

Week 7: Item Response Theory

PLSC 40502 - Statistical Models

Review

Previously

- **Cluster models**
 - "Unsupervised" learning of patterns in data
 - Estimation via Expectation-Maximization
- **Topic Modeling**
 - Finite mixture model of text
 - Documents are modeled as mixtures of "topics" and topics are distributions over words
 - Estimation via Variational EM

This week

- Item Response Theory
 - Model **discrete** responses as a function of continuous **latent** attributes
 - Logit/probit regression with **unobserved** regressors
- Ideal point models
 - Item response theory applied to **legislative voting**
 - Interpreting the latent dimensions

Item Response Theory

Item Response Theory

- In many settings, we observe **binary** or **ordinal** responses to a set of questions among a sample of units.
 - Students' responses to test questions (correct/incorrect)
 - Expert ratings of countries
 - Legislators voting on bills
- In these settings, we're interested in learning about an (interval scaled) **latent trait** of the units based on their discrete responses
 - Measuring student **ability**
 - Measuring country **characteristics**
 - Measuring legislator **ideology**
- Simple aggregation of the binary responses may give misleading results
 - Some test questions are **harder** than others and provide more information about student ability than questions that everyone gets correct.
 - Averages of ordinal ratings don't have an **interval** interpretation (the distances aren't meaningful)

Item Response Theory

- **Item Response Theory** (IRT) developed out of research on testing and evaluation.
- Observed responses to test questions are a function of:
 - **Latent traits** that are common features of respondents across all questions
 - **Item parameters** that are common features of questions across all respondents.
- **Setup:**
 - Observe N respondents indexed by $i \in \{1, 2, \dots, N\}$
 - Observe J questions indexed by $j \in \{1, 2, \dots, J\}$
 - Observe Y_{ij} responses to question i by respondent j
 - We'll work with binary Y_{ij} to start, but can generalize to other outcome distributions (typically ordinal)

One Parameter Logit (1PL)

- The baseline classic IRT model (sometimes called the "Rasch" model after Georg Rasch) assumes the following **item response function**:

$$Pr(Y_{ij} = 1) = F(\theta_i - \alpha_j)$$

where $F()$ is the logistic CDF.

- In other words,

$$Pr(Y_{ij} = 1) = \frac{1}{1 + \exp[-(\theta_i - \alpha_j)]}$$

- Or in "latent variable form"

$$Y_{ij} = \mathbf{1}(Y_{ij}^* > 0)$$

$$Y_{ij}^* = \theta_i - \alpha_j + \epsilon_{ij}$$

where ϵ_{ij} are distributed i.i.d. standard logistic

- Note that alternate $F()$ are common - such as i.i.d. normal ϵ_{ij} which yields the probit version

One Parameter Logit (1PL)

- In the 1PL model, we have **one** parameter describing the item and **one** parameter describing the individual's latent trait

$$Pr(Y_{ij} = 1) = F(\theta_i - \alpha_j)$$

- θ_i is the **latent trait** from unit i
- α_j is the **item difficulty** of question j
- Analogy to the GLM
 - α_j is the **intercept** for task j
 - θ_i is the **regressor** common across all i
 - What are we implicitly assuming?

Two Parameter Logit (2PL)

- One drawback of the 1PL model is that it only allows questions to vary in their difficulty (intercept) and not in the extent to which variation in the responses captures variation in the latent parameters.
 - Essentially assuming a constant "slope" of 1 on the θ parameter
 - But some questions might be bad at capturing θ even if there's variation in Y_{ij} .
- The two-parameter logit adds an additional **item parameter** β_j and assumes

$$Pr(Y_{ij} = 1) = F\left(\beta_j(\theta_i - \alpha_j)\right)$$

- Now each item has:
 - α_j - **item difficulty**
 - β_j - **item discrimination**
- β_j captures the extent to which the question reflects the latent trait
 - β_j close to 0 means that the probability of $Y_{ij} = 1$ is essentially uncorrelated with the latent trait
 - **Negative** β_j implies that **low** latent trait values are more likely to answer $Y_{ij} = 1$ (this creates some identifiability issues!)

Two Parameter Logit (2PL)

- Typically also see the 2PL written as:

$$Pr(Y_{ij} = 1) = F\left(\beta_j\theta_i - \tau_j\right)$$

- Think back again to the logistic regression
 - τ_j is the "intercept"
 - β_j is the "slope"
 - θ_i is the "regressor"

Identification

- While historically, IRT models were estimated via maximum-likelihood, there are many reasons why modern methods use Bayes.
 1. **Inconsistency** - The number of parameters grows as we add more **questions** and as we add more **respondents** so our ML estimators are not consistent
 2. **Non-identifiability** - The 2PL likelihood is invariant to any rescaling of the latent parameters
 - Can multiply all θ by a constant and not change the likelihood
 - Multiplying by -1 changes the interpretation of θ but not the likelihood.
- Putting a prior on θ allows for identification
 - Typically assume $\theta \sim \text{Normal}(0, 1)$
- Also need an additional constraint:
 - Either constraints on β ...
 - ...or setting some of the θ parameters to a **known** value

Estimation

- Estimation typically relies on either MCMC or a Variational EM algorithm
 - The underlying **trick** is to use existing theory for Bayesian probit (and now logit) regression to derive the conditional distributions of θ_i , β_j and τ_j
- Consider the "latent variable" form of the logit/probit regression:

$$Y_{ij}^* = \beta_j \theta_i - \tau_j + \epsilon_{ij}$$

- Conditional on θ_i , we have a regression of Y_{ij}^* on θ_i with intercept $-\tau_j$ and slope β_j
- Conditional on β_j and τ_j , we have a regression of $Y_{ij}^* + \tau_j$ on β_j with slope θ_i and no intercept.

Interpretation as a voting model

- In political science, the 2 parameter logit is the standard IRT model for analyzing voting in legislatures
- Often described in terms of **utility maximization**
 - Consider a legislator choosing to vote "Yea" $Y_{ij} = 1$ or "Nay" $Y_{ij} = 0$.
 - These positions are located in some space (we'll work in \mathbb{R}^1 for now). The "Yea" position is ζ_j and the "Nay" position is ψ_j .
- Define a utility function for legislator i : $U_i()$
 - $U_i(\zeta_j) = -\frac{1}{\sigma_j}(\theta_i - \zeta_j)^2 + \eta_{ij}$
 - $U_i(\psi_j) = -\frac{1}{\sigma_j}(\theta_i - \psi_j)^2 + \nu_{ij}$
- In other words, they get decreasing utility (in terms of quadratic distance) from policies that are further from their **ideal point**
 - They will vote $Y_{ij} = 1$ if $U_i(\zeta_j) > U_i(\psi_j)$ and $Y_{ij} = 0$ otherwise.
- η_{ij} and ν_{ij} are the "vote-specific error terms"

Interpretation as a voting model

- Returning to the "latent variable" formulation of the logit, we can write: $Y_{ij}^* = U_i(\zeta_j) - U_i(\psi_j)$
- Then, some algebra

$$Y_{ij}^* = -\frac{1}{\sigma_j}(\theta_i - \zeta_j)^2 + \eta_{ij} + \frac{1}{\sigma_j}(\theta_i - \psi_j)^2 - \nu_{ij}$$

$$Y_{ij}^* = \frac{1}{\sigma_j}(-\theta_i^2 + 2\theta_i\zeta_j - \zeta_j^2) + \frac{1}{\sigma_j}(\theta_i^2 - 2\theta_i\psi_j + \psi_j^2) + (\eta_{ij} - \nu_{ij})$$

$$Y_{ij}^* = \frac{2(\zeta_j - \psi_j)}{\sigma_j}\theta_i + \frac{(\psi_j^2 - \zeta_j^2)}{\sigma_j} + (\eta_{ij} - \nu_{ij})$$

