

Software for Tomographic Image Reconstruction

http://stir.sourceforge.net https://github.com/UCL/STIR

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STIR objectives

- Research enabler
- Offline image reconstruction and data manipulation
- Portable to any system with a capable C++ compiler
 - GNU C++, MS Visual Studio, Clang, Intel C++
 - Linux, Windows, MacOS, Solaris, ...
- Open Source

 (L)GPL now, Apache 2.0 soon
- Use Sustainable Software Development techniques
 - For software quality
 - For training the next generation of researchers



Overview

Using STIR

Extending STIR

MATLAB/Python interface

Challenges



Overview

- Using STIR
 - Overview of capabilities
 - Example results
 - User perspective
 - Missing features
- Extending STIR
- MATLAB/Python interface
- Challenges



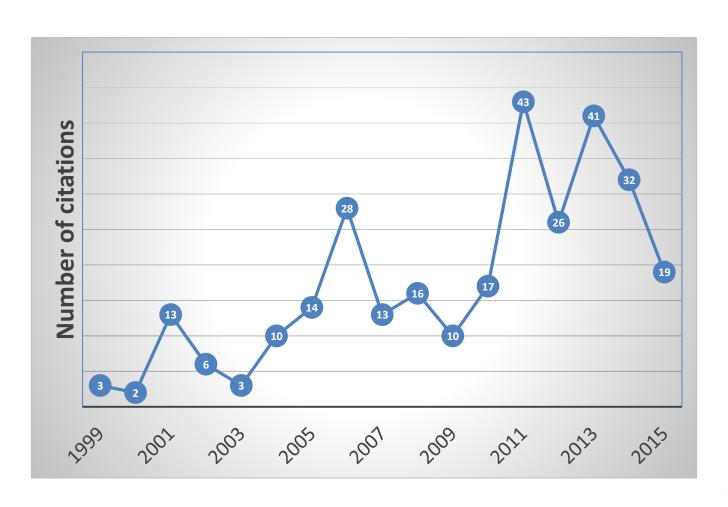
Capabilities

- PET and SPECT
- Quantitative
 - PET scatter, normalisation and randoms estimation
- Analytic and iterative 3D reconstruction algorithms
 - FBP-3DRP, FORE, OSEM, OS-MAP-OSL, OS-SPS, list-mode EM and SPS
- Pharmacokinetic modelling
 - linear models only
 - indirect and direct parametric reconstruction
- Motion correction
 - post-reconstruction and MCIR for gated data
 - LOR rebinning for rigid motion
 - no motion estimation
- Various utilities
 - data manipulation, ROI values, analytic image generation ...



User statistics

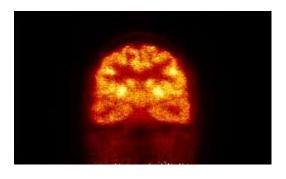
~280 subscribers to stir-users@lists.sf.net



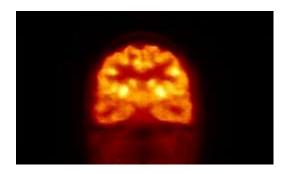


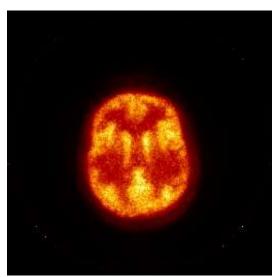
OSEM & OSL-MAP reconstruction for brain PET

