

	DBSCAN	HOBSCAN	Spectral	K-means	Hierarchical	Mixture Models	Fuzzy c-means	Mean Shift	Affinity Propagation	Latent Class Analysis (LCA)	Bisecting k-means	Self-Organizing Map (SOM)
Description	Density-Based Spatial Clustering of Applications with Noise, a non-parametric density-based clustering algorithm More info: https://en.wikipedia.org/wiki/DBSCAN	Hierarchical Density-Based Spatial Clustering of Applications with Noise, performs DBSCAN with varying epsilon values allowing for varying densities (DBSCAN does not allow for varying densities) More info: https://en.wikipedia.org/wiki/HOBSCAN , https://arxiv.org/pdf/1606.08580v1.pdf	Spectral clustering uses the eigenvalues of the similarity matrix of the data to perform dimensionality reduction prior to clustering - Spectral clustering treats the similarity matrix as an input - The similarity matrix is a matrix of quantiles representing the relative similarity of each pair of points in the dataset More info: https://en.wikipedia.org/wiki/Spectral_clustering	- Starts with k random centroids (k is user defined) and assigns each observation to the centroid closest to it - After the initial assignments, the algorithm iteratively calculates the new k centroids and then assigns each observation based on the new centroids - Divide: When all observations start in one cluster and clusters are formed through recursive splitting of the observations - This process continues until convergence is achieved (or for a minimum amount of changing) More info: https://en.wikipedia.org/wiki/K-means_clustering#Standard_K-means , https://en.wikipedia.org/wiki/K-means	- There are two forms of hierarchical clustering - Agglomerative: When each observation starts as its own cluster and clusters are merged one by one by joining the closest clusters - Divide: When all observations start in one cluster and clusters are formed through recursive splitting of the observations More info: https://en.wikipedia.org/wiki/Hierarchical_clustering	- A probabilistic method of clustering observations by probability distributions - Most common is using Gaussian Mixture models to group observations according to different Gaussian distributions More info: https://en.wikipedia.org/wiki/Mixture_model	- Fuzzy clustering is like k-means clustering except it allows observations to belong to more than one cluster at a time More info: https://en.wikipedia.org/wiki/Fuzzy_c-means	- The underlying idea of the Mean Shift algorithm is that there exists some probability density function from which the data is drawn and tries to place centroids at the modes of that density function [4] More info: https://en.wikipedia.org/wiki/Mean_shift	- Finds 'exemplars' by essentially taking an 'observation' (or 'test') for their preferred 'exemplar' is select for its problem - The 'exemplars' are members of the input data that are representative of clusters [12] More info: https://en.wikipedia.org/wiki/DBSCAN , https://arxiv.org/pdf/1606.08580v1.pdf , https://en.wikipedia.org/wiki/HOBSCAN , https://arxiv.org/pdf/1606.08580v1.pdf , https://en.wikipedia.org/wiki/DBSCAN , https://arxiv.org/pdf/1606.08580v1.pdf , 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