} \dots 0.4\text{ V}$	Camera Output 1 (GP0ut1) default: IntEna
2	Camera Out 2	Out	$U_{out}(high) = 2.4\text{ V} \dots 5\text{ V}$ $U_{out}(low) = 0\text{ V} \dots 0.4\text{ V}$	Camera Output 2 (GP0ut2) default: -
3	Camera Out 3	Out	$U_{out}(high) = 2.4\text{ V} \dots 5\text{ V}$ $U_{out}(low) = 0\text{ V} \dots 0.4\text{ V}$	Camera Output 3 (GP0ut3) default: Busy
4	Camera In 1	In	$U_{in}(high) = 3.8\text{ V} \dots 5\text{ V}$ $U_{in}(low) = 0\text{ V} \dots 1\text{ V}$	Camera Input 1 (GPIn1) default: Trigger
5	RxD RS232	In	RS232	Terminal Receive Data
6	TxD RS232	Out	RS232	Terminal Transmit Data
7	External Power		+8 ... +36 V DC	Power supply
8	External GND		GND for RS232, GPIOs and ext. power	External Ground for RS232, GPIOs and external power

Figure 33: Guppy (housing): Camera I/O connector pin assignment

Guppy (board level)

The following diagram shows the I/O pin header (2.54 mm connector) of a board level camera as viewed in pin direction:



Pin	Signal	Direction	Level	Description
1	External GND		GND for RS232, GPIOs and ext. power	External Ground for RS232, GPIOs and external power
2	External Power		+8...+36 V DC	Power supply
3	GND			
4	TxD RS232	Out	RS232	Terminal Transmit Data
5	RxD RS232	In	RS232	Terminal Receive Data
6	GND			
7	Camera In/Out 4	In/Out	$U_{in}(high) = 2\text{ V} \dots 5\text{ V}$ $U_{in}(low) = 0\text{ V} \dots 0.8\text{ V}$ $U_{out}(high) = 2.4\text{ V} \dots 5\text{ V}$ $U_{out}(low) = 0\text{ V} \dots 0.4\text{ V}$	Camera Input/Output 4 (GPIInOut4) default: -
8	Camera In/Out 3	In/Out		Camera Input/Output 3 (GPIInOut3) default: -
9	Camera In/Out 2	In/Out		Camera Input/Output 2 (GPIInOut2) default: -
10	Camera In/Out 1	In/Out		Camera Input/Output 1 (GPIInOut1) default: -

Figure 34: Guppy (board level): Camera I/O connector pin assignment

Guppy input description

Guppy (housing) input block diagram

(For board level see Chapter *Stingray board level camera: I/O pin assignment* on page 54)

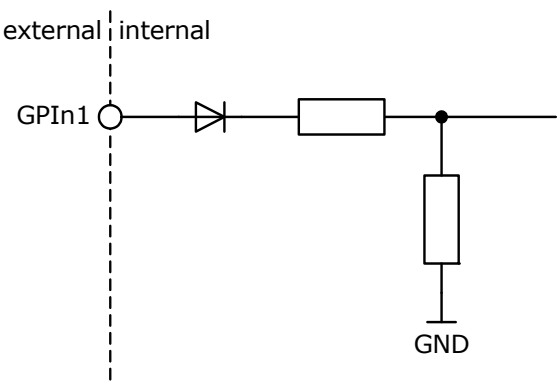


Figure 35: Guppy (housing) input block diagram

The inputs can be connected directly to +5 V. If a higher voltage is used, an external resistor must be placed in series.

Caution



Guppy

Voltages above +36 V may damage the camera.
Max. 50 mA per input.

Used input voltage	External series resistor
5 V	none
12 V	22 kΩ
24 V	56 kΩ
36 V	91 kΩ

Table 16: Guppy: external resistors for voltages higher than 5 V

Guppy delay and minimum pulse width

The **cycle delay** for all Guppy cameras is:

$t_{pdLH} < 3.0 \mu s$ and $t_{pdHL} < 1.5 \mu s$

The **minimum pulse width** for all Guppy cameras is:

$t_p > 2.2 \mu s$

Test conditions

The input signal was driven with 12 V and a 2.2 k Ω pull down resistor to GND and a 22 k Ω series resistor.