Patient data – Reconstructed Images

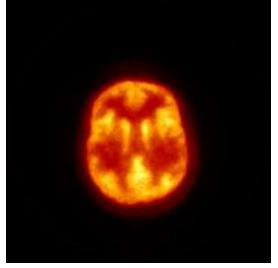


Coronal Image



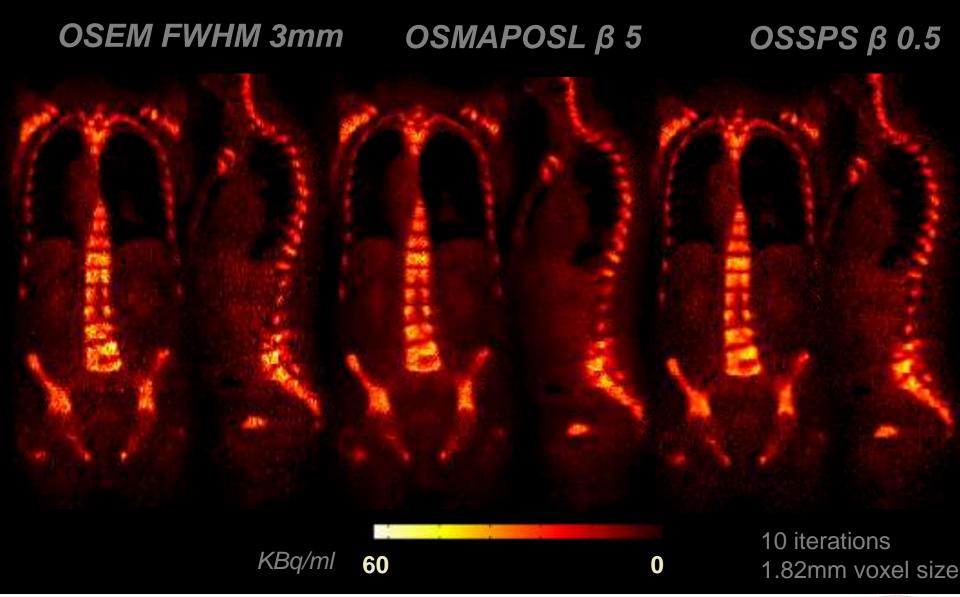


Transverse Image





Patient (F18) acquired on GE PET/CT

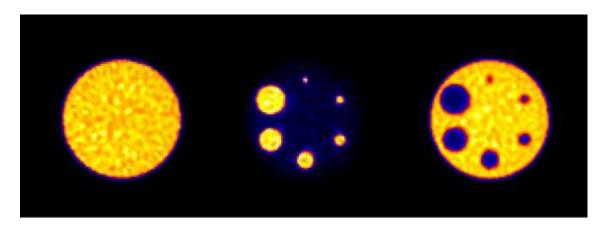




SPECT reconstruction

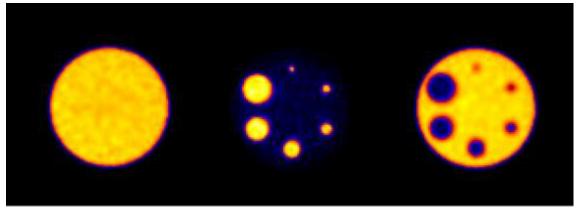
SIMULATED DATA

OSMAPOSL it 80



$$C_v = 6.8\%$$

OSSPS it 80

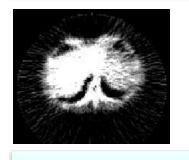


$$C_v = 2.5\%$$

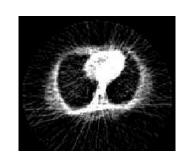
 C_v = Coefficient of variation

Non corrected

SCATTER CORRECTION EXAMPLE



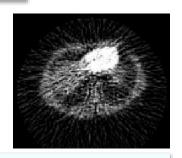


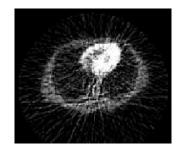




Corrected with SSS

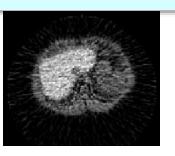




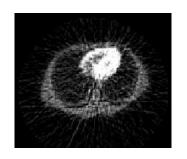




Without Scatter



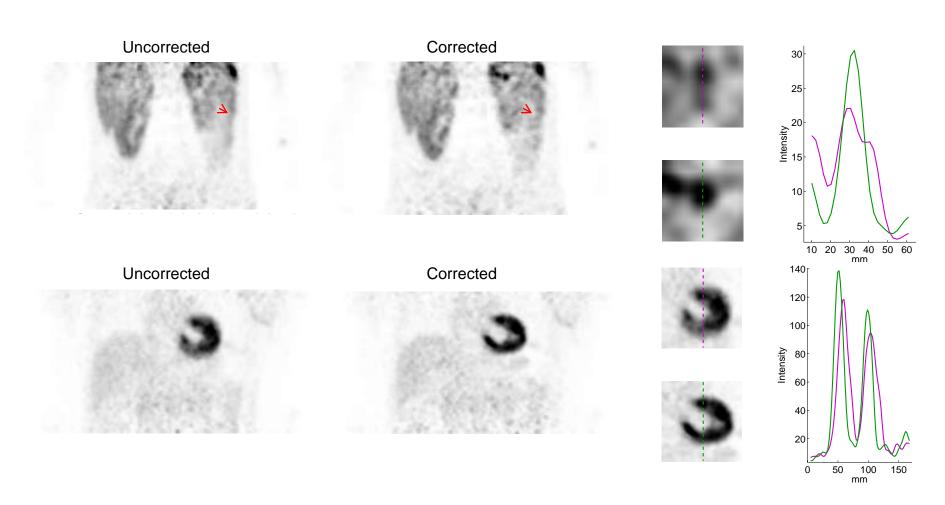








Motion-Compensated Image Reconstruction





Missing features

PET

- Reading raw data from GE, Philips (Siemens mostly ok)
- Non-cylindrical scanners
- TOF (WIP)

SPECT

- Dicom sinogram import
- Non-parallel hole collimators
- Scatter
- Extra reconstruction options
 - More optimisation algorithms
 - More priors (WIP)
- Closer connection with SimSET/GATE (WIP)
- GPU



Current user perspective

Command line utilities
 OSSPS parameterfile

- Documentation
 - PDFs (Overview, detail)
 - Wiki
 - Example parameter files
 - No easy place to start



Run-time parameter selection

```
OSSPSParameters :=
objective function type:= PoissonLogLikelihoodWithLinearModelForMeanAndProjData
PoissonLogLikelihoodWithLinearModelForMeanAndProjData Parameters:=