- And with some assumptions on the error distribution of $\epsilon_{ij} = (\eta_{ij} - \nu_{ij})$ we have our 2-parameter logit!
 - $\tau_j = -\frac{(\psi_j^2 - \zeta_j^2)}{\sigma_j}$
 - $\beta_j = \frac{2(\zeta_j - \psi_j)}{\sigma_j}$

Interpretation as a voting model

- One implicit assumption in the IRT model is a **conditional independence** assumption in responses given the latent ideology.

$$Pr(Y_{ij} = 1, Y_{ij'} = 1 | \theta_i, \beta, \tau) = Pr(Y_{ij} = 1 | \theta_i, \beta, \tau) \times Pr(Y_{ij'} = 1 | \theta_i, \beta, \tau)$$

- In other words, knowing how a legislator voted on bill j doesn't tell you anything about how they will vote on bill j' if we already know the latent positions of the legislators and bills
 - Could be violated under common legislative behavior (e.g. log-rolling, horse-trading, etc...)
 - You'll still get **something** but interpreting ideal points in this setting is a bit harder - essentially some of the "closeness" in ideal points could be driven by non-ideological factors.
 - The "utility maximization" interpretation of the 2PL also implies **single peaked** preferences
 - Legislators strictly prefer policies closer to their ideal point and disprefer ones that are further away
 - But this assumption can be violated if some extreme legislators vote against their party and with the opposition but for differing reasons
 - "Ends against the middle"
 - See **Duck-Mayr and Montgomery (2023)** for a model that tries to account for this.

Example: Improving Polity

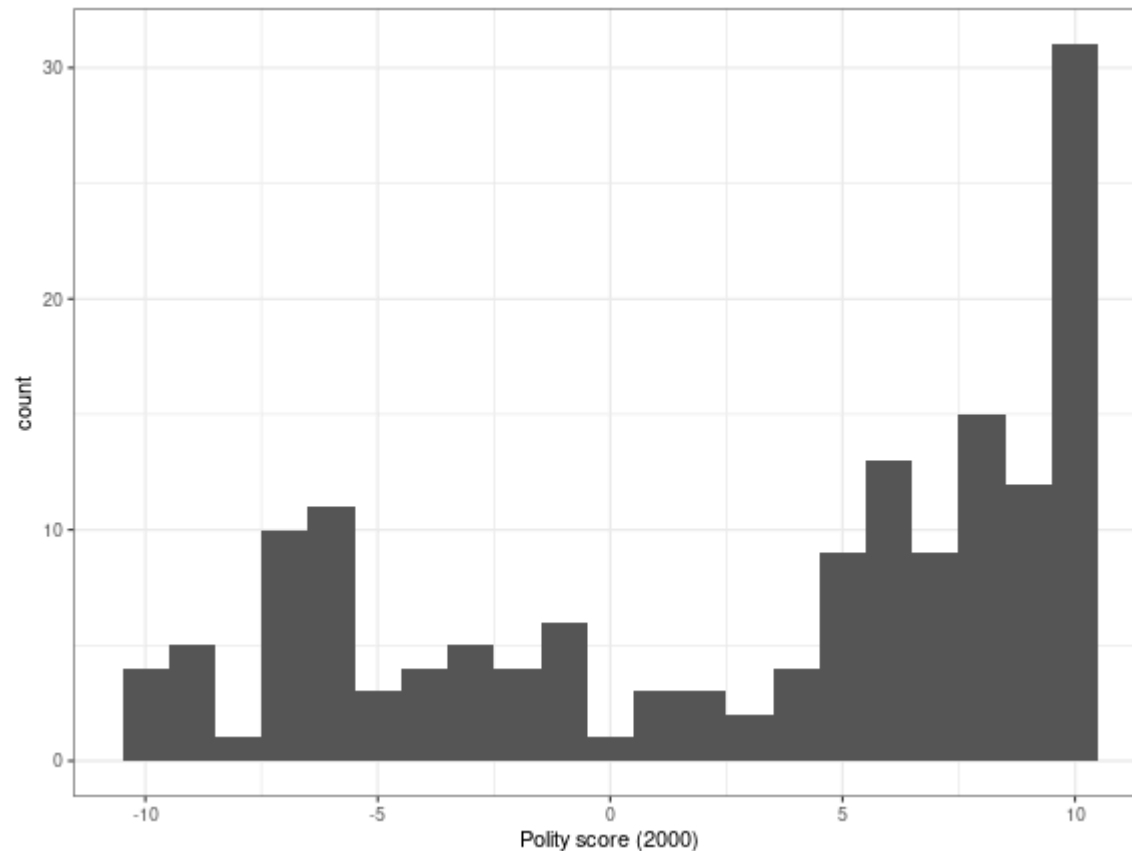
- Trier and Jackman (2008) critique the common use of Polity scores as a measure of democracy.
 - Problem of **aggregation** - naively combining the discrete, coded, measures by averaging understates measurement error and may provide a misleading measure of "democratization"
 - Instead propose modeling democracy as a **latent trait** with Polity codings as "expressions" of that latent trait.
- Let's take a look at the most recent Polity data

```
polity <- read_spss("data/p5v2018.sav")  
polity2000 <- polity %>% filter(year == 2000) %>% filter(polity != -88 & polity != -77 & polity != -66)
```

- Polity scores are a **composite** of a set of ordinal measures related to
 1. Executive recruitment
 2. Executive constraint
 3. Political competition

Example: Improving Polity

- The standard approach is to **aggregate** these scores into a "democracy" and an "autocracy" index that are added together to yield a score from -10 to 10



Example: Improving Polity

- The component scores are often not independent of one another
 - For example, "xropen" captures the extent to which executive elections are "open" but it's partially constrained by "xrcomp", the competitiveness of executive recruitment.

```
table(polity2000$xropen, polity2000$xrcomp)
```

```
##  
##      0  1  2  3  
## 0 24  0  0  0  
## 1  0  6  0  0  
## 2  0  5  0  0  
## 3  0  0  2  0  
## 4  0 20 33 65
```

Example: Improving Polity

- **Trier and Jackman (2008)** settle on three ordinal indices constructed from the Polity components as the latent "tasks" for their IRT model

```
table(polity2000$exrec)
```

```
##  
##  1  2  3  4  5  6  7  8  
##  6  5 20 14 10  2 33 65
```

```
table(polity2000$exconst)
```

```
##  
##  1  2  3  4  5  6  7  
## 15 13 26  8 25 18 50
```

```
table(polity2000$polcomp)
```

```
##  
##  1  2  3  4  5  6  7  8  9 10  
## 16 19  7  1  1 18 15 10 35 33
```

- Each of these ordinal indicators is modeled as an expression of some underlying latent "democracy" variable

Example: Improving Polity

- The model used in the paper is a **two-parameter** ordinal logit.
 - Index country-year by i , Polity indicator by j , and the K_j ordinal categories by k .
 - Latent "democracy" variable θ_i and latent "item discrimination parameter" β_j
- The probability of observing a rating for country i on indicator j , Y_{ij} is:

$$\begin{aligned} Pr(Y_{ij} = 1) &= F(\tau_{j1} - \theta_i \beta_j) \\ &\vdots \\ Pr(Y_{ij} = k) &= F(\tau_{jk} - \theta_i \beta_j) - F(\tau_{j,k-1} - \theta_i \beta_j) \\ &\vdots \\ Pr(Y_{ij} = K_j) &= 1 - F(\tau_{j,K_j-1} - \theta_i \beta_j) \end{aligned}$$

where $F()$ is the logistic CDF and $\tau_{j1} < \tau_{j2} < \dots < \tau_{j,K_j-2} < \tau_{j,K_j-1}$ are a set of ordered cut-points for indicator j