Guppy output description

Guppy output block diagram

(For board level see Chapter [Guppy \(board level\) IO block diagram](#) on page 76)

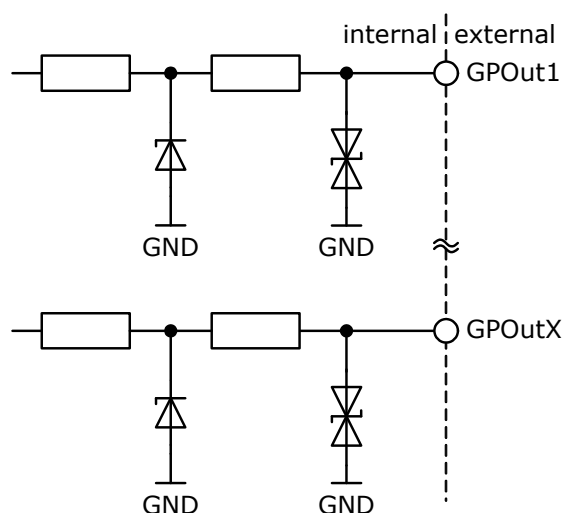


Figure 36: Guppy: output block diagram

Caution



Guppy

Max. 20 mA per output

OutVCC	Resistor value	
5 V	1 k Ω	~ 5 mA load recommended

Figure 37: Guppy: OutVCC and external resistor

Note



Guppy F-503:

IntEna is high, when all pixels are integrated simultaneously.

⇒ Using IntEna with electronic rolling shutter and global reset release shutter: see **Guppy Technical Manual**, Chapter *Trigger modi*.

Guppy delay

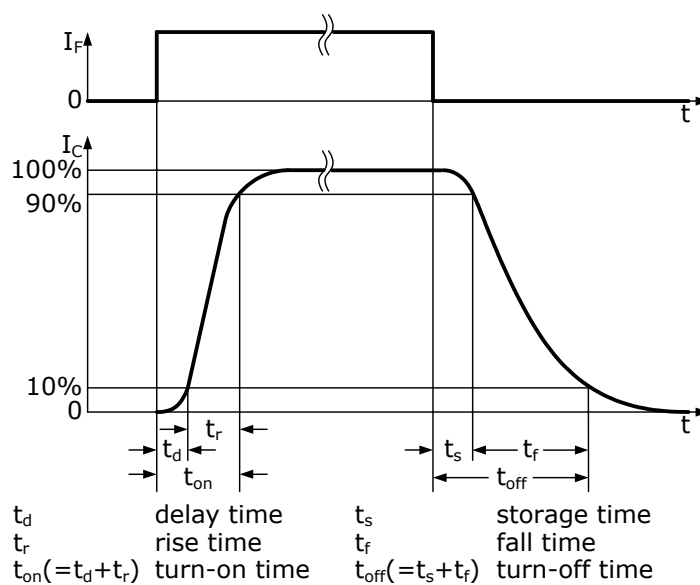


Figure 38: Guppy output switching times

For all Guppy models:

Parameter and value	
$t_d < 0.5 \mu s$	$t_s < 0.5 \mu s$
$t_r < 0.5 \mu s$	$t_f < 0.5 \mu s$
$t_{on} = t_d + t_r < 1 \mu s$	$t_{off} = t_s + t_f < 1 \mu s$