 input file := test.hs
 projector pair type := Matrix
    Projector Pair Using Matrix Parameters :=
       Matrix type := Ray Tracing
           Ray tracing matrix parameters :=
           End Ray tracing matrix parameters :=
    End Projector Pair Using Matrix Parameters :=
 Bin Normalisation type := From ProjData
   Bin Normalisation From ProjData :=
       normalisation projdata filename:= norm.hs
   End Bin Normalisation From ProjData:=
 prior type := quadratic
    Quadratic Prior Parameters:=
        penalisation factor := 1
   End Quadratic Prior Parameters:=
end PoissonLogLikelihoodWithLinearModelForMeanAndProjData Parameters:=
initial estimate:= some_image
output filename prefix := test
number of subsets:= 12
number of subiterations:= 24
relaxation parameter := 1
relaxation gamma:=.1
```

END :=

Overview

- Using STIR
- Extending STIR
 - General developer's perspective
 - Example class hierarchies
- MATLAB/Python interface

Challenges



Developer's perspective

Object-oriented (C++) and modular

Documented (doxygen)

Test framework

Extendable

- Mechanism for extending library such that current STIR applications can use your module (e.g. projector) after recompilation
- Mechanism for writing new applications using (original or extended) library

Code statistics

- Physical Source Lines of Code (SLOC)
 - = 105,886
- Total Number of Source Code Files
 - = 836
- Development Effort Estimate
 - = 26.74 Person-Years

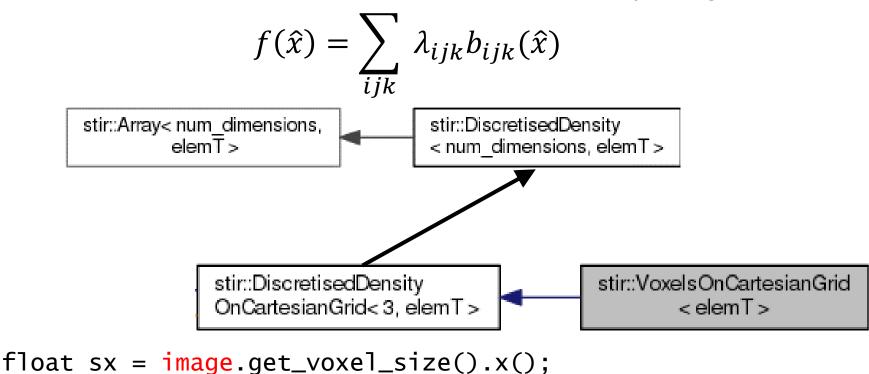
(Basic COCOMO model)

generated using David A. Wheeler's 'SLOCCount'



