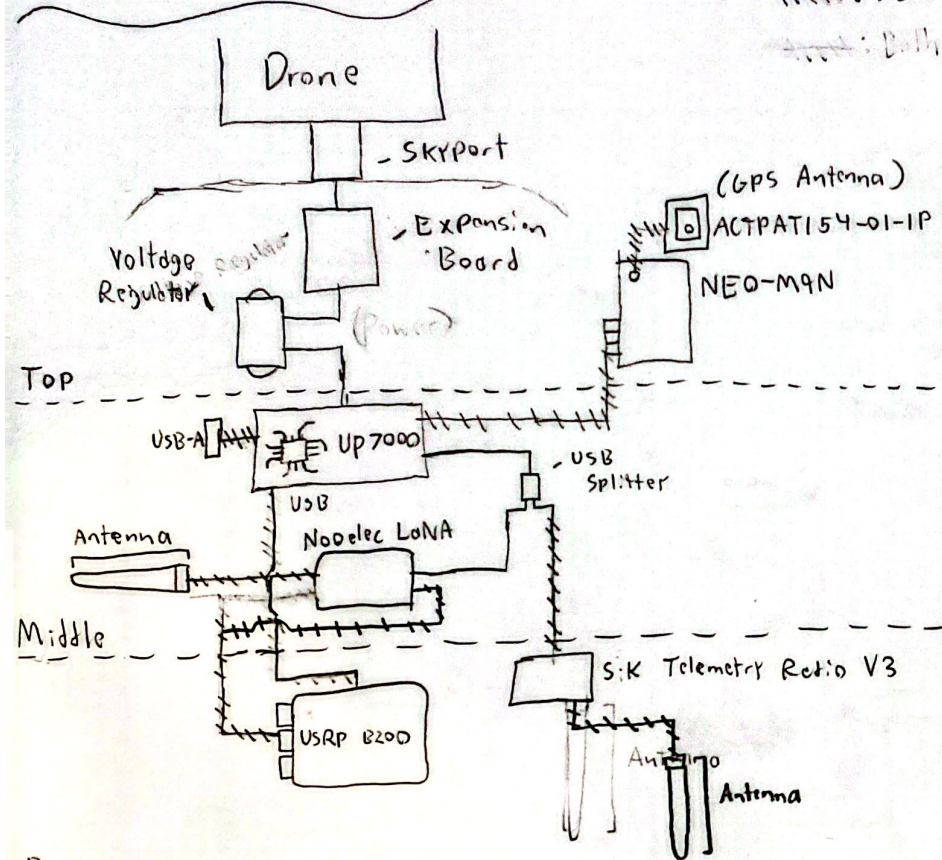


# RTT Drone Payload Updated CAD Design - Preliminary Sketch

## General System Overview



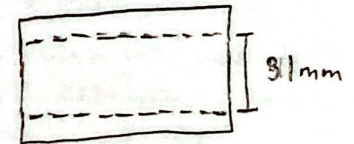
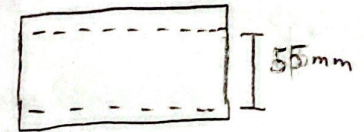
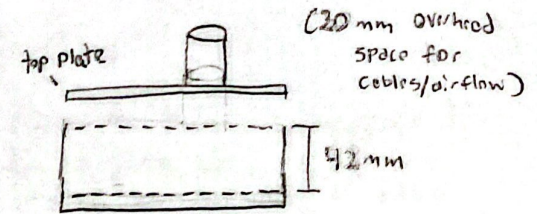
## Cables

IN: Power Cable (SKYport)  
 OUT: Regulator Wires  
 GPS Wire connectors

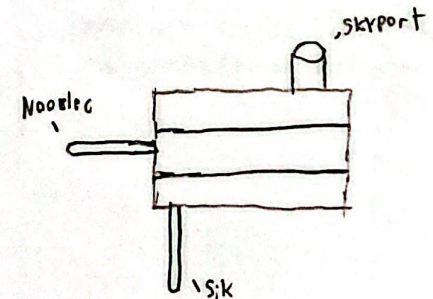
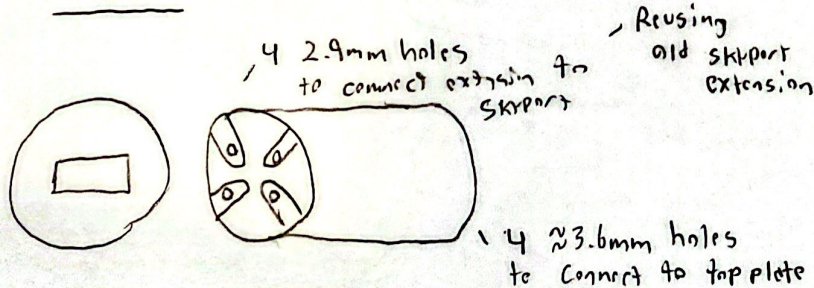
IN: Regulator Wires  
 GPS Wire Connectors