Example: Improving Polity

- Let's implement this for 2000 in Stan (we could do a full model for the entire Polity dataset, but that takes longer to run)
- First, the data block

```
data{  
  int<lower=1> N; // number of countries  
  int<lower=1> K[3]; // number of categories per task  
  int<lower=1> Y[N,3]; // responses to each task (hard-coding 3 tasks)  
}
```

Example: Improving Polity

- For the parameters, we'll define θ and β as usual...
 - ...but we'll use a trick to re-parameterize the cutpoints to make it easier to put priors on them!

```
parameters{
  array[N] real theta; // country scores;
  array[3] real beta; // discrimination parameters;
  array[3] real delta_start; // parameterization of cutpoints;
  vector<lower=0>[K[1]-2] delta1; // parameterization of distances
  vector<lower=0>[K[2]-2] delta2;
  vector<lower=0>[K[3]-2] delta3;
}
```

Example: Improving Polity

- The cutpoints are **ordered**
 - But we want to put a prior on an **unordered** parameters
 - **Solution:** Put a normal prior on the first cutpoint and then the **distances** between each gap!
 - Use the **transformed parameters** block to generate the ordered **tau**

```
transformed parameters{  
  ordered[K[1]-1] tau1;  
  tau1[1] = delta_start[1];  
  tau1[2:] = delta_start[1] + cumulative_sum(delta1);  
  ordered[K[2]-1] tau2;  
  tau2[1] = delta_start[2];  
  tau2[2:] = delta_start[2] + cumulative_sum(delta2);  
  ordered[K[3]-1] tau3;  
  tau3[1] = delta_start[3];  
  tau3[2:] = delta_start[3] + cumulative_sum(delta3);  
}
```


Example: Improving Polity

- Lastly our model using the ordered logistic specification

```
model{
  theta ~ normal(0, 1);
  beta ~ normal(0, 3);
  delta_start ~ normal(0, 2.58);
  delta1 ~ exponential(2);
  delta2 ~ exponential(2);
  delta3 ~ exponential(2);
  for (n in 1:N) {
    Y[n,1] ~ ordered_logistic(theta[n] * beta[1], tau1);
    Y[n,2] ~ ordered_logistic(theta[n] * beta[2], tau2);
    Y[n,3] ~ ordered_logistic(theta[n] * beta[3], tau3);
  }
}
```

Example: Improving Polity

- Pass in the data

```
polity_data <- list(N = nrow(polity2000), K= apply(polity2000 %>% select(exrec, exconst, polcomp),  
               MARGIN=2, FUN=function(x) {  
                 Y= polity2000 %>% select(exrec, exconst, polcomp)  
               })
```

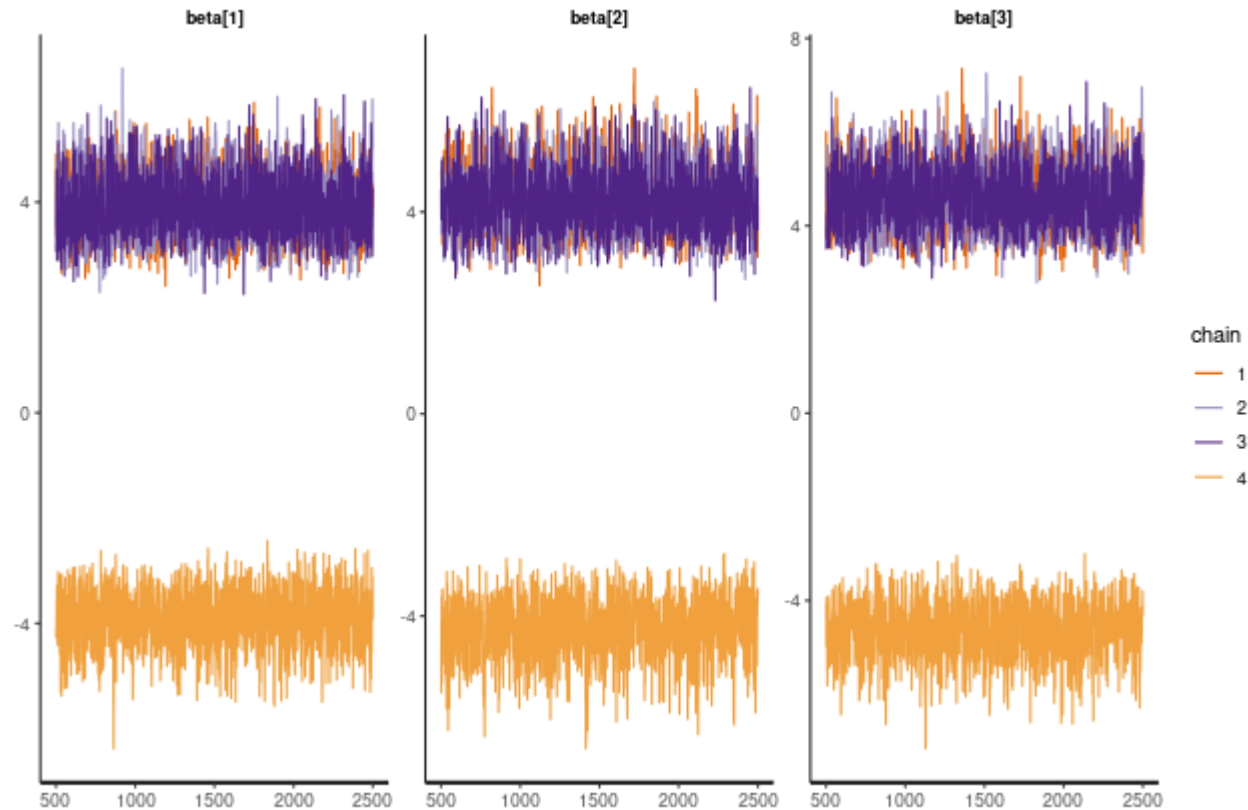
- Estimate the model (run 4 chains)
 - **Warning:** This model actually has convergence problems across the different chains

```
# This model has convergence problems  
polity_irt_bad <- stan(  
  model_code = polityirt_model, # Stan code  
  data = polity_data,           # named list of data  
  chains = 4,                   # number of Markov chains  
  warmup = 500,                 # number of warmup iterations per chain  
  iter = 2500,                  # total number of iterations per chain  
  cores = 4,                    # number of cores (could use one per chain - by default uses however  
  refresh = 0,  
  seed = 60637  
)
```

Example: Improving Polity

- What's happening here?

```
traceplot(polity_irt_bad, pars=c("beta"))
```



Example: Improving Polity

- Because the IRT model is identified only up to reflection, the MCMC ends up going to one of two posterior modes
 - β is positive and high θ reflects high democracy
 - or β is negative and high θ reflects high **autocracy**

Example: Improving Polity

- Essentially, we need to put some additional constraints on the model.
- One easy fix for this version is to make the discrimination parameters **always** positive
 - This is standard for the education/testing IRT model
 - We wouldn't want this for a voting model, but for the democracy model it's not unreasonable
 - Instead of a normal prior on β , we can use a log-normal or half-normal.
- In a voting model, we want to allow for votes to have both a positive and a negative discrimination parameter
 - Some votes have Democrats voting **Yes** and Republicans voting **No**; others have Democrats voting **No** and Republicans voting **Yes**
 - We'll instead fix some known legislators' latent ideal points to particular values using a "spike" prior