Images

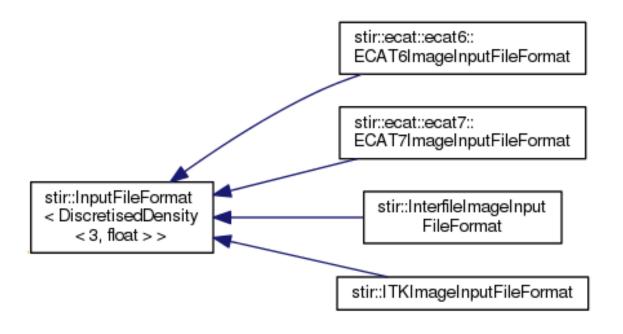
Discretised representations of a "density", e.g.



```
auto voxel_location =
  image.get_physical_coordinates_for_indices(make_coord(i,j,k));
```



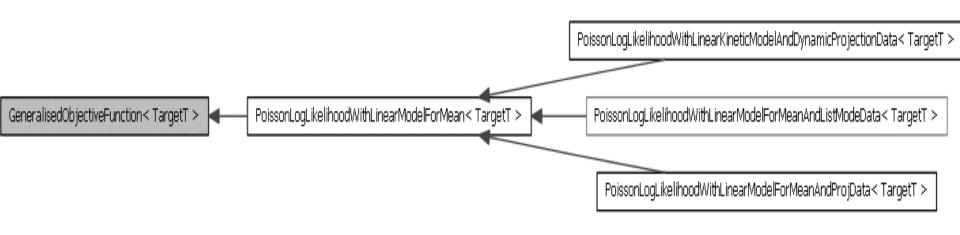
IO: pluggable factories



typedef DiscretisedDensity<3,float> ImageType; auto density_sptr(read_from_file<ImageType>(filename));



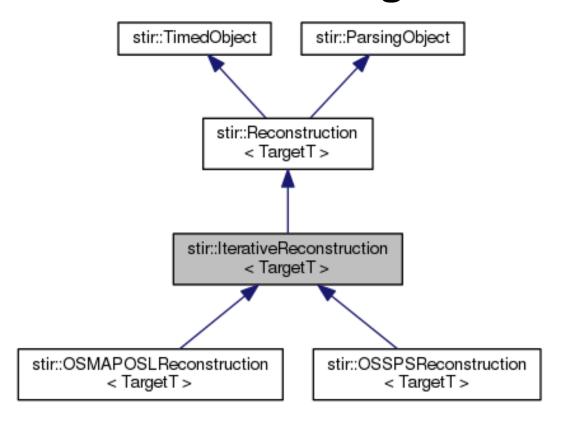
Objective functions



```
double value =
        objf.compute_objective_function (image, subset_num);
objf.compute_sub_gradient (gradient, image, subset_num);
```



Reconstruction algorithms

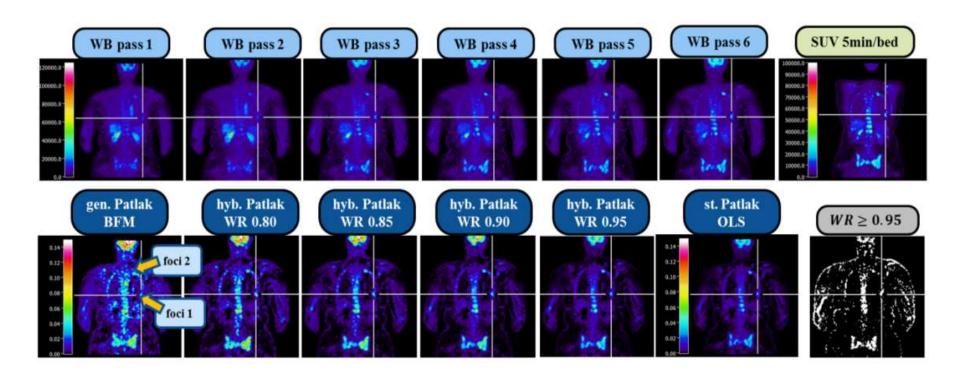


```
OSMAPOSLReconstruction<ImageType> recon(parameter_file);
recon.set_num_subiterations(5);
// reconstruct from initial image
recon.reconstruct(image);
```

Generalized whole-body Patlak PET

generalized Patlak model equation

$$\frac{C(t_k)}{C_P(t_k)} = K_i \frac{\int_0^{t_k} e^{-k_{loss}(t_k - \tau)} C_P(\tau) d\tau}{C_P(t_k)} + V, \qquad t_k > t^*,$$





Overview

- Using STIR
- Extending STIR

- MATLAB/Python interface
 - How?
 - Examples

Challenges



STIR and MATLAB/Python

- Interface constructed via SWIG
 - Simplified Wrapper and Interface Generator
 - Parses "interface" text file and C++ headers
 - Generates MATLAB/Python/C++
 - Compile to generate library
- Object-oriented MATLAB/Python (close to C++, but no templates, pointers etc)

- Work-in-Progress
 - SWIG-MATLAB is under development.