Table 17: Parameters for Guppy

Test conditions

Camera: Format_7 Mode_0, Mono8, S400, extended shutter set to minimum

Output: external 2.4 k Ω resistor to GND

Guppy (board level) IO block diagram

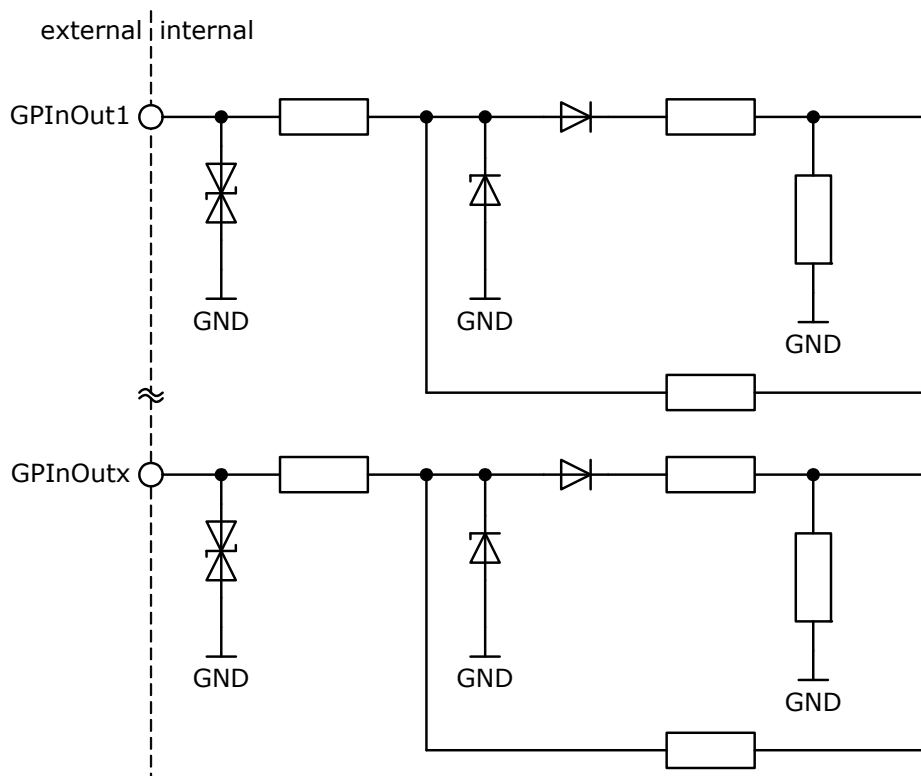


Figure 39: Guppy (board level) input block diagram

The GPIOs of the board level Guppy have the same electrical characteristics as the GPIOs of the standard (housing) Guppy.

Guppy data

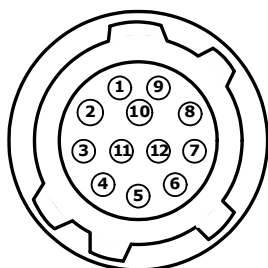
Currently RS232 data interface is not implemented.

Guppy power

In accordance to IEEE 1394a specification the power supply (+8 V ... +36 V) should deliver a current of at least 1.5 A.

Marlin camera interfaces

Marlin camera I/O connector pin assignment



Pin	Signal	Direction	Level	Description
1	External GND		GND for RS232 and ext. power	External ground for RS232 and external power
2	External Power (CCD models only)		+8 ... +36 V DC	Power supply
3				
4	Camera In 1	In	$U_{in}(high) = 2 V \dots U_{inVCC}$ $U_{in}(low) = 0 V \dots 0.8 V$	Camera Input 1 (GPIn1) default: Trigger
5				
6	Camera Out 1	Out	Open collector	Camera Output 1 (GPOut1) default: IntEna
7	Camera In GND	In	Common GND for inputs	Camera Common Input Ground (In GND)
8	RxD RS232	In	RS232	Terminal Receive Data
9	TxD RS232	Out	RS232	Terminal Transmit Data
10	Camera Out Power	In	Common VCC for outputs max. 36 V DC	External Power for digital outputs (OutVCC)
11	Camera In 2	In	$U_{in}(high) = 2 V \dots U_{inVCC}$ $U_{in}(low) = 0 V \dots 0.8 V$	Camera Input 2 (GPIn2) default: -
12	Camera Out 2	Out	Open collector	Camera Output 2 (GPOut2) default: -

Figure 40: Marlin: Camera I/O connector pin assignment

Marlin input description

Marlin input block diagram

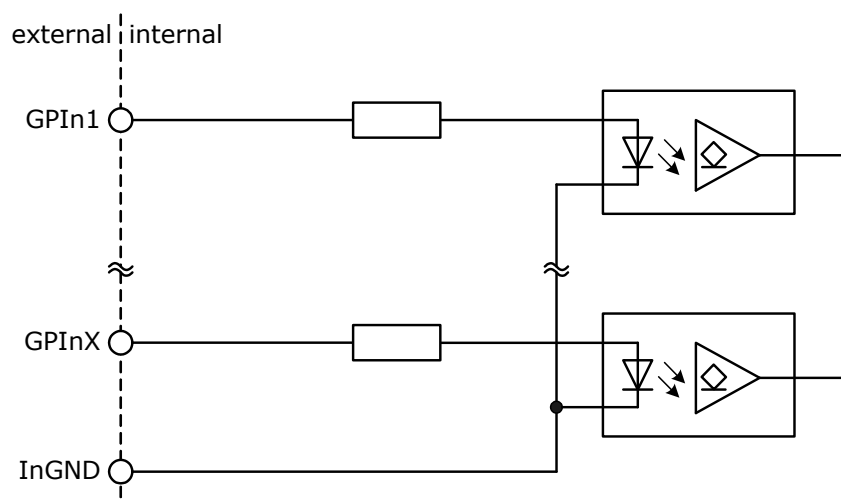


Figure 41: Marlin: input block diagram

The inputs can be connected directly to +5 V. If a higher voltage is used, an external resistor must be placed in series.