OUT: USB Cable (Sik Radio)  
 SMA Connector to USRP  
 USB Cable to USRP

IN: USB Cables (Sik Radio)  
 SMA Connector to USRP  
 USB Cable to USRP



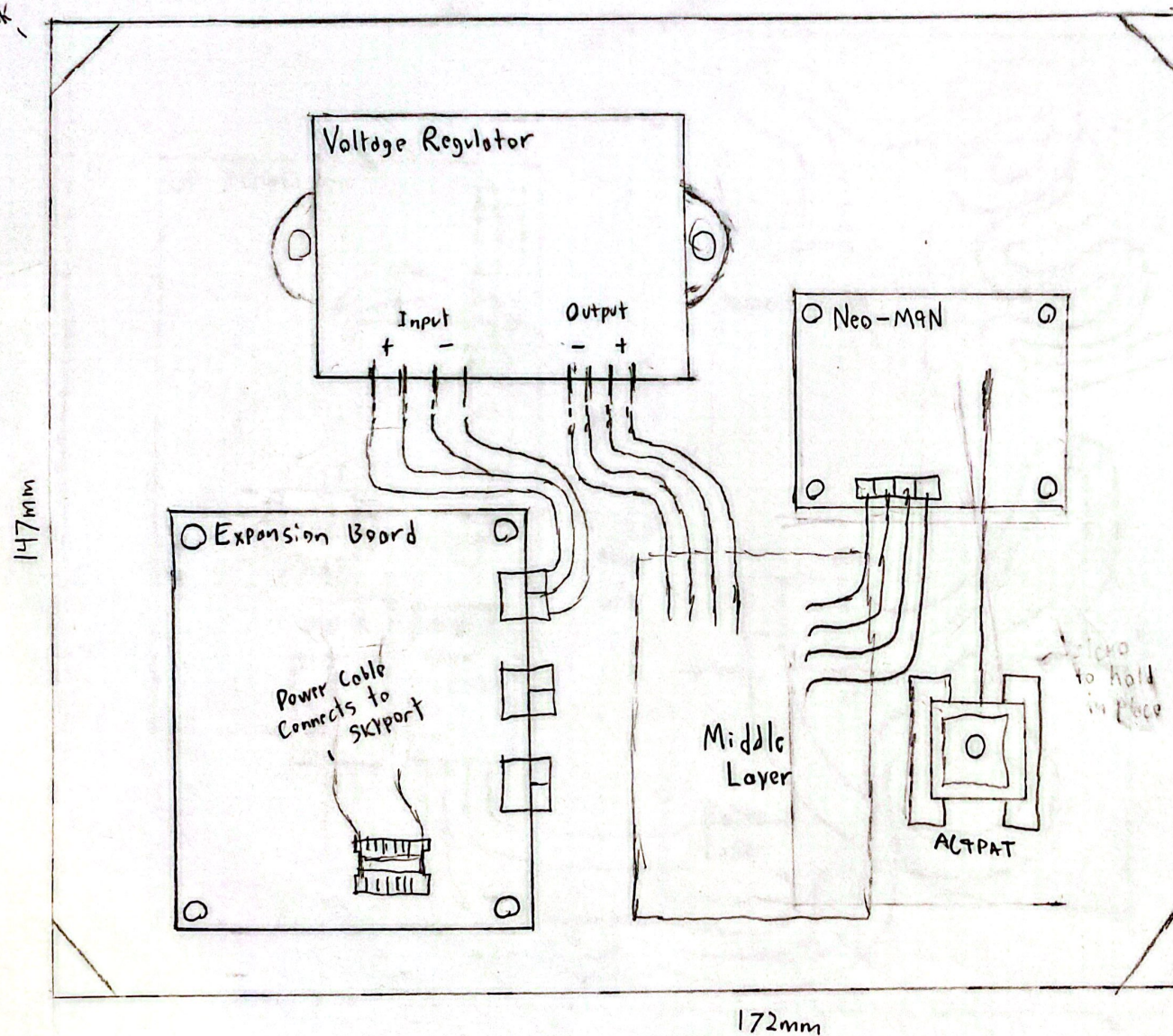
## SKYport





# Top Layer Sketch

Back



Front

## Mounting

- Velcro for ACTPAT
- 2 4.06mm holes for regulator
- 4 3.5mm holes for expansion board.
- 4 3.5mm holes for Neo-MAN

