

# STIR status and future 2022

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# Software for Tomographic Image Reconstruction

- C++ open-source library
- Data/image processing
- SPECT/PET image reconstruction (sinogram and list mode)
- Multiple scanners models
- Python and Matlab interface
- Used as "engine" by the synergistic image reconstruction framework (SIRF)

# STIR 5.0 new features (March 2022)

See [Summary of changes in STIR release 5.0](#)

Main items:

- Block detectors (and generic location)  
Geometry specification, IO, projectors
- View-offset
- Maximum Likelihood Estimation of normalisation factors
- Virtual crystals for ROOT
- Radionuclide information and calibration
- *Parallelproj* integration



# parallelproj

OpenMP and CUDA libraries for 3D Joseph non-TOF and TOF forward and back projectors

[gschramm/parallelproj: code for parallel TOF and NONTOF projections \(github.com\)](https://github.com/gschramm/parallelproj)

Remaining issues with STIR integration:

- copying to/from GPU memory
- bugs for block detector (fixed (?) on master)
- potential for voxels missed
- no tests integrated
- not yet in listmode reconstruction

# Some anecdotal timings

## **PC:**

- processor: AMD Ryzen 9 5900 (12 cores)
- GeForce RTX 3070 (24GB memory, 5888 CUDA cores)
- 32GB RAM
- Windows 10 Pro

## **Compilers:**

- Visual Studio 2022
- gcc 9 (under WSL 1)

# Data/projector information

- Siemens mMR
  - {127, 344, 344} voxels of size {2.03, 2.08, 2.08}
  - span 1 and 11
- Projectors:
  - parallelproj (v0.8)
    - always single LOR
  - ray tracing matrix
    - 5 tangential LORs
    - Axial LORs: 1 for span 11, 2 for span 1
- Wall-clock timing of forward\_project
  - Includes IO
  - Includes set-up time (2<sup>nd</sup> projection is faster)

# Span 11 results

- RT projection matrix
  - VS (with caching) 30.3s
  - VS (no caching): 35.9s
  - gcc (no caching): 23.973s
- Parallelproj
  - gcc OpenMP: 28s
  - VS CUDA: 9.1s
    - copy image to device: 1.2s
    - Call to parallel\_proj\_forward\_cuda: 1.9s ( 2 chunks: 3.2s)

# Span 1 results

- RT projection matrix
  - VS (with caching) 329.3s
  - VS (no caching): 321.5s
  - gcc (no caching): 207.7s
- Parallelproj
  - VS CUDA: 41.5s
    - copy image to device: 1.2s
    - Call to parallel\_proj\_forward\_cuda: (2 chunks): 6s
  - Note: Georg Schramm's independent timings imply this should be faster



# Some comments

- parallelproj – CUDA is considerably faster (note however, factor 5/10 due to #LORs)
  - overhead due to conversion of STIR objects (avoidable)
  - overhead due to CPU/GPU memory transfer (needs a lot of work)
- for OpenMP performance, your compiler matters
- need for benchmarking tool
  - Repeat projections
  - Different scanners

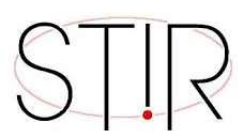
# STIR 5.1 features

[Summary of changes in STIR release 5.1 \(github\)](#)

- Improvements to listmode reconstruction (Nikos)
- Support for PENNPET Explorer listmode data (if proprietary libraries are found) (Nikos)
  - Potentially Philips data, too
- Scatter simulation, estimation and down/up-sampling adapted for scanner with Block geometry (Daniel and Kris)
- Various small changes to add functionality to Python interface (Markus Jehl)
- Python projection data visualiser (in examples/python) (Robert Twyman)

