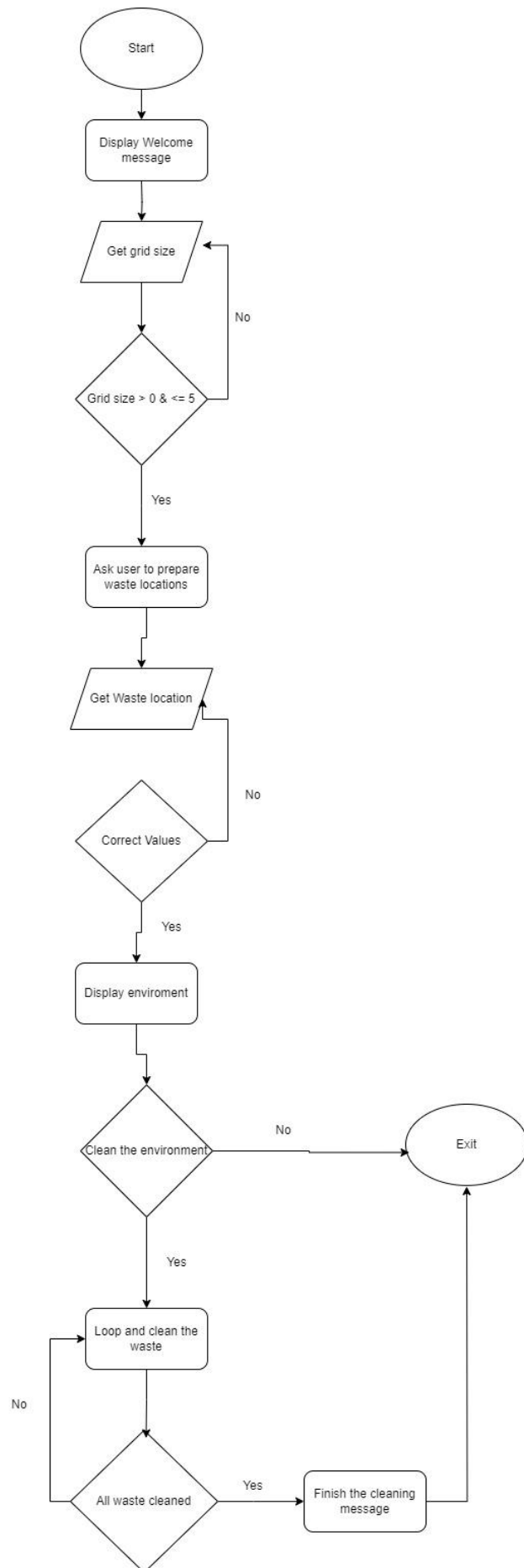


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created a dynamic map showing the movement of the Robot cleaner	2nd - 4th feb	5th - 7th feb	8th - 10th feb	11th - 13th feb	14th - 16th feb	17th - 19th feb
Task 1						
Defined Grid class and environment						
Waste location to be defined						
Define a function to check if grid has been cleaned						
Task 2						
Function to display the environment with or without the robot's position using PrettyTable						
Task 3						
Running the agent						
Defined a function to hold and update the waste location status						
Created a dynamic map showing the movement of the Robot cleaner						
Created a widget to collect users input and defined a function to display all cleaned status update as output for user after cleaning						