Caution

Marlin



Voltages above +36 V may damage the camera.

Used input voltage (U_{inVCC})	External series resistor
5 V	none
12 V	0.82 k Ω
24 V	2.2 k Ω
36 V	3.3 k Ω

Table 18: Marlin: external resistors for voltages higher than 5 V

Parameter	Value
Initial on-current	5 mA
Flux voltage of the LED (@ 10 mA)	1.5 V
Maximum off-current	0.25 mA
Maximum input current	15 mA

Table 19: Marlin: input parameters

Marlin delay and minimum pulse width

The **cycle delay** for all Marlin cameras is:

$t_{pdLH} < 1 \mu s$ and $t_{pdHL} < 1 \mu s$

The **minimum pulse width** for all Marlin cameras is:

$t_p > 2.2 \mu s$

Test conditions

The input signal was driven with 12 V and a 2.2 k Ω pull down resistor to GND.

Marlin output description

Marlin output block diagram

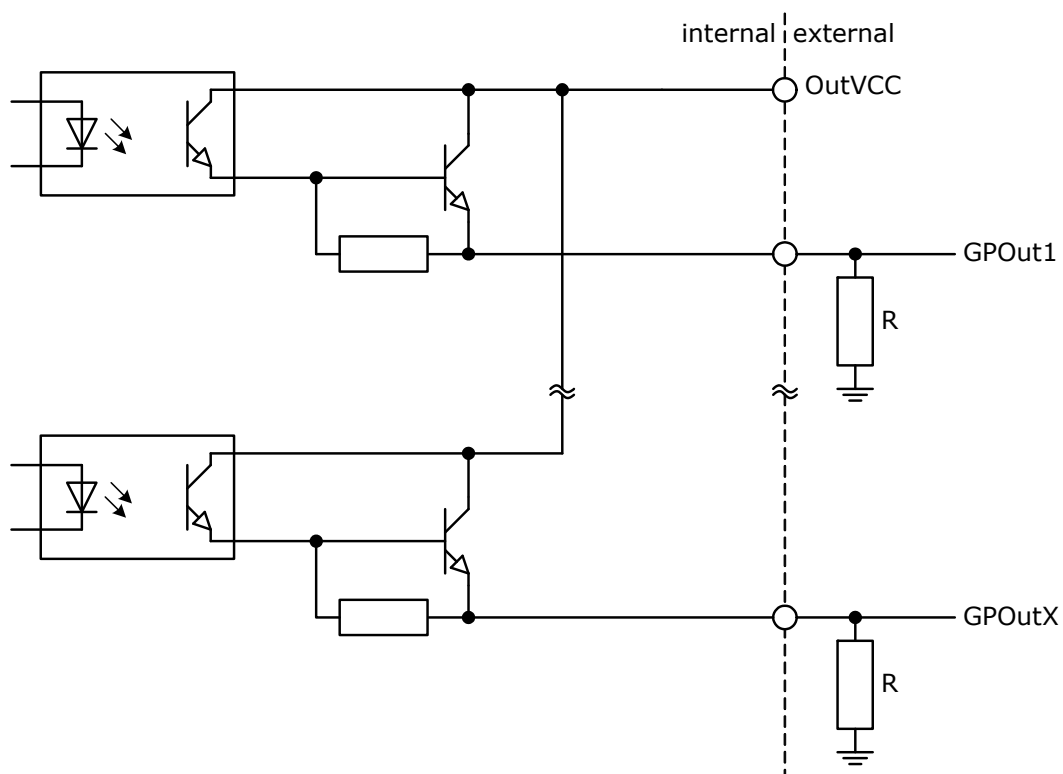


Figure 42: Marlin: output block diagram

Caution



Marlin

- Max. 200 mA per output
- OutVCC > 36 V may damage the camera.

