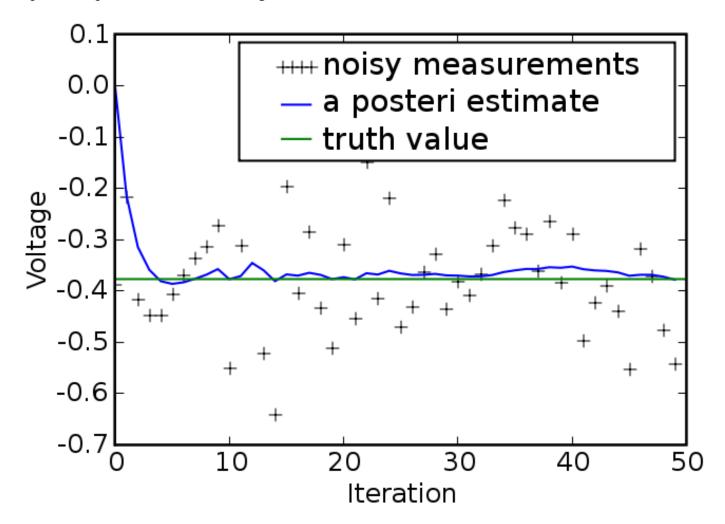
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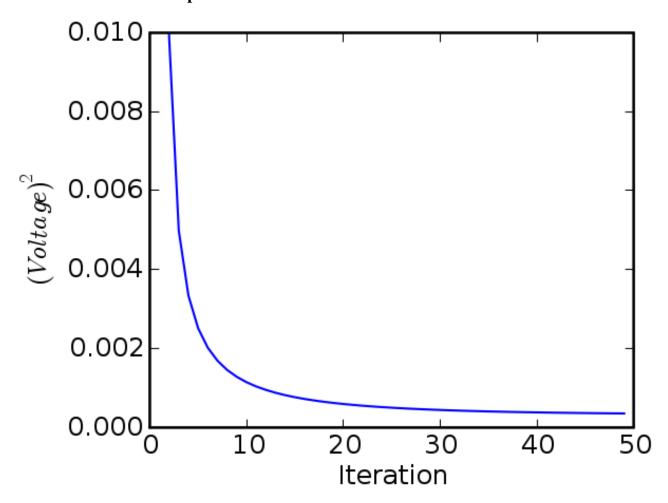
Cookbook / KalmanFiltering

This is code implements the example given in pages 11-15 of An Introduction to the Kalman Filter by Greg Welch and Gary Bishop, University of North Carolina at Chapel Hill, Department of Computer Science.

It produces plots that look something like this:



Estimate vs. iteration step



Estimated *a priori* error vs. iteration step

```
# Kalman filter example demo in Python

# A Python implementation of the example given in pages 11-15 of "An
# Introduction to the Kalman Filter" by Greg Welch and Gary Bishop,
# University of North Carolina at Chapel Hill, Department of Computer
# Science, TR 95-041,
# http://www.cs.unc.edu/~welch/kalman/kalmanIntro.html

# by Andrew D. Straw

import numpy
import pylab

# intial parameters
n_iter = 50
sz = (n_iter,) # size of array
x = -0.37727 # truth value (typo in example at top of p. 13 calls
```

```
this z)
z = numpy.random.normal(x, 0.1, size=sz) # observations (normal about)
x, sigma=0.1)
Q = 1e-5 \# process variance
# allocate space for arrays
xhat=numpy.zeros(sz) # a posteri estimate of x
                        # a posteri error estimate
P=numpy.zeros(sz)
xhatminus=numpy.zeros(sz) # a priori estimate of x
Pminus=numpy.zeros(sz) # a priori error estimate
                    # gain or blending factor
K=numpy.zeros(sz)
R = 0.1**2 # estimate of measurement variance, change to see effect
# intial guesses
xhat[0] = 0.0
P[0] = 1.0
for k in range(1, n iter):
    # time update
    xhatminus[k] = xhat[k-1]
    Pminus[k] = P[k-1]+Q
   # measurement update
    K[k] = Pminus[k]/(Pminus[k]+R)
    xhat[k] = xhatminus[k]+K[k]*(z[k]-xhatminus[k])
    P[k] = (1-K[k])*Pminus[k]
pylab.figure()
pylab.plot(z,'k+',label='noisy measurements')
pylab.plot(xhat, 'b-', label='a posteri estimate')
pylab.axhline(x,color='g',label='truth value')
pylab.legend()
pylab.xlabel('Iteration')
pylab.ylabel('Voltage')
pylab.figure()
valid iter = range(1,n iter) # Pminus not valid at step 0
pylab.plot(valid iter,Pminus[valid iter],label='a priori error
estimate')
pylab.xlabel('Iteration')
pylab.ylabel('$(Voltage)^2$')
pylab.setp(pylab.gca(),'ylim',[0,.01])
pylab.show()
```

CategoryCookbook

Cookbook/KalmanFiltering (last edited 2006-07-24 00:52:56 by AndrewStraw)