## Routing

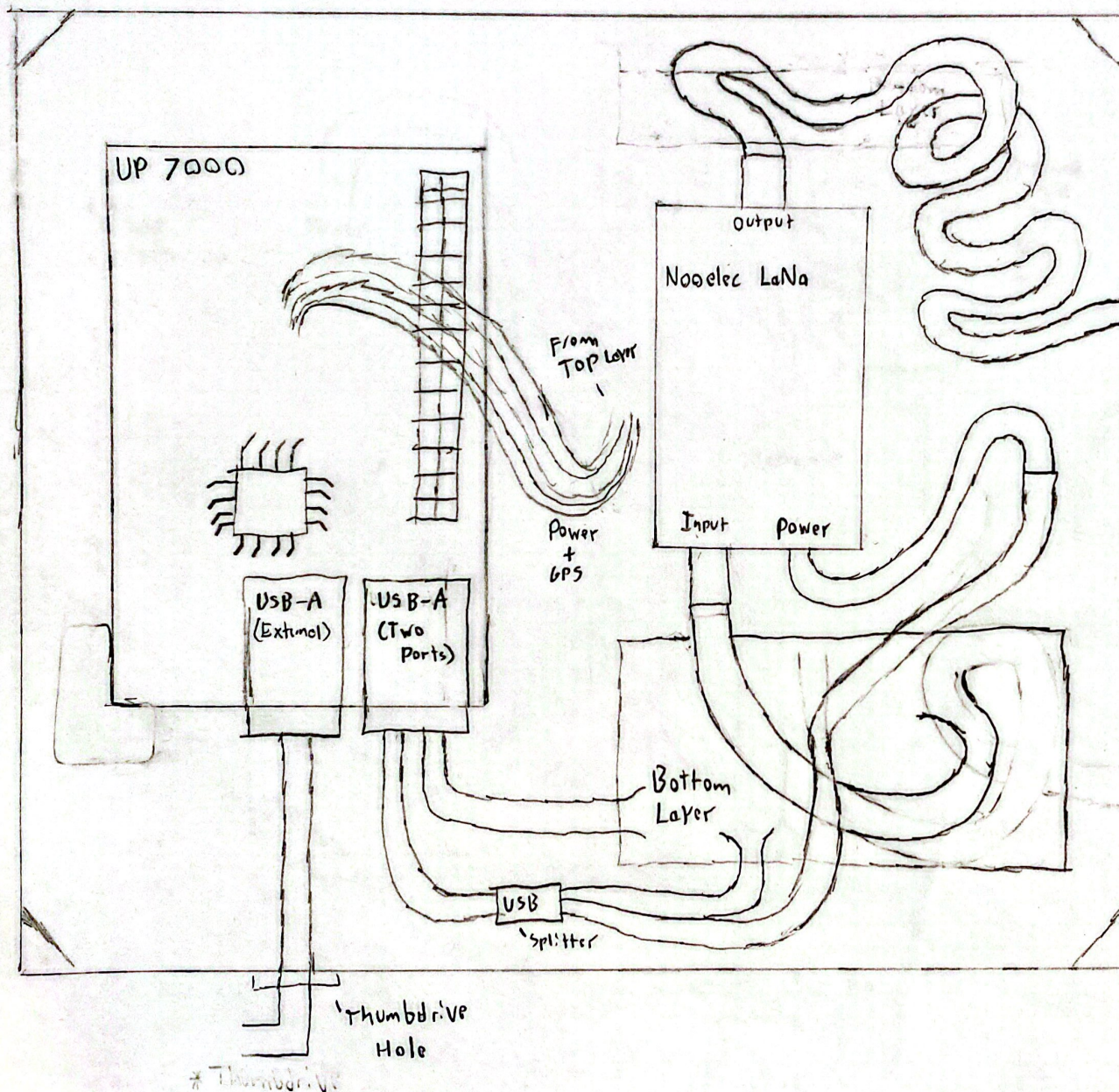
- All cables going out will go through a hole connecting the top and middle layer.
- Power cable will come from skyport to provide power to payload

## Notes

- Updated design will use the same/similar socket heads to screw each layer in place, 4 3.6mm holes



# Middle Layer Sketch



## Mounting

- Velcro for Nooelec LaNa since it has no screw holes.
- Friction fit for the UP 7000.