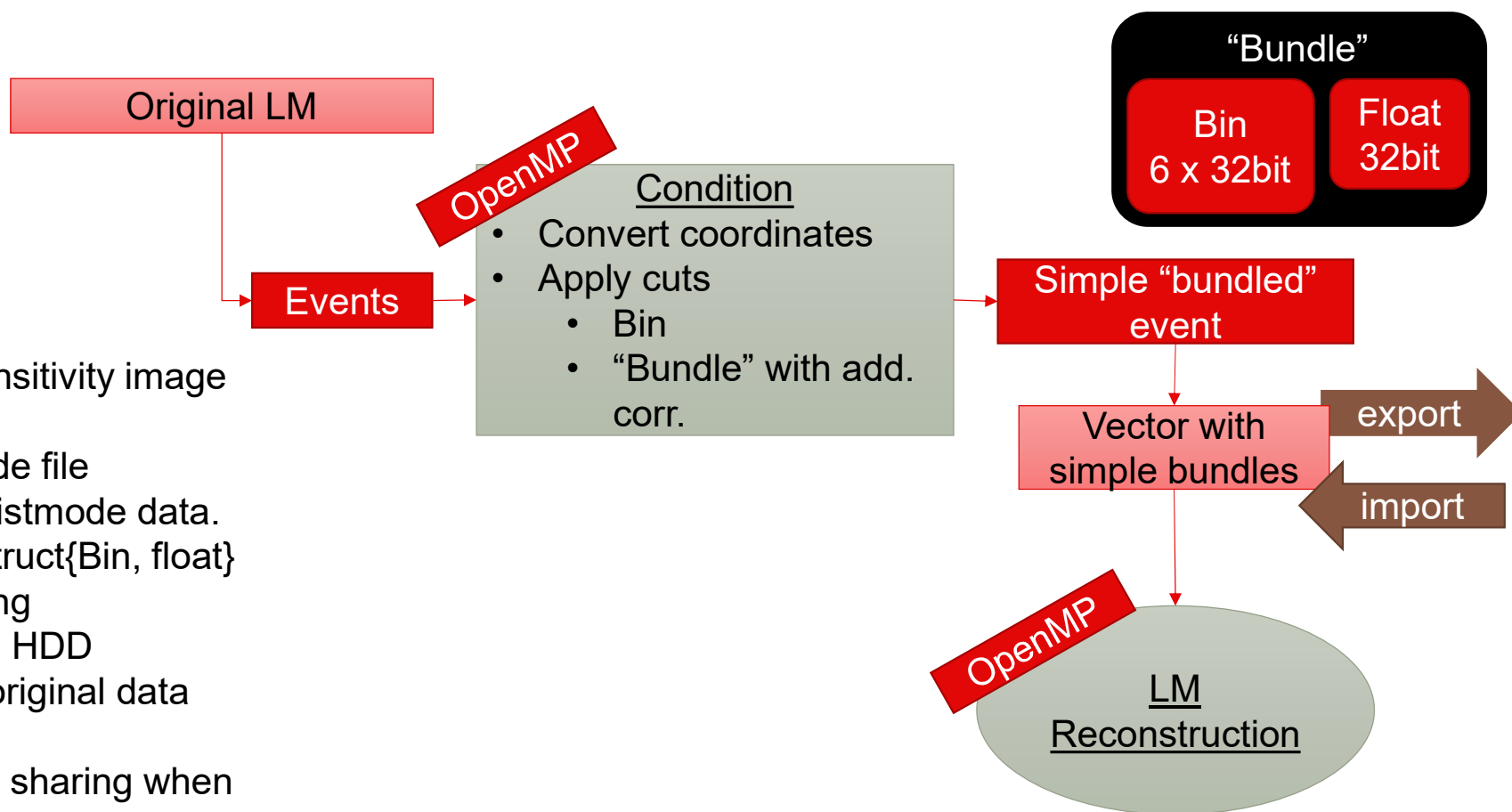
To be merged:

- Adaptation of MLE normalisation/randoms code for BlocksOnCylindrical (Daniel)