OutVCC	Resistor value	~ 5 mA load recommended
5 V	1 k Ω	
12 V	2.4 k Ω	
24 V	4.7 k Ω	

Figure 43: Marlin: OutVCC and external resistor

Marlin delay

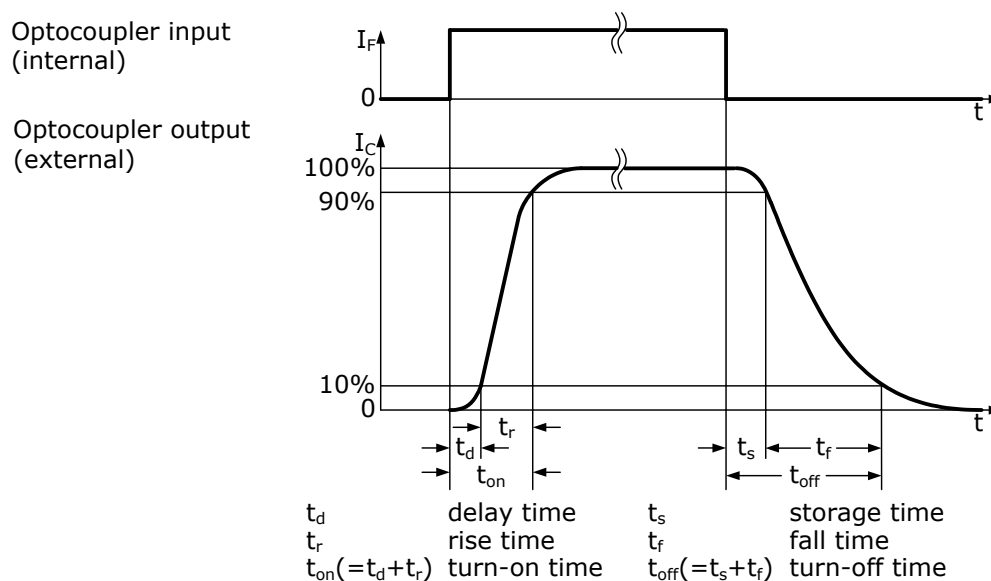


Figure 44: Marlin output switching times

For all Marlin models:

Parameter and value	
$t_d \approx 1 \mu s$	$t_s \approx 55 \mu s$
$t_r \approx 1 \mu s$	$t_f \approx 75 \mu s$
$t_{on} = t_d + t_r \approx 2 \mu s$	$t_{off} = t_s + t_f \approx 130 \mu s$ (t_{off} can deviate by $\pm 5 \mu s$)

Table 20: Parameters for Marlin

Test conditions

Camera: Format_7 Mode_0, Mono8, S400, extended shutter set to minimum

Output: external 2.4 k Ω resistor to GND, power input for output ports set to 12 V

Marlin data

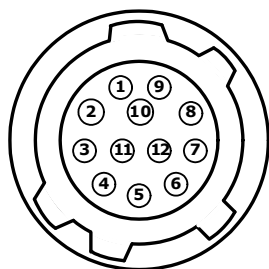
The RS232 data interface has a typical output voltage from ± 4.2 V.

Marlin power

In accordance to IEEE 1394a specification the power supply (+8 V ... +36 V) should deliver a current of at least 1.5 A.

Oscar camera interfaces

Oscar camera I/O connector pin assignment



Pin	Signal	Direction	Level	Description
1	External GND		GND for RS232 and ext. power	External ground for RS232 and external power
2	External Power		+8 ... +36 V DC	Power supply
3				
4	Camera In 1	In	$U_{in}(high) = 2 V \dots U_{inVCC}$ $U_{in}(low) = 0 V \dots 0.8 V$	Camera Input 1 (GPIIn1) default: Trigger
5				
6	Camera Out 1	Out	Open emitter	Camera Output 1 (GPOut1) default: IntEna
7	Camera In GND	In	Common GND for inputs	Camera Common Input Ground (In GND)
8	RxD RS232	In	RS232	Terminal Receive Data
9	TxD RS232	Out	RS232	Terminal Transmit Data
10	Camera Out Power	In	Common VCC for outputs max. 36 V DC	External Power for digital outputs (OutVCC)
11	Camera In 2	In	$U_{in}(high) = 2 V \dots U_{inVCC}$ $U_{in}(low) = 0 V \dots 0.8 V$	Camera Input 2 (GPIIn2) default: -
12	Camera Out 2	Out	Open emitter	Camera Output 2 (GPOut2) default: -

