

DeepMVS: Learning Multi-View Stereopsis



Code available! http://bit.ly/deepmvs





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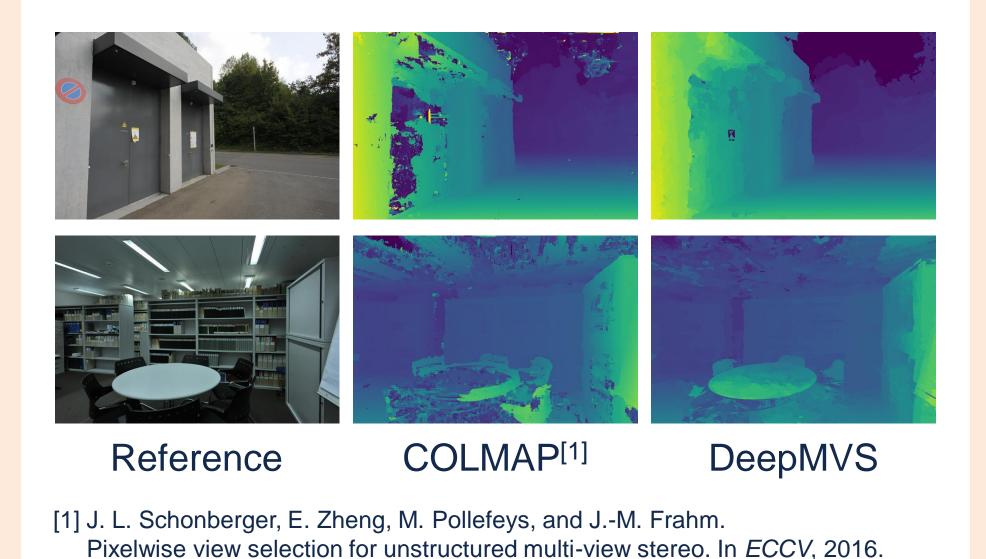
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Problem



Challenges

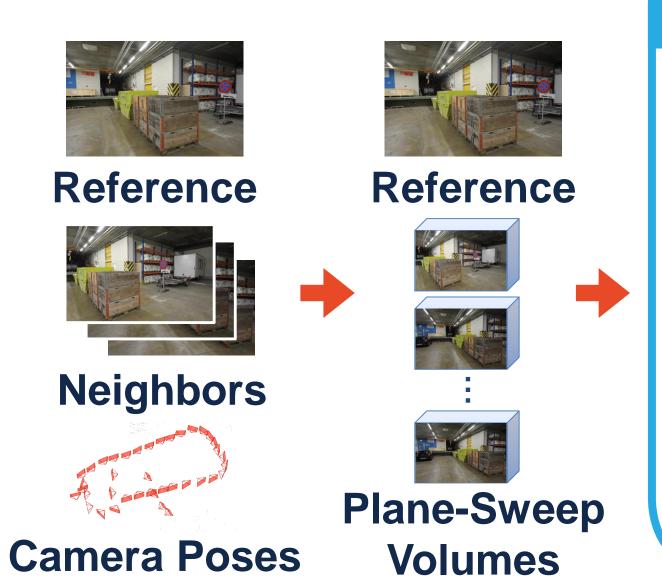
- Poorly textured regions
- Reflective surfaces
- Thin structures



Contributions

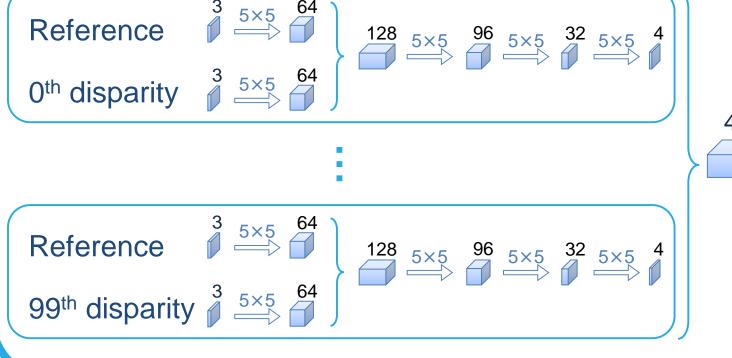
- ConvNet for multi-view stereo
- Arbitrary numbers of input images
- Accurate disparity estimation