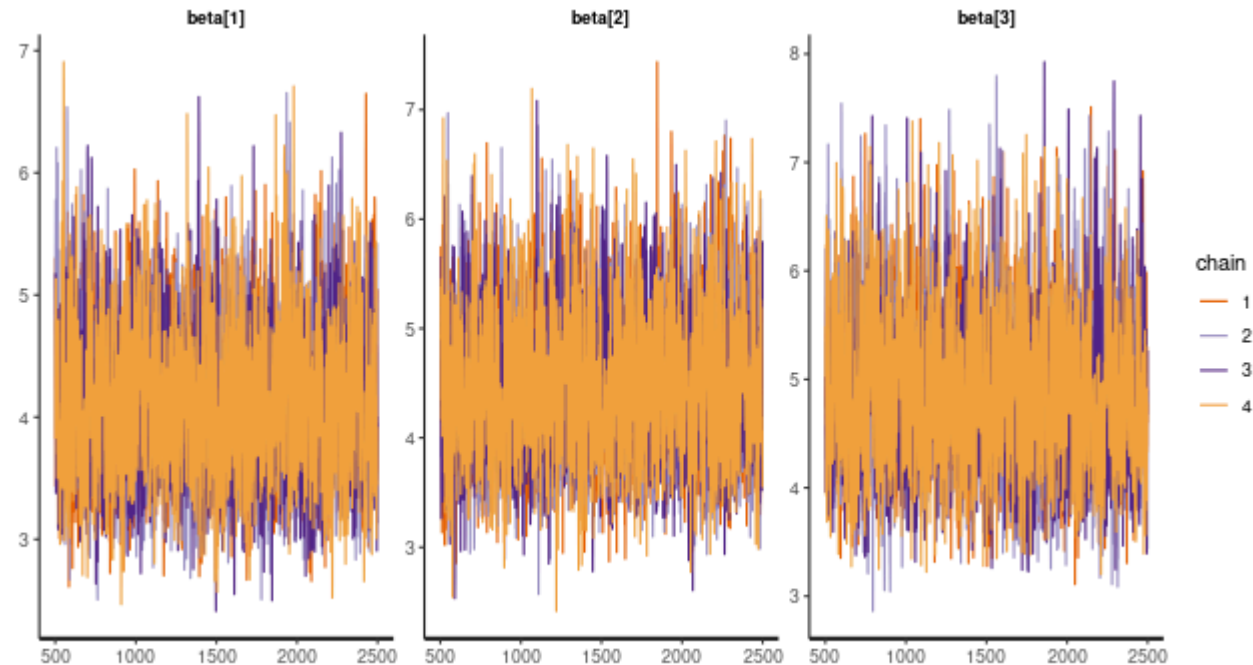
Example: Improving Polity

```
# In this model, we restrict the betas to be positive
polity_irt <- stan(
  model_code = polityirt_model_fixed, # Stan code
  data = polity_data,                # named list of data
  chains = 4,                        # number of Markov chains
  warmup = 500,                      # number of warmup iterations per chain
  iter = 2500,                       # total number of iterations per chain
  cores = 4,                         # number of cores (could use one per chain - by default uses however
  refresh = 0,
  seed = 60637
)
```

Example: Improving Polity

- Problem solved!

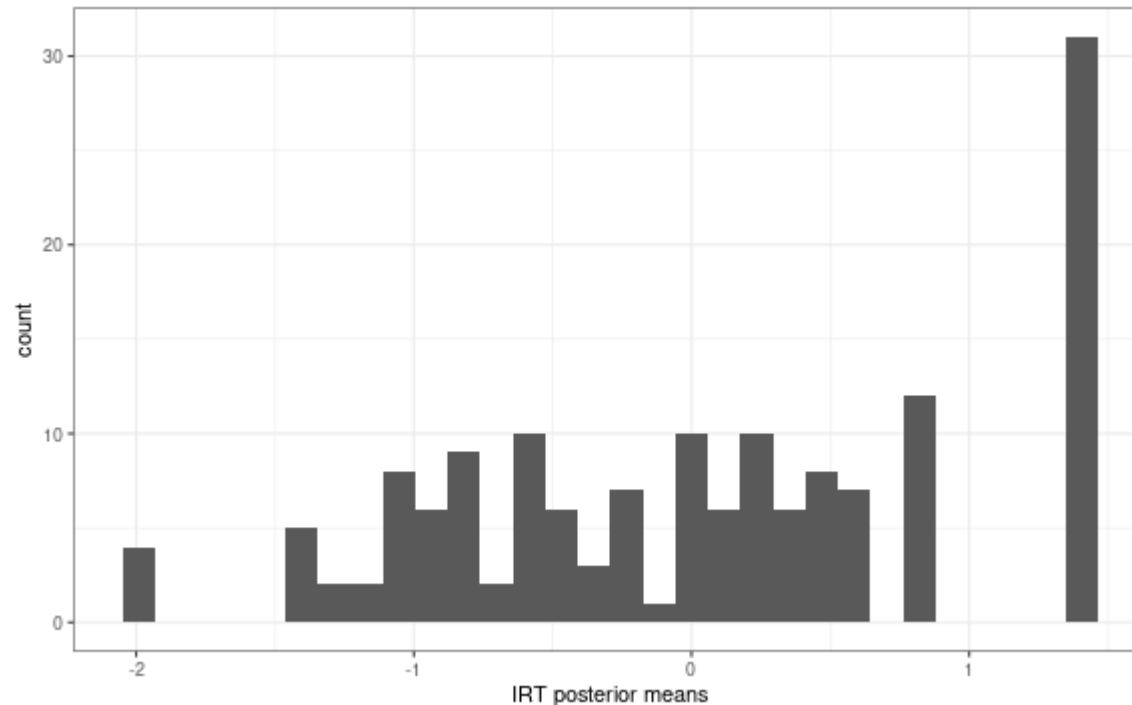
```
traceplot(polity_irt, pars=c("beta"))
```



Example: Improving Polity

- Get the latent democracy scores

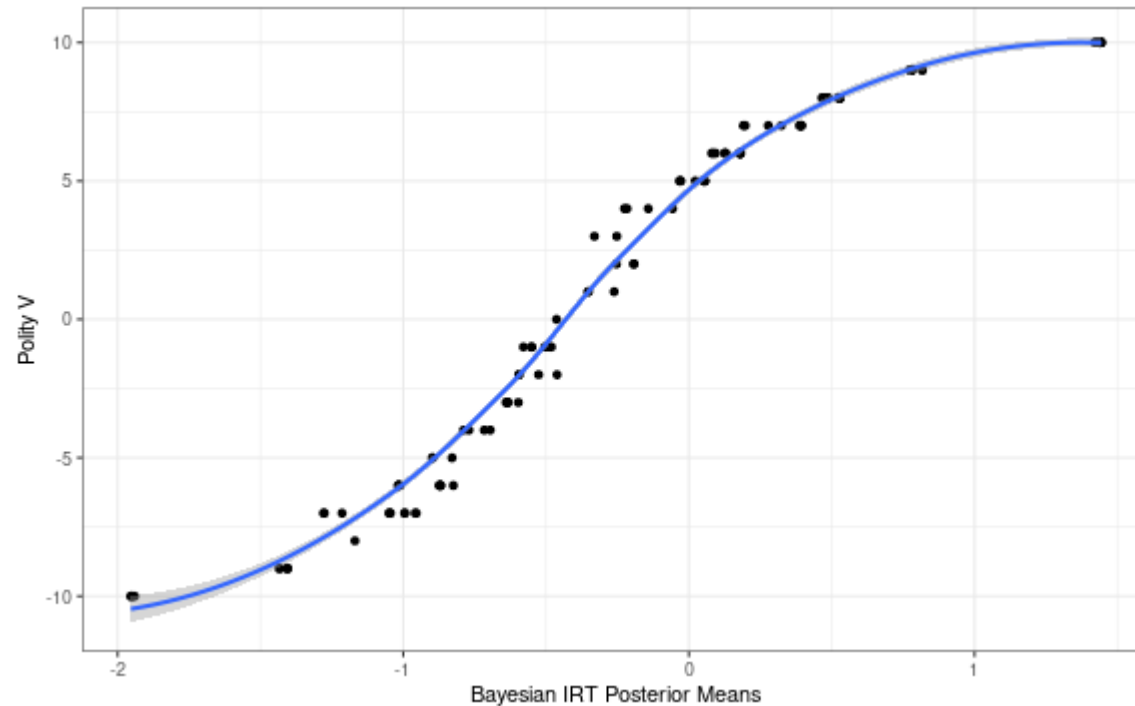
```
democracy_scores <- rstan::extract(polity_irt)$theta  
polity2000$pm_irt <- colMeans(democracy_scores)  
polity2000 %>% ggplot(aes(x=pm_irt)) + geom_histogram() + xlab("IRT posterior means") + theme_k
```



