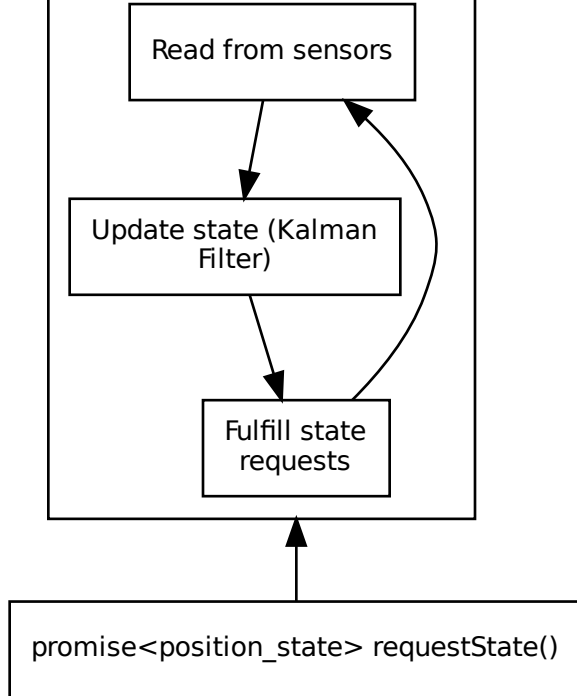
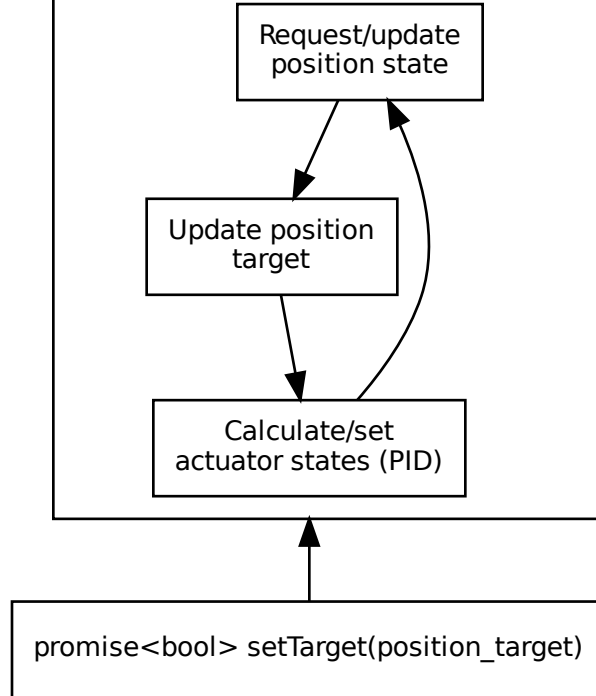


Thread 0: Localization



Thread 1: Detumbling/positioning



Thread 2: Communications