Figure 45: Oscar: Camera I/O connector pin assignment

Oscar input description

Oscar input block diagram

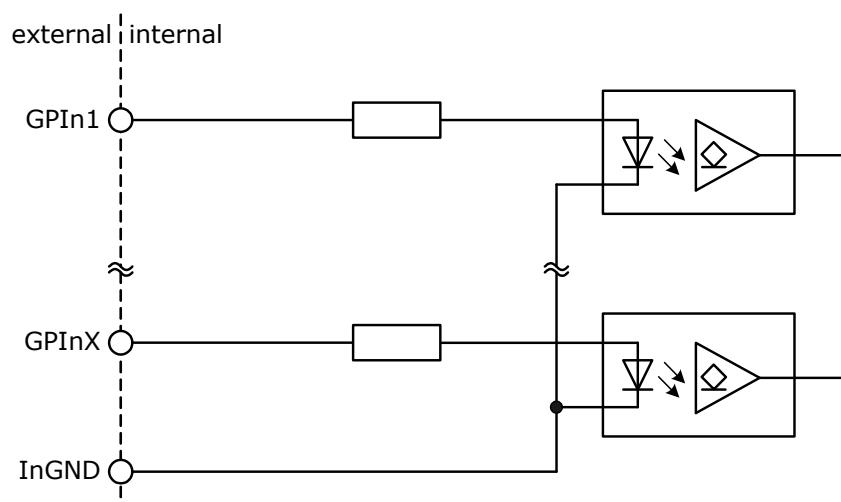


Figure 46: Oscar: input block diagram

The inputs can be connected directly to +5 V. If a higher voltage is used, an external resistor must be placed in series.

Caution



Oscar

Voltages above +36 V may damage the camera.

Used input voltage (U_{inVCC})	External series resistor
5 V	none
12 V	0.82 k Ω
24 V	2.2 k Ω
36 V	3.3 k Ω

Table 21: Oscar: external resistors for voltages higher than 5 V

Parameter	Value
Initial on-current	5 mA
Flux voltage of the LED (@ 10 mA)	1.5 V
Maximum off-current	0.25 mA
Maximum input current	15 mA

Table 22: Oscar: input parameters

Oscar delay and minimum pulse width

The **cycle delay** for all Oscar cameras is:

$t_{pdLH} < 1 \mu s$ and $t_{pdHL} < 1 \mu s$

The **minimum pulse width** for all Oscar cameras is:

$t_p > 2.2 \mu s$

Test conditions

The input signal was driven with 12 V and a 2.2 k Ω pull down resistor to GND.