Example: Improving Polity

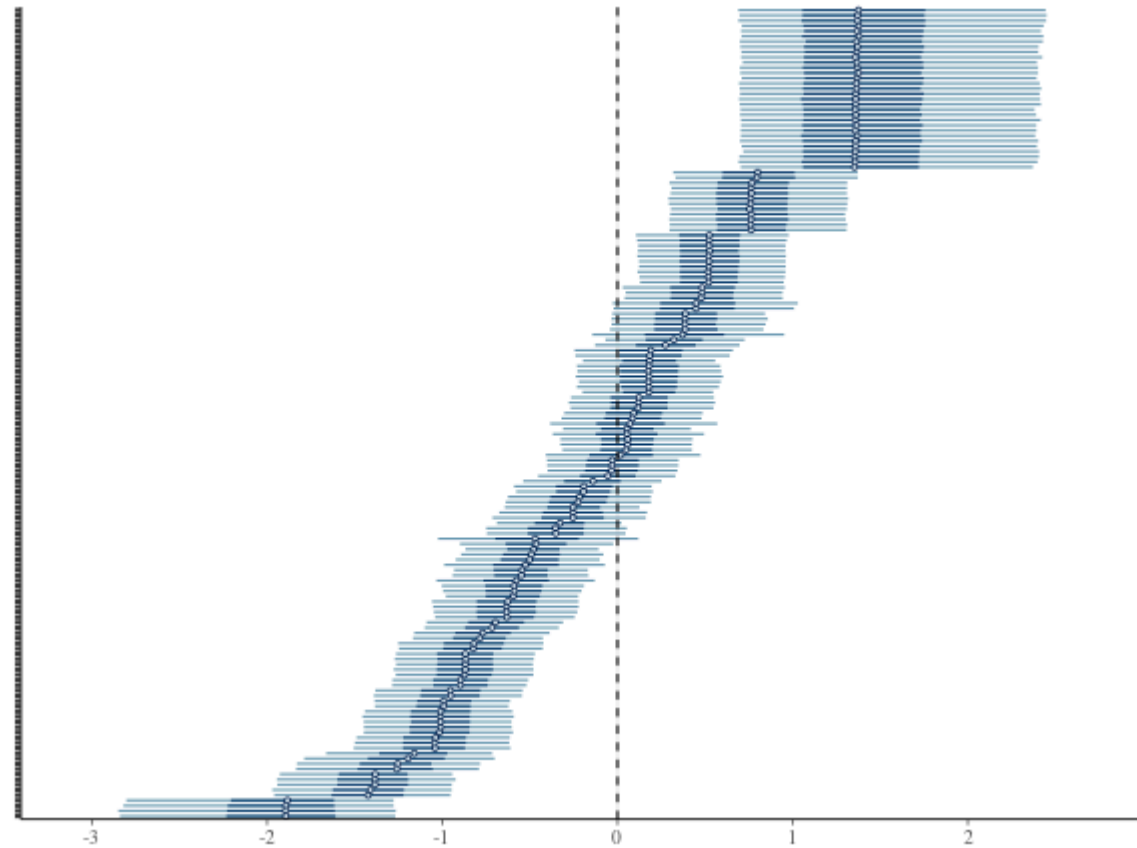
- Plot against the "Polity" scores

```
polity2000 %>% ggplot(aes(x=pm_irt, y=polity2)) + geom_point() + geom_smooth() + xlab("Bayesian IRT Posterior Means")
```