# Listmode improvements

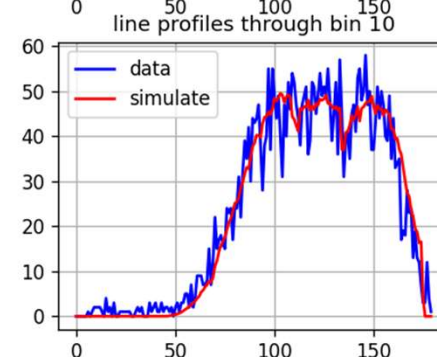
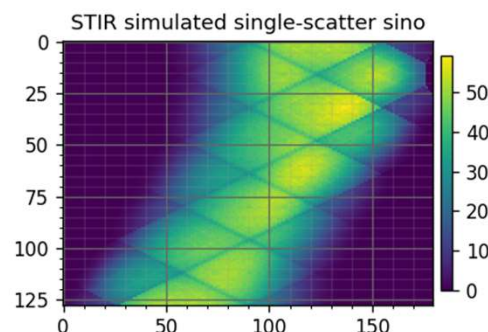
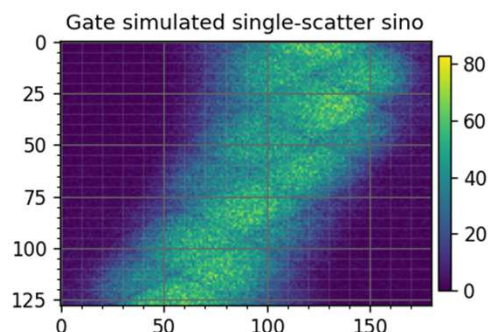
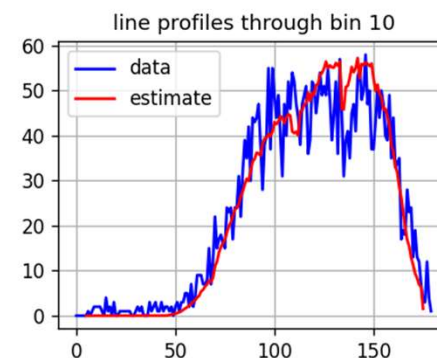
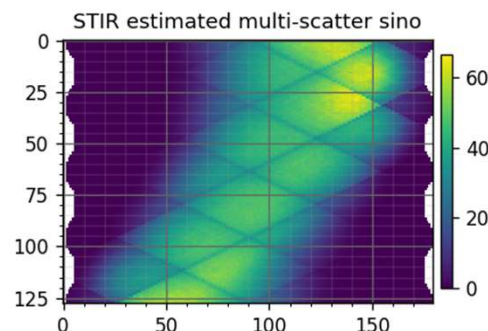
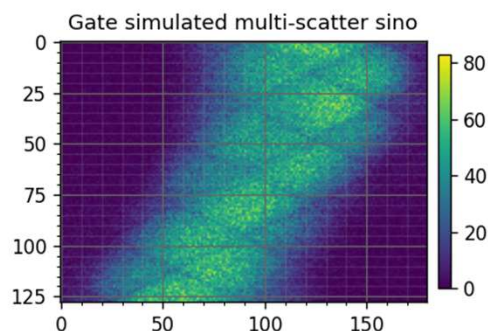
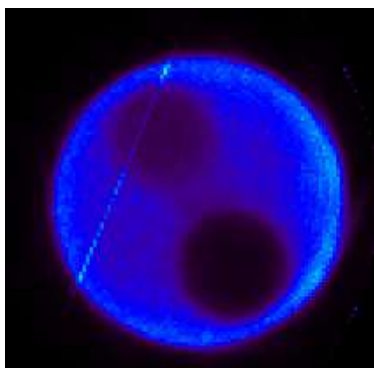
- Use of OpenMP
  - Calculation of sensitivity image
  - Reconstruction
- Cache in RAM listmode file
  - Simplification of listmode data.
  - Event bundles: struct{Bin, float}
  - Parallel processing
  - Write / Load from HDD
    - Agnostic to original data format
    - Permits data sharing when exact IO is not known



# Adapting scatter to BlocksOnCylindrical geometry

- Scatter estimation does not use SSRB to downsample but uses segment 0
- Downsample scanner only in axial direction and remove gaps
- Upsample of m coordinate done via nearest neighbour interpolation -> no need of inverse SSRB

Reconstructed phantom



*Image courtesy of E. Mikhaylova, Positron*

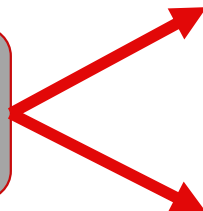
# Templating function for normalisation

Void Function(ProjDataInfoCylindricalNoArcCorr&, ...)



```
template <class TProjDataInfo>  
Void Function(TProjDataInfo&, ...)
```

TProjDataInfo



ProjDataInfoCylindricalNoArcCorr

ProjDataInfoBlocksOnCylindricalNoArcCorr

# STIR 6.0

Main feature: TOF (*Nikos Efthimiou, Elise Emond et al.*)

Current status:

- almost up-to-date with master
- recently enabled symmetries and caching
  - resulting in speed-up
    - Most when enabling caching but need lots of memory
- “awkward” loops

# Other PRs (in progress)

Pinhole SPECT

*Matthew Strugari and Carlés Falcón*

Alternative MCIR implementation (using adjoint warping as opposed to inverse)

*Richard Brown and Kris Thielemans*

Axial effects in ECAT8 normalisation

*Kris Thielemans*

Multiple bed position support

*Ashley Gillman et al.*

# STIR 7.0 (in progress)

Multiple energy window support for PET  
*Ludovica Brusaferrì et al.*

- Data structures
- Scatter simulation
- gradients of projector and scatter estimator w.r.t. emission and attenuation image  
=> MLAA using energy information