Oscar output description

Oscar output block diagram

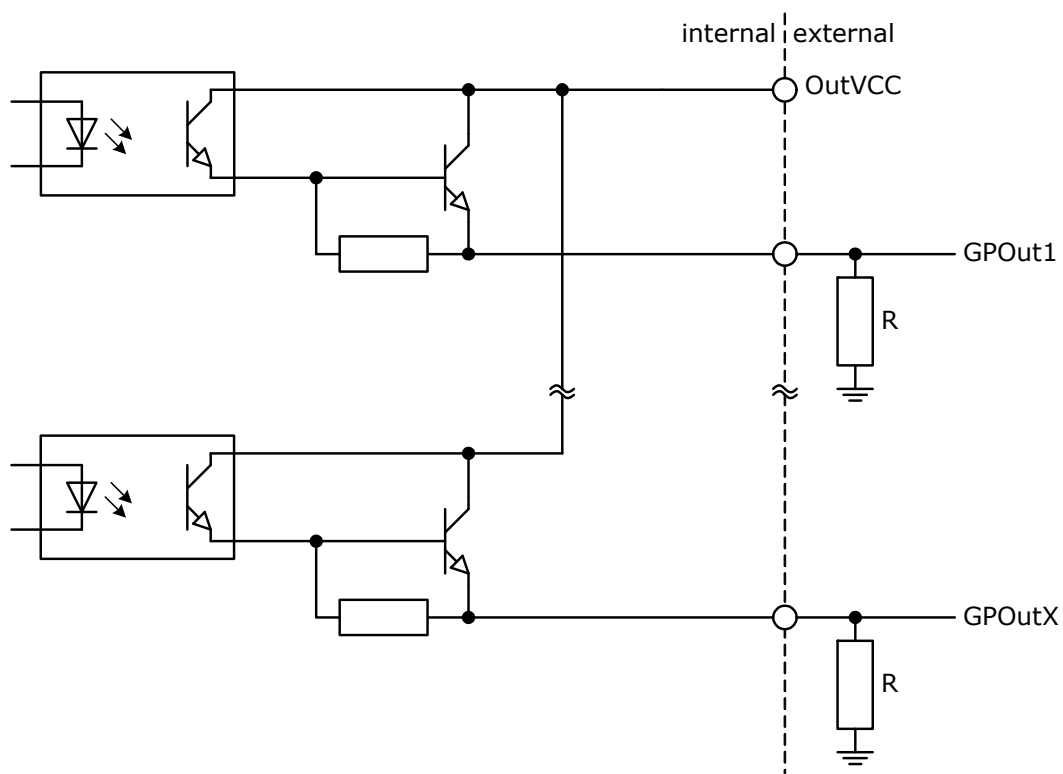


Figure 47: Oscar: output block diagram

Caution



Oscar

- Max. 200 mA per output
- OutVCC > 36 V may damage the camera.

OutVCC	Resistor value	~ 5 mA load recommended
5 V	1 k Ω	
12 V	2.4 k Ω	
24 V	4.7 k Ω	

Figure 48: Oscar: OutVCC and external resistor

Oscar delay

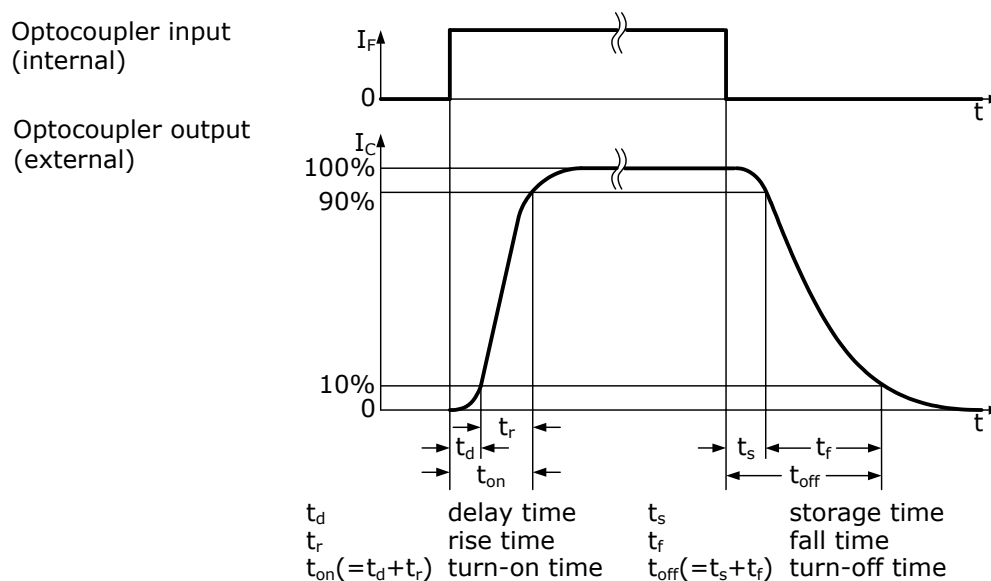


Figure 49: Oscar output switching times

For all Oscar models:

Parameter and value	
$t_d \approx 1 \mu s$	$t_s \approx 55 \mu s$
$t_r \approx 1 \mu s$	$t_f \approx 75 \mu s$
$t_{on} = t_d + t_r \approx 2 \mu s$	$t_{off} = t_s + t_f \approx 130 \mu s$ (t_{off} can deviate by $\pm 5 \mu s$)

Table 23: Parameters for Oscar

Test conditions

Camera: Format_7 Mode_0, Mono8, S400, extended shutter set to minimum

Output: external 2.4 k Ω resistor to GND, power input for output ports set to 12 V

Oscar data

The RS232 data interface has a typical output voltage from ± 4.2 V.

Oscar power

In accordance to IEEE 1394a specification the power supply (+8 V ... +36 V) should deliver a current of at least 1.5 A.

Firmware update

Firmware updates can be carried out without opening the camera.

Note



For further information read the application note:

How to update Guppy/Guppy PRO/Pike/Stingray firmware.

This application note and the firmware itself is only accessible for distributors. End customers have to contact technical support.

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