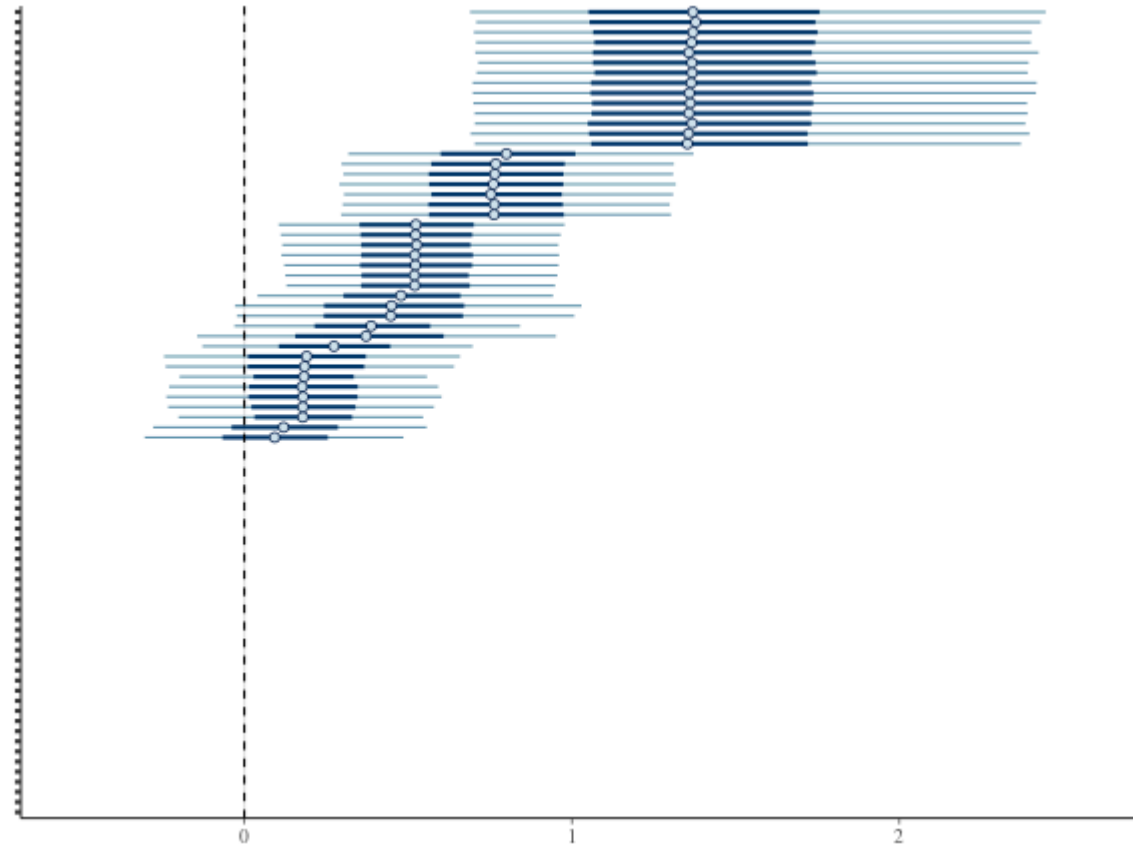
Example: Improving Polity

- Plot posteriors by country



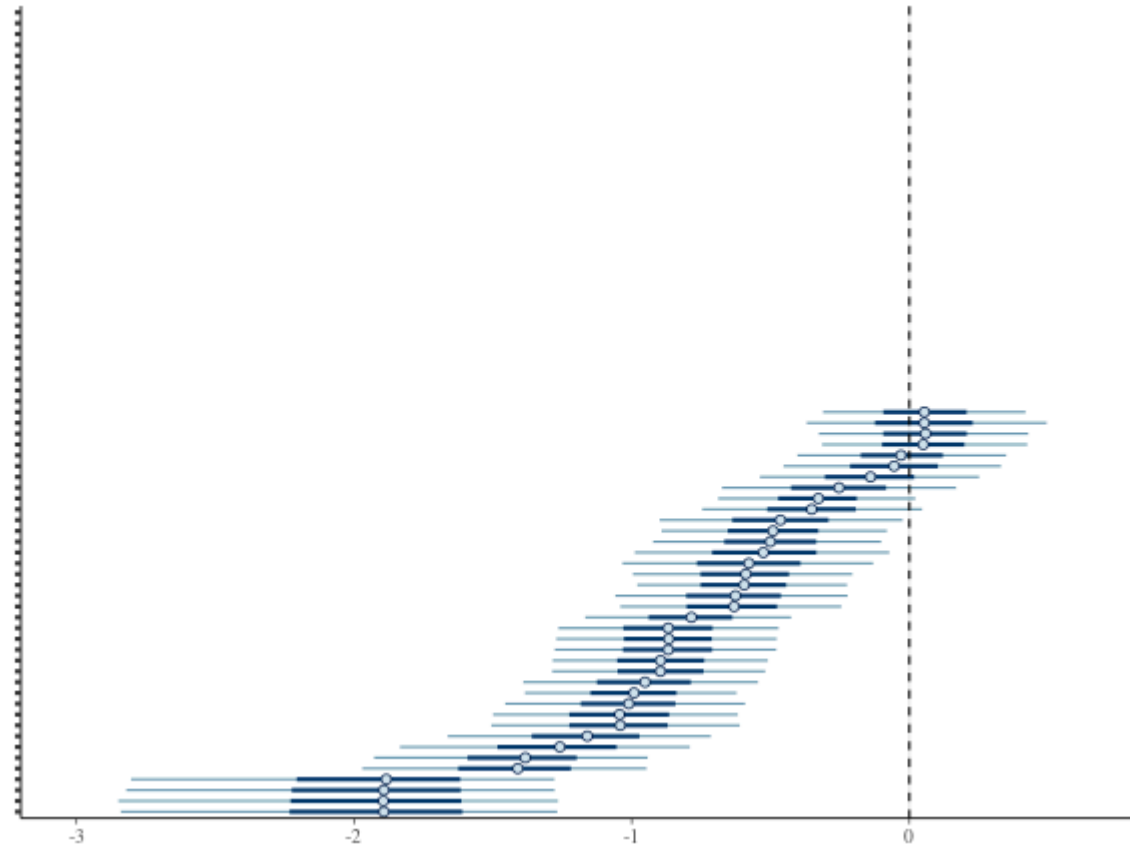
Example: Improving Polity

- A common classification of states as "democracies" that is commonly used is $\text{Polity} \geq 6$
 - What does that look like for the posteriors of those states?



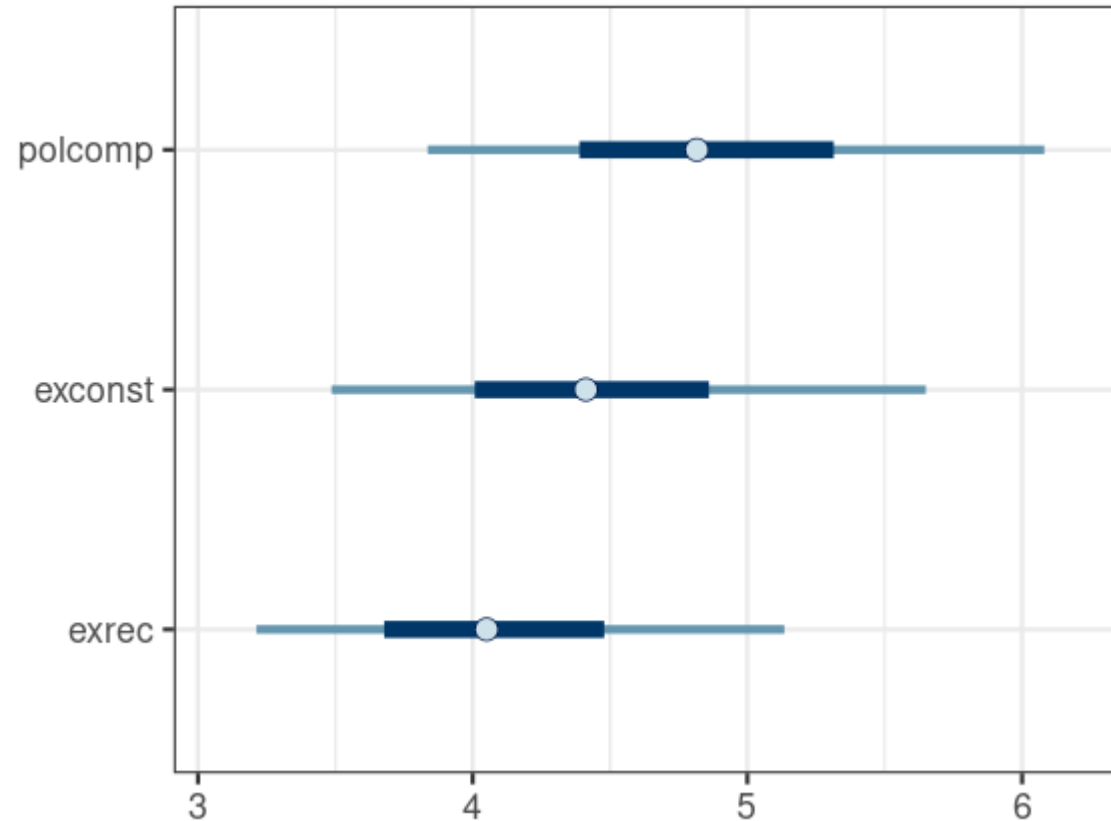
Example: Improving Polity

- How about the "non-democracies" $\text{Polity} < 6$?



Example: Improving Polity

- We can also get a sense of what component indices are most driving the ideal points by plotting β_j



Dynamic IRT model

- So far, we've focused on settings with just one time period.
 - **Jackman and Trier (2008)** estimate latent democracy scores for each year entirely separately.
- But this seems inefficient. The previous year's latent score is probably a good predictor of this year's score.
 - How do we incorporate this in the model?
- Put a **random walk prior** on θ_i
 - In political science, first used by **Martin and Quinn (2002)** to study ideology of supreme court justices.
 - Many other applications to different settings (e.g. UNGA voting by **Bailey et. al. (2017)**)

Dynamic IRT model

- We observe roll call votes for N legislators on J bills across T time periods.
 - Y_{ijt} denotes the choice (1 = Yea, 0 = Nay)
 - Note that not all legislators will vote in every time period, not every bill appears in every time period, etc...
- Same two-parameter set-up as before with a time-specific ideal point θ_{it} . **Martin and Quinn (2002)** use the probit link here.

$$Pr(Y_{ijt} = 1) = F\left(\alpha_j + \beta_j\theta_{it}\right)$$

Dynamic IRT model

- Same (diffuse) normal priors on the bill parameters β_j and α_j
- For the **first** ideal point for legislator i θ_{i0} , we use a standard normal prior.
- But each successive ideal point is assumed to come from a random walk centered on the *previous* ideal point

$$\theta_{it} \sim \mathcal{N}(\theta_{i(t-1)}, \omega^2)$$

- ω^2 is a user-specified "smoothing parameter" -- what is our prior belief about how "jumpy" the ideal points are from year-to-year.
 - $\omega^2 \rightarrow 0$ is equivalent to a **pooled** IRT model where every legislator has the same ideal point in each session.
 - $\omega^2 \rightarrow \infty$ is equivalent to the setting where each time period is analyzed **completely separately**