## Routing

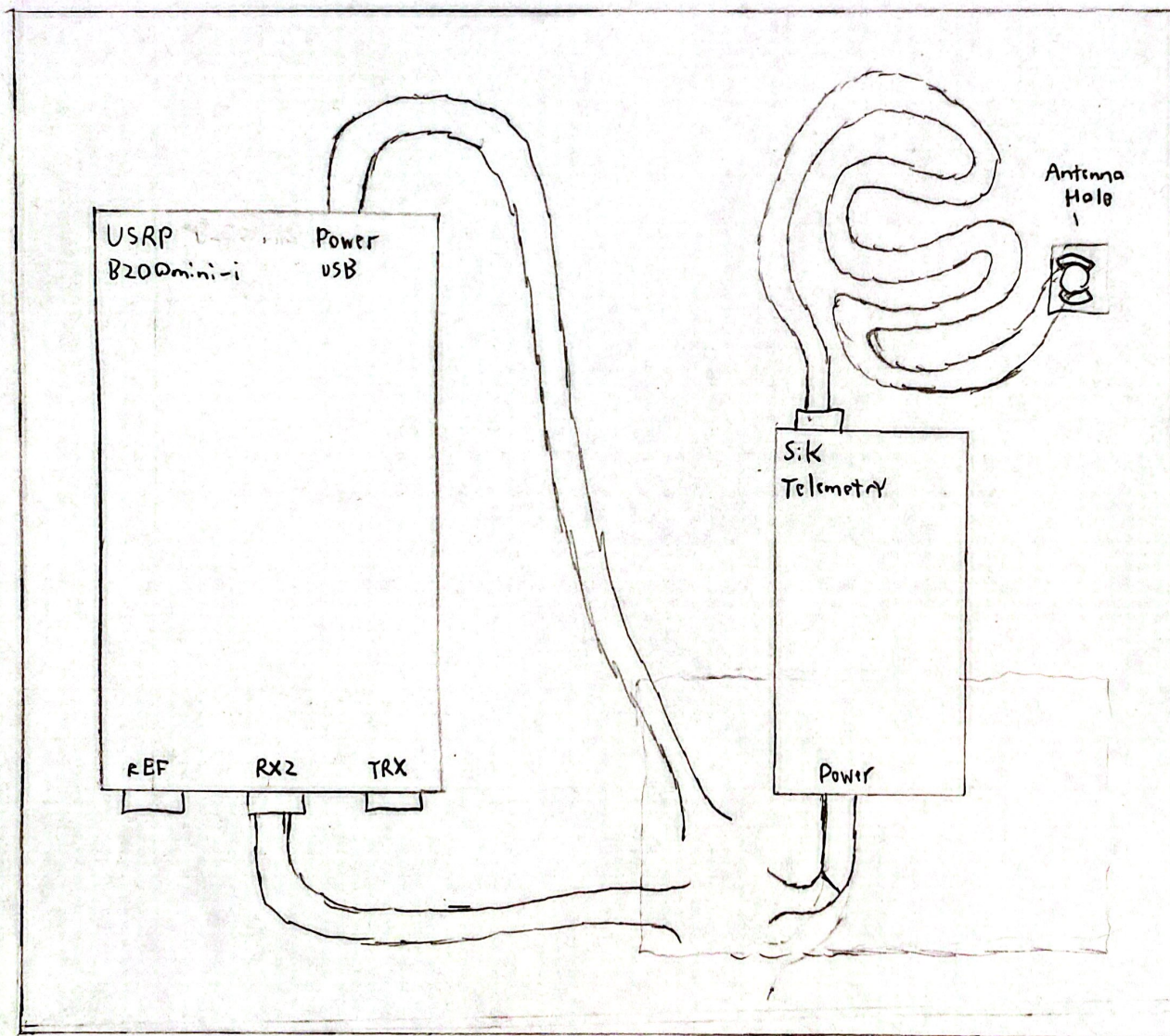
- Cables from top layer all connect to the UP7000.
- One USB-A port saved for thumbdrive access externally, as well as a hole for Antenna via SMA.
- One hole leading to bottom layer, input of Nooelec LaNa, and two usb cables (1 male & 1 female) for power.

## Notes

- USB splitter is 1 male → 2 female
- USB-A external will need some space away from thumbdrive hole



# Bottom Layer Sketch



## Mounting

- Velcro or friction fit may be used for the USRP and SIK Radio, due to lack of screw holes

## Routing

- Cables from the middle layer come through a hole, 2 usb cables to power the USRP & SIK radio.
- A cable from the Noelec LoRa connects to the USRP.
- An SMA cable from the SIK Radio connects to an external antenna from the bottom.