# Other things that we want/need

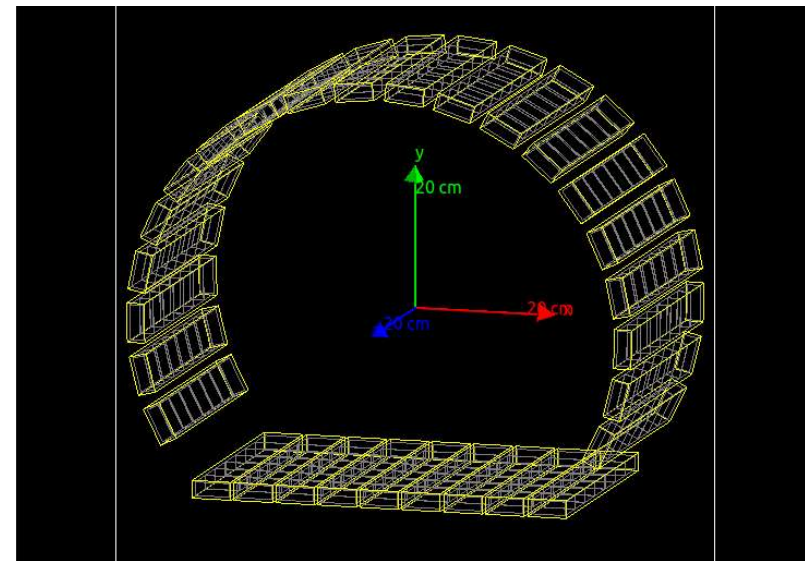
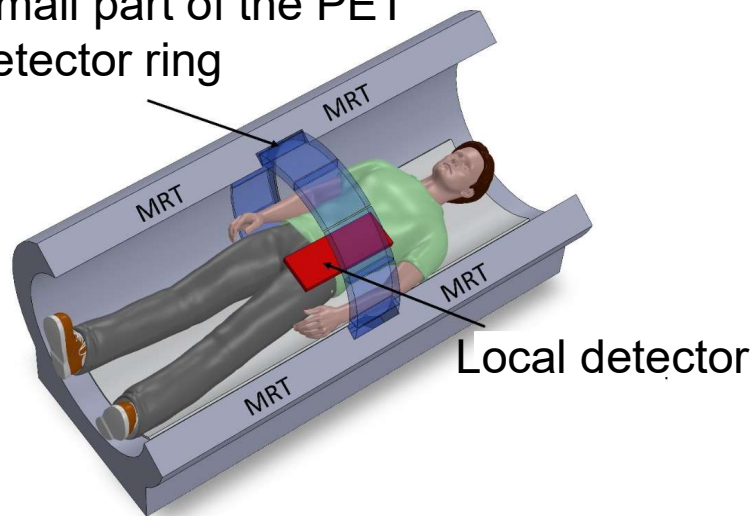
- Finalise calibration to obtain kBq/ml
- Include dead-time modelling for scanners
- Multi-detector layer support
- Easy deployment  
(increasing reliance on dependencies makes this harder)
  - Conda (done)
  - Pip
  - Docker/VM (done via [SIRF-SuperBuild](#), but could be made STIR-specific)
- Updating of STIR-Exercises

# HD-MetaPET - LAFOV PET/MRI

Florian Mueller, Stephan Naunheim & Yannick Kuhl on behalf of the HD-MetaPET Team

- Integration of non-cylindrical PET in a clinical MRI system
- Large axial FOV
- Local detector as “booster” for PET spatial resolution

Small part of the PET  
detector ring



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# Contributing to STIR, SIRF ...

- Ask questions
- Answer questions
- Test new (and old) functionality
- File bug reports
- Add use cases to wiki
- Participate in discussions on code, design etc
- Solve some small “issue”
- Join in a (virtual) hackathon
- Contribute a feature

# Why contribute to STIR?

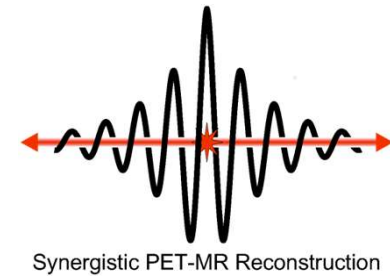
- Join a friendly community
- Advance STIR and therefore science
- Feel good about yourself
- Get credit for your work and advance your CV
- Get citations for your contributions
- Get funding for travel and exchanges
- Get one of the yearly SyneRBI awards (£400, £200, £100)

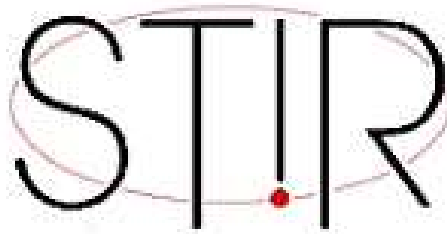
# Acknowledgments

## File formats

- GE Healthcare
- Siemens Healthineers

EPSRC CCP-SyneRBI provides resources for networking, travel exchanges and research software engineer support (mostly dedicated to SIRF and its ecosystem)





Main publication:

Thielemans, Tsoumpas, *et al* (2012) STIR: Software for Tomographic Image Reconstruction Release 2, *Physics in Medicine and Biology*, 57(4):867-83.

But please cite

- relevant papers on STIR features that you use.
- version specific DOI (includes all authors to that version)

[STIR: Software for Tomographic Image Reconstruction | Zenodo](#)