Illustration: Supreme Court Ideology

- Martin and Quinn (2002) implement an MCMC algorithm for this model.
 - Imai, Lo and Olmsted (2016) develop a faster Variational EM algorithm for obtaining the posterior modes.
 - Implemented in the **emIRT** package (along with the Martin and Quinn data)
- Load up the package

```
library(emIRT)
```

- Load up the Martin and Quinn data

```
data(mq_data)
```

Illustration: Supreme Court Ideology

- What does the "data matrix" look like?

```
mq_data$data.mq$rc[,4]
```

##	Harlan	Black	Douglas	Stewart	Marshall	Brennan
##	0	1	0	0	0	0
##	White	Warren	Clark	Frankfurter	Whittaker	Burton
##	0	0	0	0	0	0
##	Reed	Fortas	Goldberg	Minton	Jackson	Burger
##	0	0	0	0	0	0
##	Blackmun	Powell	Rehnquist	Stevens	O'Connor	Scalia
##	0	0	0	0	0	0
##	Kennedy	Souter	Thomas	Ginsburg	Breyer	Rutledge
##	0	0	0	0	0	0
##	Murphy	Vinson	Byrnes	Sutherland	Cardozo	Brandeis
##	0	0	0	-1	1	1
##	Butler	McReynolds	Hughes	OJRoberts	Stone	Roberts
##	-1	-1	1	-1	1	0
##	Alito	Sotomayor	Kagan			
##	0	0	0			

Illustration: Supreme Court Ideology

- How about the priors?

```
mq_data$priors.mq$beta.mu
```

```
##      [,1]  
## [1,]    0  
## [2,]    0
```

```
mq_data$priors.mq$beta.sigma
```

```
##      [,1] [,2]  
## [1,]    1    0  
## [2,]    0    1
```

Illustration: Supreme Court Ideology

- We use informative priors on some of the θ values to get identification

```
mq_data$priors.mq$x.mu0[mq_data$priors.mq$x.mu0 != 0]
```

```
## [1] -2  1  3
```

```
mq_data$priors.mq$x.sigma0[mq_data$priors.mq$x.mu0 != 0]
```

```
## [1] 0.1 0.1 0.1
```

Which justices do these correspond to?

```
rownames(mq_data$data.mq$rc)[mq_data$priors.mq$x.mu0 != 0]
```

```
## [1] "Black"      "Stewart"    "Rehnquist"
```

Illustration: Supreme Court Ideology

- How much smoothing are we doing?

```
head(mq_data$priors.mq$omega2)
```

```
##      [,1]  
## [1,] 0.1  
## [2,] 0.1  
## [3,] 0.1  
## [4,] 0.1  
## [5,] 0.1  
## [6,] 0.1
```

Illustration: Supreme Court Ideology

- Let's estimate the model

```
mq_estimates <- dynIRT(.data = mq_data$data.mq,  
                      .starts = mq_data$cur.mq,  
                      .priors = mq_data$priors.mq,  
                      .control = {list(  
                        threads = 1,  
                        verbose = TRUE,  
                        thresh = 1e-6,  
maxit=500  
                      )})
```

```
##  
## =====  
## dynIRT: Dynamic IRT via Variational Inference  
##  
## Iteration: 50  
##      Done in 51 iterations, using 1 threads.  
## =====
```

```
## Delete point estimates of 0, which are justices missing from that session  
mq_results <- c(t(mq_estimates$means$x))  
mq_results[mq_results==0] <- NA  
mq_results <- na.omit(mq_results)
```

Illustration: Supreme Court Ideology

- Let's make a plot

```
justice_df <- data.frame(justices = rownames(mq_data$data.mq$rc))
justice_df$justice_id <- 1:nrow(justice_df)
justice_df$startsession <- mq_data$data.mq$startlegis[,1]
justice_df$endsession <- mq_data$data.mq$endlegis[,1]
justice_df
```

##	justices	justice_id	startsession	endsession
## 1	Harlan	1	17	33
## 2	Black	2	0	33
## 3	Douglas	3	1	37
## 4	Stewart	4	21	43
## 5	Marshall	5	30	53
## 6	Brennan	6	19	52
## 7	White	7	24	55
## 8	Warren	8	16	31
## 9	Clark	9	12	29
## 10	Frankfurter	10	1	24
## 11	Whittaker	11	19	24
## 12	Burton	12	8	20
## 13	Reed	13	0	19
## 14	Fortas	14	28	31
## 15	Goldberg	15	25	27
## 16	Minton	16	12	18
## 17	Jackson	17	4	16

Illustration: Supreme Court Ideology

- Let's make a plot

```
results_df <- data.frame(justices = mq_data$justiceName, idealpoints = mq_results)
results_df <- left_join(results_df, justice_df, by="justices")
results_df <- results_df %>% group_by(justices) %>% mutate(session = (row_number() - 1) + start
results_df
```

```
## # A tibble: 697 × 6
## # Groups:   justices [45]
##   justices idealpoints justice_id startsession endsession session
##   <chr>      <dbl>      <int>      <dbl>      <dbl>      <dbl>
## 1 Harlan    0.432          1         17         33         17
## 2 Harlan    0.714          1         17         33         18
## 3 Harlan    0.900          1         17         33         19
## 4 Harlan    1.06           1         17         33         20
## 5 Harlan    1.07           1         17         33         21
## 6 Harlan    1.09           1         17         33         22
## 7 Harlan    1.03           1         17         33         23
## 8 Harlan    1.17           1         17         33         24
## 9 Harlan    1.14           1         17         33         25
## 10 Harlan   1.09           1         17         33         26
## # i 687 more rows
```