Python: objective function computation

```
## initialise reconstruction object via a parameter file
recon=stir.OSMAPOSLReconstruction3DFloat('recon_demo_OSEM.par');
## construct image related to the data to reconstruct
projdata=stir.ProjData.read_from_file('input_sinogram.hs');
target=stir.FloatVoxelsOnCartesianGrid(projdata.get_proj_data_info());
## set-up objective function
recon.set_up(target);
% get corresponding objective function
poissonobj=recon.get_objective_function();
## compute gradient of objective function
# put some data in the image
target.fill(1);
# create an image to store the gradient
gradient=target.get_empty_copy();
poissonobj.compute_sub_gradient(gradient,target)
## display
gradientdata=stirextra.to_numpy(gradient);
pylab.figure();
pylab.imshow(gradientdata[10,:,:])
pylab.show()
```

MATLAB: objective function computation

```
%% initialise reconstruction object via a parameter file
recon=stir.OSMAPOSLReconstruction3DFloat('recon_demo_OSEM.par');
%% construct image related to the data to reconstruct
projdata=stir.ProjData.read_from_file('input_sinogram.hs');
target=stir.FloatVoxelsOnCartesianGrid(projdata.get_proj_data_info());
%% set-up objective function
recon.set_up(target);
% get corresponding objective function
poissonobj=recon.get_objective_function();
%% compute gradient of objective function
% put some data in the image
target.fill(1);
% create an image to store the gradient
gradient=target.get_empty_copy();
poissonobj.compute_sub_gradient(gradient,target)
% display
gradientdata=gradient.to_matlab();
figure;
imshow(gradientdata(:,:,10),[])
```

Overview

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Challenges



Challenges (I)

- Lots of functionality
 - Good software design is crucial
 - Modular/flexible involves overhead

- Large code-base
 - Good software design is crucial
 - Not enough documentation
 - Too much documentation

Rapid development in software/hardware



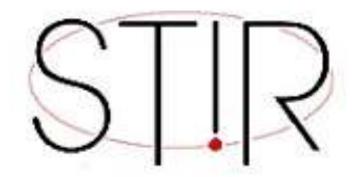
Challenges (II)

Manage user expectations

- Foster user involvement
 - Lots of questions on the mailing list
 - Current group of "developers" is small
 - Hopefully will increase with Python/MATLAB capabilities

Needs time investment





Main publication:

Thielemans, Tsoumpas, *et al* (2012) STIR: Software for Tomographic Image Reconstruction Release 2, *Physics in Medicine and Biology*, 57(4):867-83.





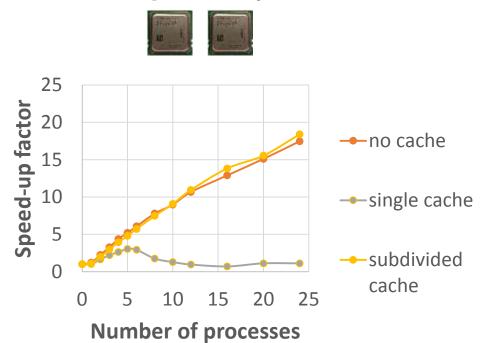




Parallelisation

- Cluster: MPI
- Multi-threading: OpenMP

Dual-Opteron system



Wall-clock times per MLEM iteration

Siemens mMR data (span 11)

No threading	315s
20 threads	20s



Future contributions

- 4D Generalised Patlak for multi-bed position data Nicolas Karakatsanis, Arman Rahmim, Habib Zaidi
- List-mode reconstruction fixes Nikos Efthimiou, Charalampos Tsoumpas
- TOF Nikos Efthimiou, Charalampos Tsoumpas
- Non-cylindrical scanners => cylindrical Jannis Fischer
- Support for GE PET-MR