Method



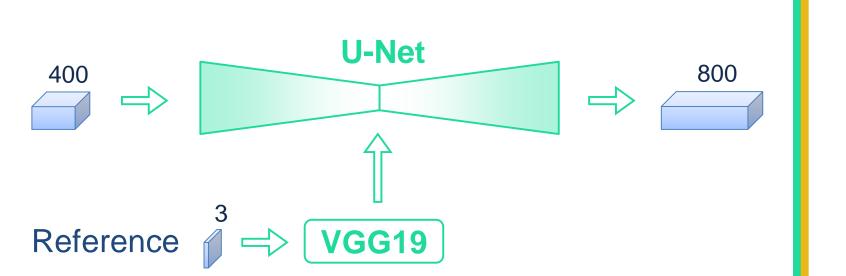
Patch Matching

 Detect photo-consistency $\stackrel{5\times5}{\longrightarrow}$ Conv + SELU



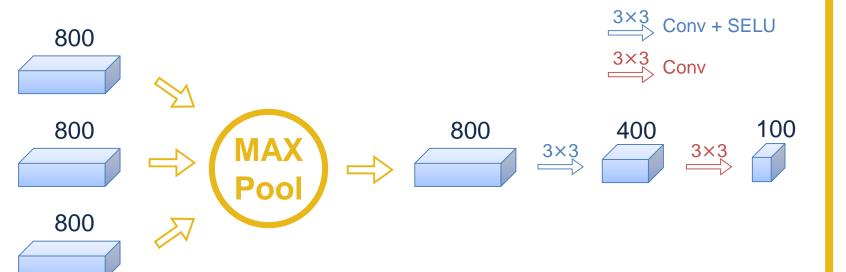
Intra-Volume Feature Aggregation

- U-Net: Large receptive field
- VGG: Semantic features



Inter-Volume Feature Aggregation

- Max-pool features across volumes
- Any number & order of images





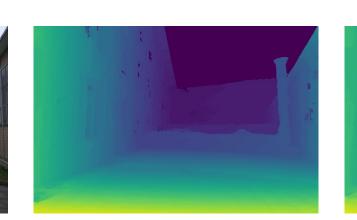
Map

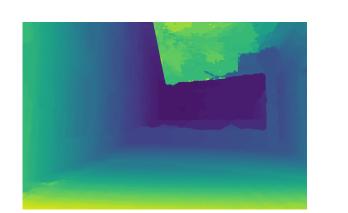
MVS-Synth Dataset

- 12,000 images from GTA V
- Realistic, complete & accurate









Reference

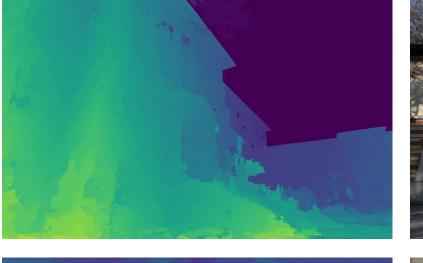
with MVS-Synth w/o MVS-Synth

Problems of existing datasets

	Real-World Datasets	Synthetic Datasets
Pros	Represent the real world	Cheap Complete & Accurate
Cons	Expensive Incomplete & Inaccurate	Unrealistic

Results



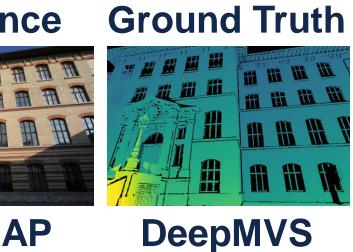


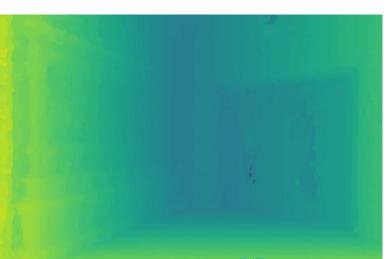
Quantitative comparisons on ETH3D Dataset

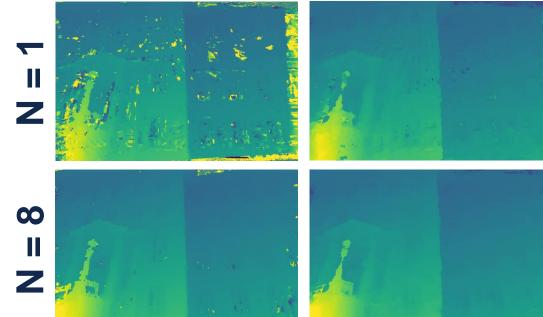












Geo. error distribution

Algorithm	Completeness	Geometric error	Photometric error	0.16
DeMoN (median)	100%	0.201	0.367	0.12 - · · · · · · · · · · · · · · · · · ·
COLMAP (filtered)	71%	0.007	0.178	0.08 - 0.06 -
COLMAP (unfiltered)	100%	0.046	0.218	ပီ 0.04 - 0.02 -
DeepMVS	100%	0.036	0.224	0.00

MAP (unfiltered)

Geo. error for N = 1 - 8Ours 0.012 **COLMAP** ៦ 0.010∤ 은 0.008 0.006 0.0042 3 4 5 6 7 8 9 Number of neighbor images (N)