Illustration: Supreme Court Ideology

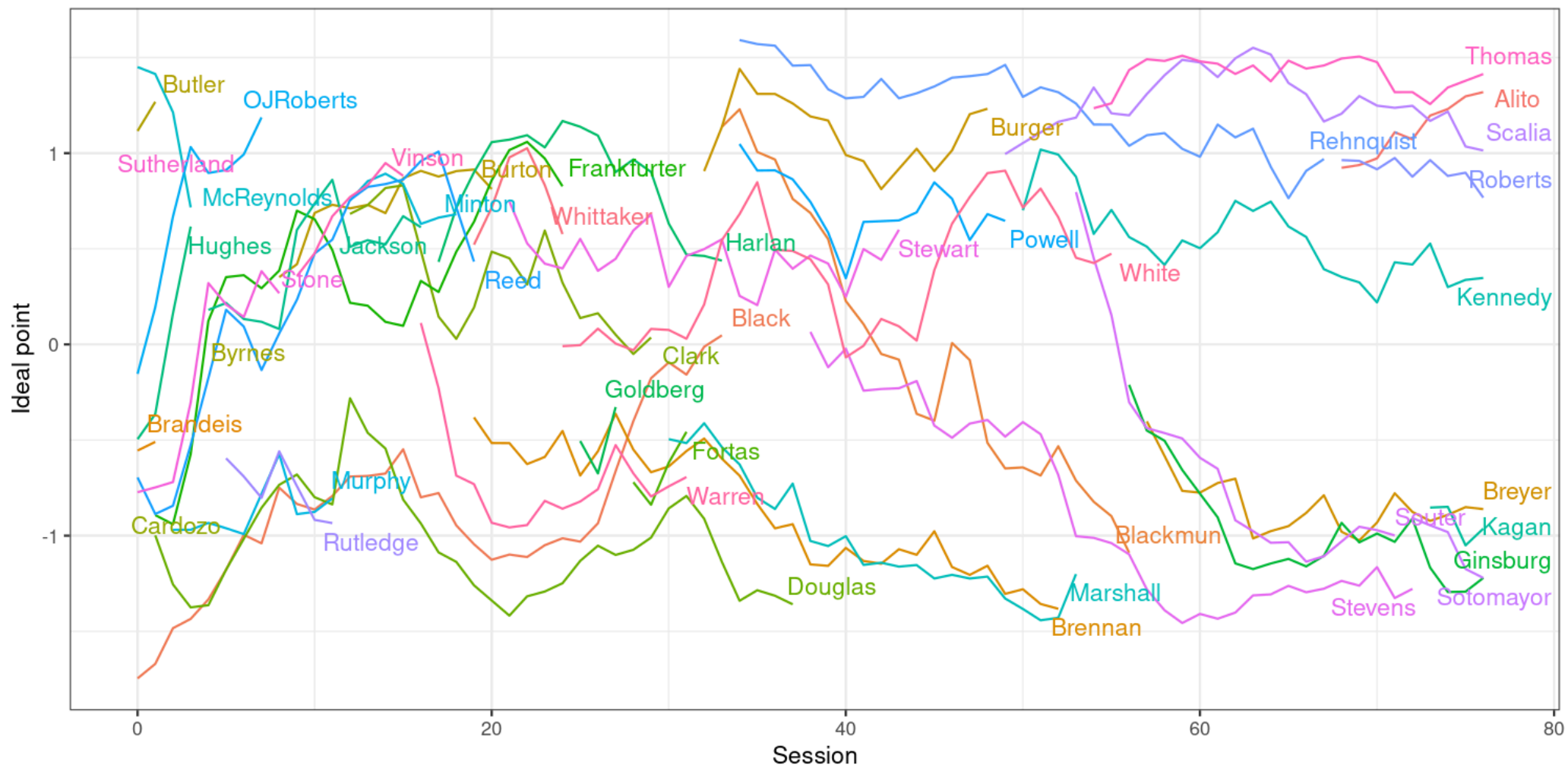


Illustration: Supreme Court Ideology

- What happens when we use a lower smoothing variance?

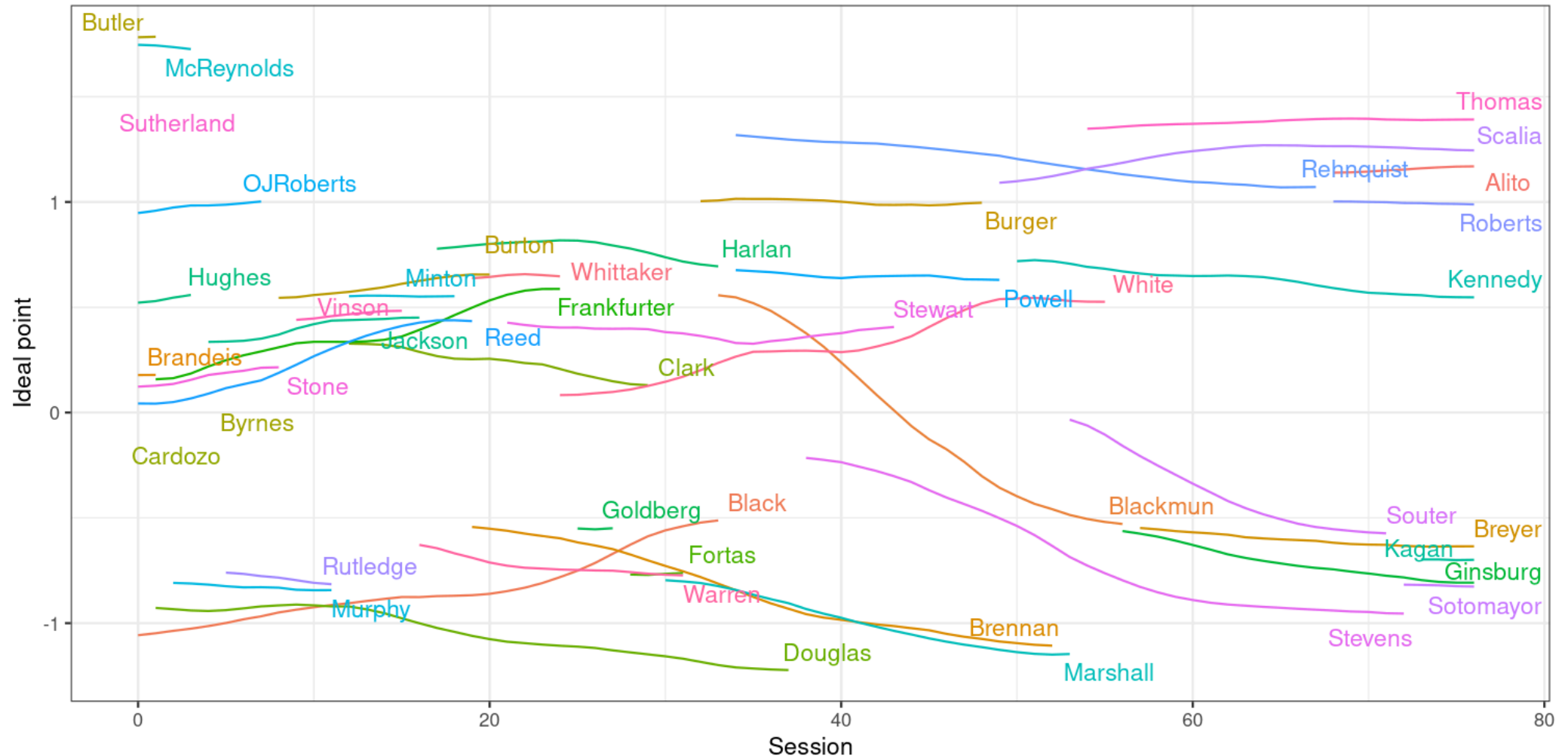
```
mq_data$priors.mq.strong <- mq_data$priors.mq
mq_data$priors.mq.strong$omega2[,1] <- .001

mq_estimates_heavysmooth <- dynIRT(.data = mq_data$data.mq,
                                   .starts = mq_data$cur.mq,
                                   .priors = mq_data$priors.mq.strong,
                                   .control = {list(
                                     threads = 1,
                                     verbose = TRUE,
                                     thresh = 1e-6,
                                     maxit=500
                                   )})
```

```
##
## =====
## dynIRT: Dynamic IRT via Variational Inference
##
##      Done in 45 iterations, using 1 threads.
## =====
```

```
## Delete point estimates of 0, which are justices missing from that session
mq_results_heavysmooth <- c(t(mq_estimates_heavysmooth$means$x))
mq_results_heavysmooth[mq_results_heavysmooth==0] <- NA
mq_results_heavysmooth <- na.omit(mq_results_heavysmooth)
```

Illustration: Supreme Court Ideology



Summary

- Like clustering models, Item Response Theory (IRT) models treat the outcome as a function of a **latent variable**
 - However, in IRT, the **latent variable** is typically continuous rather than a discrete
- As with clustering, imagine a regression model with **unknown regressors**
 - Our goal is to draw inferences about these regressors under the model structure.
- Inference algorithms leverage the fact that **conditional** on the latent regressors, the model has a familiar structure (e.g. logistic regression)
 - But note similar identifiability problems as clustering (invariance to rotation/reflection)
- **Careful!** - Results dependent on model structure!
 - Interpretation of the model parameters is ultimately up to the researchers - no inherent "meaning" to the latent scale.

